

# Bidirectional path tracing



15-468, 15-668, 15-868  
Physics-based Rendering  
Spring 2025, Lecture 13



# Course announcements

- Materials from yesterday's recitation posted on Slack.
- Yannis is traveling for SIGGRAPH next week.
  - Lectures by Sreekar Ranganathan (Tuesday) and Bailey Miller (Thursday).

# Overview of today's lecture

- Types of light paths.
- Light tracing.
- Bidirectional path tracing.

# Slide credits

Most of these slides were directly adapted from:

- Wojciech Jarosz (Dartmouth).



# Light Paths



# Light Paths

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Express light paths in terms of the surface interactions that have occurred

A light path is a chain of linear segments joined at event “vertices”



# Heckbert's Classification

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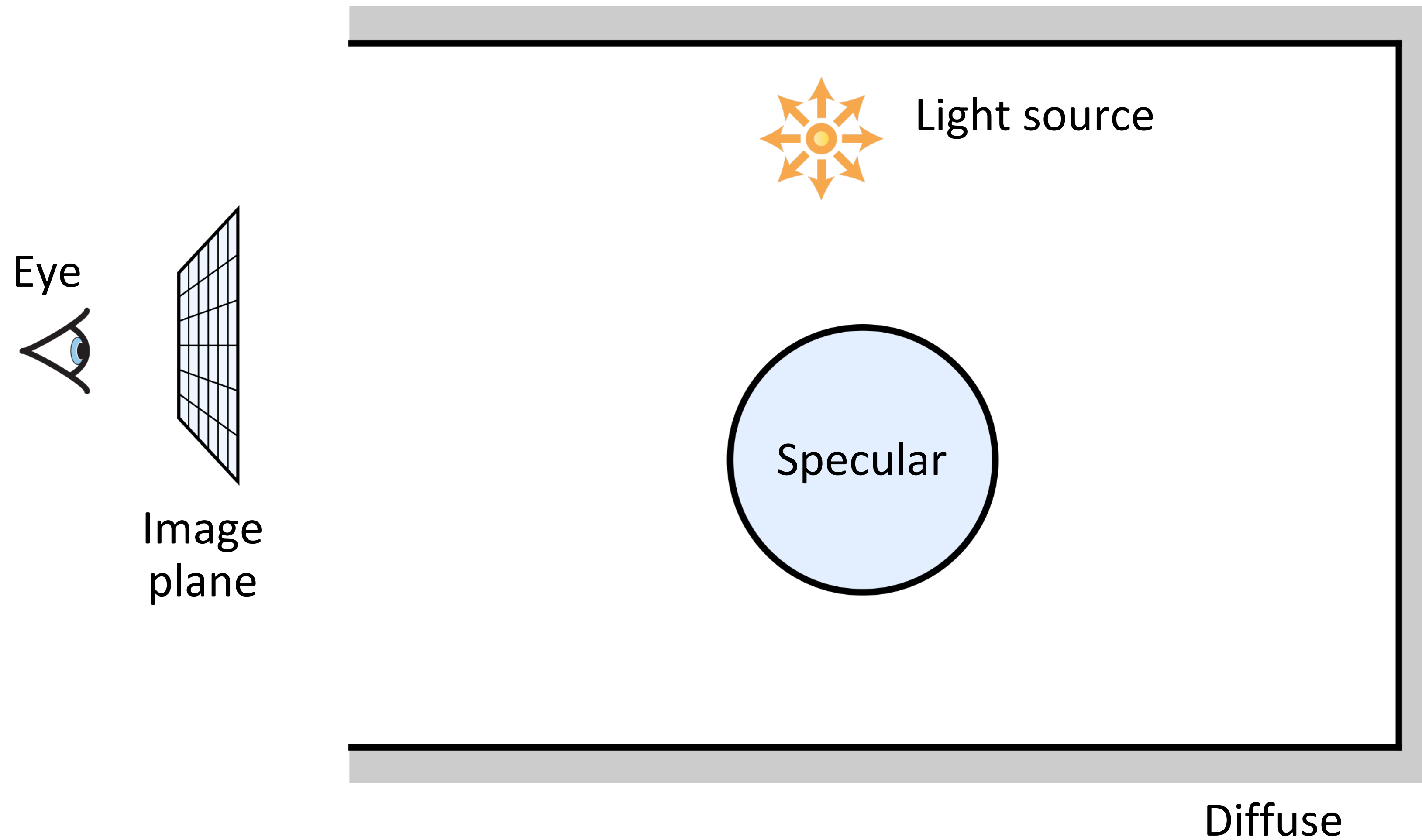
Classification of “vertices”:

- $L$  : a light source
- $E$  : the eye
- $S$  : a specular reflection
- $D$  : a diffuse reflection



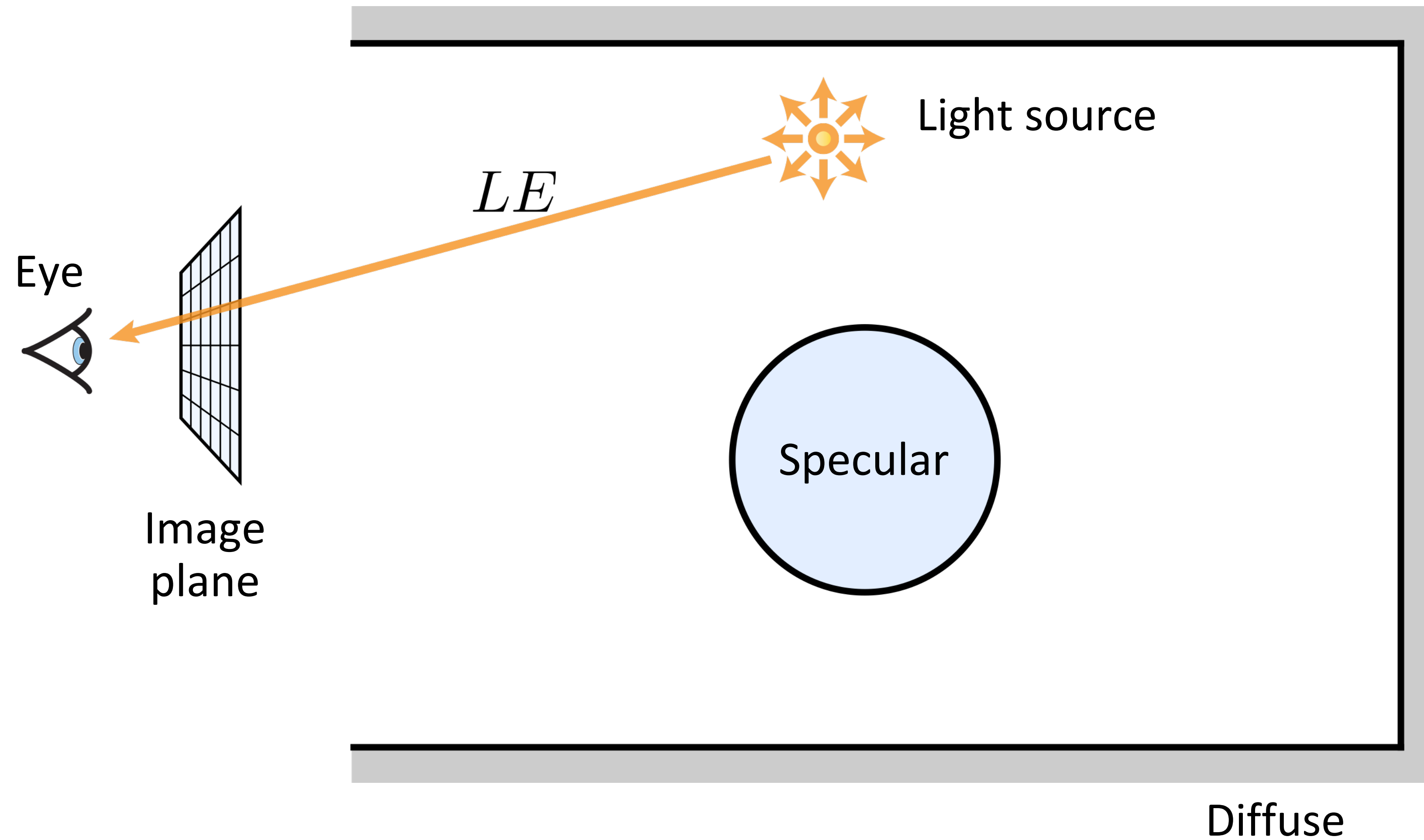
# Heckbert's Classification

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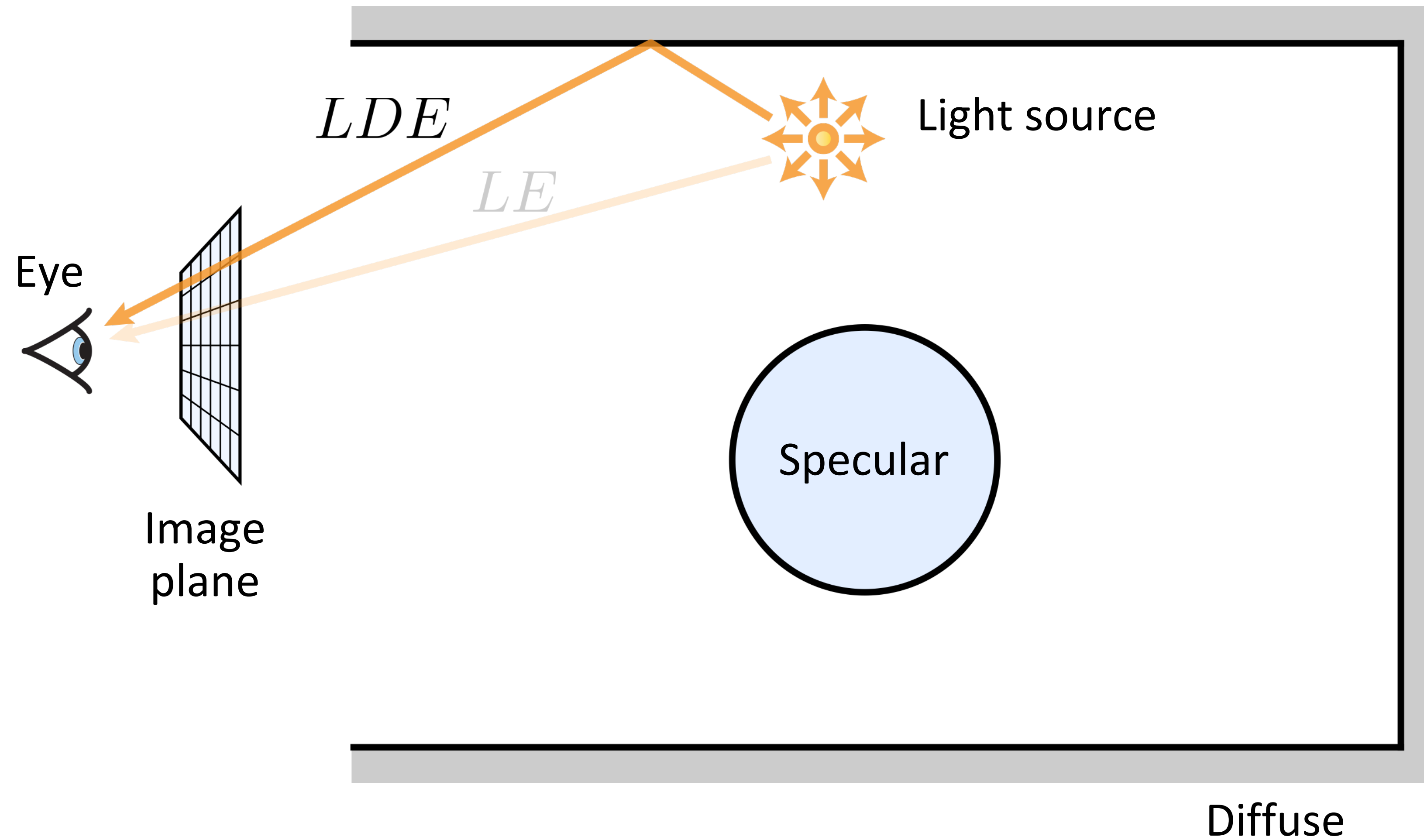


# Heckbert's Classification

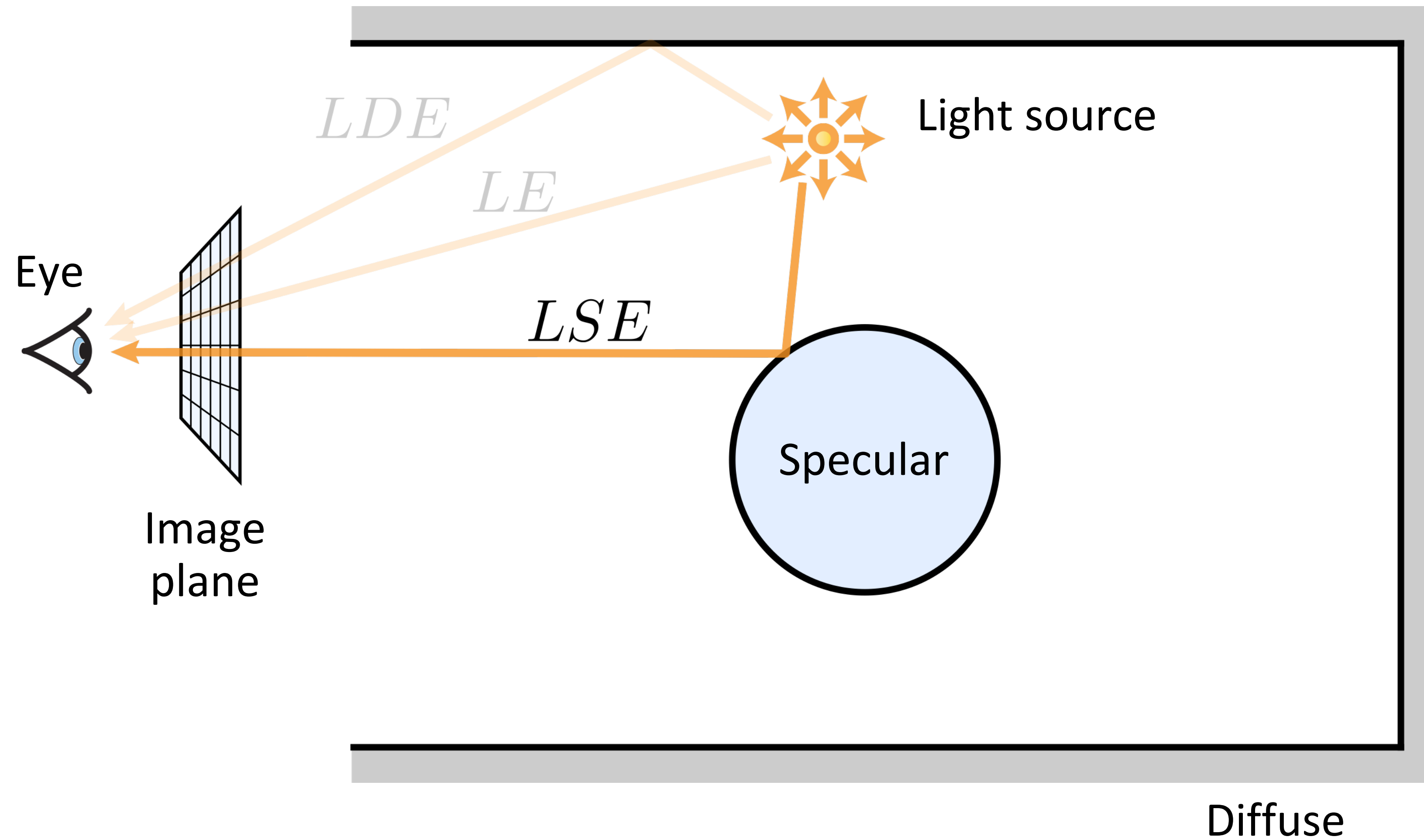




# Heckbert's Classification

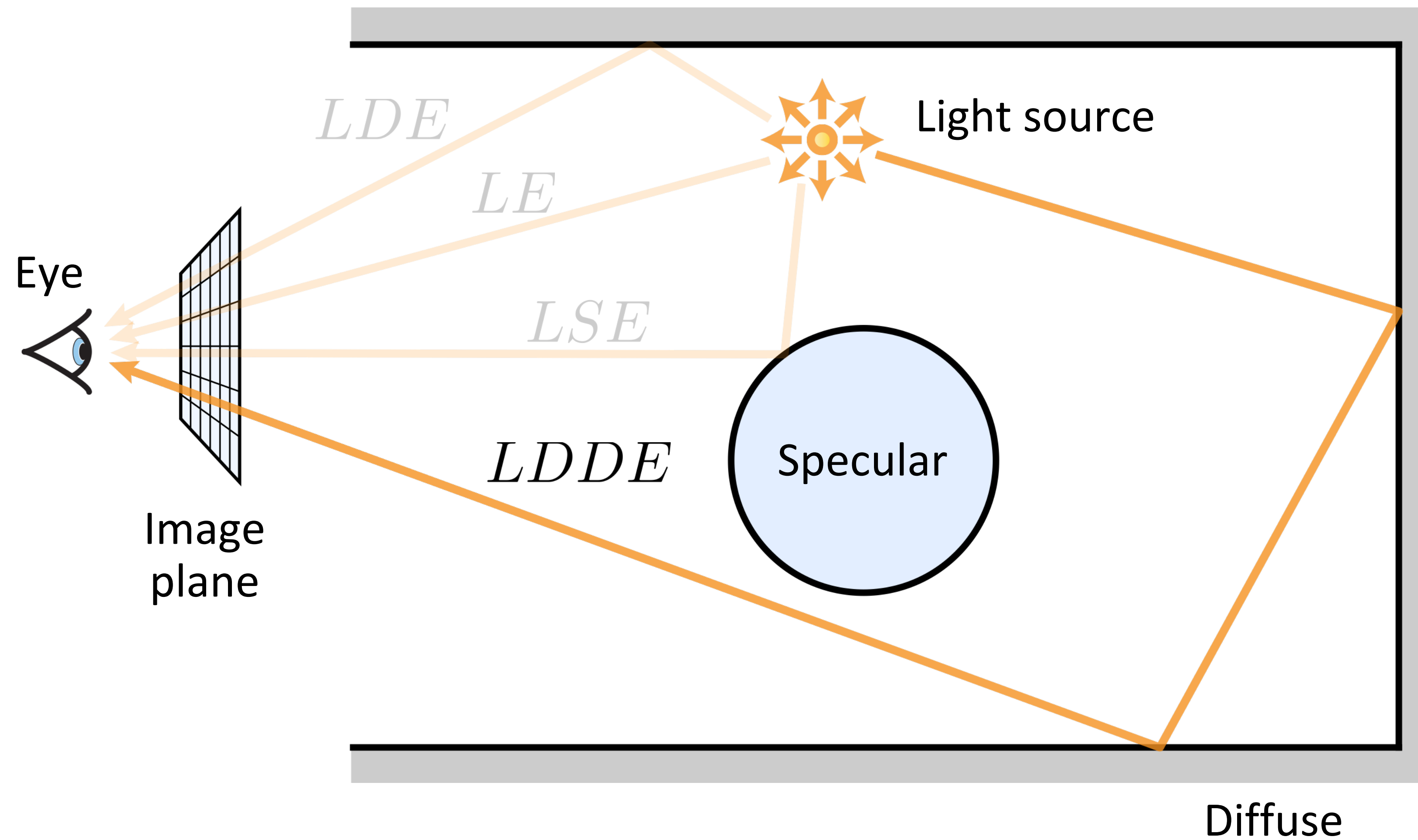


# Heckbert's Classification

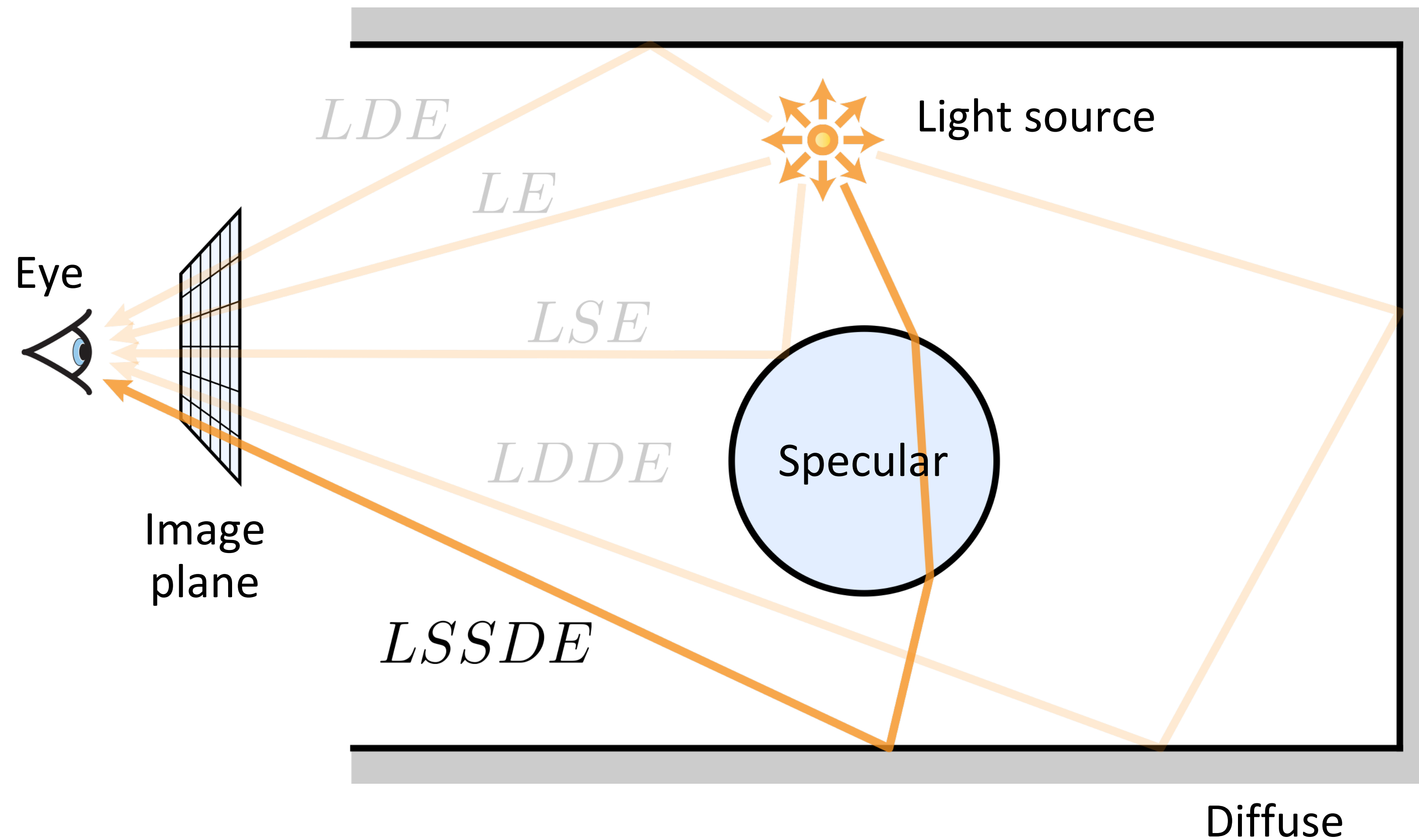




# Heckbert's Classification



# Heckbert's Classification





# Heckbert's Classification

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Can express arbitrary classes of paths using a regular expression type syntax:

- $k^+$  : one or more of event  $k$
- $k^*$  : zero or more of event  $k$
- $k?$  : zero or one  $k$  events
- $(k|h)$  : a  $k$  or  $h$  event

# Heckbert's Classification

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Direct illumination:  $L(D|S)E$

Indirect illumination:  $L(D|S)(D|S)^+E$



# Heckbert's Classification

---

Direct illumination:  $L(D|S)E$

Indirect illumination:  $L(D|S)(D|S)^+E$

Full global illumination:  $L(D|S)^*E$

# Diffuse inter-reflections: $LDD^+E$

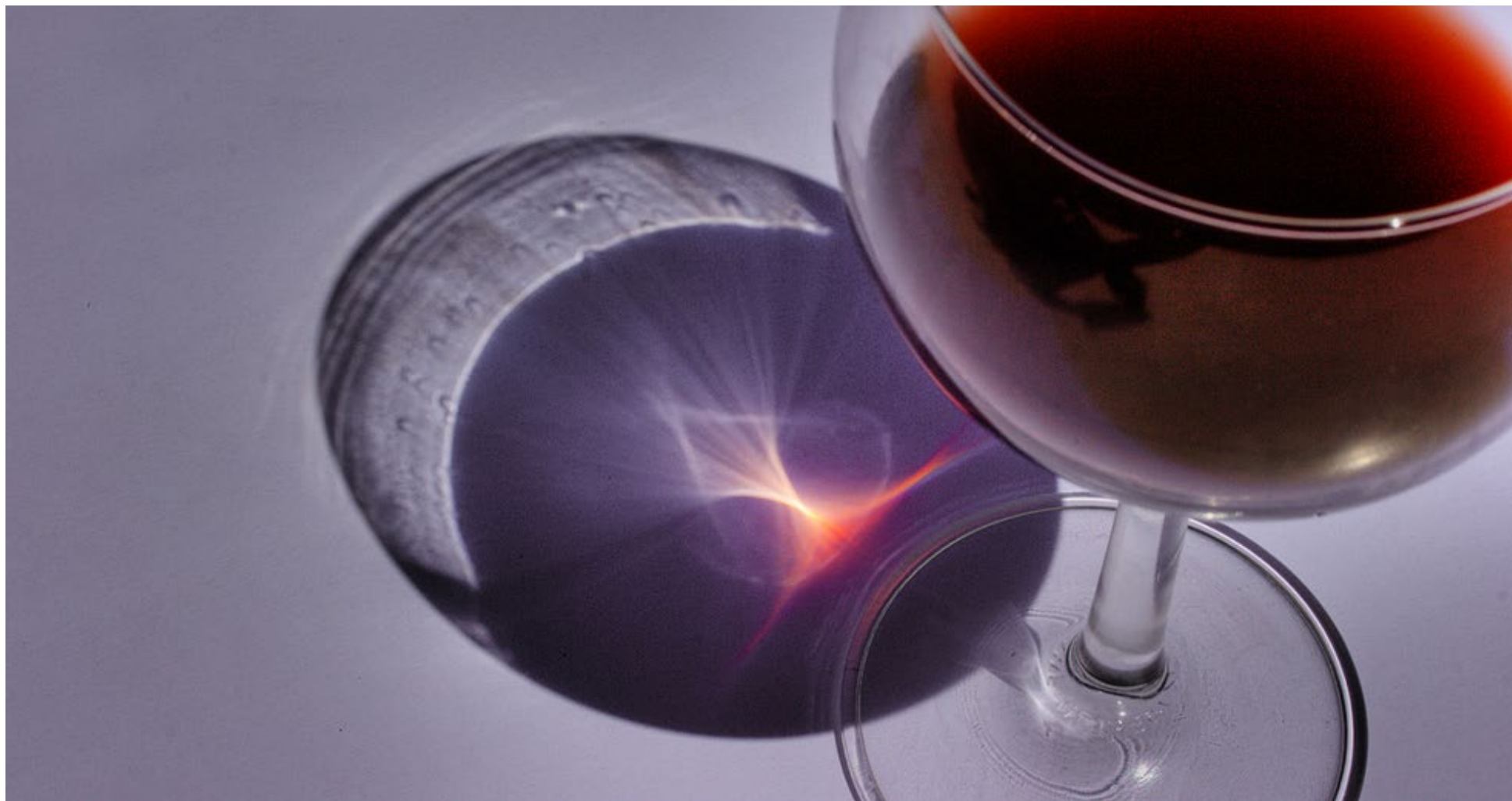
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# Caustics: $LS^+DE$

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# Subsurface Scattering

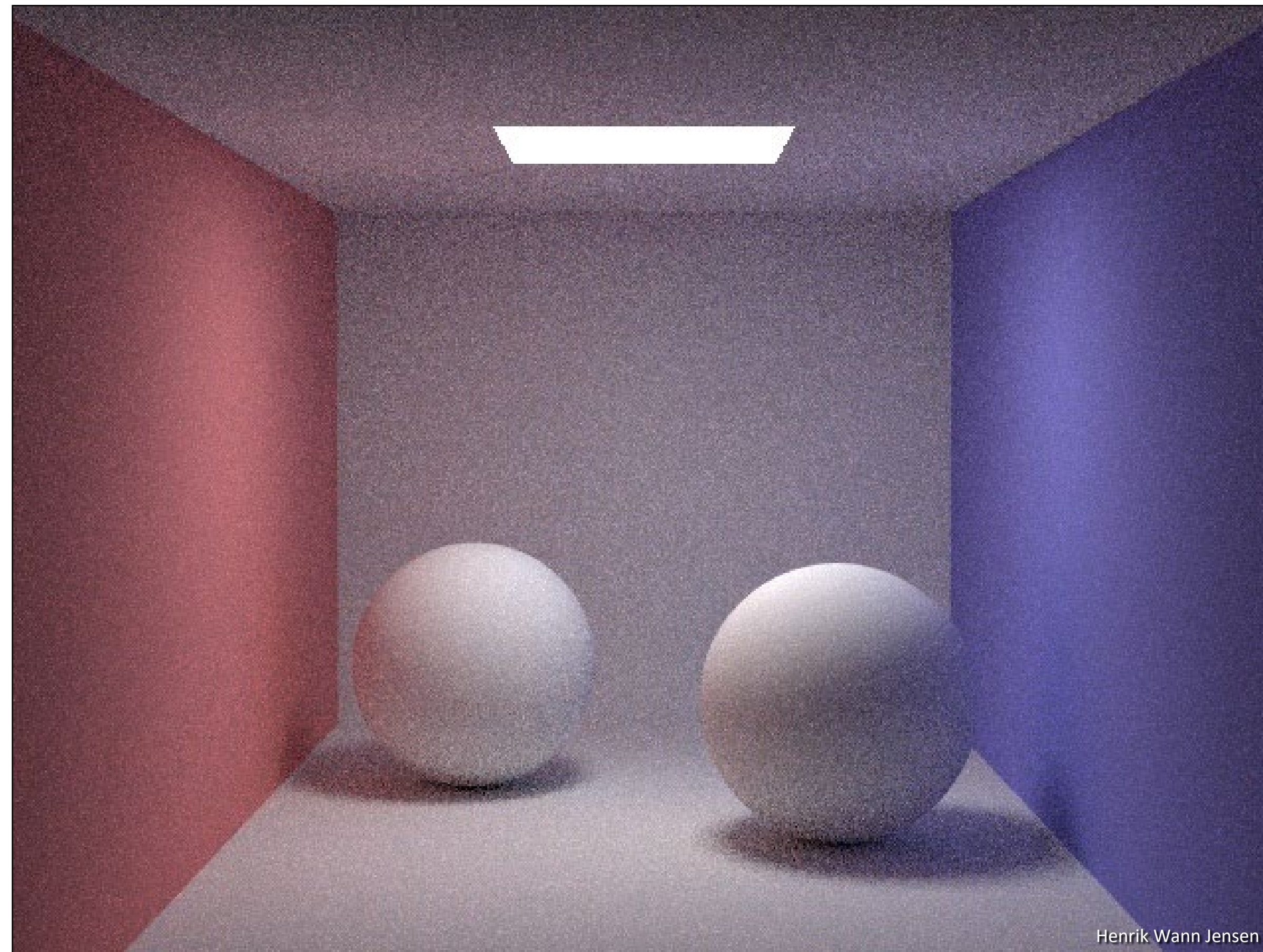
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# A Simple Scene

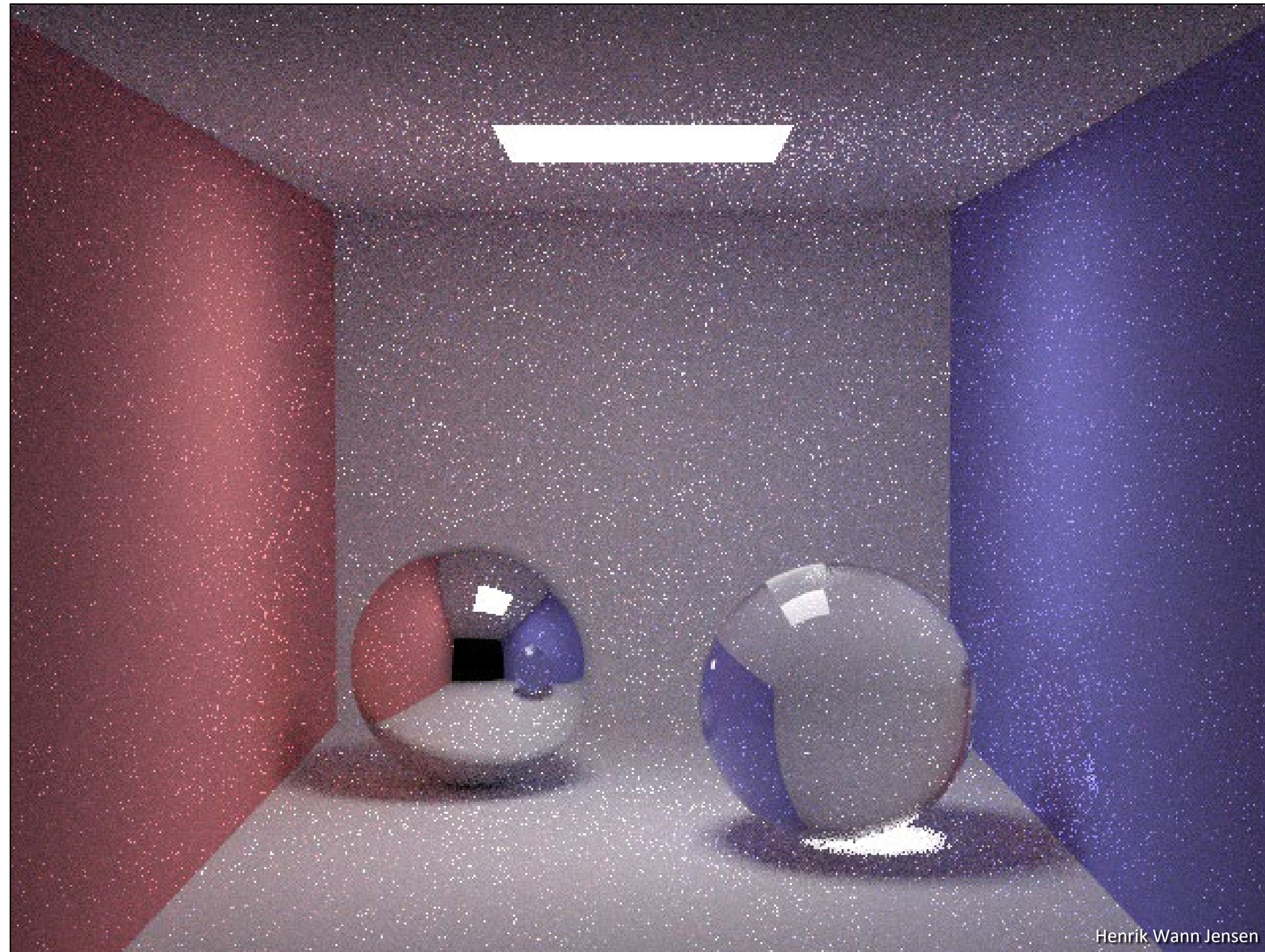
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10 paths/pixel

# + Glass/Mirror Material

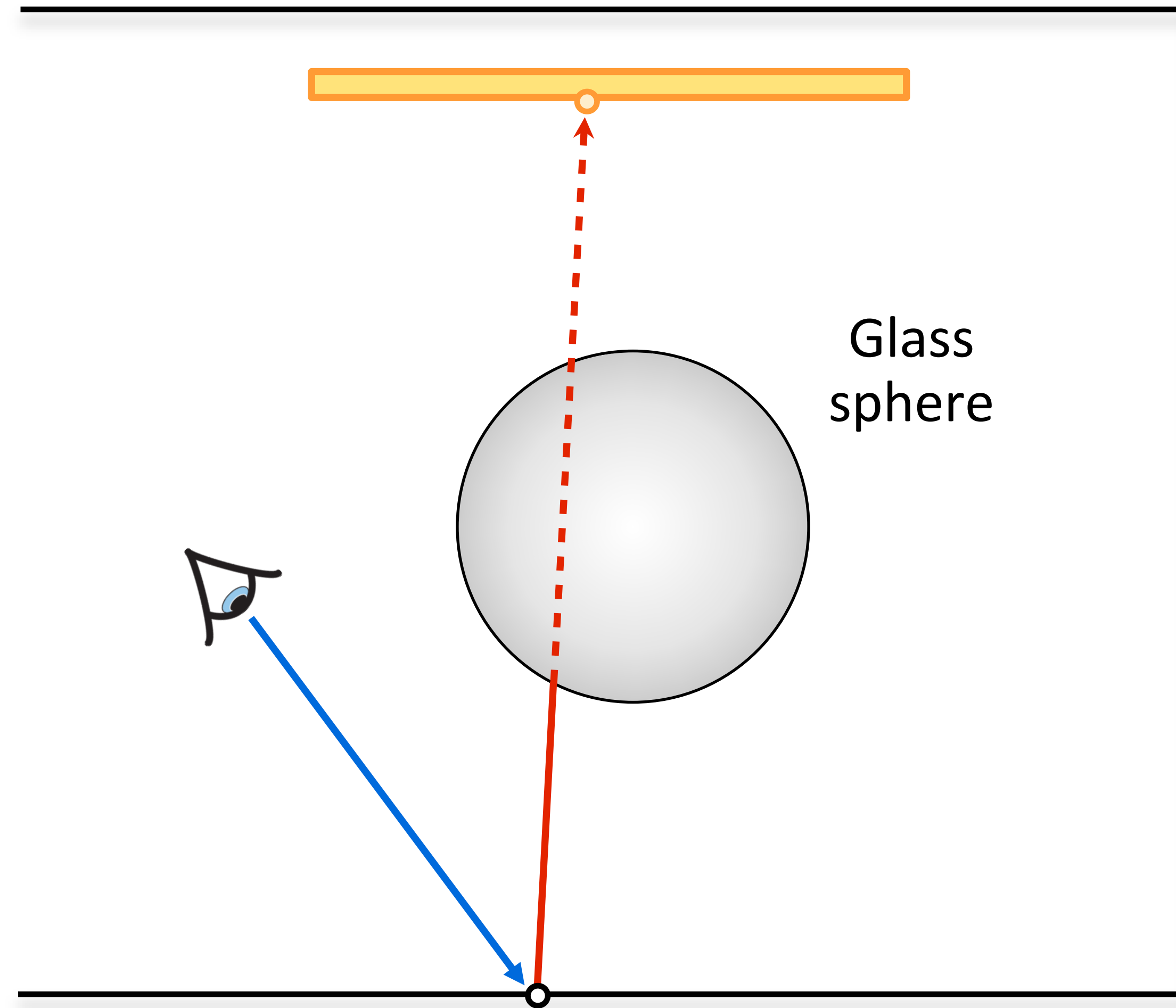
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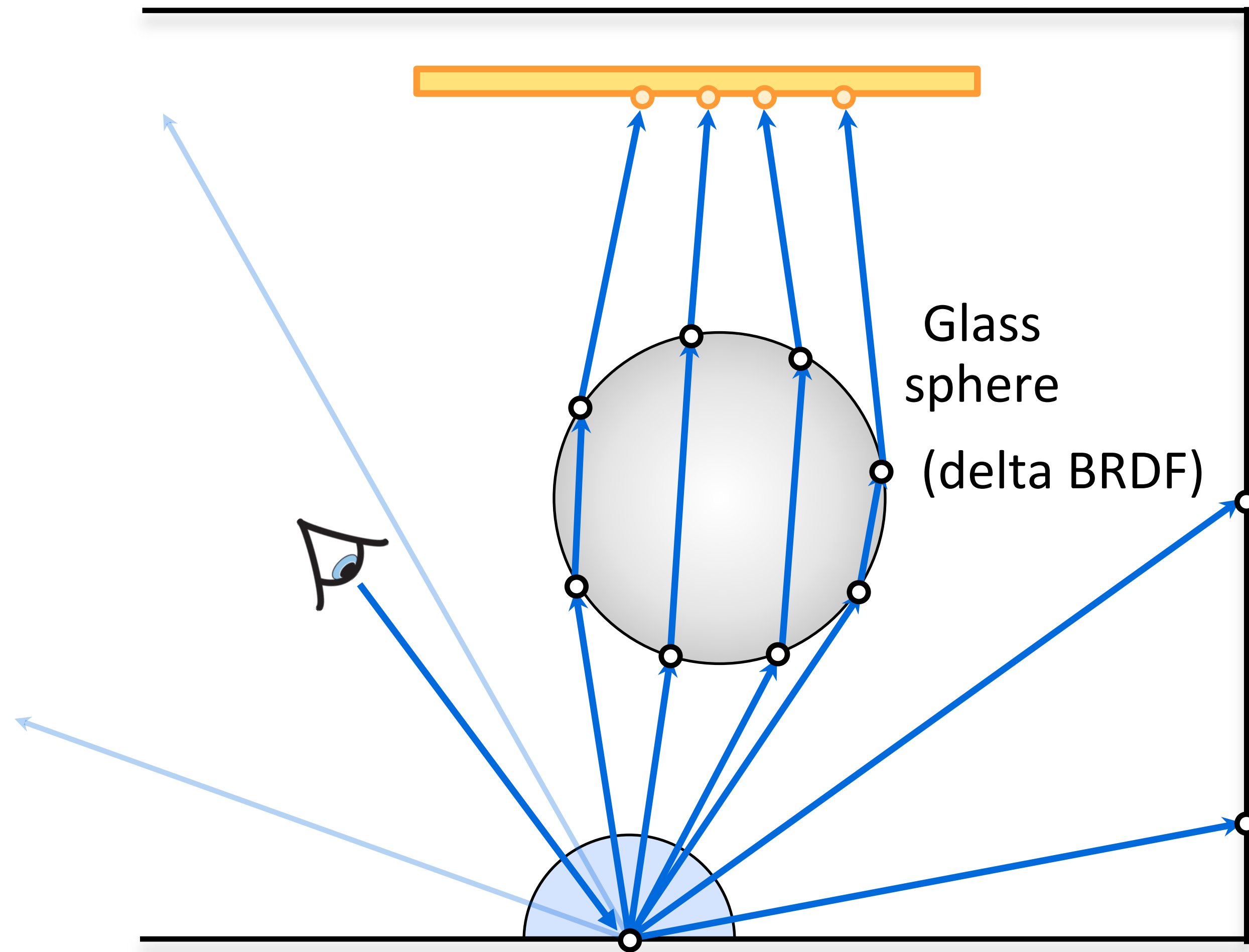
10 paths/pixel



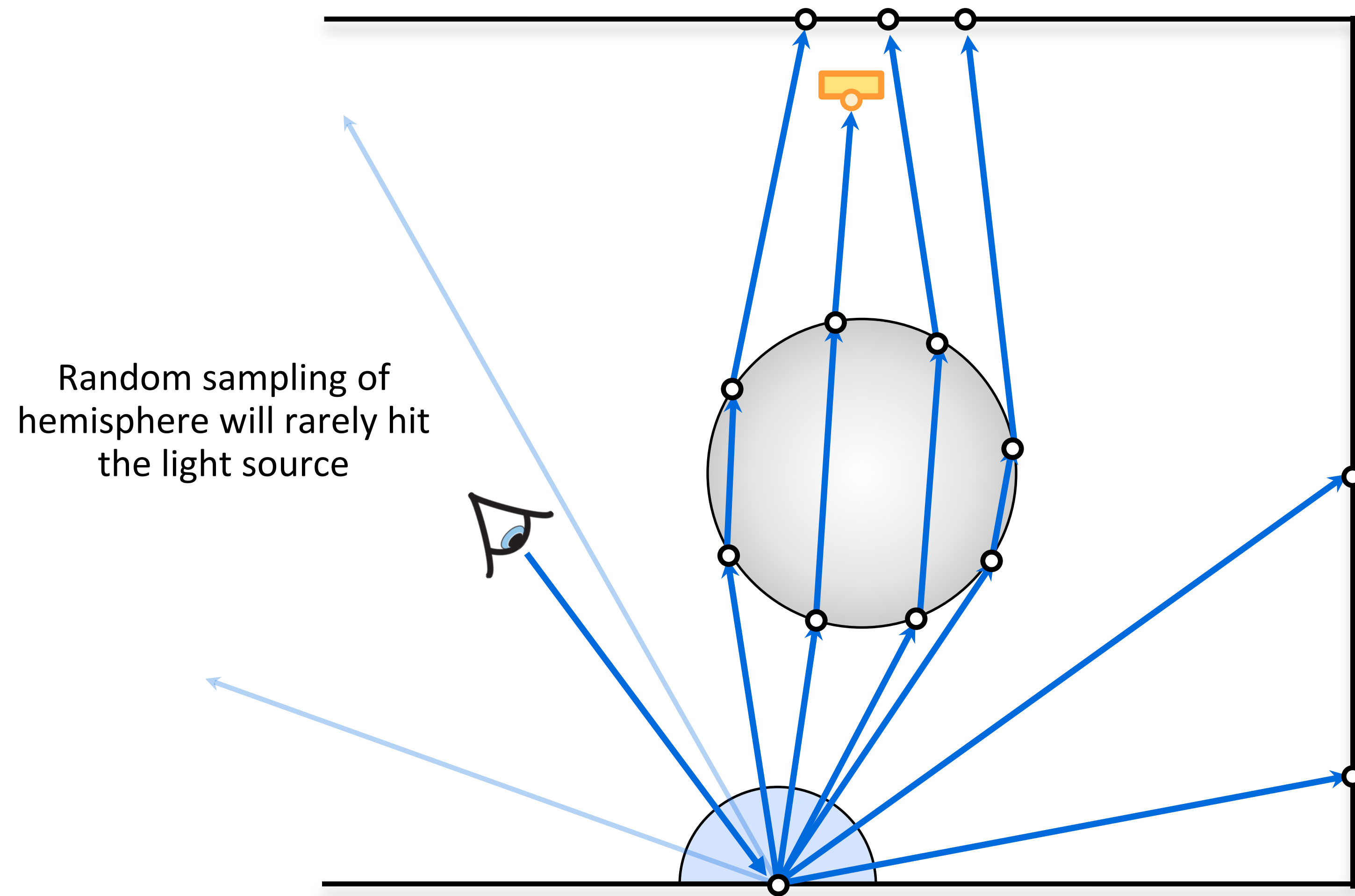
# Path Tracing Caustics



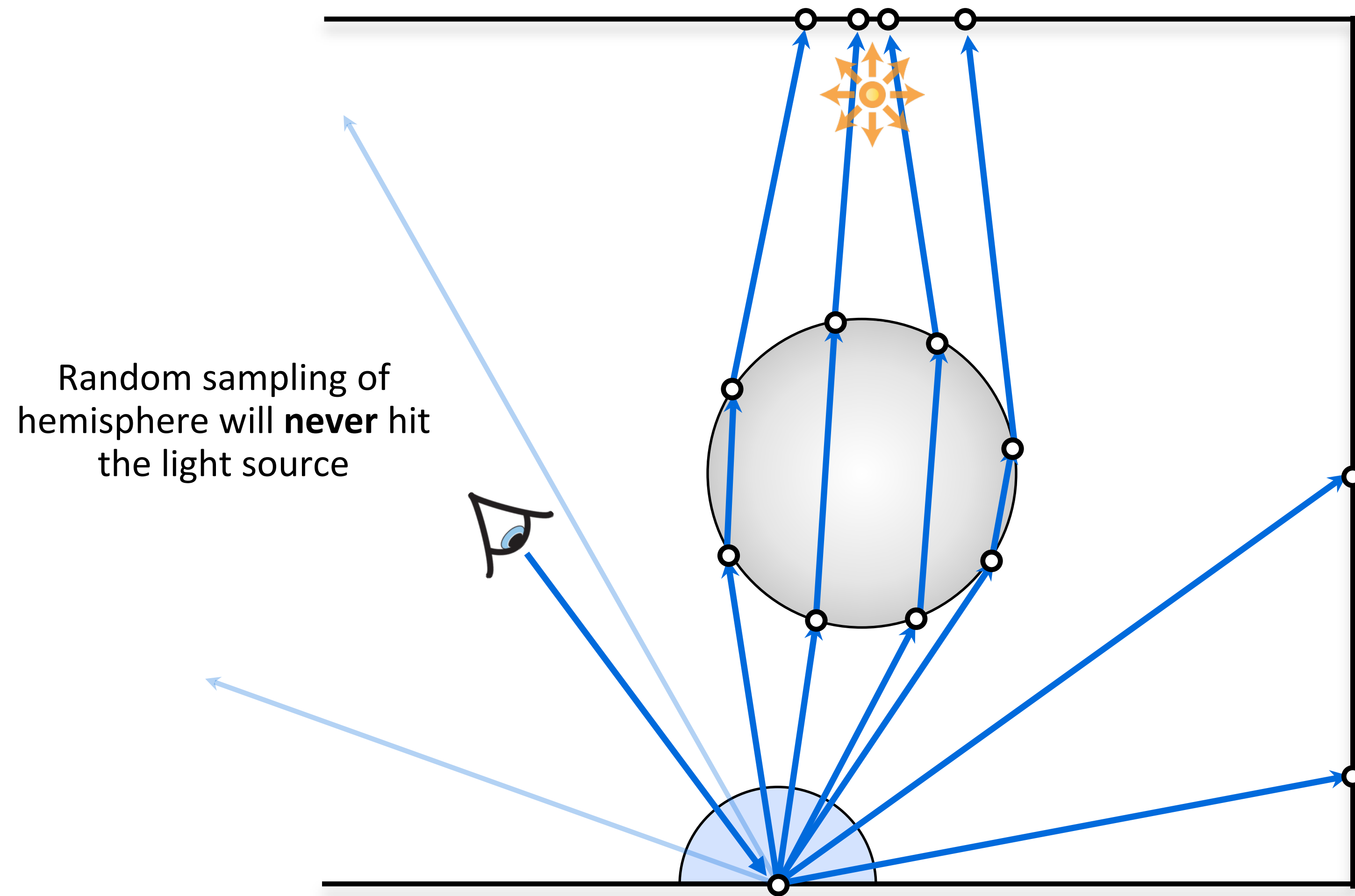
# Path Tracing Caustics



# Path Tracing Caustics



# Path Tracing Caustics





# Let's just give it more time...

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Nature  $\sim 2 \times 10^{33}$  / second

Fastest GPU ray tracer  $\sim 2 \times 10^8$  / second

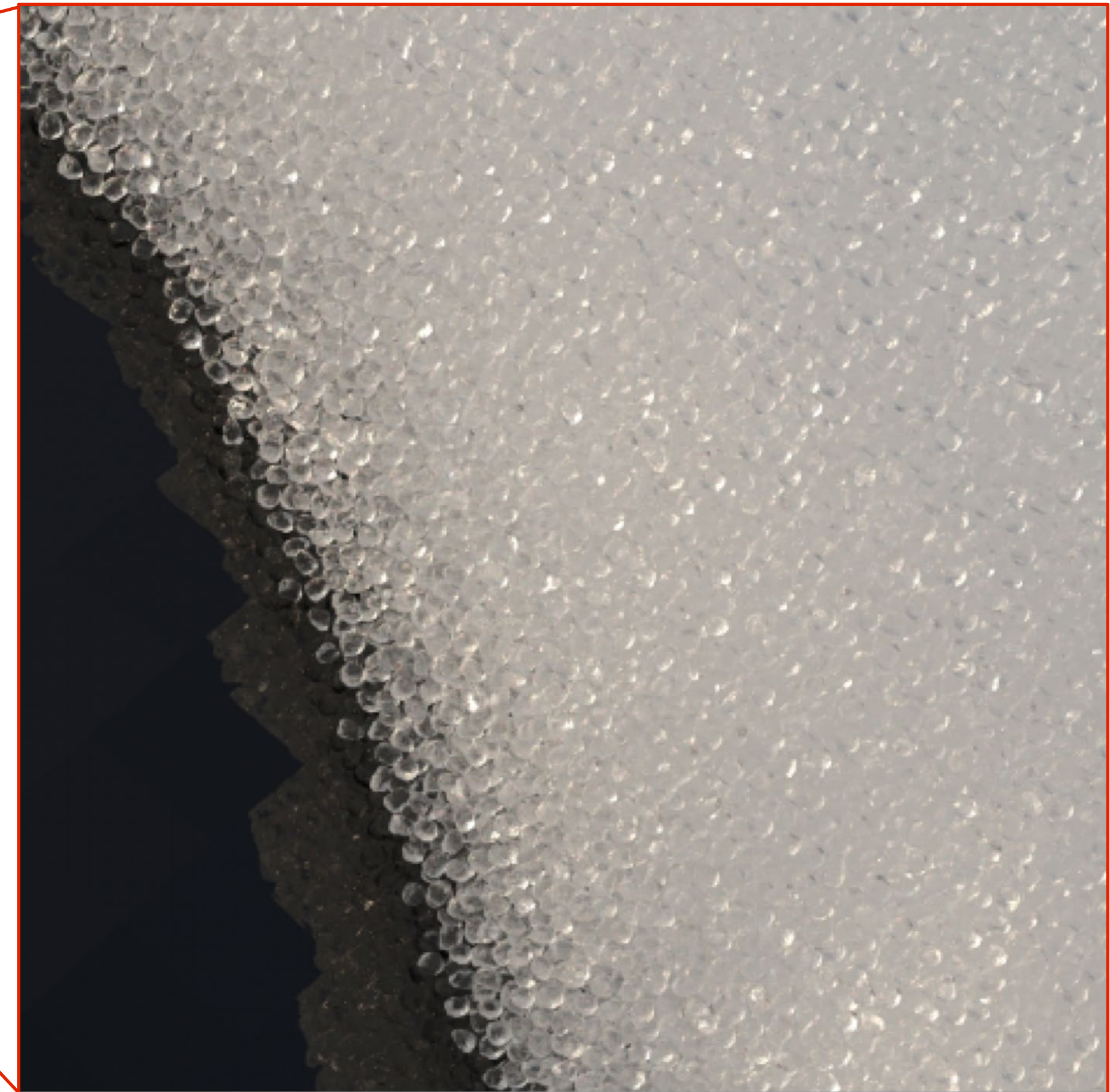


Tim Webber, Gravity VFX supervisor



# Let's just give it more time...

---



1 image ~ 8 core years  
(parallelized on a cluster)

# Path Tracing - Summary

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- ✓ Full solution to the rendering equation
- ✓ Simple to implement
- ✗ Slow convergence
  - requires 4x more samples to half the error
- ✗ Robustness issues
  - does not handle some light paths well (or not at all), e.g. caustics ( $LS^+DE$ )
- ✗ No reuse or caching of computation
- ✗ General sampling issue
  - makes only locally good decisions



# Today's agenda

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Measurement Equation

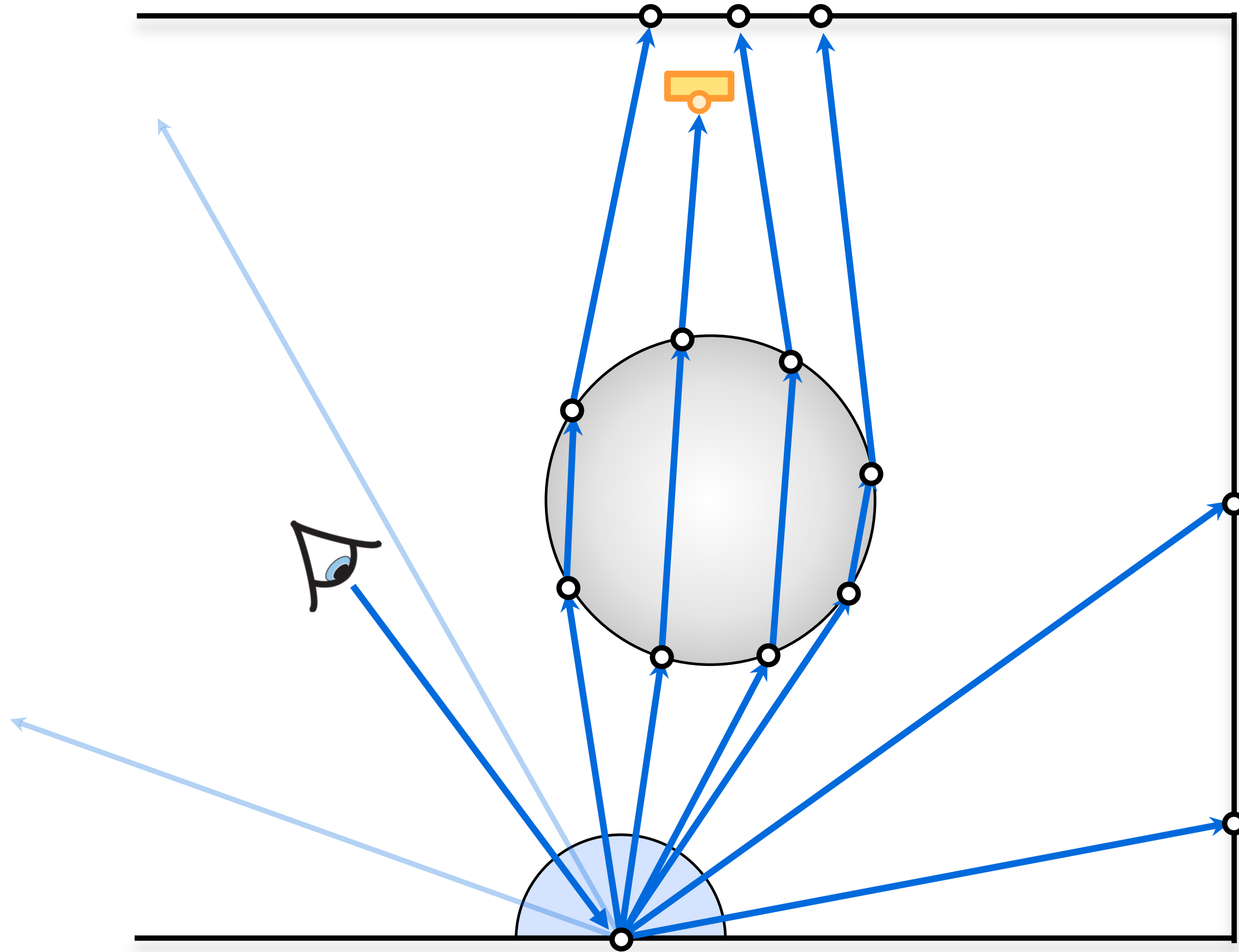
Path Integral Framework

Solving the Rendering Equation

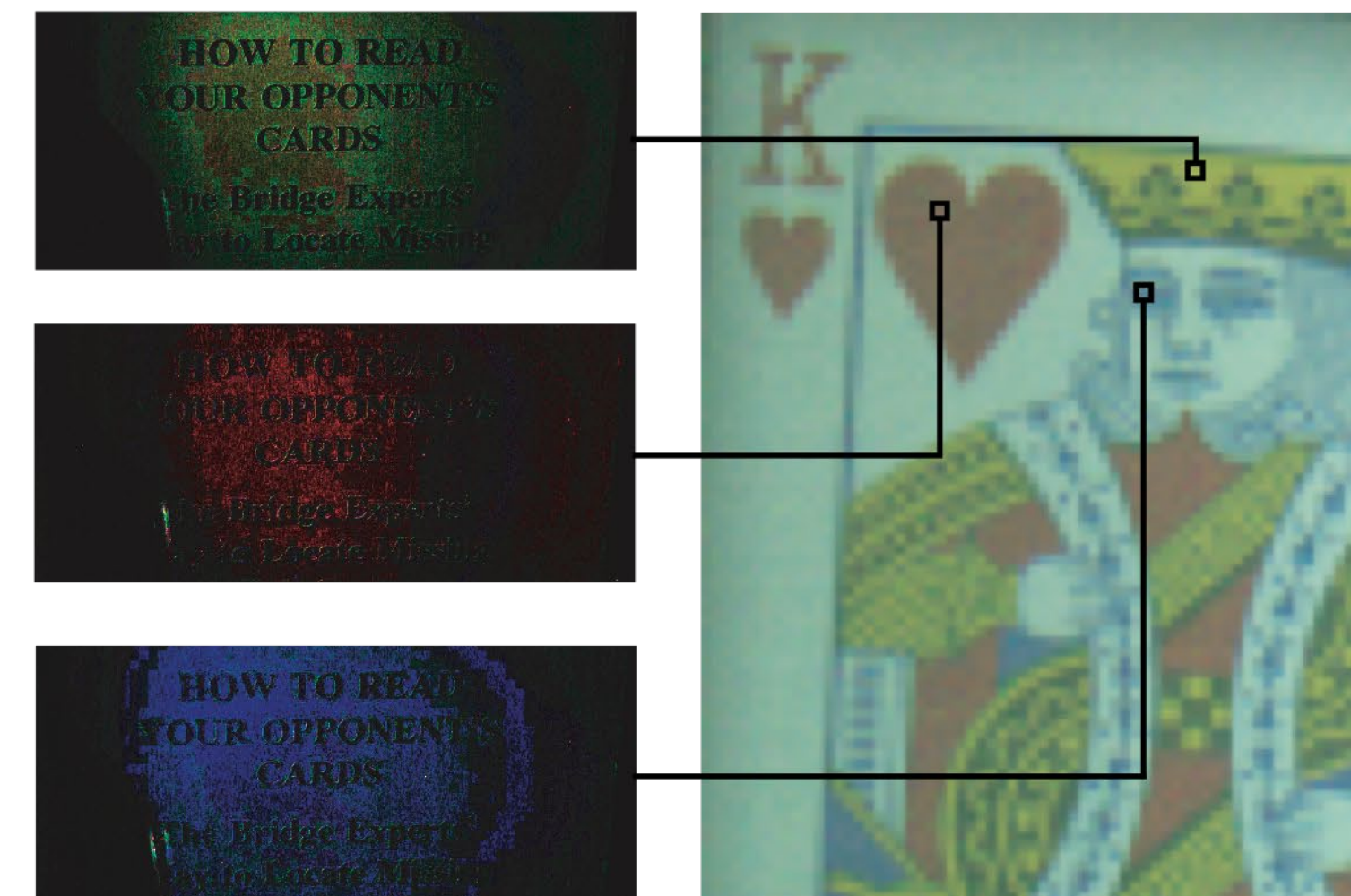
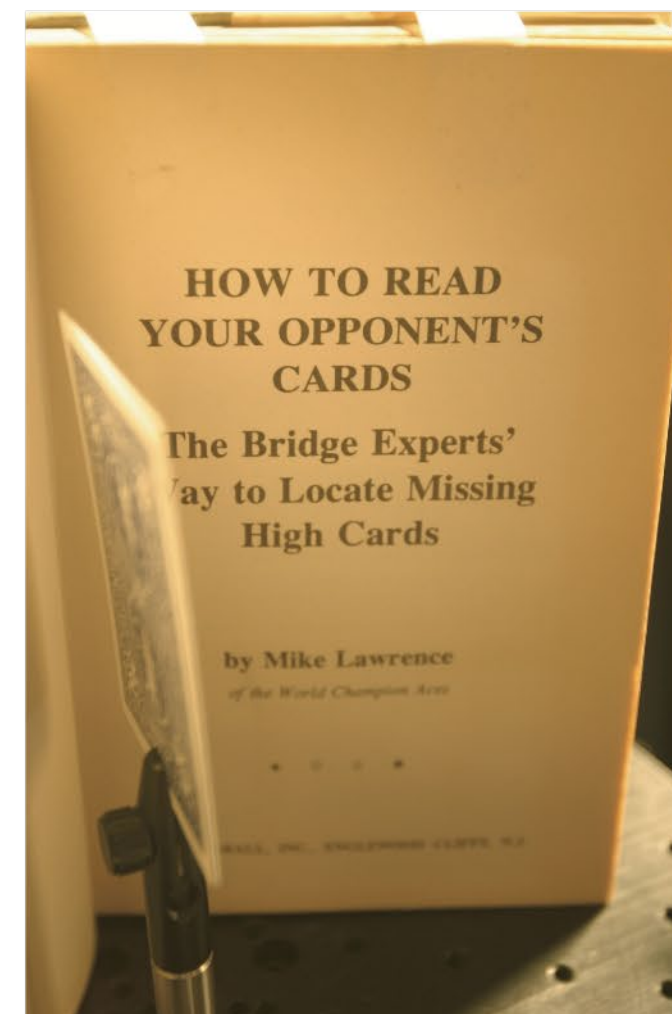
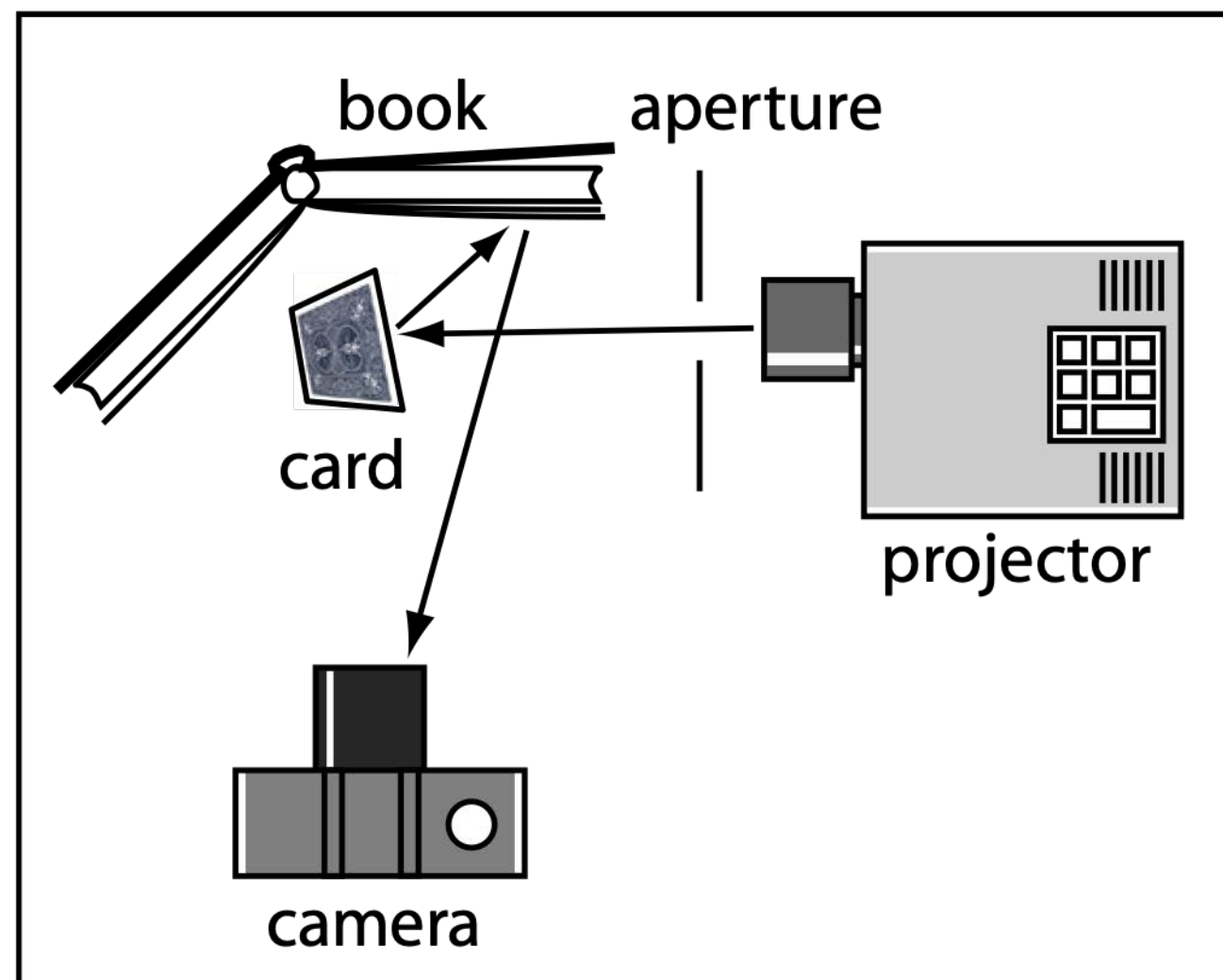
- Light tracing
- Bidirectional path tracing



# Can we simulate this better?



# Light transport is symmetric



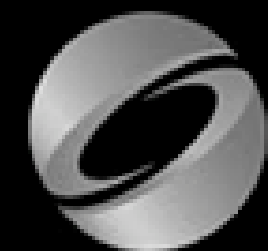
Dual Photography [Sen et al. 2005]

# Dual Photography

Pradeep Sen\*   Billy Chen\*   Gaurav Garg\*   Stephen R. Marschner†  
Mark Horowitz\*   Marc Levoy\*   Hendrik P.A. Lensch\*

\*Stanford University

†Cornell University

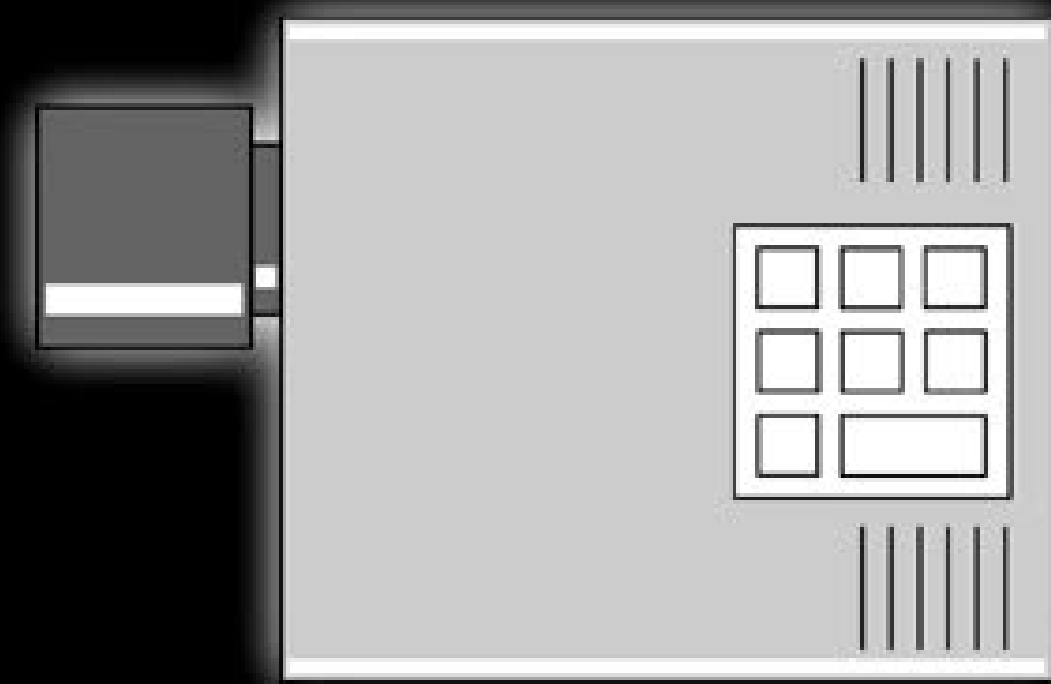


**SIGGRAPH**2005





card



projector

# Duality of Radiance and Importance

# Measurement Equation

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Rendering equation describes radiative equilibrium at point  $\mathbf{x}$ :

$$L_o(\mathbf{x}, \vec{\omega}_o) = L_e(\mathbf{x}, \vec{\omega}_o) + \int_{H^2} f_r(\mathbf{x}, \vec{\omega}_i, \vec{\omega}_o) L_i(\mathbf{x}, \vec{\omega}_i) \cos \theta_i d\vec{\omega}_i$$

We are interested in the total radiance contributing to pixel  $j$ :

$$I_j = \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta d\vec{\omega} d\mathbf{x}$$

*response* of the sensor at film location  $\mathbf{x}$   
to radiance arriving from direction  $\vec{\omega}$   
(often referred to as *emitted importance*)



# Radiometry as Measurements

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Weighted integral of 5D radiance function

$$\int_V \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L(\mathbf{x}, \vec{\omega}) d\vec{\omega} d\mathbf{x}$$

Other radiometric quantities are measurements

- expressing *irradiance* in terms of radiance:

$$\int_{H^2} L(\mathbf{x}, \vec{\omega}) \cos \theta d\vec{\omega} = E(\mathbf{x})$$

Integrate radiance over hemisphere

- expressing *flux/power* in terms of radiance:

$$\int_A \int_{H^2} L(\mathbf{x}, \vec{\omega}) \cos \theta d\vec{\omega} dA(\mathbf{x}) = \Phi(A)$$

Integrate radiance over hemisphere and area

# Radiance vs. Importance

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## Radiance

- emitted from light sources
- describes *amount of light* traveling within a differential beam

## Importance

- “emitted” from sensors
- describes the *response of the sensor* to radiance traveling within a differential beam

# Duality of Radiance & Importance

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$$I_j = \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{x}$$



# Duality of Radiance & Importance

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$$\begin{aligned} I_j &= \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) L_o(\mathbf{y}, \mathbf{x}) \, d\mathbf{y} d\mathbf{x} \end{aligned}$$

outgoing quantities

Let's expand  $L_o$  and consider  
direct illumination only

# Duality of Radiance & Importance

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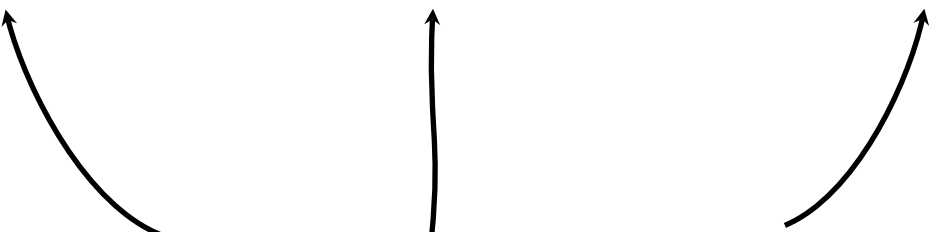
$$\begin{aligned} I_j &= \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) L_o(\mathbf{y}, \mathbf{x}) \, d\mathbf{y} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A \int_{A_{\text{light}}} W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) f(\mathbf{y}, \mathbf{z}, \mathbf{x}) G(\mathbf{y}, \mathbf{z}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{z} d\mathbf{y} d\mathbf{x} \end{aligned}$$

emitted quantities with  
identical measure

Let's swap the inner  
and outer integral

# Duality of Radiance & Importance

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$$\begin{aligned} I_j &= \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) L_o(\mathbf{y}, \mathbf{x}) \, d\mathbf{y} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A \int_{A_{\text{light}}} W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) f(\mathbf{y}, \mathbf{z}, \mathbf{x}) G(\mathbf{y}, \mathbf{z}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{z} d\mathbf{y} d\mathbf{x} \\ &= \int_{A_{\text{light}}} \int_A \int_{A_{\text{film}}} W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) f(\mathbf{y}, \mathbf{z}, \mathbf{x}) G(\mathbf{y}, \mathbf{z}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{x} d\mathbf{y} d\mathbf{z} \end{aligned}$$


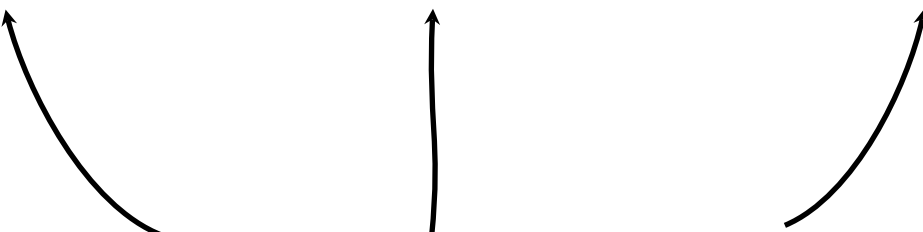
symmetric functions



# Duality of Radiance & Importance

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$$\begin{aligned} I_j &= \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) L_o(\mathbf{y}, \mathbf{x}) \, d\mathbf{y} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A \int_{A_{\text{light}}} W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) f(\mathbf{y}, \mathbf{z}, \mathbf{x}) G(\mathbf{y}, \mathbf{z}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{z} d\mathbf{y} d\mathbf{x} \\ &= \int_{A_{\text{light}}} \int_A \int_{A_{\text{film}}} W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{y}, \mathbf{x}) f(\mathbf{y}, \mathbf{x}, \mathbf{z}) G(\mathbf{z}, \mathbf{y}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{x} d\mathbf{y} d\mathbf{z} \end{aligned}$$

  
symmetric functions

# Duality of Radiance & Importance

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$$\begin{aligned} I_j &= \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) L_o(\mathbf{y}, \mathbf{x}) \, d\mathbf{y} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A \int_{A_{\text{light}}} W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) f(\mathbf{y}, \mathbf{z}, \mathbf{x}) G(\mathbf{y}, \mathbf{z}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{z} d\mathbf{y} d\mathbf{x} \\ &= \int_{A_{\text{light}}} \int_A \int_{A_{\text{film}}} W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{y}, \mathbf{x}) f(\mathbf{y}, \mathbf{x}, \mathbf{z}) G(\mathbf{z}, \mathbf{y}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{x} d\mathbf{y} d\mathbf{z} \\ &= \int_{A_{\text{light}}} \int_A W_o(\mathbf{y}, \mathbf{z}) G(\mathbf{z}, \mathbf{y}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{y} d\mathbf{z} \end{aligned}$$

# Duality of Radiance & Importance

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$$\begin{aligned} I_j &= \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) L_o(\mathbf{y}, \mathbf{x}) \, d\mathbf{y} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A \int_{A_{\text{light}}} W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) f(\mathbf{y}, \mathbf{z}, \mathbf{x}) G(\mathbf{y}, \mathbf{z}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{z} d\mathbf{y} d\mathbf{x} \\ &= \int_{A_{\text{light}}} \int_A \int_{A_{\text{film}}} W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{y}, \mathbf{x}) f(\mathbf{y}, \mathbf{x}, \mathbf{z}) G(\mathbf{z}, \mathbf{y}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{x} d\mathbf{y} d\mathbf{z} \\ &= \int_{A_{\text{light}}} \int_A W_o(\mathbf{y}, \mathbf{z}) G(\mathbf{z}, \mathbf{y}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{y} d\mathbf{z} \\ &= \int_{A_{\text{light}}} \int_{H^2} W_i(\mathbf{z}, \vec{\omega}) L_e(\mathbf{z}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{z} \end{aligned}$$



# Duality of Radiance & Importance

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$$\begin{aligned} I_j &= \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{x} \\ &= \int_{A_{\text{light}}} \int_{H^2} W_i(\mathbf{z}, \vec{\omega}) L_e(\mathbf{z}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{z} \end{aligned}$$

The diagram illustrates the duality of radiance and importance through two equivalent integral equations. The first equation,  $I_j = \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{x}$ , is annotated with 'emitted importance' pointing to  $W_e$  and 'incident radiance' pointing to  $L_i$ . The second equation,  $= \int_{A_{\text{light}}} \int_{H^2} W_i(\mathbf{z}, \vec{\omega}) L_e(\mathbf{z}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{z}$ , is annotated with 'emitted radiance' pointing to  $L_e$  and 'incident importance' pointing to  $W_i$ . The arrows highlight the symmetry between the two formulations.

# Duality of Radiance & Importance

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Path tracing

start from *film*, search for *radiance* at light

$$I_j = \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{x}$$
$$= \int_{A_{\text{light}}} \int_{H^2} W_i(\mathbf{z}, \vec{\omega}) L_e(\mathbf{z}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{z}$$

Light tracing

start from *light*, search for *importance* at sensor

# Light Tracing

# Light Tracing

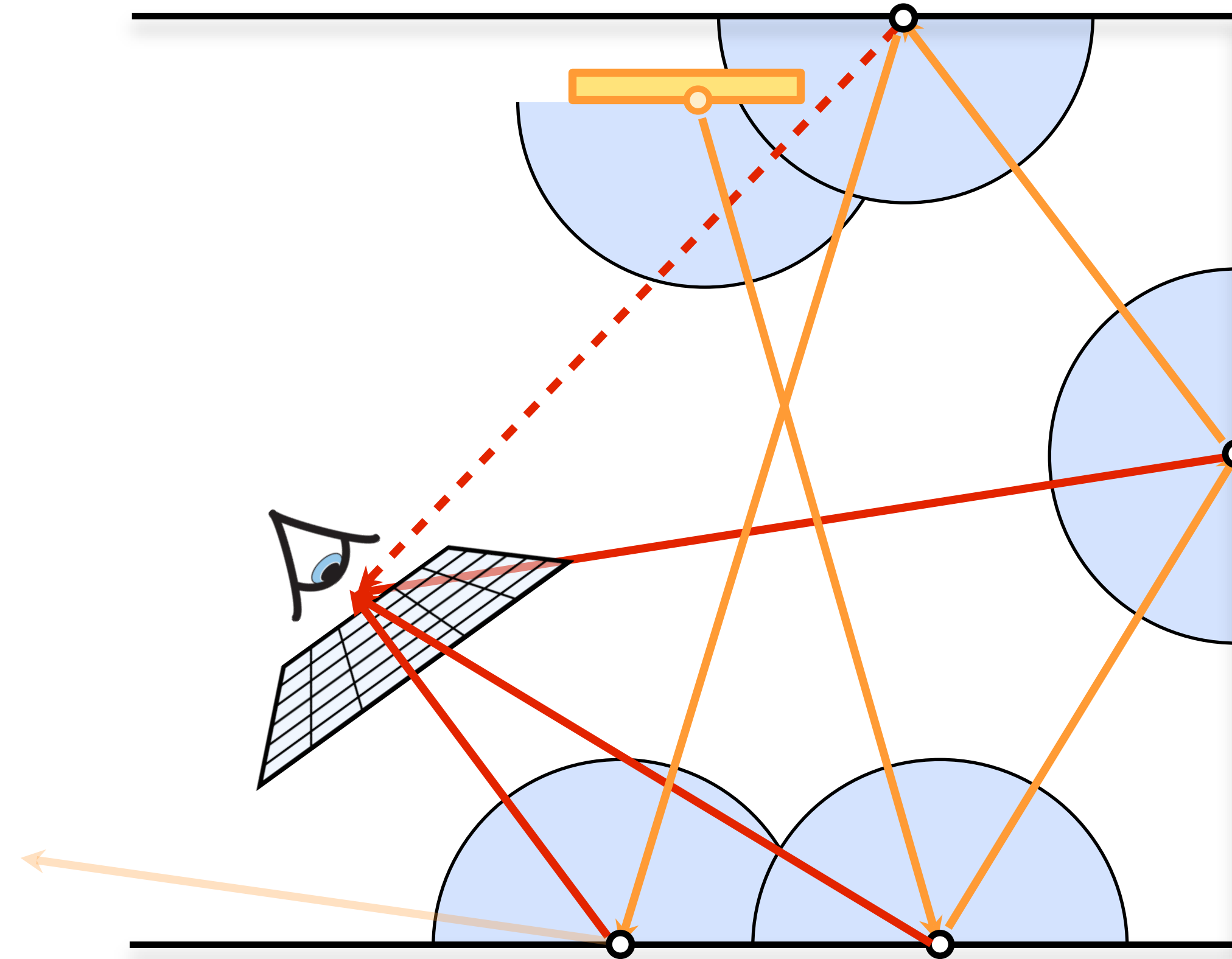
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Shoot multiple paths from light sources hoping to randomly hit the sensor

- Optionally: at each path vertex, connect to the image using next-event estimation (a.k.a. shadow rays in PT)

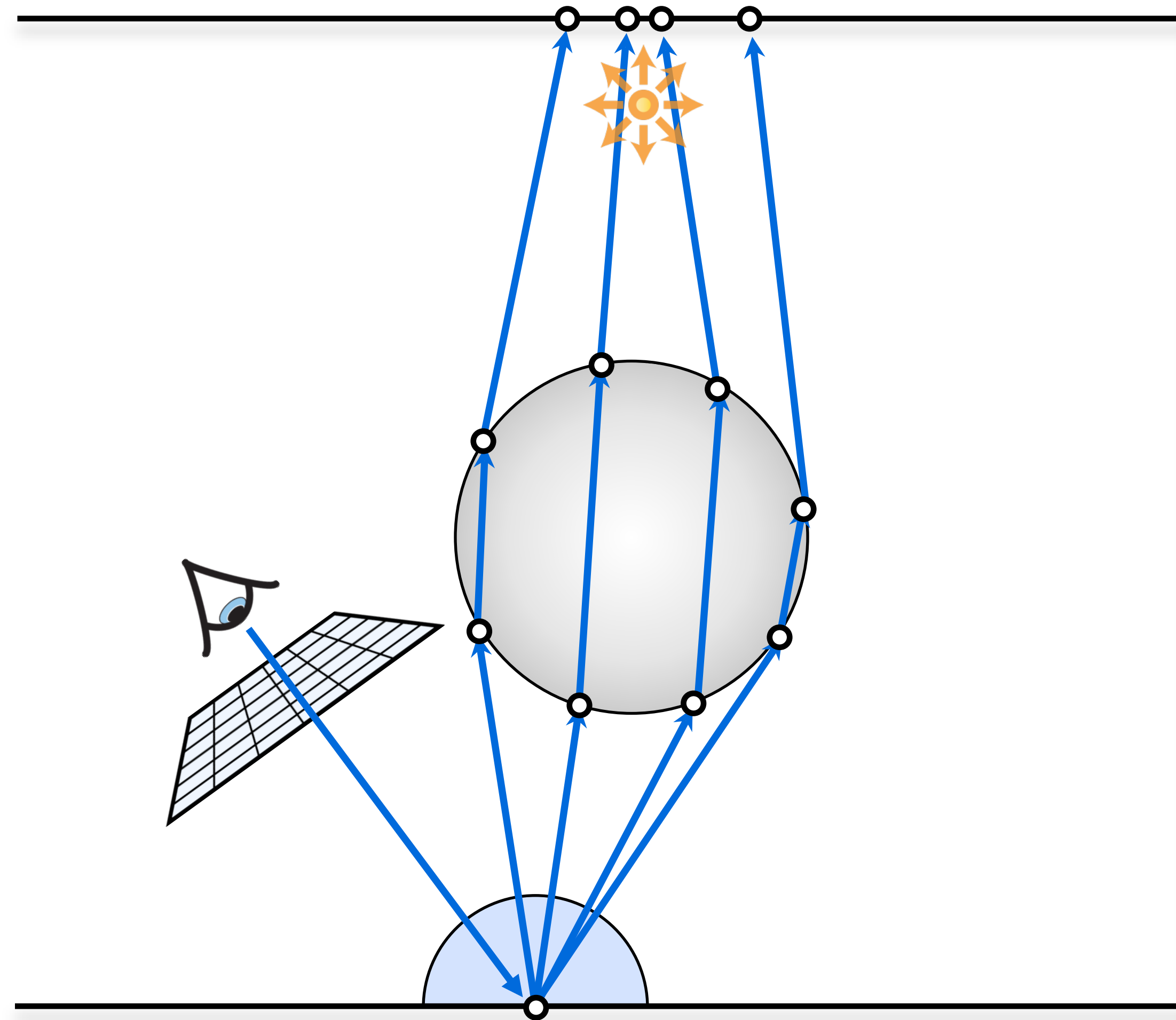


# Light Tracing with NEE

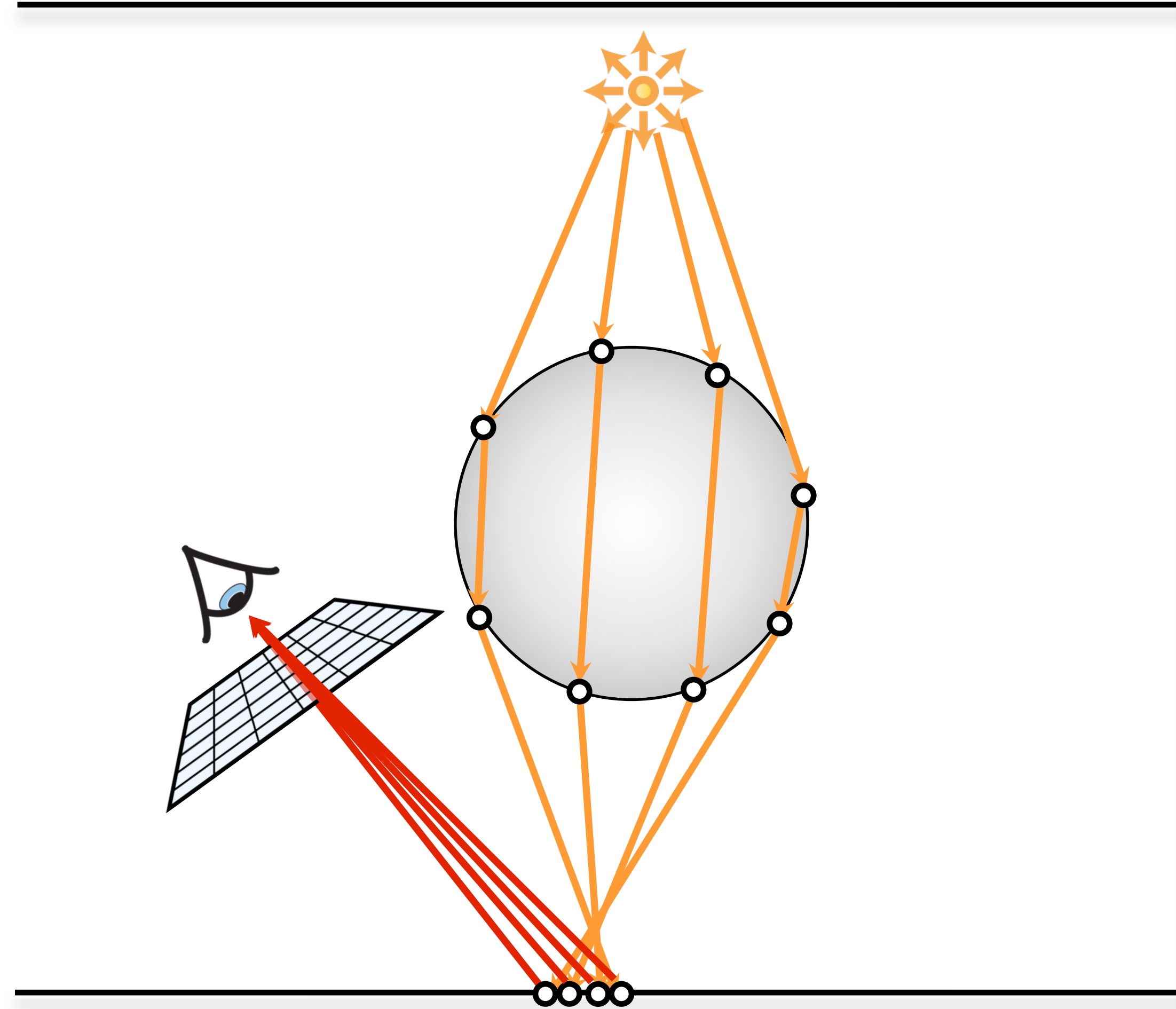


## Splat to the image at each vertex

# Path Tracing Caustics



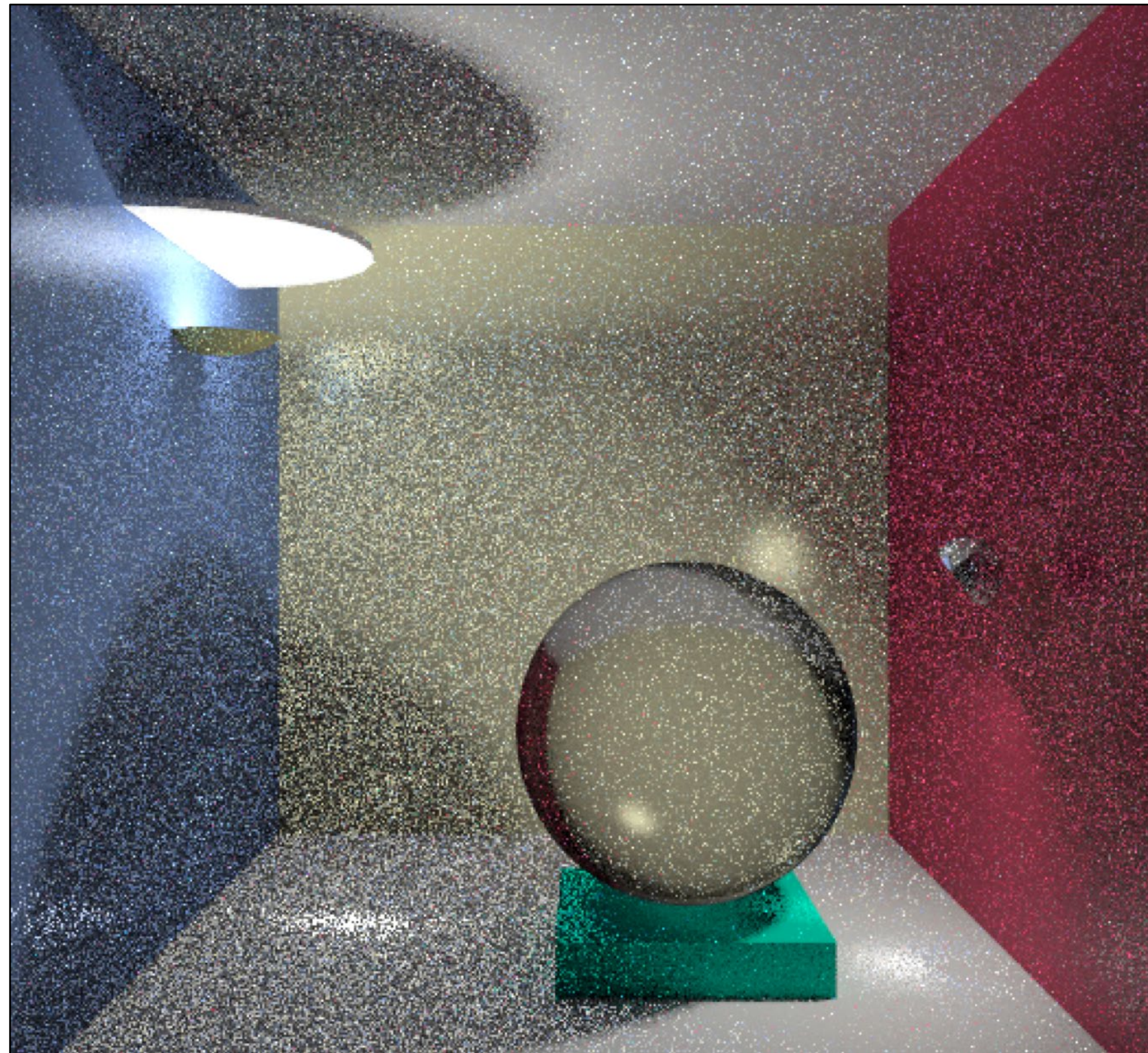
# Light Tracing Caustics



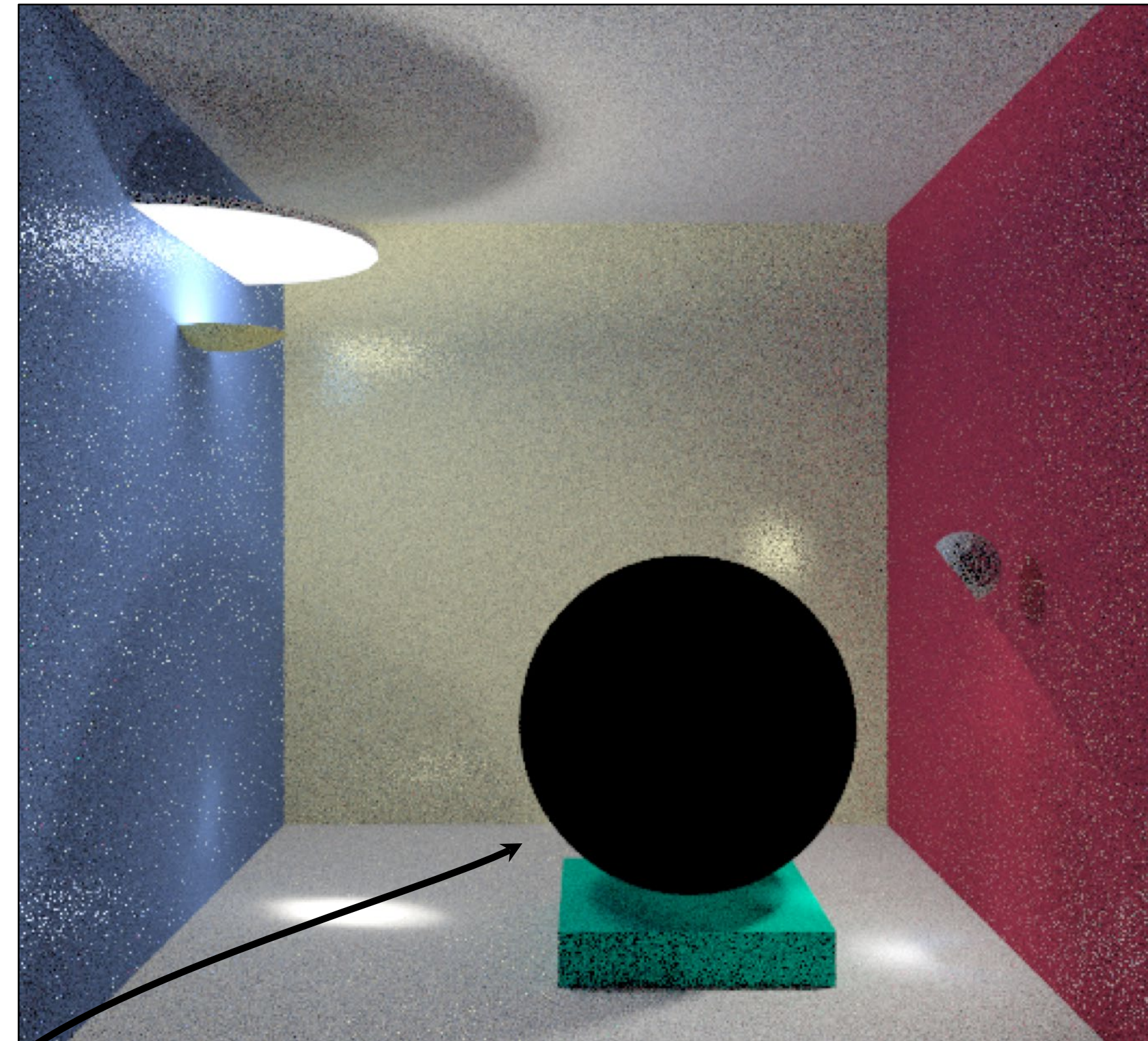


# Path vs. Light Tracing

Path tracing



Light tracing



Images courtesy of F. Suykens

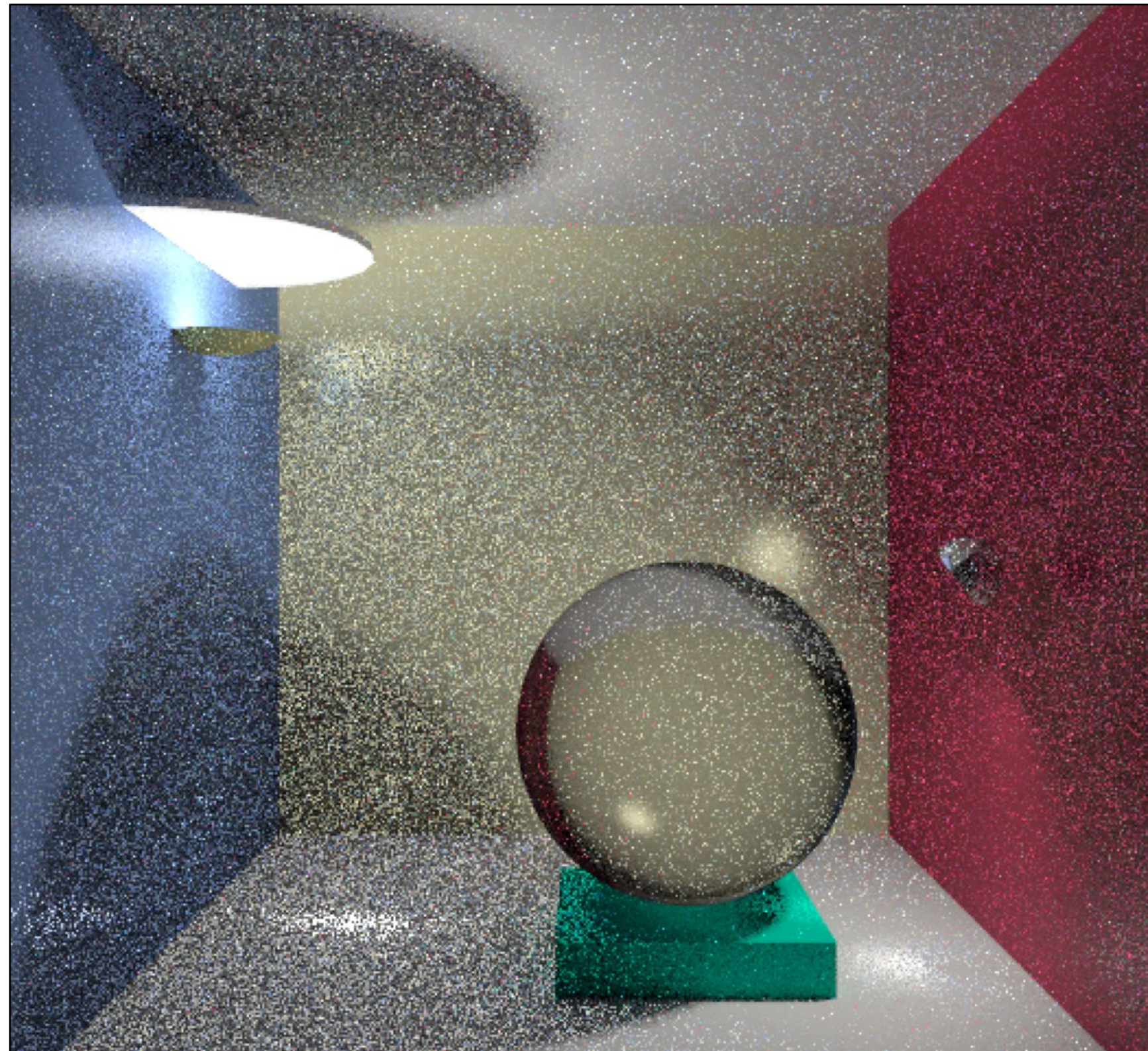
Why is this glass sphere black?



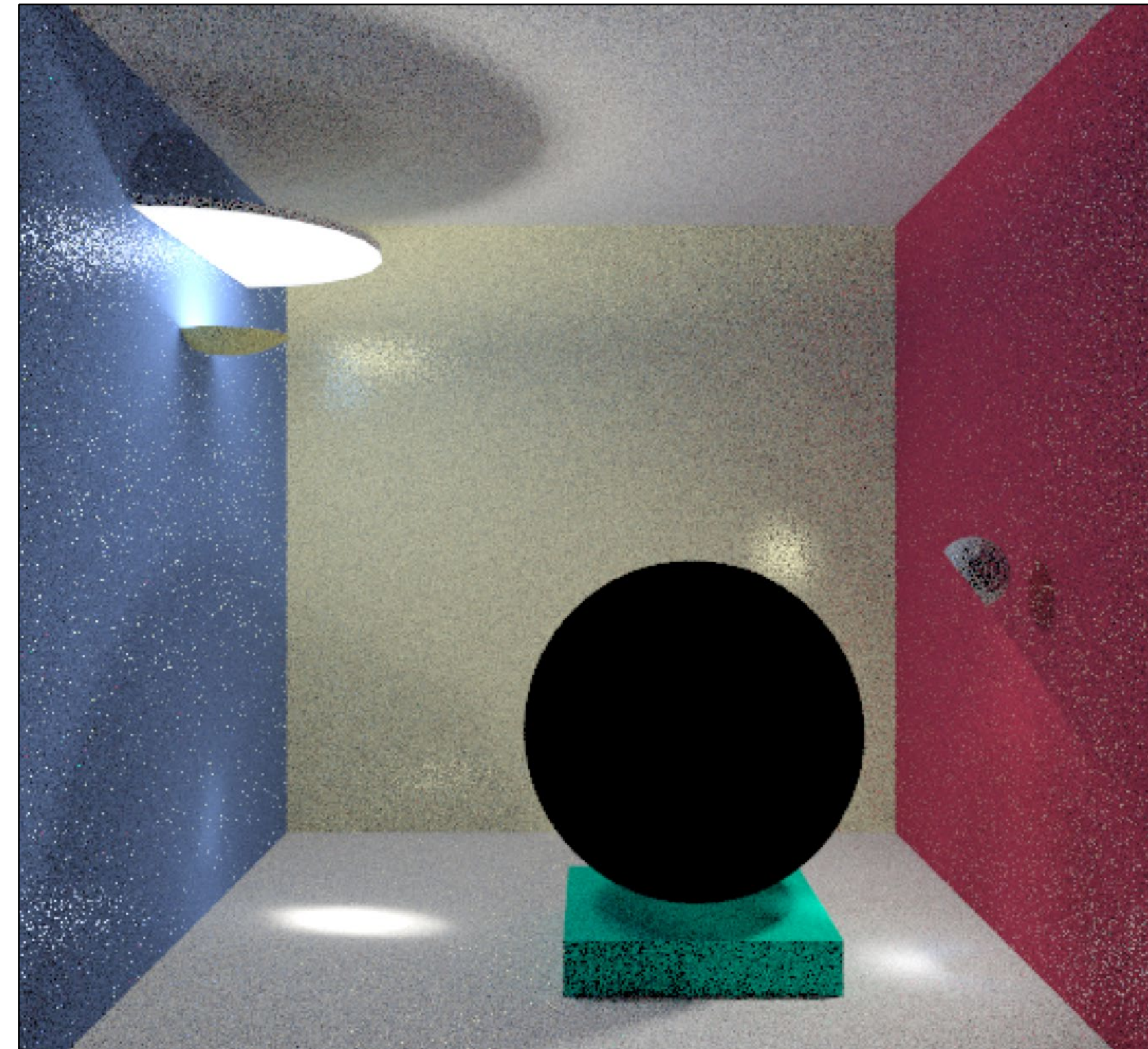
# Path vs. Light Tracing

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Path tracing



Light tracing



Images courtesy of F. Suykens

Can we combine them?



# Path Integral Framework

# Measurement Equation

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$$\begin{aligned} I_j &= \int_A \int_A W_e(\mathbf{x}_0, \mathbf{x}_1) G(\mathbf{x}_0, \mathbf{x}_1) L_o(\mathbf{x}_1, \mathbf{x}_0) d\mathbf{x}_1 d\mathbf{x}_0 \\ &= \int_A \int_A W_e(\mathbf{x}_0, \mathbf{x}_1) G(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_1, \mathbf{x}_0) + \int_A f(\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_0) G(\mathbf{x}_1, \mathbf{x}_2) L_o(\mathbf{x}_2, \mathbf{x}_1) d\mathbf{x}_2 d\mathbf{x}_1 d\mathbf{x}_0 \\ &= \int_A \int_A W_e(\mathbf{x}_0, \mathbf{x}_1) G(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_1, \mathbf{x}_0) + \int_A f(\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_0) G(\mathbf{x}_1, \mathbf{x}_2) L_e(\mathbf{x}_2, \mathbf{x}_1) + \int_A f(\mathbf{x}_2, \mathbf{x}_3, \mathbf{x}_1) G(\mathbf{x}_2, \mathbf{x}_3) L_e(\mathbf{x}_3, \mathbf{x}_2) + \int_A \cdots d\mathbf{x}_4 d\mathbf{x}_3 d\mathbf{x}_2 d\mathbf{x}_1 d\mathbf{x}_0 \end{aligned}$$

Hard to concisely express arbitrary light transport with all the nested integrals

Let's find a better way



# Path Integral Form of Measurement Eq.

$$\begin{aligned}
 I_j &= \int_A \int_A W_e(\mathbf{x}_0, \mathbf{x}_1) G(\mathbf{x}_0, \mathbf{x}_1) L_o(\mathbf{x}_1, \mathbf{x}_0) d\mathbf{x}_1 d\mathbf{x}_0 \\
 &= \iint_A W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_1, \mathbf{x}_0) G(\mathbf{x}_0, \mathbf{x}_1) d\mathbf{x}_1 d\mathbf{x}_0 \\
 &\quad + \iiint_A W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_2, \mathbf{x}_1) G(\mathbf{x}_0, \mathbf{x}_1) f(\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_0) G(\mathbf{x}_1, \mathbf{x}_2) d\mathbf{x}_2 d\mathbf{x}_1 d\mathbf{x}_0 + \cdots \\
 &\quad + \int \cdots \int_A W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_k, \mathbf{x}_{k-1}) G(\mathbf{x}_0, \mathbf{x}_1) \prod_{j=1}^{k-1} f(\mathbf{x}_j, \mathbf{x}_{j+1}, \mathbf{x}_{j-1}) G(\mathbf{x}_j, \mathbf{x}_{j+1}) d\mathbf{x}_k \cdots d\mathbf{x}_0 + \cdots
 \end{aligned}$$

introduce:  $\mathcal{P}_k = \{\bar{\mathbf{x}} = \mathbf{x}_0 \cdots \mathbf{x}_k; \mathbf{x}_0 \cdots \mathbf{x}_k \in A\}$

space of all paths with  $k$  segments

# Path Integral Form of Measurement Eq.

$$I_j = \int_A \int_A W_e(\mathbf{x}_0, \mathbf{x}_1) G(\mathbf{x}_0, \mathbf{x}_1) L_o(\mathbf{x}_1, \mathbf{x}_0) d\mathbf{x}_1 d\mathbf{x}_0$$

$$= \int_{\mathcal{P}_1} \overset{\text{Emission}}{W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_1, \mathbf{x}_0) G(\mathbf{x}_0, \mathbf{x}_1) d\bar{\mathbf{x}}_1}$$

$$+ \int_{\mathcal{P}_2} \overset{\text{Direct illumination (3 vertices)}}{W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_2, \mathbf{x}_1) G(\mathbf{x}_0, \mathbf{x}_1) f(\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_0) G(\mathbf{x}_1, \mathbf{x}_2) d\bar{\mathbf{x}}_2} + \dots$$

$$+ \int_{\mathcal{P}_k} \overset{\text{(k-2)-bounce illumination (k vertices)}}{W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_k, \mathbf{x}_{k-1}) G(\mathbf{x}_0, \mathbf{x}_1) \prod_{j=1}^{k-1} f(\mathbf{x}_j, \mathbf{x}_{j+1}, \mathbf{x}_{j-1}) G(\mathbf{x}_j, \mathbf{x}_{j+1}) d\bar{\mathbf{x}}_k} + \dots$$

introduce:  $T(\bar{\mathbf{x}}_k) = G(\mathbf{x}_0, \mathbf{x}_1) \prod_{j=1}^{k-1} f(\mathbf{x}_j, \mathbf{x}_{j+1}, \mathbf{x}_{j-1}) G(\mathbf{x}_j, \mathbf{x}_{j+1})$

*throughput of path*      $\bar{\mathbf{x}}_k$

# Path Integral Form of Measurement Eq.

$$I_j = \int_A \int_A W_e(\mathbf{x}_0, \mathbf{x}_1) G(\mathbf{x}_0, \mathbf{x}_1) L_o(\mathbf{x}_1, \mathbf{x}_0) d\mathbf{x}_1 d\mathbf{x}_0$$

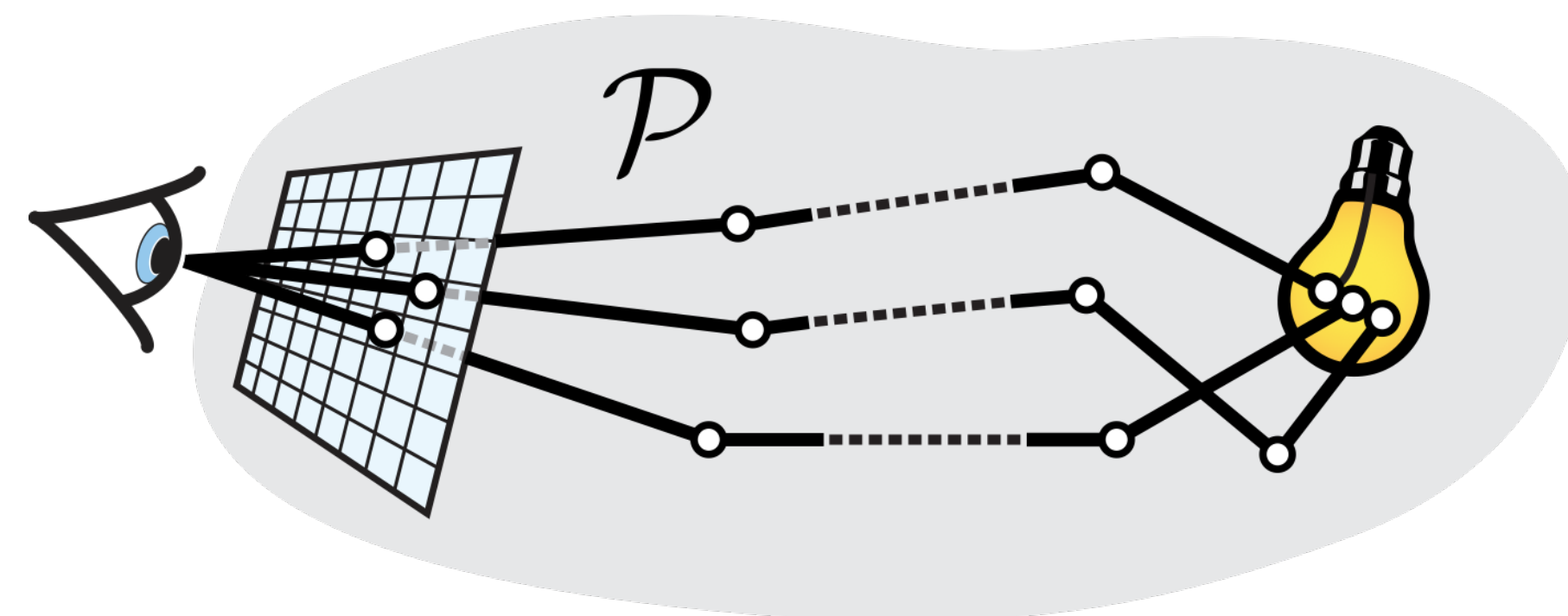
$$= \int_{\mathcal{P}_1} W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_1, \mathbf{x}_0) T(\bar{\mathbf{x}}_1) d\bar{\mathbf{x}}_1$$

$$+ \int_{\mathcal{P}_2} W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_2, \mathbf{x}_1) T(\bar{\mathbf{x}}_2) d\bar{\mathbf{x}}_2 + \dots$$

$$+ \int_{\mathcal{P}_k} W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_k, \mathbf{x}_{k-1}) T(\bar{\mathbf{x}}_k) d\bar{\mathbf{x}}_k + \dots$$

introduce:  $\mathcal{P} = \bigcup_{k=1}^{\infty} \mathcal{P}_k$

the *path space*, i.e. the space of all paths of all lengths





# Path Integral Form of Measurement Eq.

---

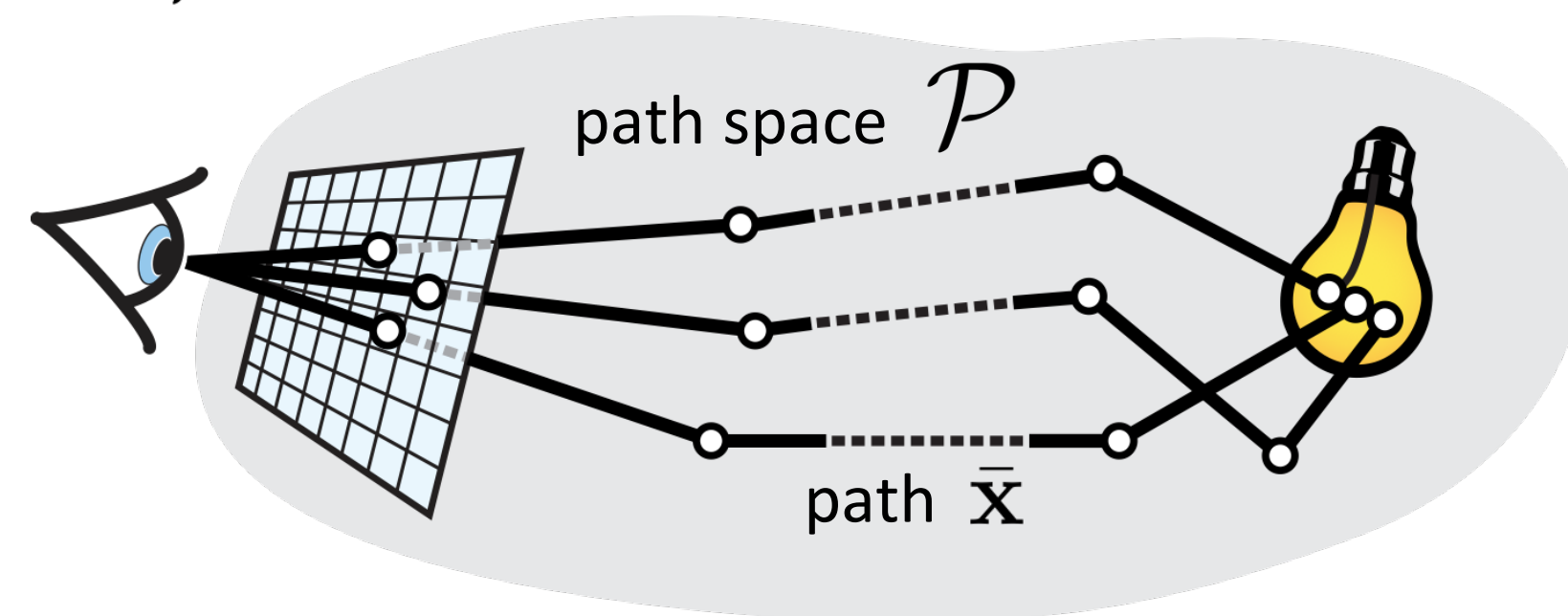
$$I_j = \int_A \int_A W_e(\mathbf{x}_0, \mathbf{x}_1) G(\mathbf{x}_0, \mathbf{x}_1) L_o(\mathbf{x}_1, \mathbf{x}_0) d\mathbf{x}_1 d\mathbf{x}_0$$

$$= \int_{\mathcal{P}} W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_k, \mathbf{x}_{k-1}) T(\bar{\mathbf{x}}) d\bar{\mathbf{x}}$$

global illumination (all paths of all lengths)

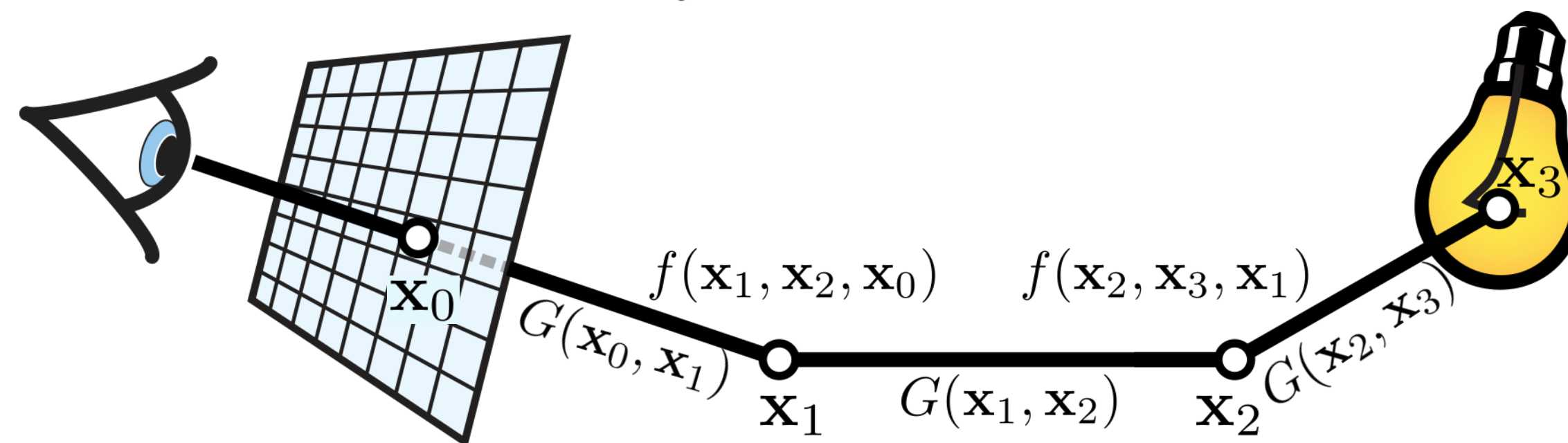
# Path Integral Form of Measurement Eq.

$$I_j = \int_{\mathcal{P}} W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_k, \mathbf{x}_{k-1}) T(\bar{\mathbf{x}}) d\bar{\mathbf{x}}$$



path throughput

$$T(\bar{\mathbf{x}}) = G(\mathbf{x}_0, \mathbf{x}_1) \prod_{j=1}^{k-1} f(\mathbf{x}_j, \mathbf{x}_{j+1}, \mathbf{x}_{j-1}) G(\mathbf{x}_j, \mathbf{x}_{j+1})$$



# Path Integral Form of Measurement Eq.

---

$$I_j = \int_{\mathcal{P}} W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_k, \mathbf{x}_{k-1}) T(\bar{\mathbf{x}}) d\bar{\mathbf{x}}$$

Advantages:

- no recursion, no “nasty” nested integrals
- emphasizes symmetry of light transport
- easy to relate different rendering algorithms
- focuses on path geometry, independent of strategy for constructing paths
- MC estimator on path space looks much simpler



# Path Integral Form of Measurement Eq.

---

$$I_j = \int_{\mathcal{P}} W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_k, \mathbf{x}_{k-1}) T(\bar{\mathbf{x}}) d\bar{\mathbf{x}}$$

Monte Carlo estimator:

$$I_j \approx \frac{1}{N} \sum_{i=1}^N \frac{W_e(\mathbf{x}_{i,0}, \mathbf{x}_{i,1}) L_e(\mathbf{x}_{i,k}, \mathbf{x}_{i,k-1}) T(\bar{\mathbf{x}}_i)}{p(\bar{\mathbf{x}}_i)}$$

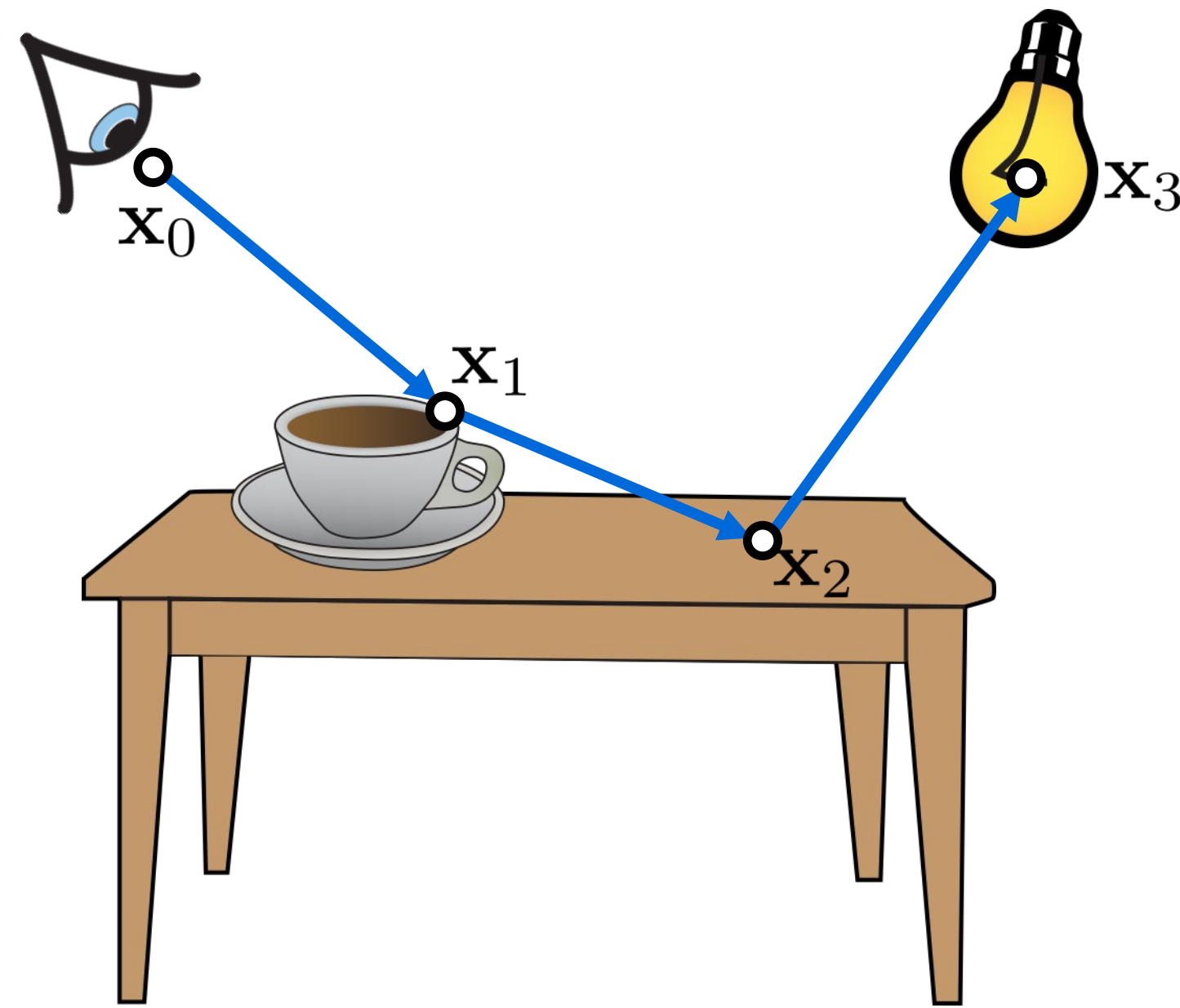
$$p(\bar{\mathbf{x}}) = p(\underbrace{\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{k-1}, \mathbf{x}_k}_{\text{joint PDF of path vertices}})$$

path PDF

# Path Construction

$$p(\bar{\mathbf{x}}) = p(\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{k-1}, \mathbf{x}_k)$$

Path tracing w/o NEE

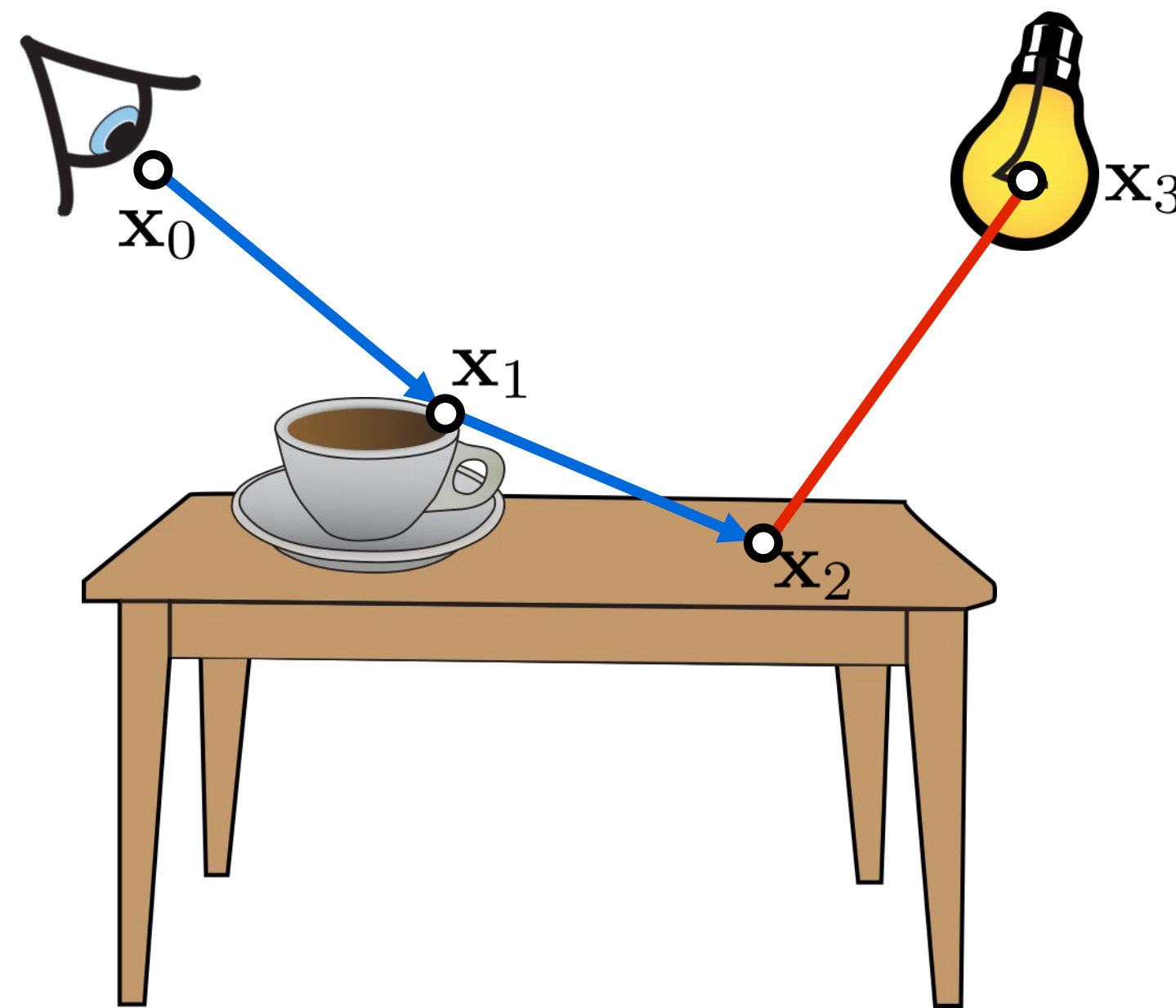


$$\begin{aligned} p(\bar{\mathbf{x}}) &= p(\mathbf{x}_0) \\ &\times p(\mathbf{x}_1 | \mathbf{x}_0) \\ &\times p(\mathbf{x}_2 | \mathbf{x}_0 \mathbf{x}_1) \\ &\times p(\mathbf{x}_3 | \mathbf{x}_0 \mathbf{x}_1 \mathbf{x}_2) \end{aligned}$$

# Path Construction

$$p(\bar{\mathbf{x}}) = p(\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{k-1}, \mathbf{x}_k)$$

Path tracing with NEE



$$\begin{aligned} p(\bar{\mathbf{x}}) &= p(\mathbf{x}_0) \\ &\times p(\mathbf{x}_1 | \mathbf{x}_0) \\ &\times p(\mathbf{x}_2 | \mathbf{x}_0 \mathbf{x}_1) \\ &\times p(\mathbf{x}_3) \end{aligned}$$

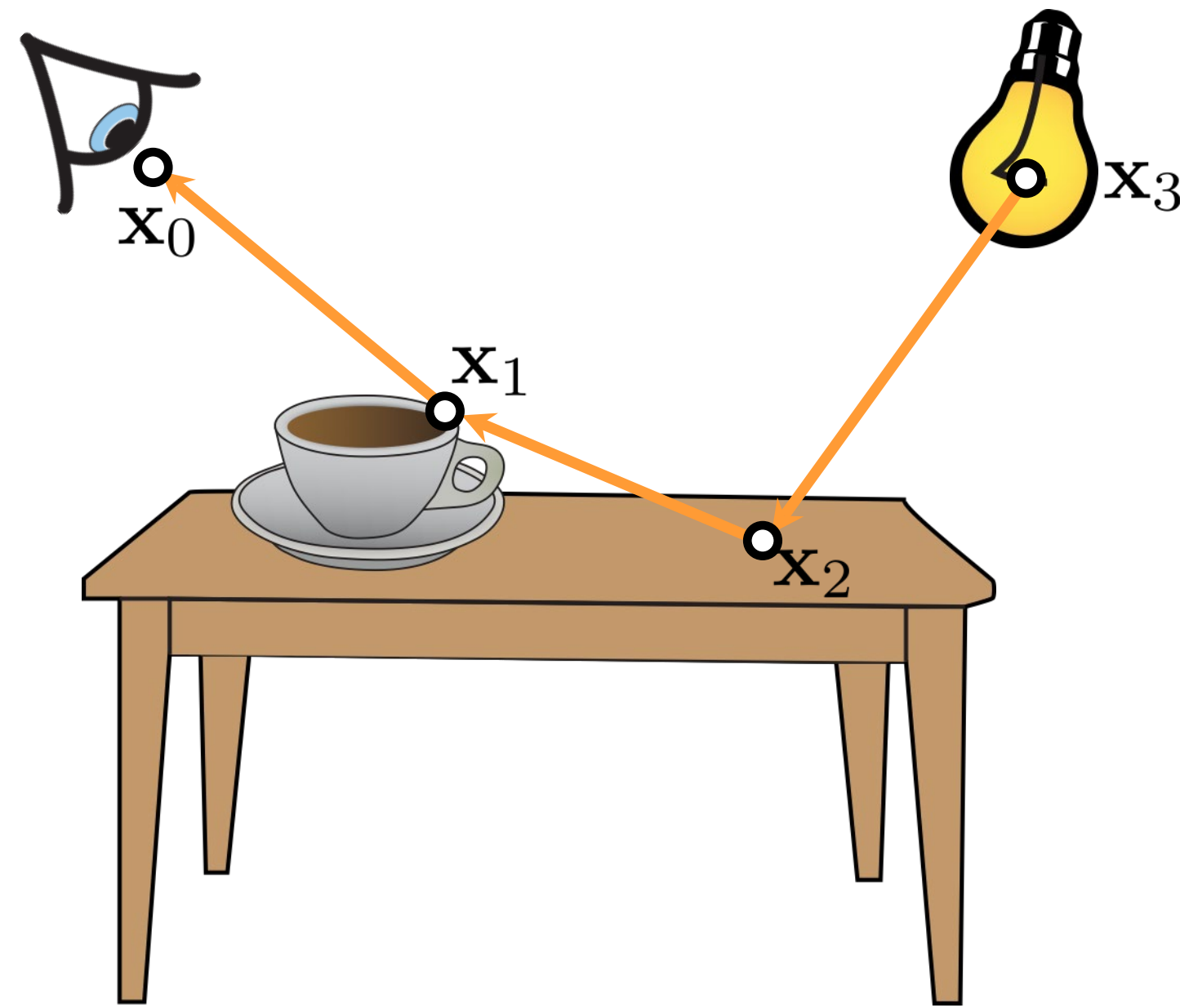
assuming uniform area sampling



# Path Construction

$$p(\bar{\mathbf{x}}) = p(\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{k-1}, \mathbf{x}_k)$$

Light tracing

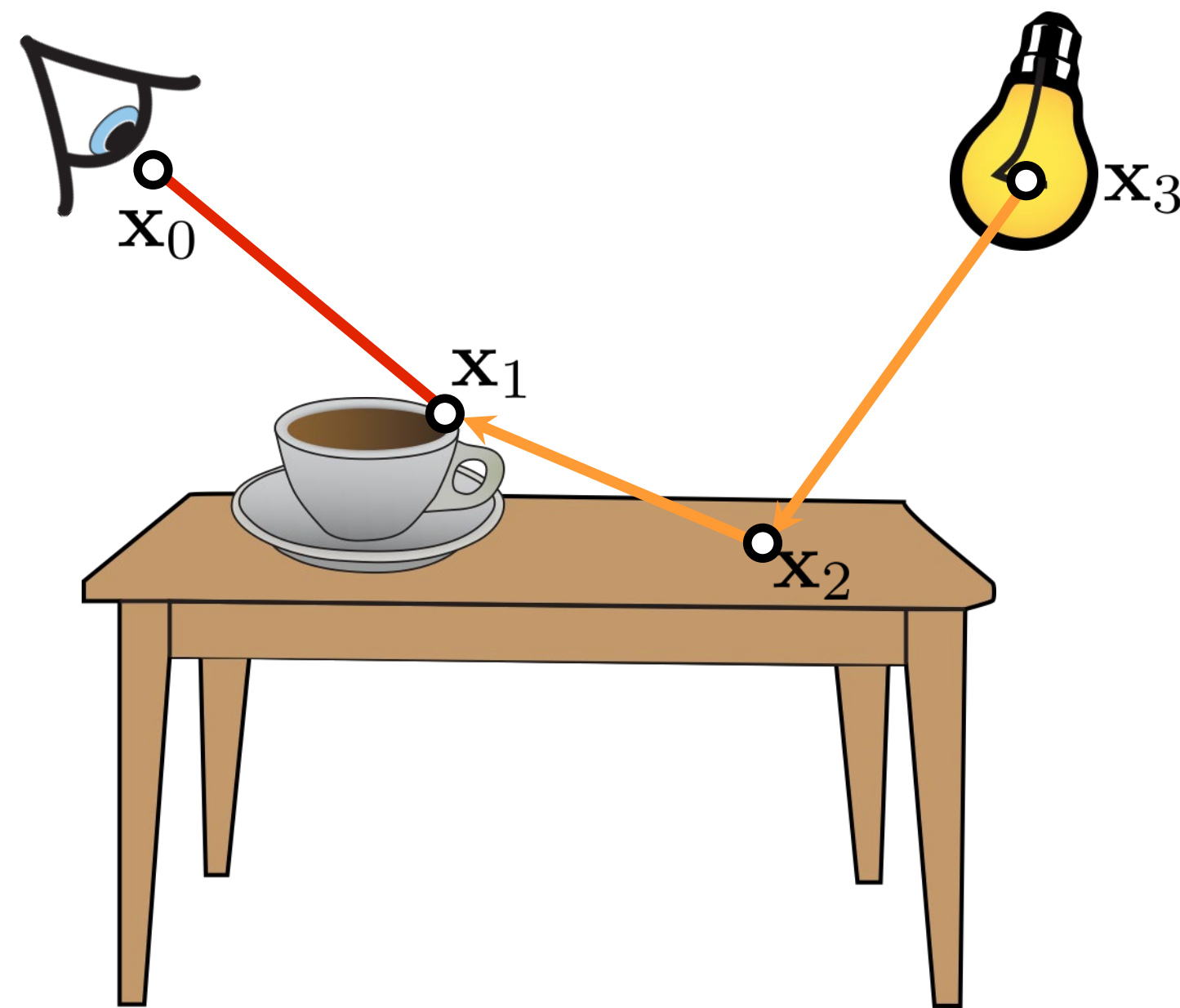


$$\begin{aligned} p(\bar{\mathbf{x}}) &= p(\mathbf{x}_0 | \mathbf{x}_3 \mathbf{x}_2 \mathbf{x}_1) \\ &\quad \times p(\mathbf{x}_1 | \mathbf{x}_3 \mathbf{x}_2) \\ &\quad \times p(\mathbf{x}_2 | \mathbf{x}_3) \\ &\quad \times p(\mathbf{x}_3) \end{aligned}$$

# Path Construction

$$p(\bar{\mathbf{x}}) = p(\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{k-1}, \mathbf{x}_k)$$

Light tracing with NEE



assuming uniform aperture sampling

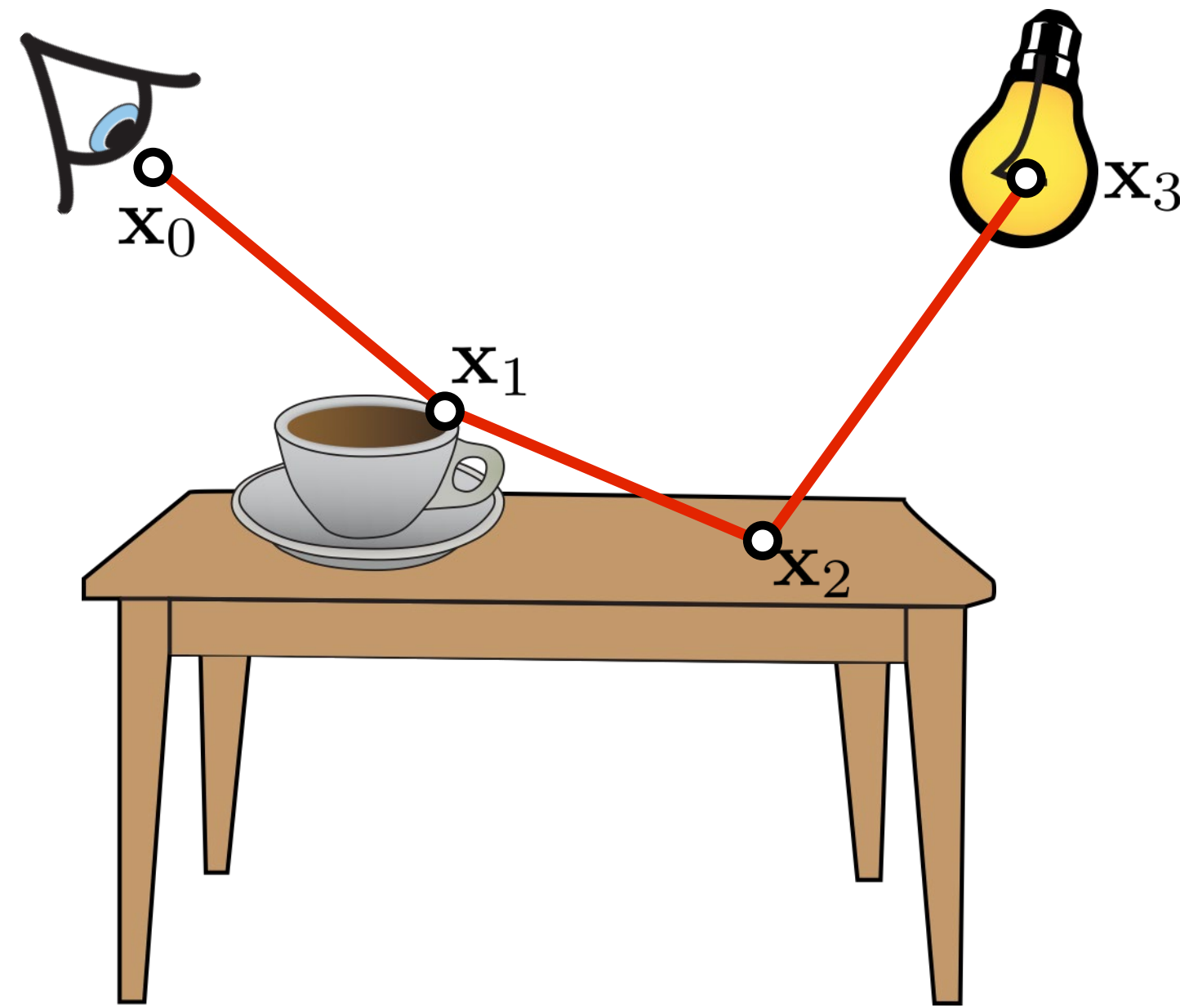
$$p(\bar{\mathbf{x}}) = p(\mathbf{x}_0) \times p(\mathbf{x}_1 | \mathbf{x}_3 \mathbf{x}_2) \times p(\mathbf{x}_2 | \mathbf{x}_3) \times p(\mathbf{x}_3)$$

# Path Construction

---

$$p(\bar{\mathbf{x}}) = p(\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{k-1}, \mathbf{x}_k)$$

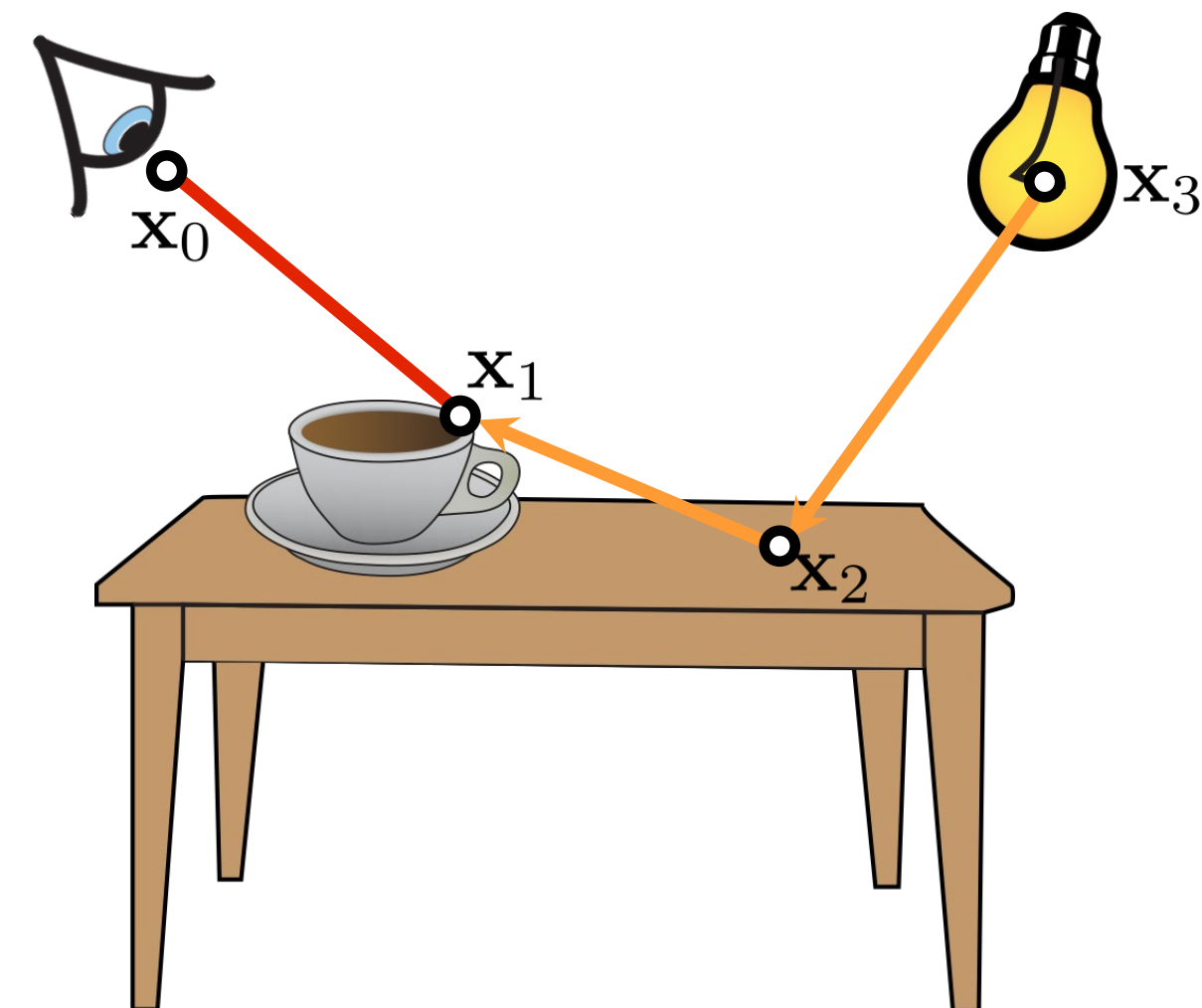
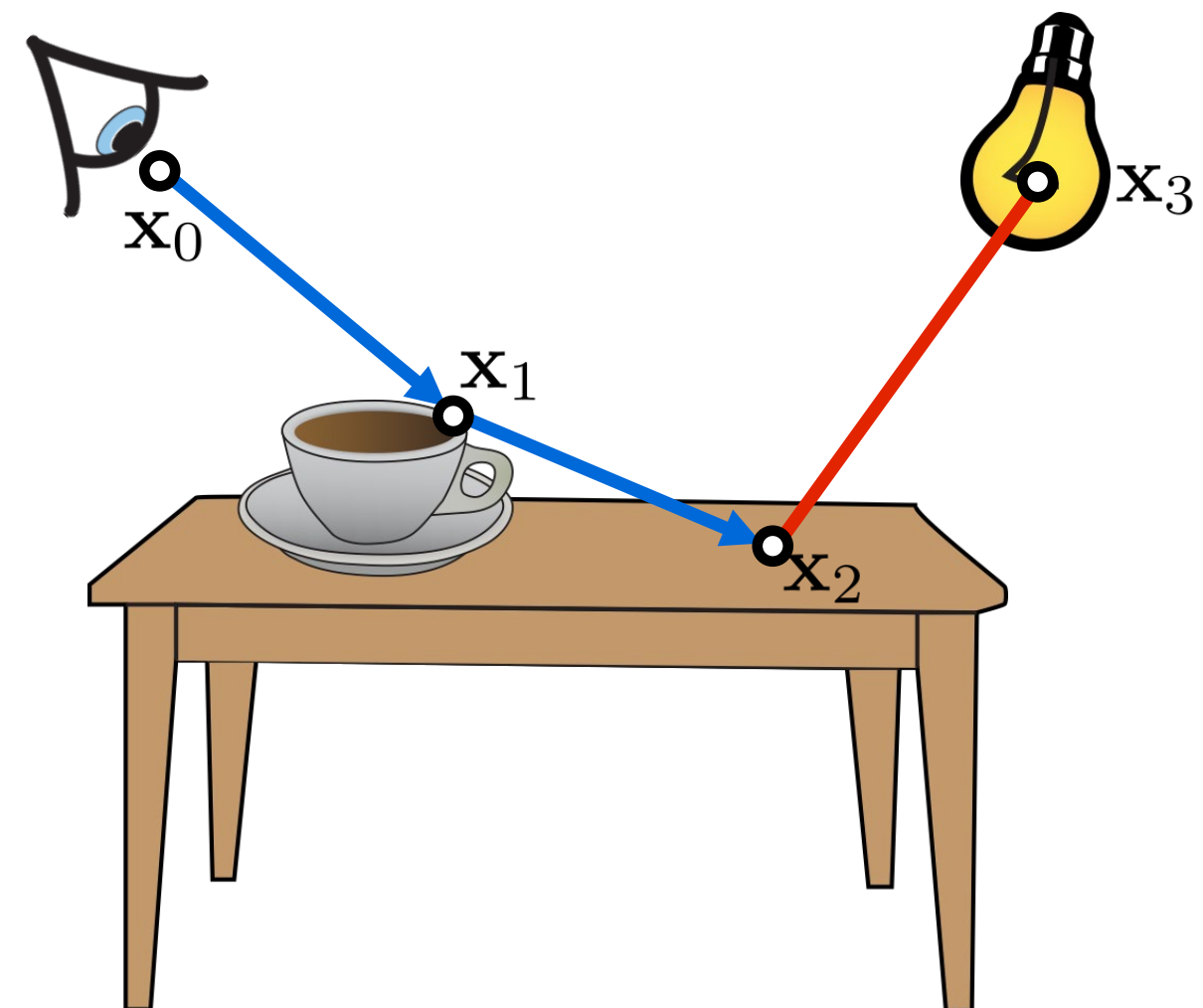
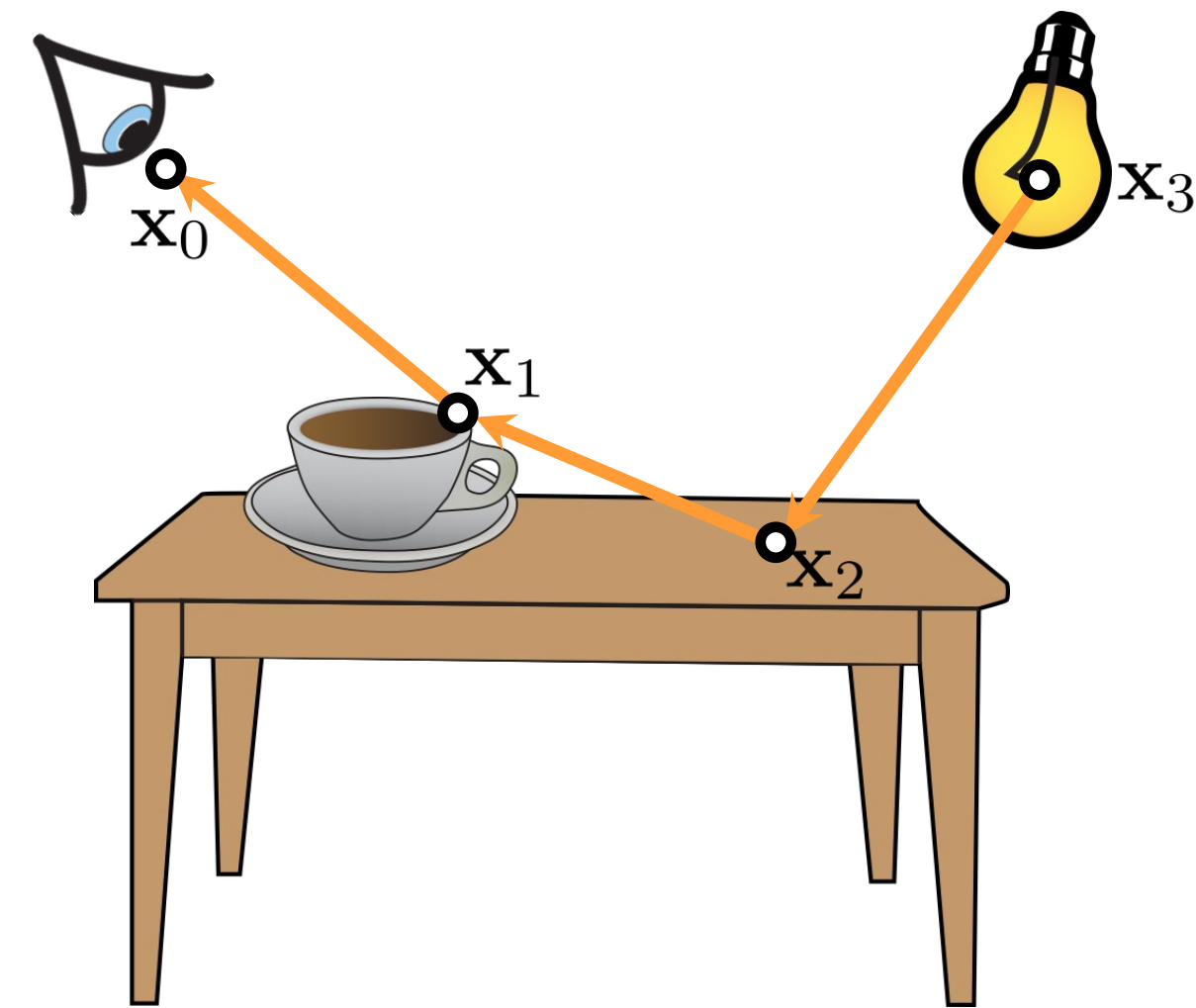
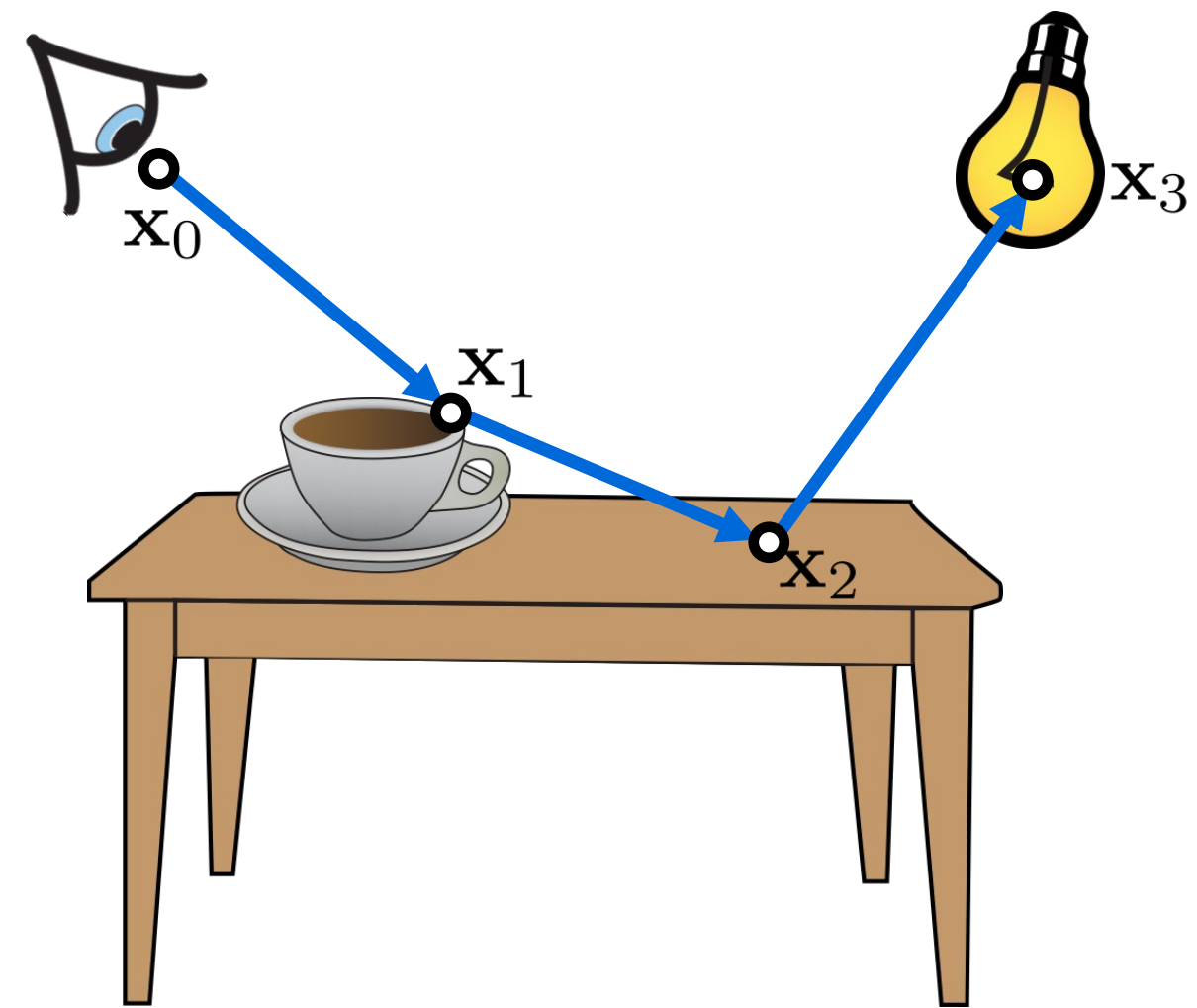
Independent sampling of path vertices  
(not very practical though)



$$\begin{aligned} p(\bar{\mathbf{x}}) &= p(\mathbf{x}_0) \\ &\times p(\mathbf{x}_1) \\ &\times p(\mathbf{x}_2) \\ &\times p(\mathbf{x}_3) \end{aligned}$$



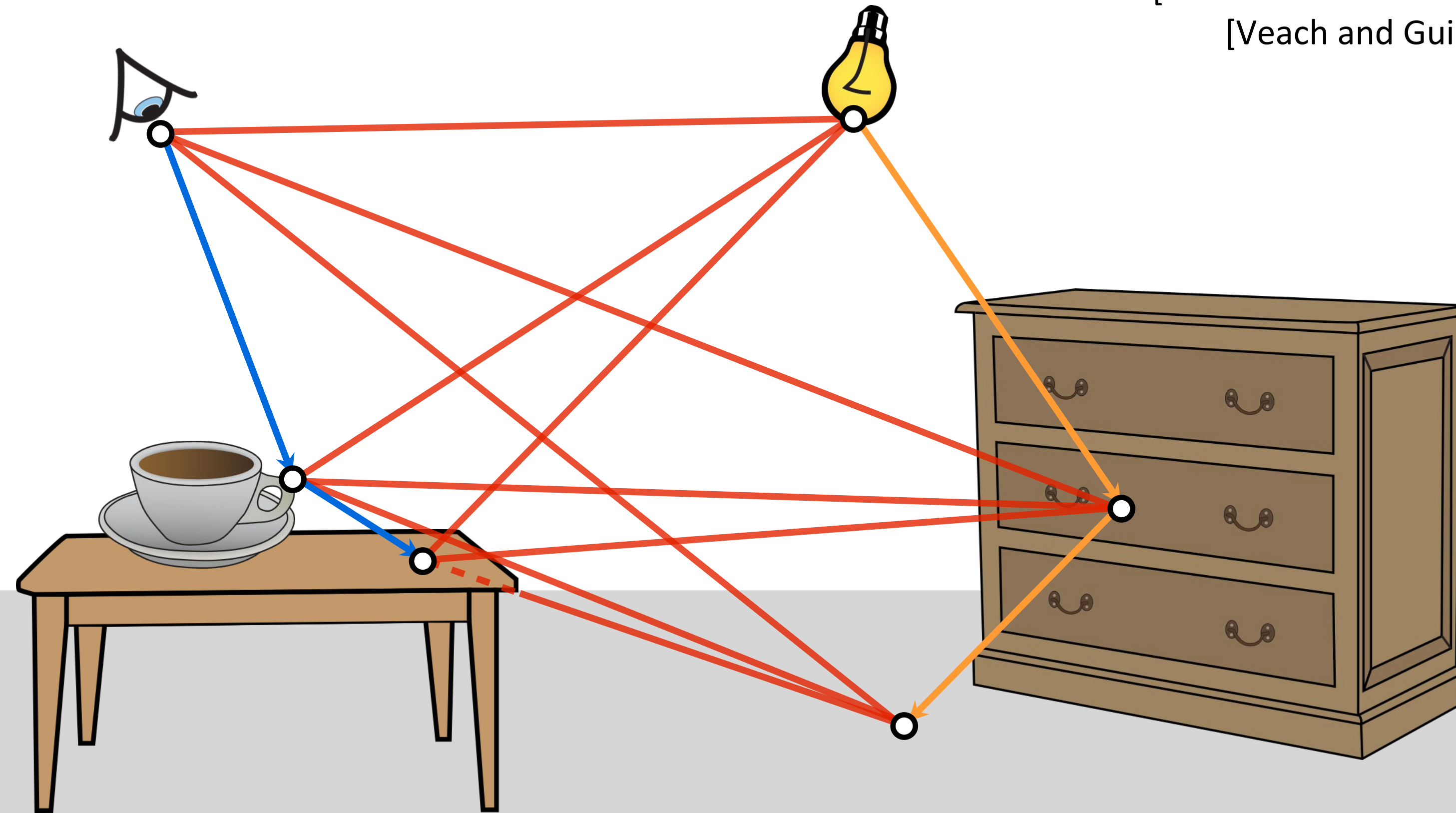
# Can we combine them?



# Bidirectional Path Tracing

# Bidirectional Path Tracing

[Lafortune and Willem 1993]  
[Veach and Guibas 1994]



$t$  - # vertices on camera subpath  
 $s$  - # vertices on light subpath  
 $ts$  - # connections



# Bidirectional Path Tracing

---

**color estimate (point  $x$ )**

```
{  
    lp = sample light subpath  
    cp = sample camera subpath for image point  $x$   
  
    for each vertex  $s$  in lp  
        for each vertex  $t$  in cp  
            fullPath = join(cp[0.. $s$ ], lp[0.. $t$ )  
            splat(fullPath.screenPos,  
fullPath.contrib)  
}
```

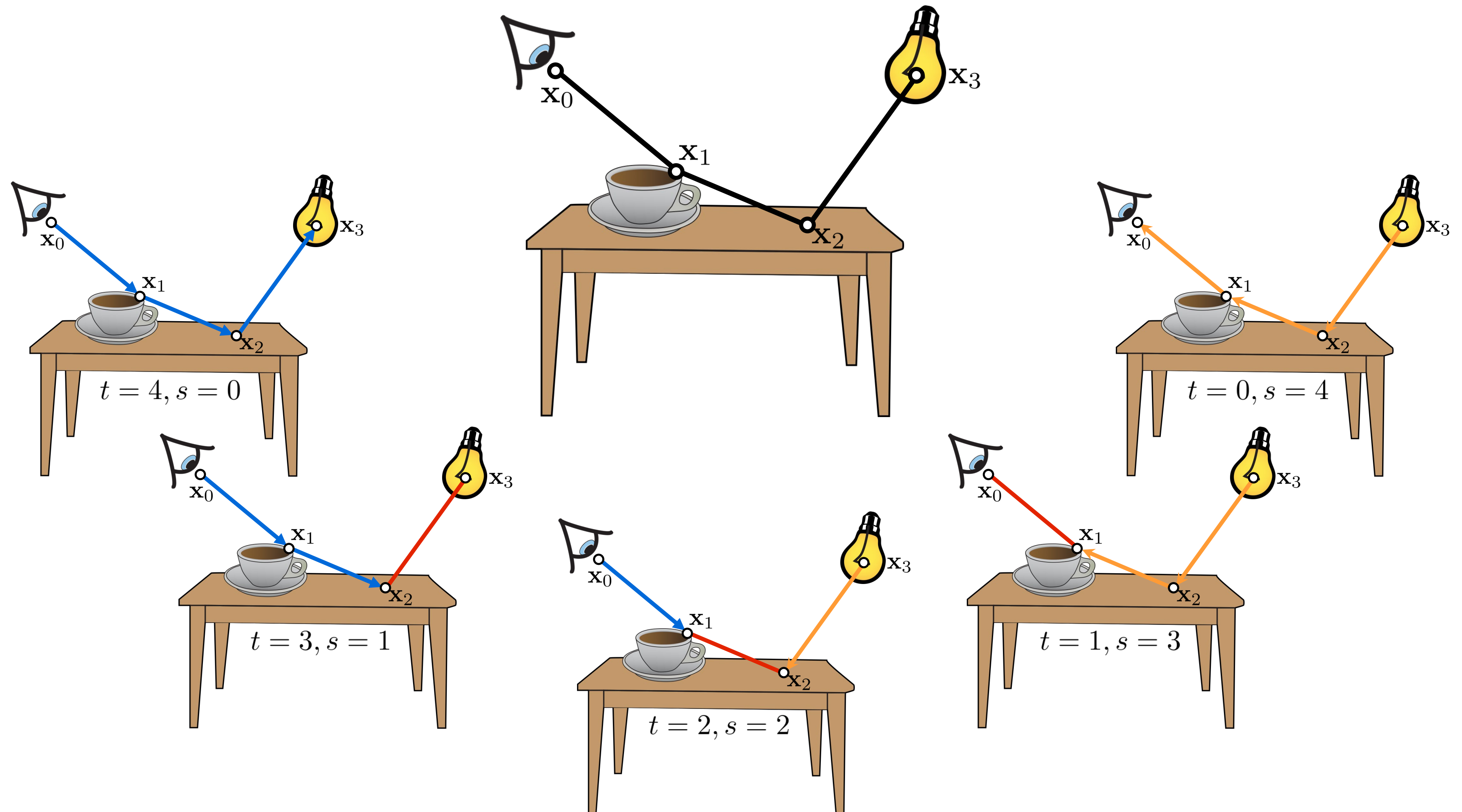
# Bidirectional Path Tracing

---

## Key observations:

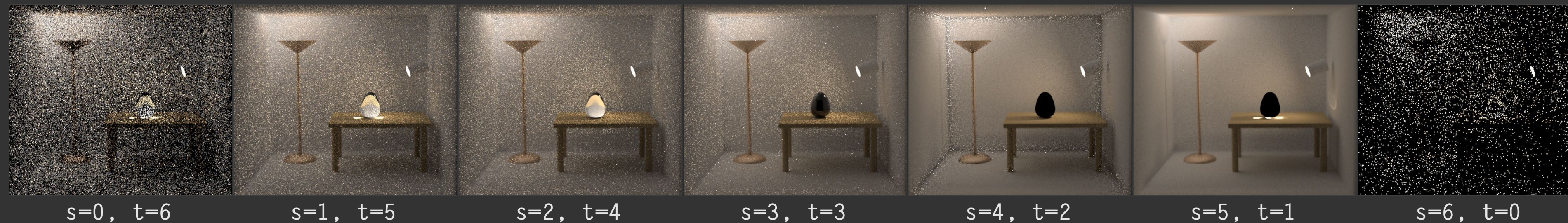
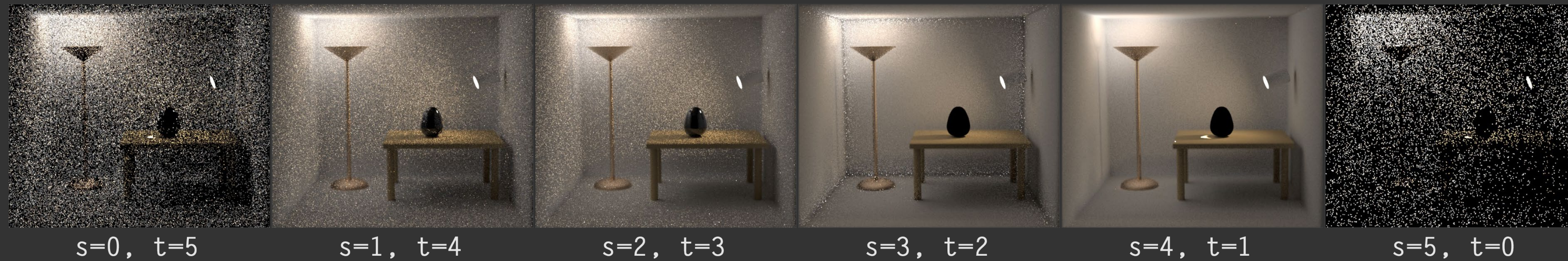
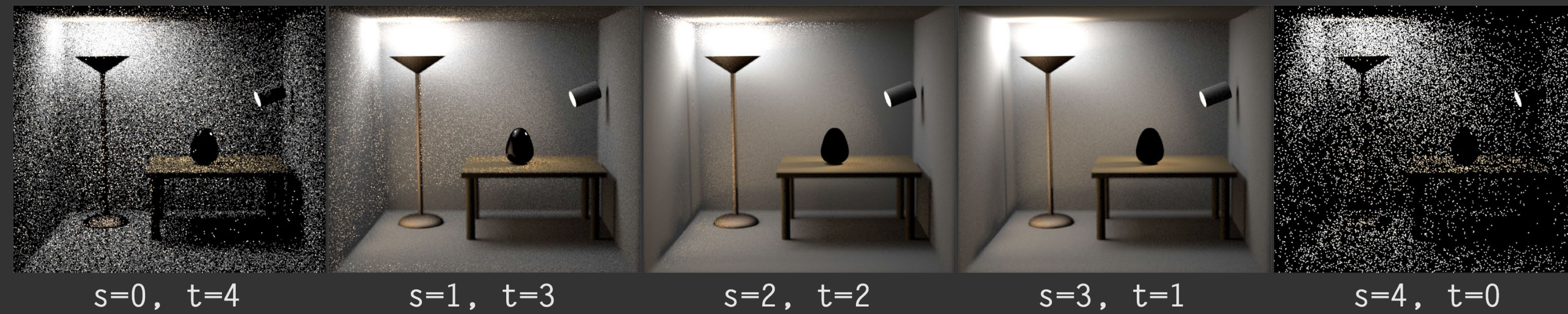
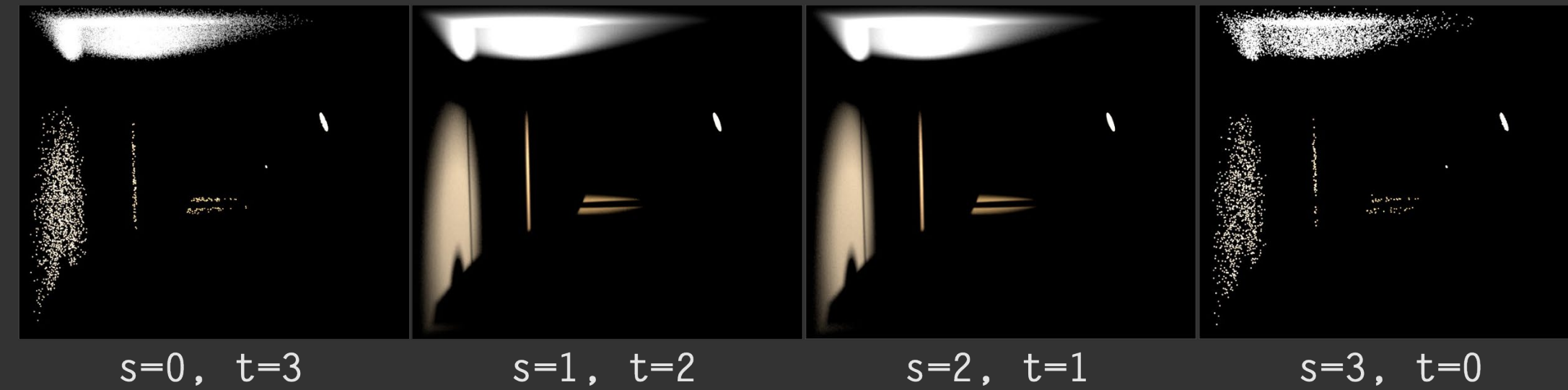
- Every path (formed by connecting camera sub-path to light sub-path) with  $k$  vertices can be constructed using  $k+1$  strategies
- For a particular path length, all strategies estimate the same integral
- Each strategy has a different PDF, i.e., each strategy has different strengths and weaknesses
- Let's combine them using MIS!

# Bidirectional Path Tracing





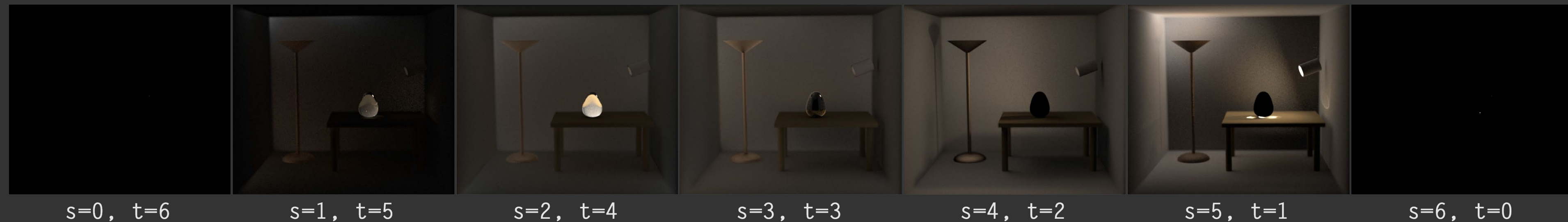
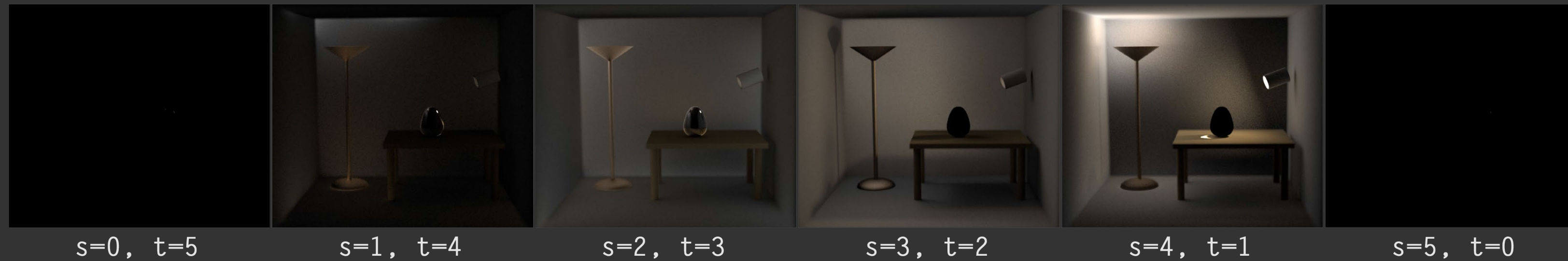
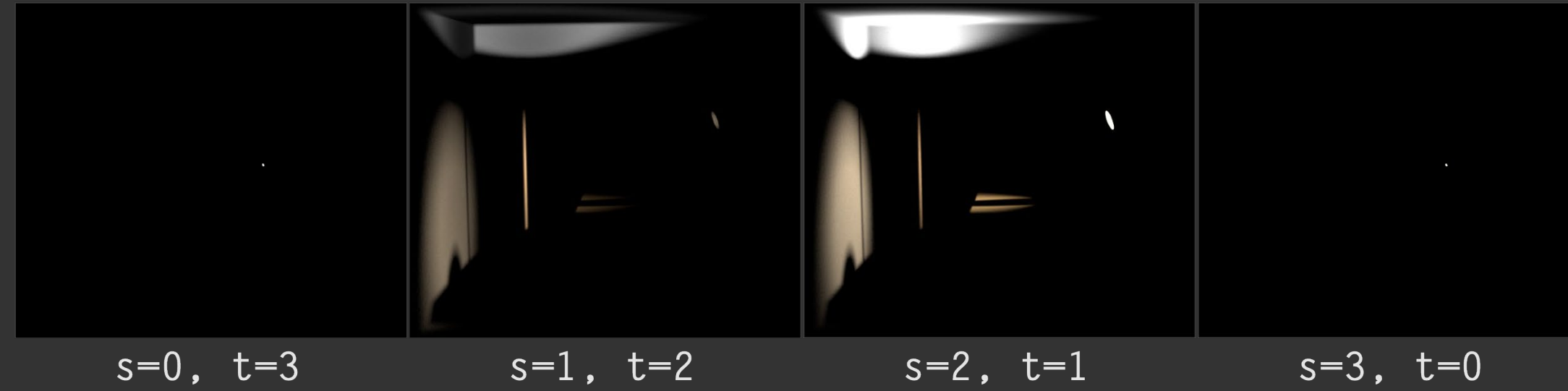
# Bidirectional Path Tracing



Images courtesy of W. Jakob



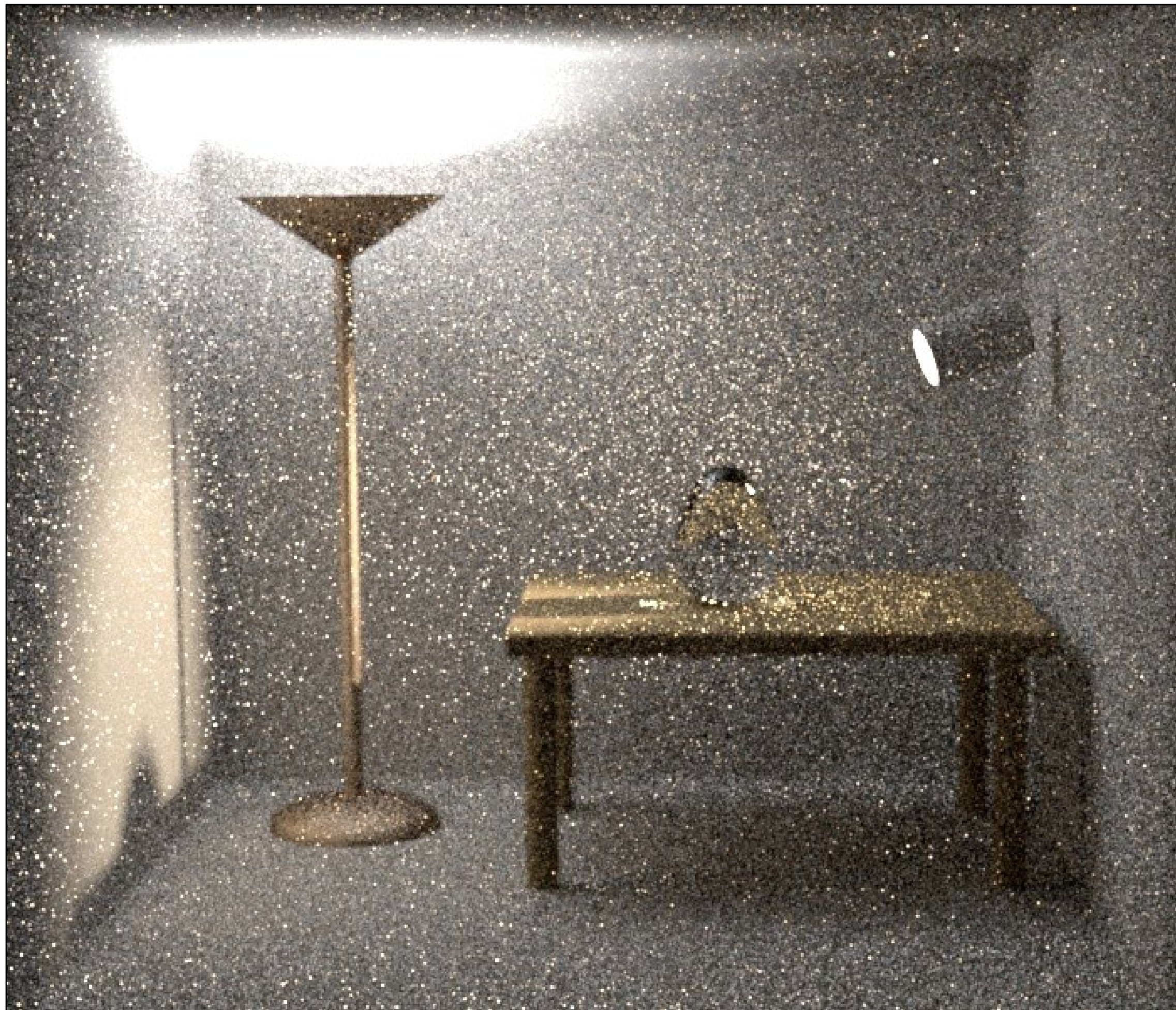
# Bidirectional Path Tracing (MIS)



# Bidirectional Path Tracing

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(Unidirectional) path tracing



Bidirectional path tracing

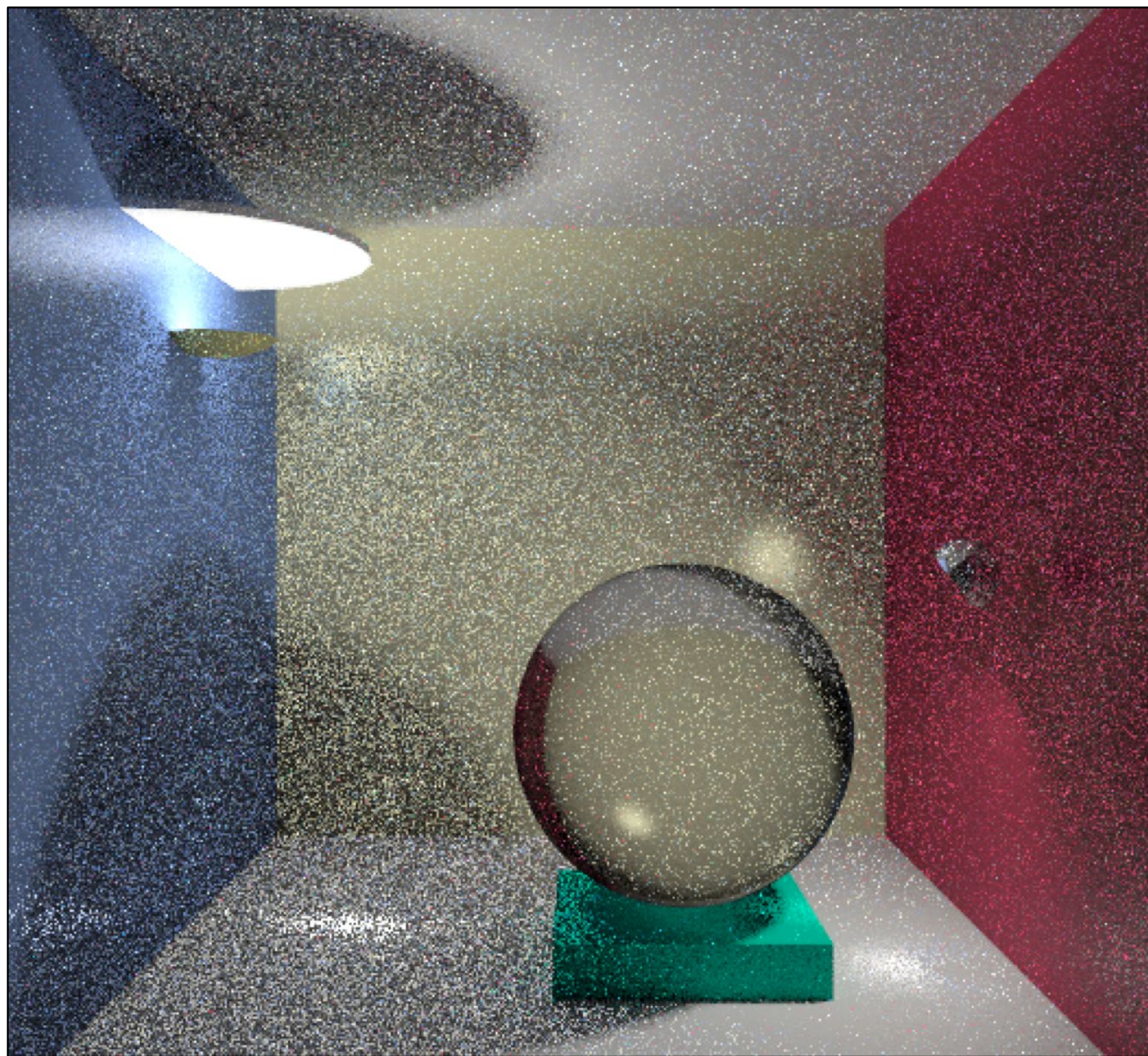




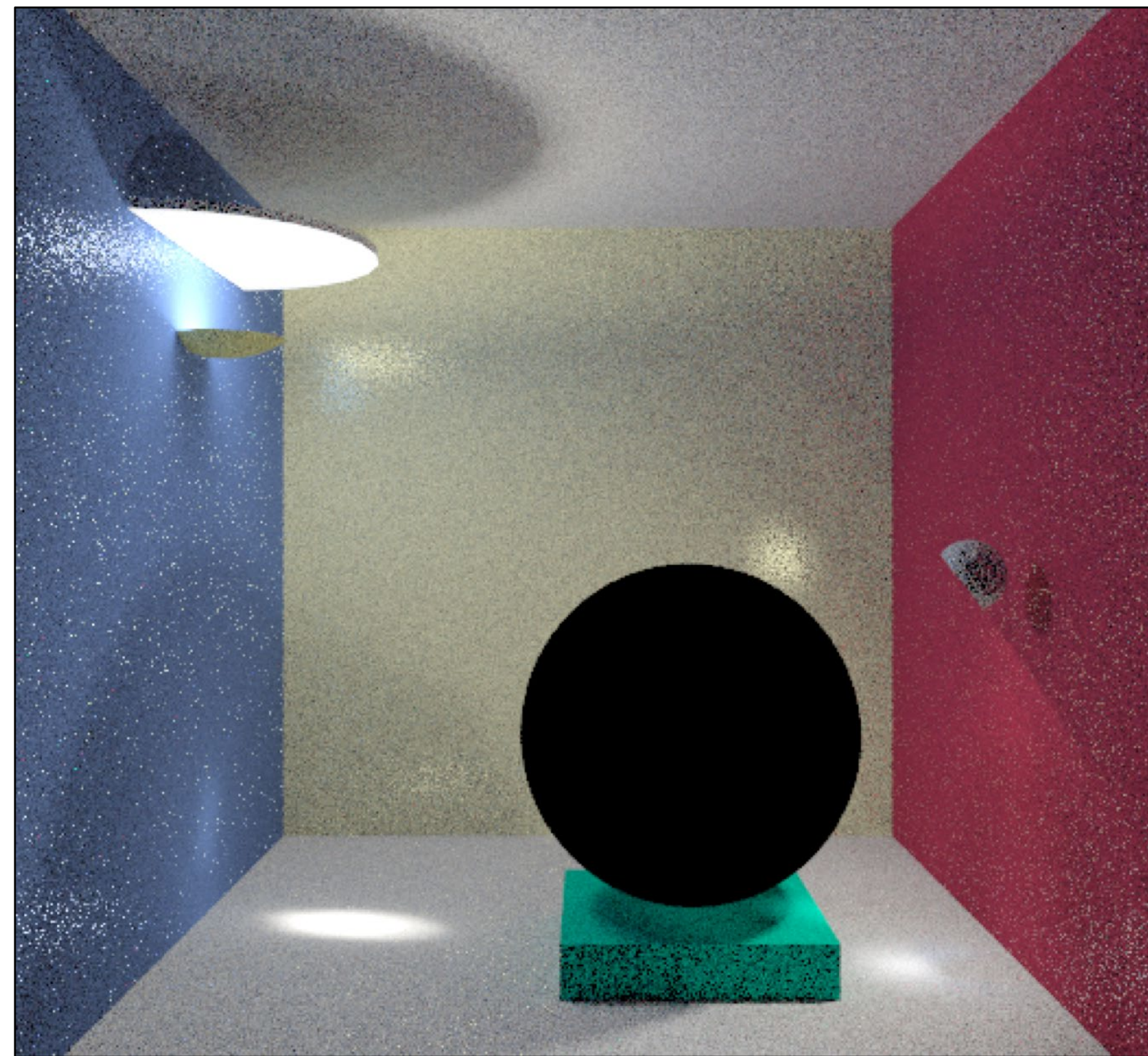
# Bidirectional Path Tracing

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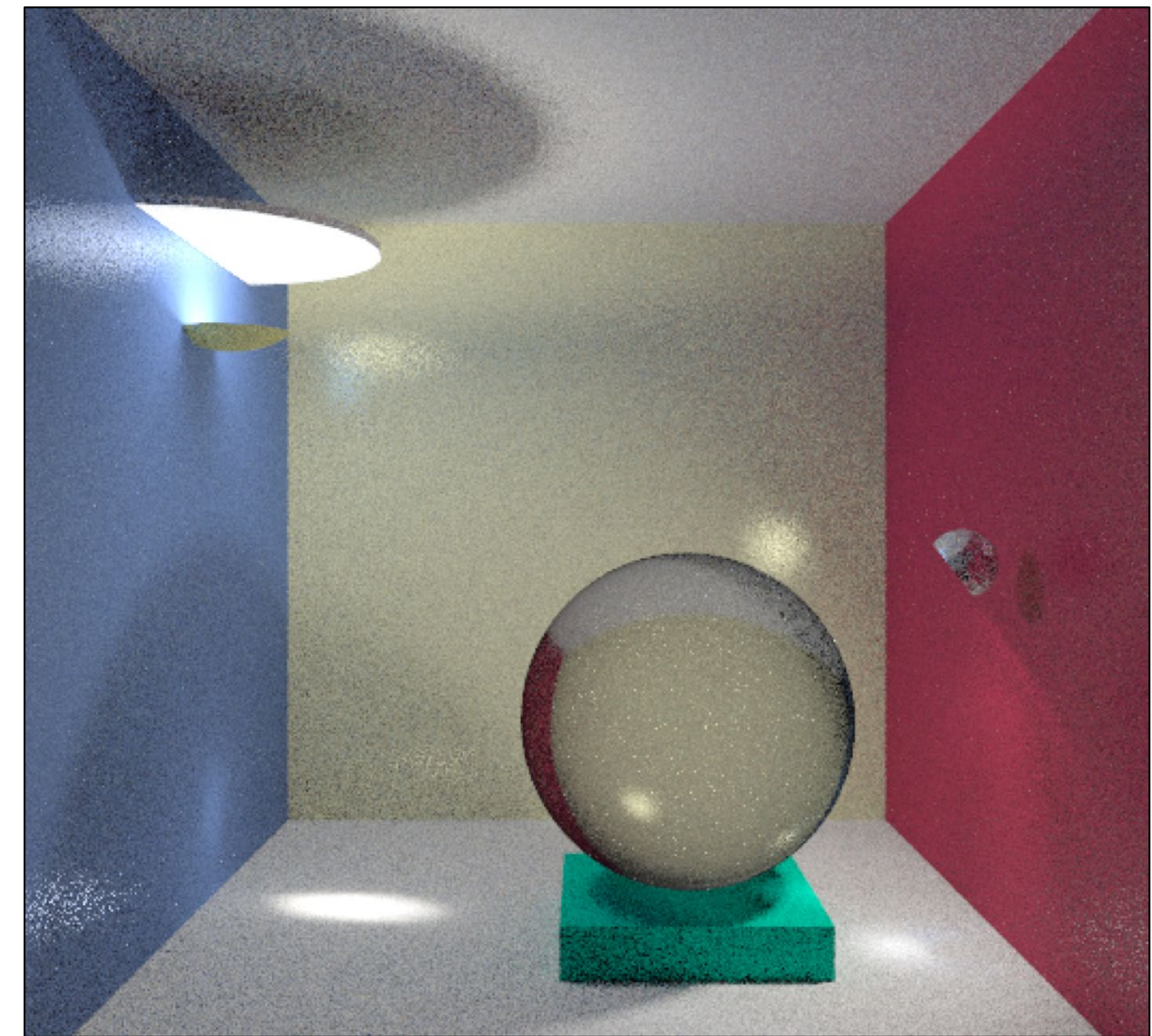
Path tracing



Light tracing



Bidirectional PT





# Still not robust enough...

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Reference

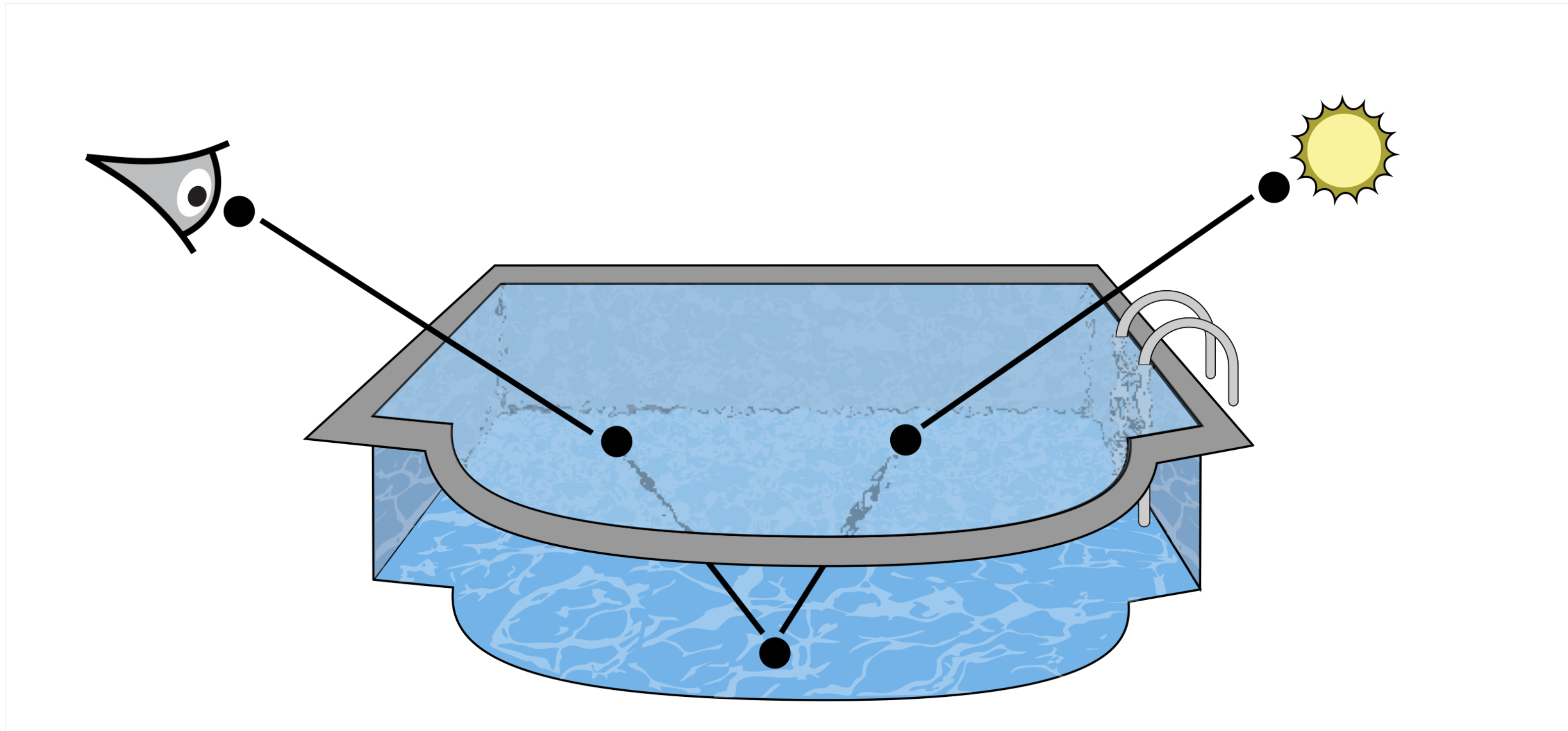
Bidirectional PT





# Still not robust enough...

---



*LSDSE* paths are difficult for any unbiased method

# Still not robust enough...

---

## Extensions

- Combination with photon mapping
  - Unified Path Sampling [Hachisuka et al. 2012]
  - Vertex Connection Merging [Georgiev et al. 2012]
- Metropolis sampling (global PDF)
- Path-space regularization [Kaplanyan et al. 2013]
- Path guiding (learn global PDF)