Ray Tracing



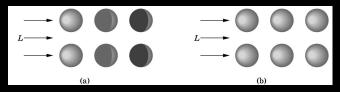
Ray Casting
Ray-Surface Intersections
Barycentric Coordinates
Reflection and Transmission
[Shirley, Ch.9]
Ray Tracing Handouts

Announcements

- Assignment 2 Grades Returned
- Assignment 3 Out Today

Local vs. Global Rendering Models

- Local rendering models (graphics pipeline)
 - Object illuminations are independent
 - No light scattering between objects
 - No real shadows, reflection, transmission
- Global rendering models
 - Ray tracing (highlights, reflection, transmission)
 - Radiosity (surface interreflections)



Object Space vs. Image Space

- Graphics pipeline: for each object, render
 - Efficient pipeline architecture, on-line
 - Difficulty: object interactions
- Ray tracing: for each pixel, determine color
 - Pixel-level parallelism, off-line
 - Difficulty: efficiency, light scattering
- Radiosity: for each two surface patches, determine diffuse interreflections
 - Solving integral equations, off-line
 - Difficulty: efficiency, reflection

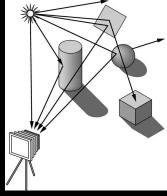
Forward Ray Tracing

• Rays as paths of photons in world space

• Forward ray tracing: follow photon from light

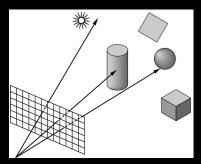
sources to viewer

 Problem: many rays will not contribute to image!



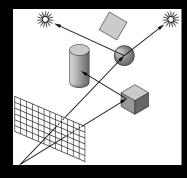
Backward Ray Tracing

- Ray-casting: one ray from center of projection through each pixel in image plane
- Illumination
 - 1. Phong (local as before)
 - 2. Shadow rays
 - 3. Specular reflection
 - 4. Specular transmission
- (3) and (4) are recursive



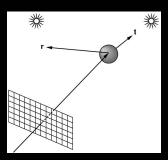
Shadow Rays

- Determine if light "really" hits surface point
- Cast shadow ray from surface point to light
- If shadow ray hits opaque object,no contribution
- Improved diffuse reflection



Reflection Rays

- Calculate specular component of illumination
- Compute reflection ray (recall: backward!)
- Call ray tracer recursively to determine color
- Add contributions
- Transmission ray
 - Analogue for transparent or translucent surface
 - Use Snell's laws for refraction
- Later:
 - Optimizations, stopping criteria

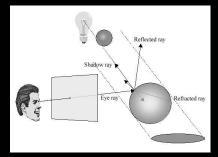


Ray Casting

- Simplest case of ray tracing
- · Required as first step of recursive ray tracing
- · Basic ray-casting algorithm
 - For each pixel (x,y) fire a ray from COP through (x,y)
 - For each ray & object calculate closest intersection
 - For closest intersection point p
 - · Calculate surface normal
 - For each light source, calculate and add contributions
- Critical operations
 - Ray-surface intersections
 - Illumination calculation

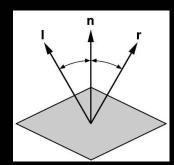
Recursive Ray Tracing

- Calculate specular component
 - Reflect ray from eye on specular surface
 - Transmit ray from eye through transparent surface
- Determine color of incoming ray by recursion
- Trace to fixed depth
- Cut off if contribution below threshold



Angle of Reflection

- Recall: incoming angle = outgoing angle
- $r = 2(I \uparrow n) n \bar{I}$
- For incoming/outgoing ray negate I!
- Compute only for surfaces with actual reflection
- Use specular coefficient
- Add specular and diffuse components

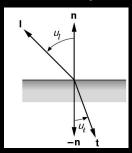


Refraction

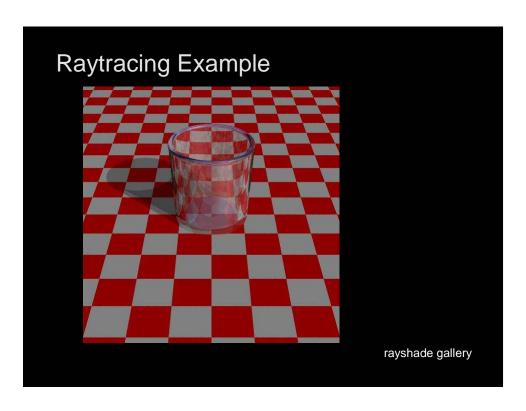
- Index of refraction is relative speed of light
- Snell's law
 - $-\eta_1$ = index of refraction for upper material
 - η_t = index of refraction for lower material

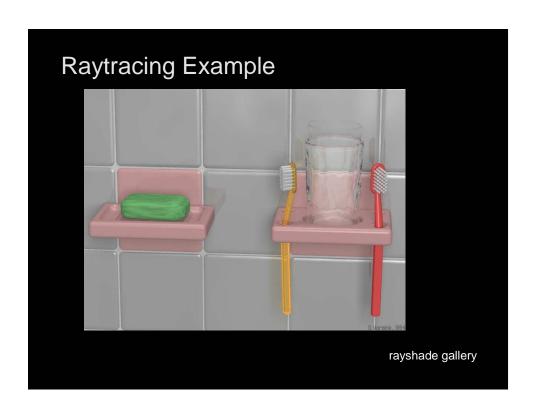
$$[U = \theta]$$

$$egin{aligned} rac{\sin(heta_l)}{\sin(heta_t)} &= rac{\eta_l}{\eta_l} = \eta \ \mathbf{t} &= -rac{1}{\eta}\mathbf{l} - (\cos(heta_t) - rac{1}{\eta}\cos(heta_l))\mathbf{n} \ \mathrm{where} & \cos(heta_l) &= \mathbf{l} \cdot \mathbf{n} \ \mathrm{and} & \cos^2(heta_t) &= 1 - rac{1}{\eta^2}(\mathbf{1} - \mathbf{l} \cdot \mathbf{n}) \end{aligned}$$





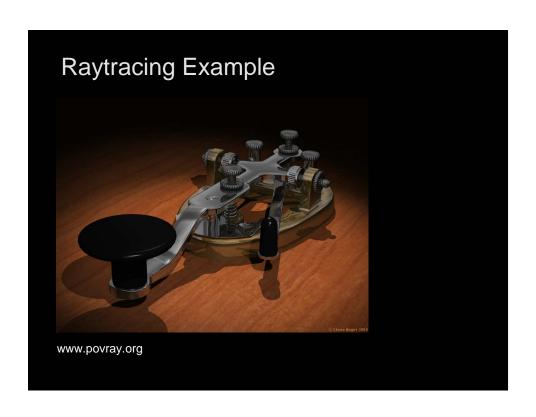




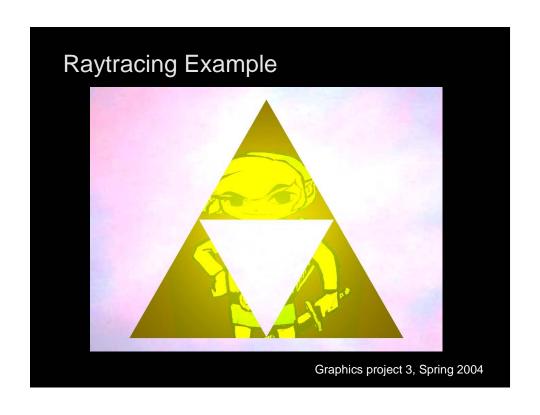












Intersections

Ray-Surface Intersections

- General implicit surfaces
- General parametric surfaces
- Specialized analysis for special surfaces
 - Spheres
 - Planes
 - Polygons
 - Quadrics
- Do not decompose objects into triangles!
- CSG is also a good possibility

Rays and Parametric Surfaces

- Ray in parametric form
 - Origin $\mathbf{p}_0 = [\mathbf{x}_0 \ \mathbf{y}_0 \ \mathbf{z}_0 \ \mathbf{1}]^\mathsf{T}$
 - Direction $\mathbf{d} = [\mathbf{x}_d \ \mathbf{y}_d \ \mathbf{z}_d \ \mathbf{0}]^T$
 - Assume **d** normalized $(x_d^2 + y_d^2 + z_d^2 = 1)$
 - Ray $p(t) = p_0 + dt$ for t > 0
- Surface in parametric form
 - Point $\mathbf{q} = g(\mathbf{u}, \mathbf{v})$, possible bounds on \mathbf{u}, \mathbf{v}
 - Solve $\mathbf{p} + \mathbf{d} t = g(u, v)$
 - Three equations in three unknowns (t, u, v)

Rays and Implicit Surfaces

- Ray in parametric form
 - Origin $\mathbf{p}_0 = [\mathbf{x}_0 \ \mathbf{y}_0 \ \mathbf{z}_0 \ \mathbf{1}]^T$
 - Direction $\mathbf{d} = [\mathbf{x}_d \ \mathbf{y}_d \ \mathbf{z}_d \ 0]^t$
 - Assume **d** normalized $(x_d^2 + y_d^2 + z_d^2 = 1)$
 - Ray $p(t) = p_0 + dt$ for t > 0
- Implicit surface
 - Given by $f(\mathbf{q}) = 0$
 - Consists of all points \mathbf{q} such that $f(\mathbf{q}) = 0$
 - Substitute ray equation for **q**: $f(\mathbf{p}_0 + \mathbf{d} t) = 0$
 - Solve for t (univariate root finding)
 - Closed form (if possible) or numerical approximation

Ray-Sphere Intersection I

- Common and easy case
- Define sphere by
 - Center $\mathbf{c} = [\mathbf{x}_c \ \mathbf{y}_c \ \mathbf{z}_c \ \mathbf{1}]^T$
 - Radius r
 - Surface $f(\mathbf{q}) = (x x_c)^2 + (y y_c)^2 + (z z_c)^2 r^2 = 0$
- Plug in ray equations for x, y, z:

$$x = x_0 + x_d t
 y = y_0 + y_d t
 z = z_0 + z_d t$$

$$(x_0 + x_d t - x_c)^2
+ (y_0 + y_d t - y_c)^2
+ (z_0 + z_d t - z_c)^2 = r^2$$

Ray-Sphere Intersection II

Simplify to

$$at^2 + bt + c = 0$$

where

$$\begin{aligned} a &= x_d^2 + y_d^2 + z_d^2 = 1 \quad \text{since } |\mathbf{d}| = 1 \\ b &= 2\left(x_d(x_0 - x_c) + y_d(y_0 - y_c) + z_d(z_0 - z_c)\right) \\ c &= (x_0 - x_c)^2 + (y_0 - y_c)^2 + (z_0 - z_c)^2 - r^2 \end{aligned}$$

Solve to obtain t₀ and t₁

$$t_{0,1} = \frac{-b \pm \sqrt{b^2 - 4c}}{2}$$

Check if t_0 , $t_1 > 0$ (ray) Return min(t_0 , t_1)

Ray-Sphere Intersection III

• For lighting, calculate unit normal

$$\mathbf{n} = \frac{1}{r} [(x_i - x_c) (y_i - y_c) (z_i - z_c) 0]^T$$

• Negate if ray originates inside the sphere!

Simple Optimizations

- Factor common subexpressions
- · Compute only what is necessary
 - Calculate b² 4c, abort if negative (why?)
 - Compute normal only for closest intersection
 - Other similar optimizations [Handout]

Ray-Polygon Intersection I

- Assume planar polygon
 - 1. Intersect ray with plane containing polygon
 - 2. Check if intersection point is inside polygon
- Plane
 - Implicit form: ax + by + cz + d = 0
 - Unit normal: $\mathbf{n} = [a \ b \ c \ 0]^T$ with $a^2 + b^2 + c^2 = 1$
- Substitute:

$$a(x_0 + x_d t) + b(y_0 + y_d t) + c(z_0 + z_d t) + d = 0$$

• Solve:
$$t = \frac{-(ax_0 + by_0 + cz_0 + d)}{ax_d + by_d + cz_d}$$

Ray-Polygon Intersection II

- Substitute t to obtain intersection point in plane
- Test if point inside polygon [see Handout]

Ray-Quadric Intersection

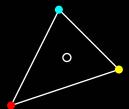
- Quadric f(p) = f(x, y, z) = 0, where f is polynomial of order 2
- Sphere, ellipsoid, paraboloid, hyperboloid, cone, cylinder
- Closed form solution as for sphere
- Important case for modelling in ray tracing
- Combine with CSG

[see Handout]

Barycentric Coordinates

Interpolated Shading for Ray Tracing

- Assume we know normals at vertices
- How do we compute normal of interior point?
- Need linear interpolation between 3 points
- Barycentric coordinates
- Yields same answer as scan conversion

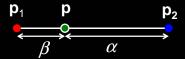


Barycentric Coordinates in 1D

Linear interpolation

$$-\mathbf{p}(t) = (1-t)\mathbf{p}_1 + t\mathbf{p}_2, 0 \le t \le 1$$

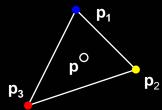
- $-\mathbf{p}(t) = \alpha \mathbf{p}_1 + \beta \mathbf{p}_2$ where $\alpha + \beta = 1$ \mathbf{p} is between \mathbf{p}_1 and \mathbf{p}_2 iff $0 \le \alpha, \beta \le 1$
- Geometric intuition
 - Weigh each vertex by ratio of distances from ends



 α , β are called barycentric coordinates

Barycentric Coordinates in 2D

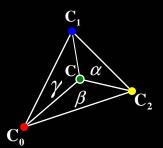
Given 3 points instead of 2



- Define 3 barycentric coordinates, α , β , γ
- p = α p₁ + β p₂ + γ p₃
 p inside triangle iff 0 ≤ α, β, γ ≤ 1, α + β + γ = 1
- How do we calculate α , β , γ given **p**?

Barycentric Coordinates for Triangle

• Coordinates are ratios of triangle areas



$$\alpha = \frac{Area(\mathbf{CC_1C_2})}{Area(\mathbf{C_0C_1C_2})}$$

$$\beta = \frac{Area(\mathbf{C_0CC_2})}{Area(\mathbf{C_0C_1C_2})}$$

$$\gamma = \frac{Area(\mathbf{C_0C_1C})}{Area(\mathbf{C_0C_1C_2})} = 1 - \alpha - \beta$$

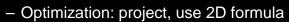
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Computing Triangle Area

- In 3 dimensions
 - Use cross product

 - Parallelogram formula
 Area(ABC) = (1/2)|(B − A) § (C − A)|



- In 2 dimensions
 - Area(x-y-proj(ABC)) = $(1/2)((b_x - a_x)(c_y - a_y) - (c_x - a_x)(b_y - a_y))$

Ray Tracing Preliminary Assessment

- Global illumination method
- Image-based
- Pros:
 - Relatively accurate shadows, reflections, refractions
- Cons:
 - Slow (per pixel parallelism, not pipeline parallelism)
 - Aliasing
 - Inter-object diffuse reflections

Ray Tracing Acceleration

- Faster intersections
 - Faster ray-object intersections
 - · Object bounding volume
 - Efficient intersectors
 - Fewer ray-object intersections
 - Hierarchical bounding volumes (boxes, spheres)
 - · Spatial data structures
 - Directional techniques
- Fewer rays
 - Adaptive tree-depth control
 - Stochastic sampling
- Generalized rays (beams, cones)

