

## 16-899: Reference list for Monday, Feb 17<sup>th</sup>

We talked about this paper:

Trinkle JC, Paul RP. Planning for dexterous manipulation with sliding contacts. The International Journal of Robotics Research. 1990 Jun 1;9(3):24-48.

<http://www.cs.rpi.edu/~trink/Papers/TPijrr90.pdf>

If there had been time, I had queued up some discussion of these papers, taking a bit of a random hop through time. You may also want to take a look if you have not seen them before.

Erdmann M. An exploration of nonprehensile two-palm manipulation. The International Journal of Robotics Research. 1998 May 1;17(5):485-503.

<http://repository.cmu.edu/cgi/viewcontent.cgi?article=1247&context=robotics>

Jäkel R, Schmidt-Rohr SR, Rühl SW, Kasper A, Xue Z, Dillmann R. Learning of planning models for dexterous manipulation based on human demonstrations. International Journal of Social Robotics. 2012 Nov 1;4(4):437-48.

<http://link.springer.com/article/10.1007/s12369-012-0162-y>