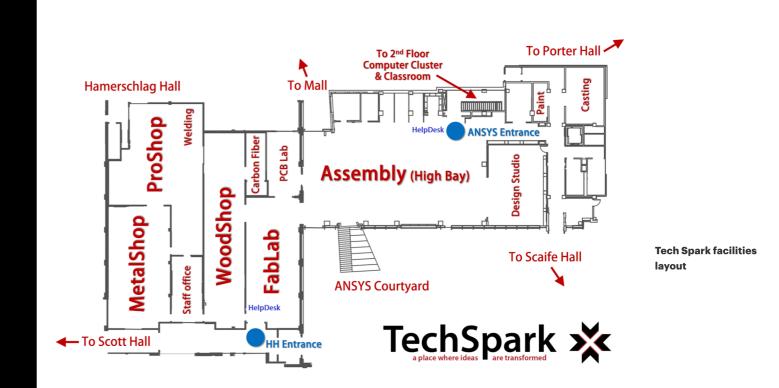
# **Final Projects**

- Find something that fits your specific interests and strengths
- We may be able to help you find resources <u>https://engineering.cmu.edu/techspark/index.html</u>



#### **Facilities layout**

**Example Projects** 

- whiskers
- task and motion planner for manipulation
- mixed soft / rigid hand design
- measuring success of canonical grasps on benchmark tasks
- building a hand with nonlinear passive compliant joints
- building a hand for supporting large weights
- learning to push in simulation with a soft hand
- optimizing hand design for robust translation / rotation

#### ... and some more

- grasping scanned objects in the real world
- building hand plus force based behaviors
- building soft hand and exploring synergies for dexterous tasks
- developing mathematical models of soft gripper behavior
- exploring whether synergies can assist in learning to manipulate in simulation using OpenAI Gym
- labelling human manipulation tasks

#### Ideas / Themes

## Make a hand

- Yale OpenHand project <u>https://www.eng.yale.edu/</u> grablab/openhand/
- Soft Robotics Toolkit <u>https://softroboticstoolkit.com/</u>
- follow a published paper
- 3D print and test a simple soft hand
- Build a sensor mitten

## Simulation ideas

- Create and test a simulation model of the human index finger (muscles, tendons, bones...)
- Manipulation learning with Gymnasium <u>https://github.com/Farama-Foundation/Gymnasium</u>
- Contact capture, tracking, and modeling

# Simulators to check out

- MuJoCo <u>https://mujoco.org/</u>
- Isaac Sim <u>https://developer.nvidia.com/isaac-sim</u>
- SOFA <u>https://www.sofa-framework.org/</u>
- Klamp't (IROS 2016 Simulation Manipulation Challenge) <u>http://motion.cs.illinois.edu/klampt/</u>
- DART <u>https://dartsim.github.io/</u>
- IPC (large deformation dynamics) <u>https://github.com/ipc-sim/IPC</u>
- Box2D

### Other ideas

- Planning and/or control
- Hands in computer graphics / VR
- Sensor design, development, testing
- Human subjects studies (dexterous manipulation "in the wild")
- "Area" studies (more like a very detailed research report with suggestions for future research)

# Final Thoughts

- What question do you want to answer?
- What idea to you want to test?
- What area do you want to explore further / understand better?