Today we talked about:

**SIMBICON: Simple Biped Locomotion Control**
KangKang Yin, Kevin Loken, and Michiel van de Panne
*ACM Transactions on Graphics (Proc. ACM SIGGRAPH 2007)*
http://www.cs.ubc.ca/~van/papers/Simbicon.htm


Robert Full’s lab: http://polypedal.berkeley.edu/cgi-bin/twiki/view/PolyPEDAL/WebHome

The RHex robot http://kodlab.seas.upenn.edu/RHex/Home

Mitsuo Kawato’s robotics lab at ATR: http://www.cns.atr.jp/bri/en/research/learningbiped-locomotion/