# Recap from Monday

- Visualizing Networks
- Caffe overview
- Slides are now online

## Today

- Edges and Regions, GPB
- Fast Edge Detection Using Structured Forests
  - Zhihao Li
- Holistically-Nested Edge Detection
  - Yuxin Wu
- Selective Search for Object Recognition
  - Chun-Liang Li

## Logistics

- Please read:
  - Region-based Convolutional Networks for Accurate Object Detection and Semantic Segmentation
- If you're up next, please meet us
- Project Proposals Due in < 1 week</li>
  - If you have questions, ask to meet

# **Edges and Regions**

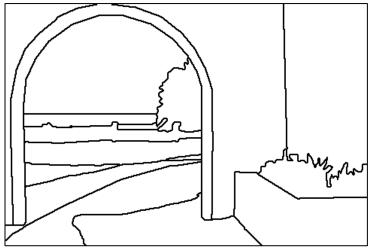
David Fouhey

#### Task

"I stand at the window and see a house, trees, sky. Theoretically I might say there were 327 brightnesses and nuances of colour. Do I have "327"? No. I have sky, house, and trees."

-Max Wertheimer





Quote from Jitendra Malik's page

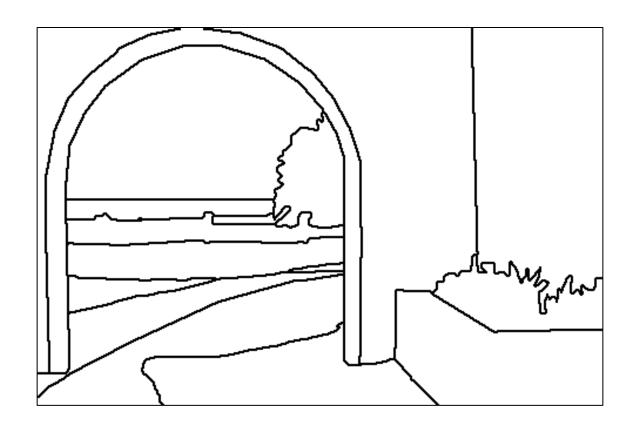
# Approaching the Task – Regions

Decomposing image into K connected regions (Clustering task)

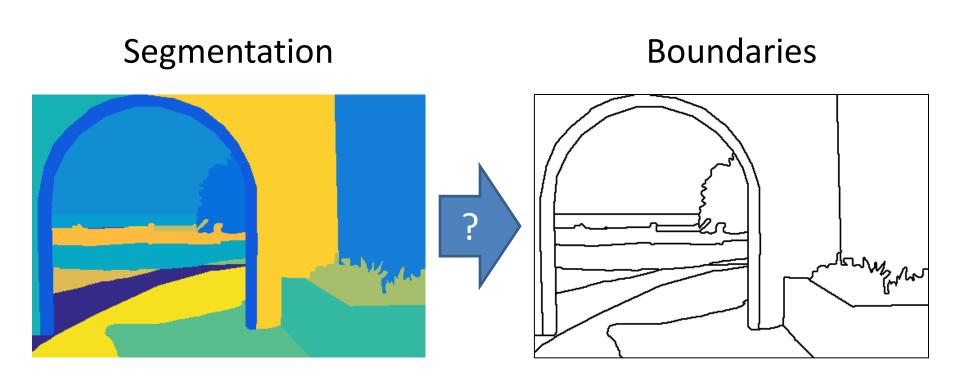


# Approaching the Task – Edges

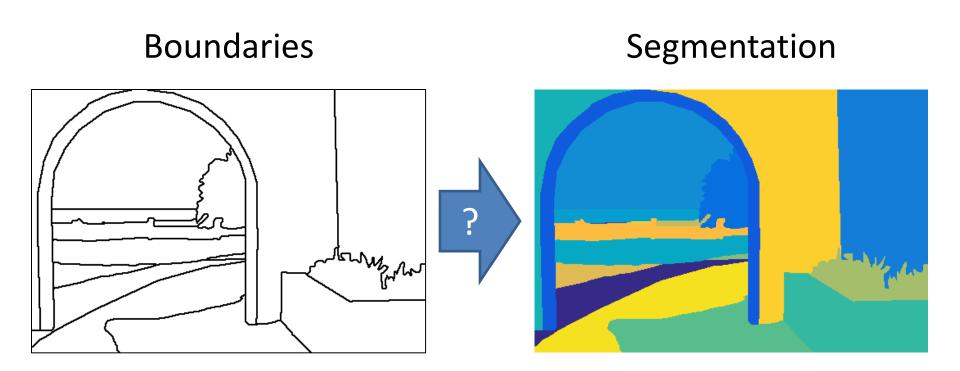
HxWx {0,1} classification problem



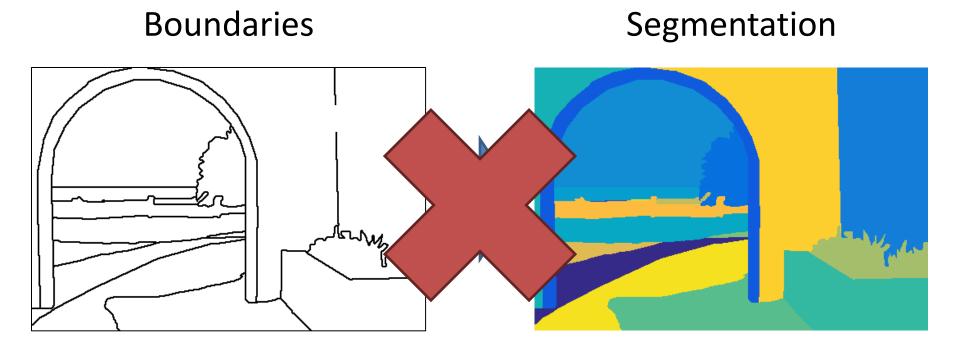
# Are the Tasks Equivalent?



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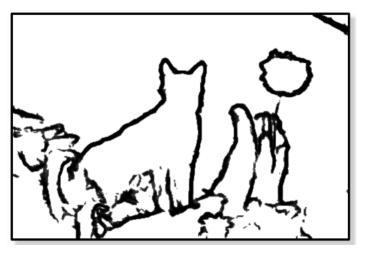


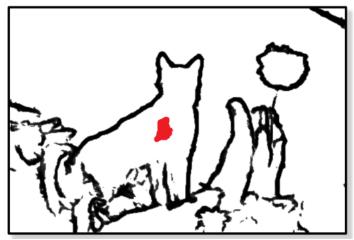
Contours have to be closed!

#### Does This Matter in the CNN Era?

HED – State of the Art









## Are These Well-Defined Tasks?

Should blue and yellow go in the same segment?

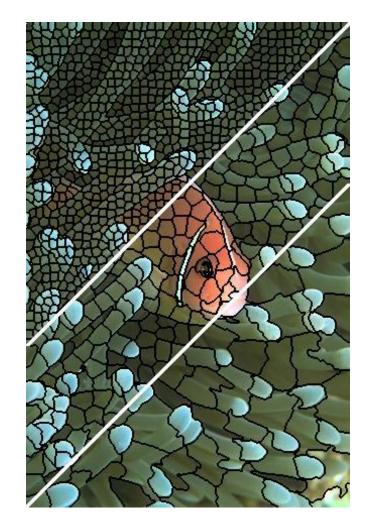


Image credit: NYU depth dataset

# Successes – Superpixels

**Problem:** >10^5 pixels intractable for reasoning

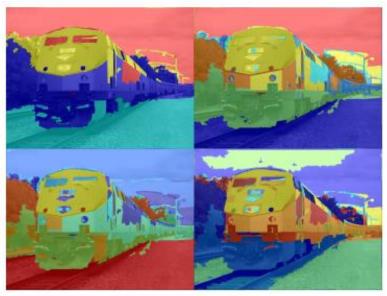
Solution: use bigger/super pixels that don't ruin any boundaries



## Successes – Multiple Segmentations

- Problem: No one segmentation is good
- **Solution**: Use many, figure it out later





# Contributions of Paper

- Merges the (edges + regions) approaches
- Introduces machinery used throughout vision
- Landmark paper in segmentation/boundary detection
- Note: the <u>questions</u> are often as important as the answers

## Questions from Piazza

- Where's the learning?!
  - Great idea! Two papers next
- What's this useful for?
  - Great question! Last paper today, paper for Monday.

#### Dataset – BSDS 500

#### **Images**

- 500 Total
- 300 Training, 200 Testing

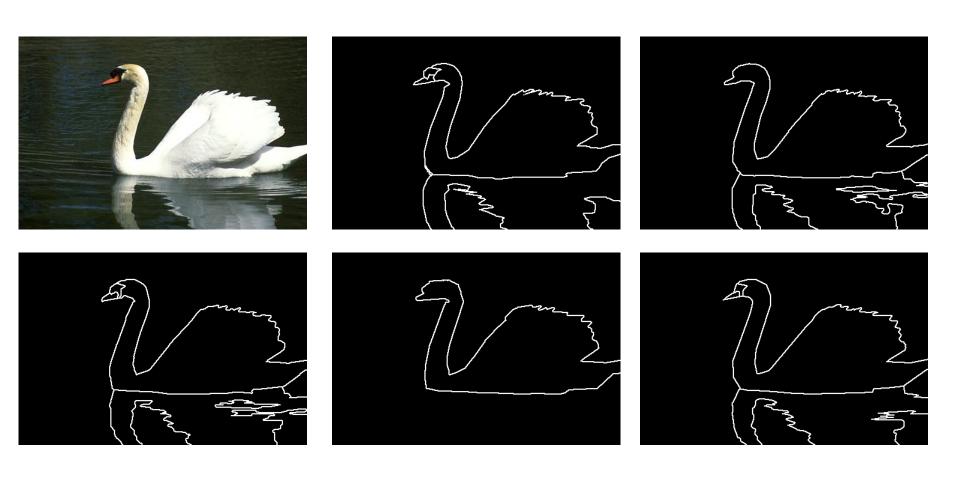
#### **Annotation**

- 5 annotators (CV students) per image
- Annotators annotate segment

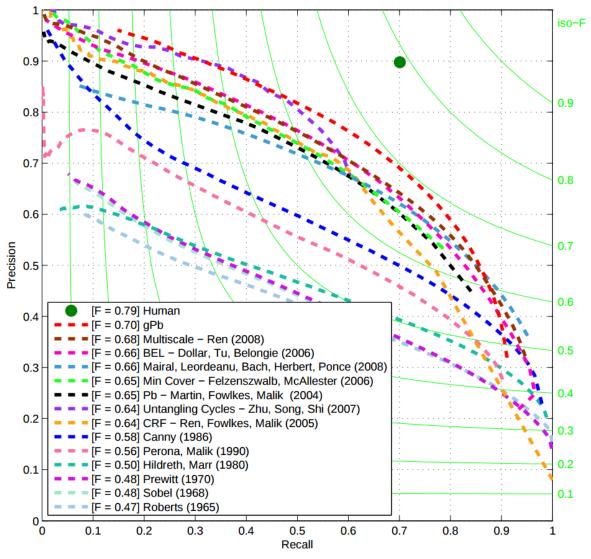
#### Dataset – Instructions

Divide each image into pieces, where each piece represents a distinguished thing in the image. It is important that all of the pieces have approximately equal importance. The number of things in each image is up to you. Something between 2 and 20 should be reasonable for any of our images

# Dataset – Image and Annotations



### Evaluation Criteria – Boundaries



Precision
= TP / (TP+FP)
(fraction of predicted + results that are +)

Recall
= TP / (TP+FN)
(fraction of + results that are predicted +)

## Evaluation Criteria – Segments

 In words: Average the intersection/union of the best predicted region for all GT regions, weighted by GT region size

$$\mathcal{C}(S' \to S) = \frac{1}{N} \sum_{R \in S} |R| \cdot \max_{R' \in S'} \mathcal{O}(R, R') \quad \mathcal{O}(R, R') = \frac{|R \cap R'|}{|R \cup R'|}$$

 Previous evaluation criteria don't clearly distinguish dumb baselines from algorithm outputs

#### **GPB-OWT-UCM**

Boundary Detection

Local Discontinuity

Segmentation Machinery

Spectral Embedding

Boundary Detection

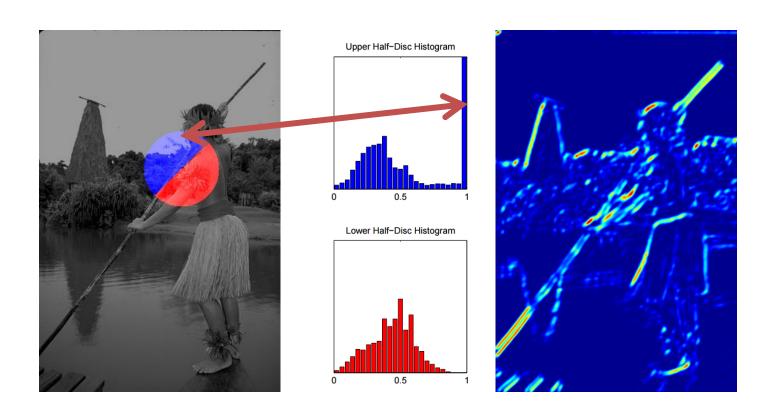
Spectral Discontinuity

Segmentation Machinery

**OWT+UCM** 

### **Local Terms**

• Core Idea: can compute <u>histogram</u> distances



## **Local Terms**

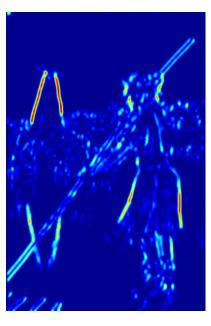
Luminance Image

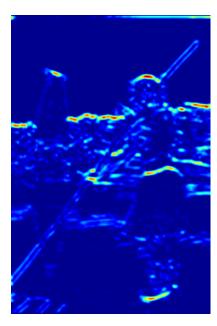
Orientation 1

Orientation 2

Max over Orientations









## **Local Terms**

Luminance Image

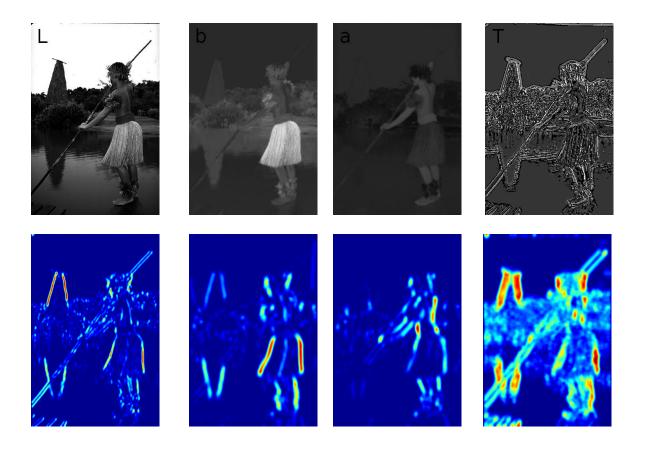


Max over Orientations

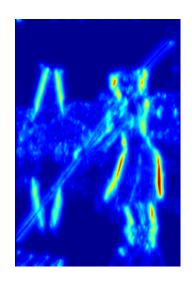


# Local Terms – Multiple Cues

#### Accumulate evidence per-orientation



Weighted
Sum of
Predictions



## Learning

- Simple linear combinations = few parameters
- Gradient ascent in the reading
- Logistic regression in past

Contour strength weights in feature + scale 
$$mPb(x,y,\theta) = \sum_{s} \sum_{i} \alpha_{i,s} G_{i,\sigma(i,s)}(x,y,\theta)$$

#### **GPB-OWT-UCM**

Boundary Detection

Local Discontinuity

Segmentation Machinery

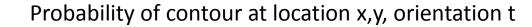
Spectral Embedding

Boundary Detection

Spectral Discontinuity

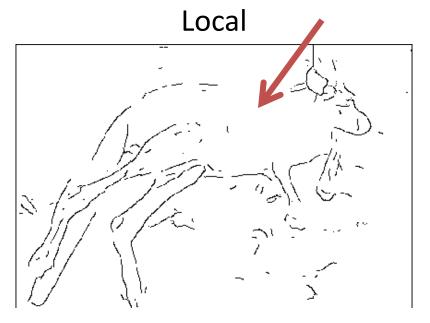
Segmentation Machinery

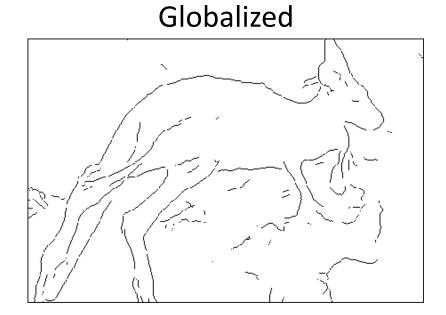
**OWT+UCM** 



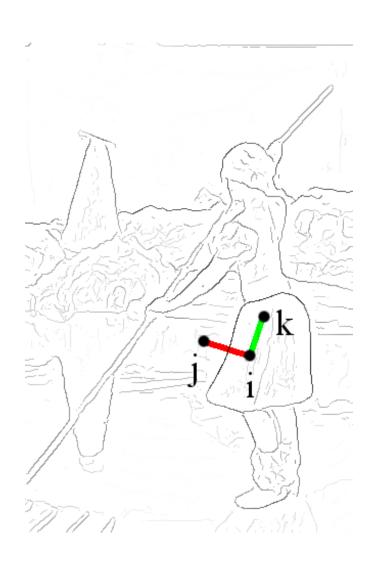
## Globalization – Motivation







### Globalization



### $W \in R^{(HW)x(HW)}$

#### **Normal Spectral Clustering**

- 1. Use W to produce embedding/space defined by eigenvectors of a system of equations. See links on Piazza for why
- 2. Cluster in induced space

#### **This Paper**

- Use W to produce embedding/space defined by eigenvectors of a system of equations
- 2. Treat eigenvectors as images, compute gradient

## Globalization

Input



Eigenvectors of Spectral System



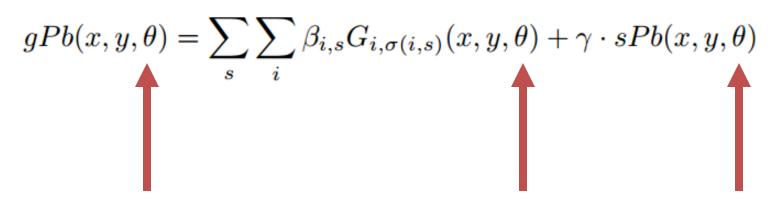


Weighted **Sum of Gradients** 



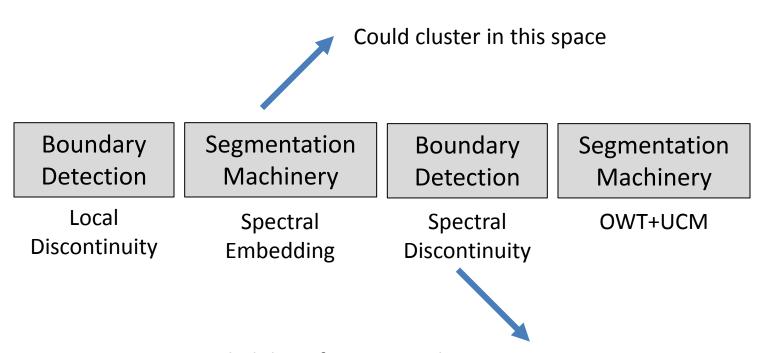
# Combining Global + Local

Linear weighting; weights learned with gradient ascent



Orientations processed **separately** throughout Why is this important?

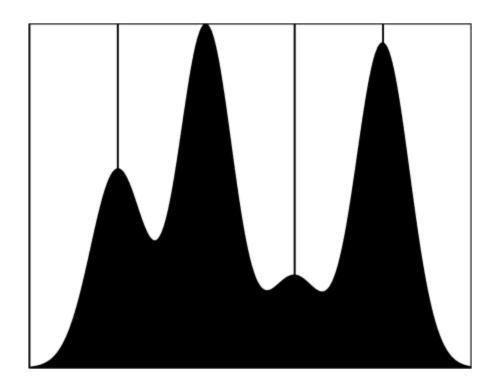
#### **GPB-OWT-UCM**



Probability of contour at location x,y, orientation t taking into consideration soft segmentations

#### Watershed Transform – 1D Version

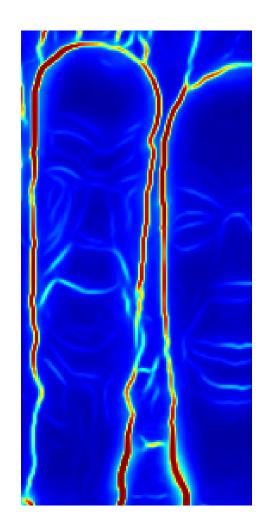
- Black region: probability of boundary
- Black lines: watershed boundaries

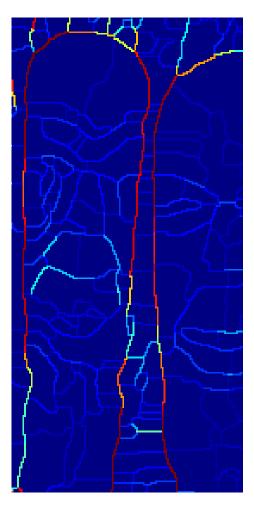


#### Orientation

Problem:
probability of
boundary is
orientationdependent

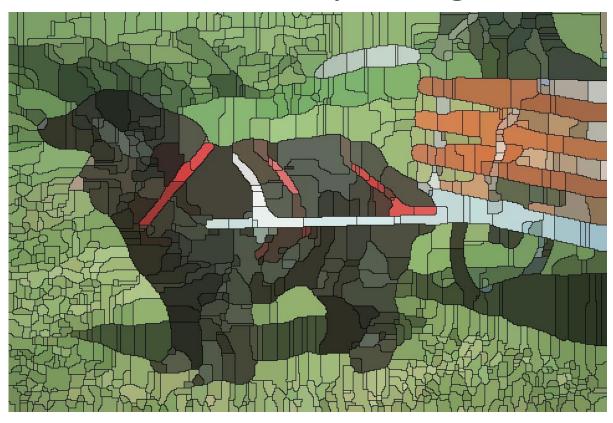
**Solution:** get probability of boundary in direction





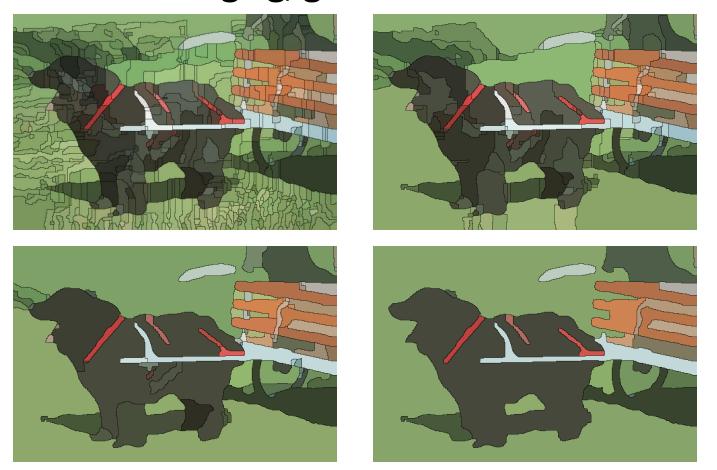
## Output of Watershed Transform

"Oversegmentation" of image with boundary strengths



## **UCM**

Hierarchical merging; guarantees closed contours



### **GPB-OWT-UCM**

Boundary Detection

Local Discontinuity

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Spectral Embedding Boundary Detection

Spectral Discontinuity

Segmentation Machinery

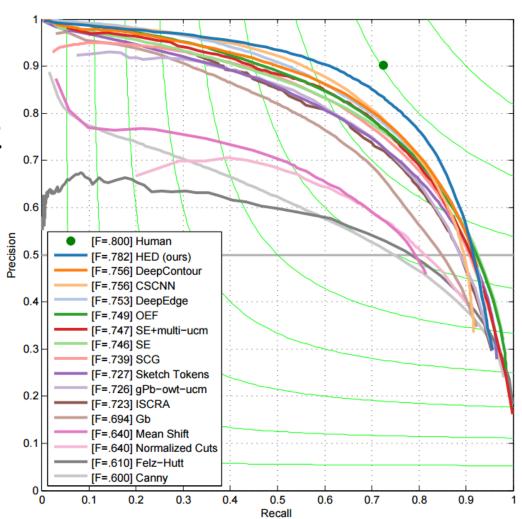
**OWT+UCM** 

Contour that can be cut at any point to yield closed regions

#### Results – State of the Art

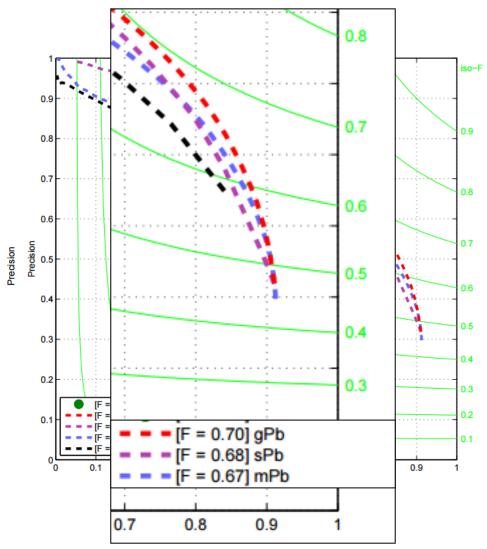
**This**: 72.6

Current SOA: 78.2



# Results – Ablative Analysis

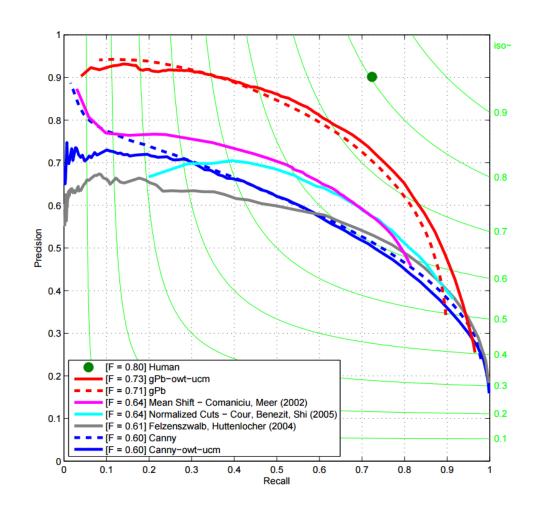
- Combining Local + Global helps
- Why does local help in high-recall regime?



# Results – Ablative Analysis

#### OWT/UCM:

- Ensures closed boundaries
- Helps a little



## Next Up

- Fast Edge Detection Using Structured Forests
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  - Yuxin Wu
- Selective Search for Object Recognition
  - Chun-Liang Li

# Stash