

# Bidirectional path tracing



15-468, 15-668, 15-868  
Physics-based Rendering  
Spring 2023, Lecture 13

# Course announcements

- Take-home quiz 8 posted, due Wednesday 3/29 at 3:00.
- Programming assignment 4 posted, due Friday 3/31 at 23:59.
  - How many of you have looked at/started/finished it?
  - Any questions?

# Overview of today's lecture

- Types of light paths.
- Light tracing.
- Bidirectional path tracing.

# Slide credits

Most of these slides were directly adapted from:

- Wojciech Jarosz (Dartmouth).

# Light Paths

# Light Paths

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Express light paths in terms of the surface interactions that have occurred

A light path is a chain of linear segments joined at event “vertices”

# Heckbert's Classification

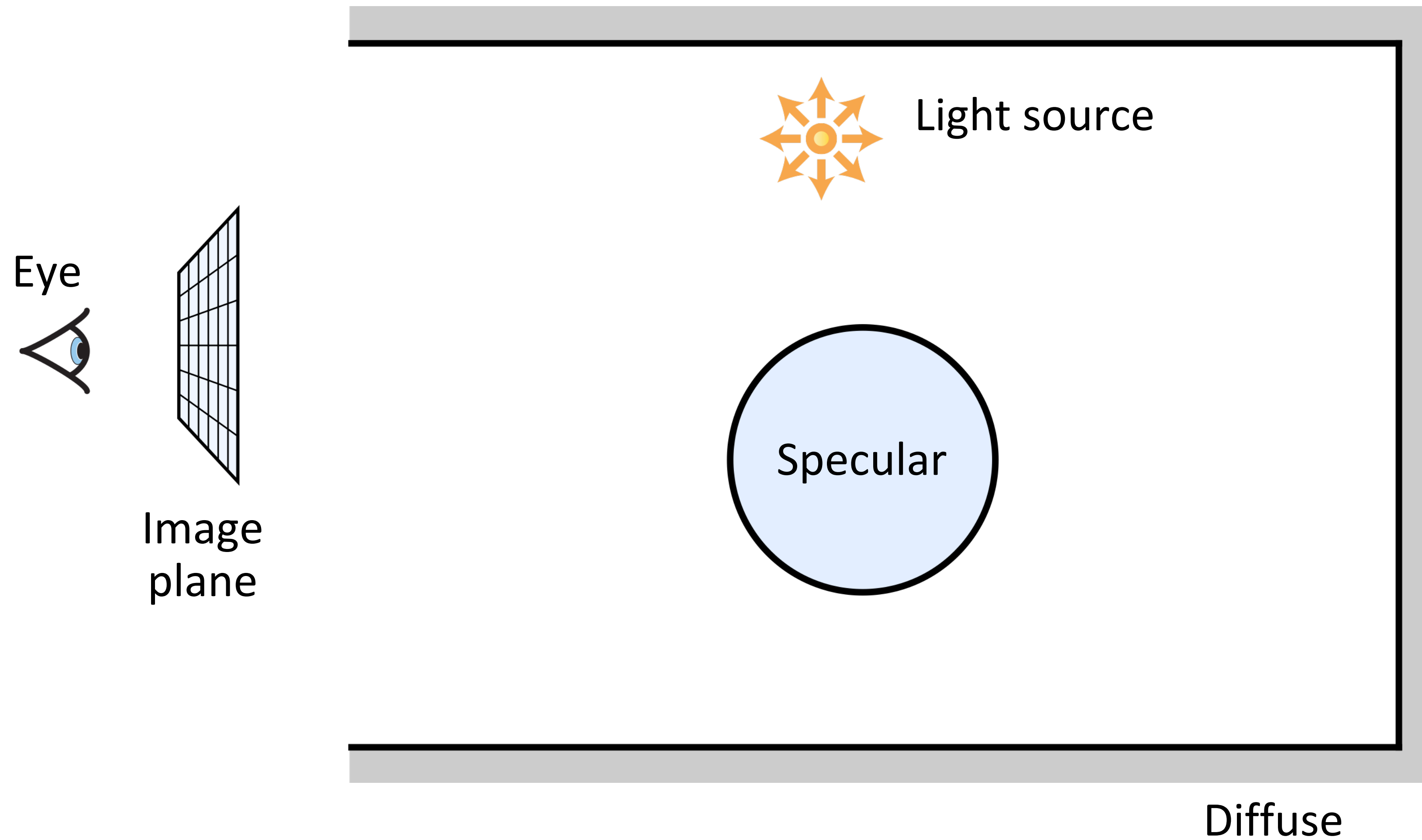
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Classification of “vertices”:

- $L$  : a light source
- $E$  : the eye
- $S$  : a specular reflection
- $D$  : a diffuse reflection

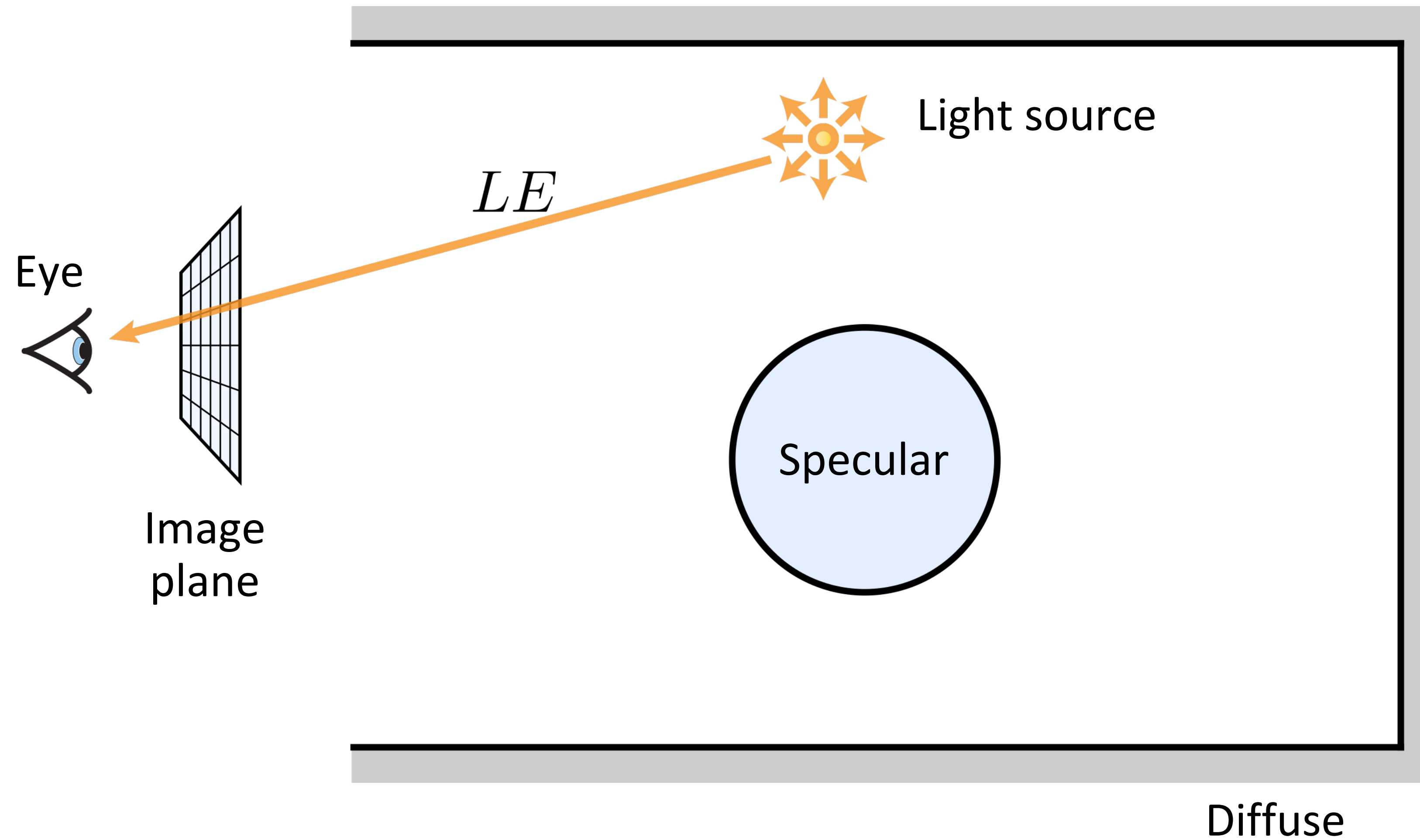
# Heckbert's Classification

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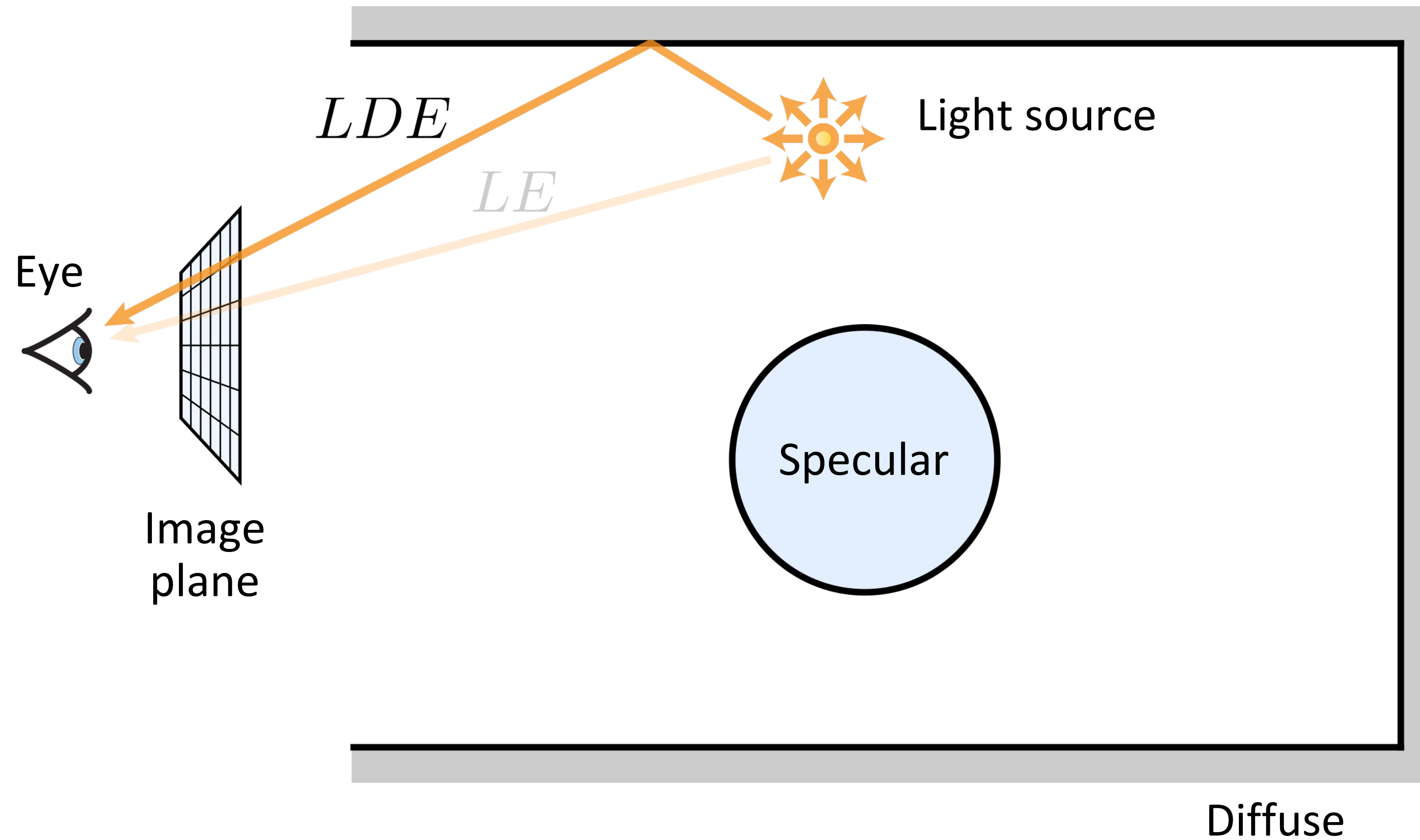




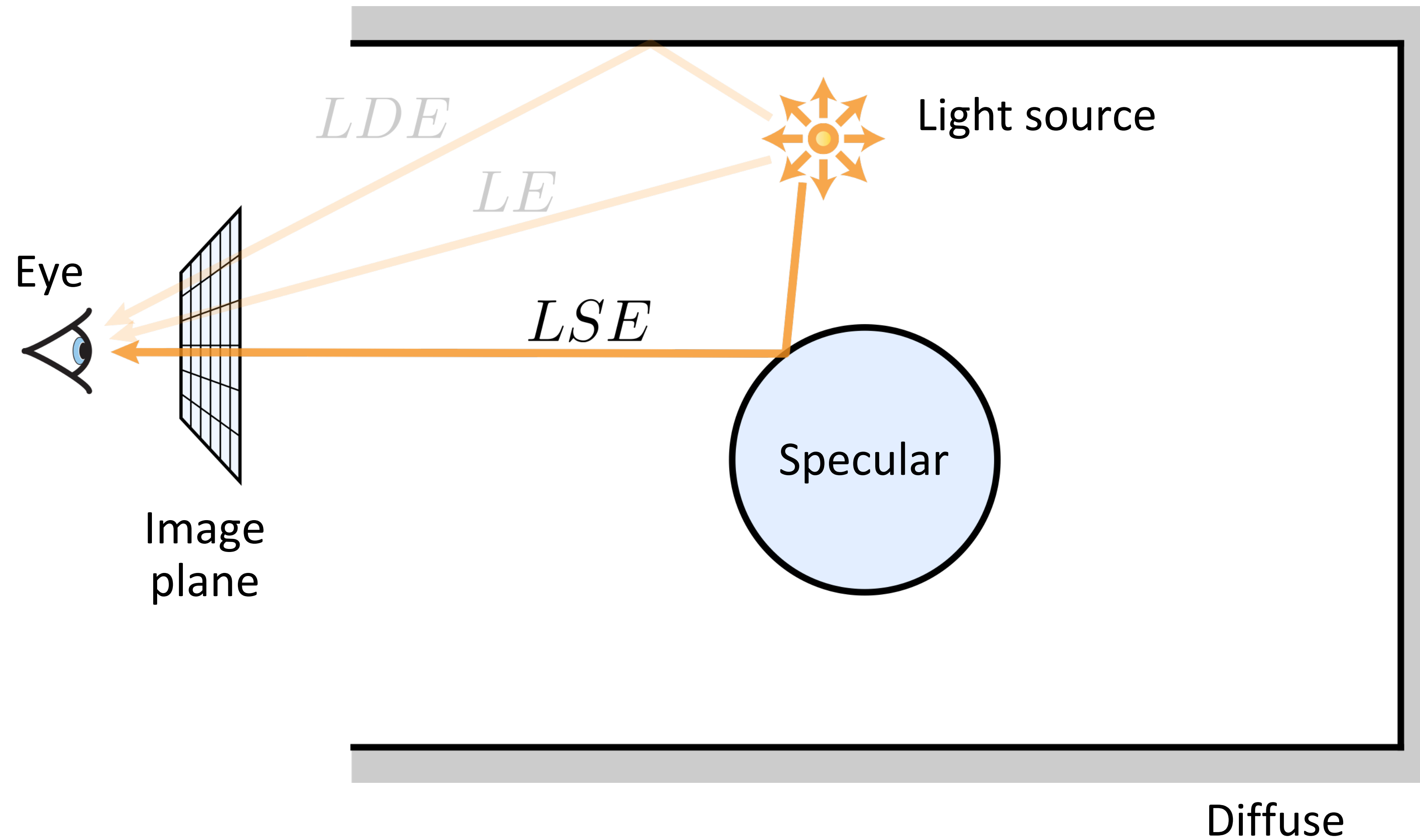
# Heckbert's Classification



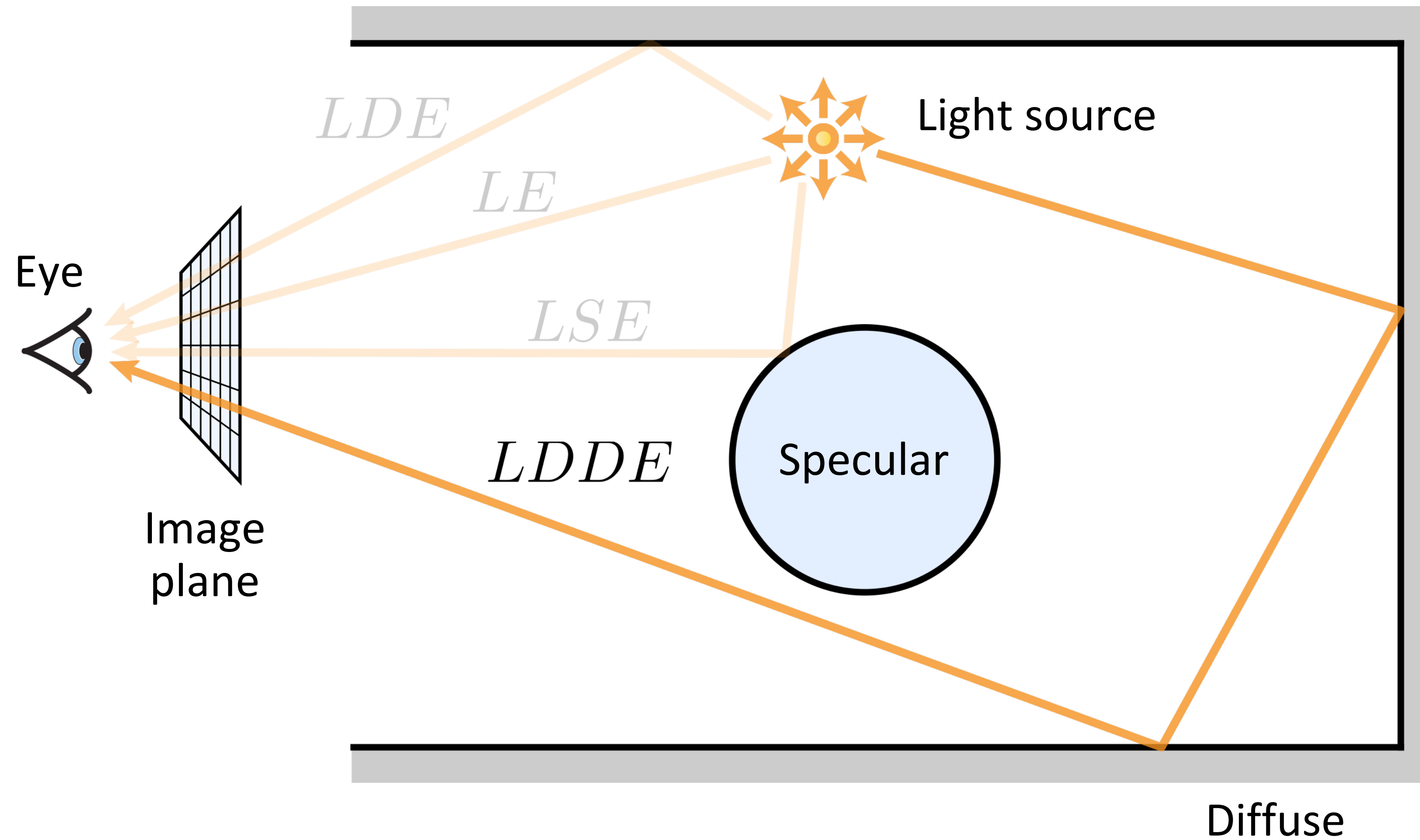
# Heckbert's Classification



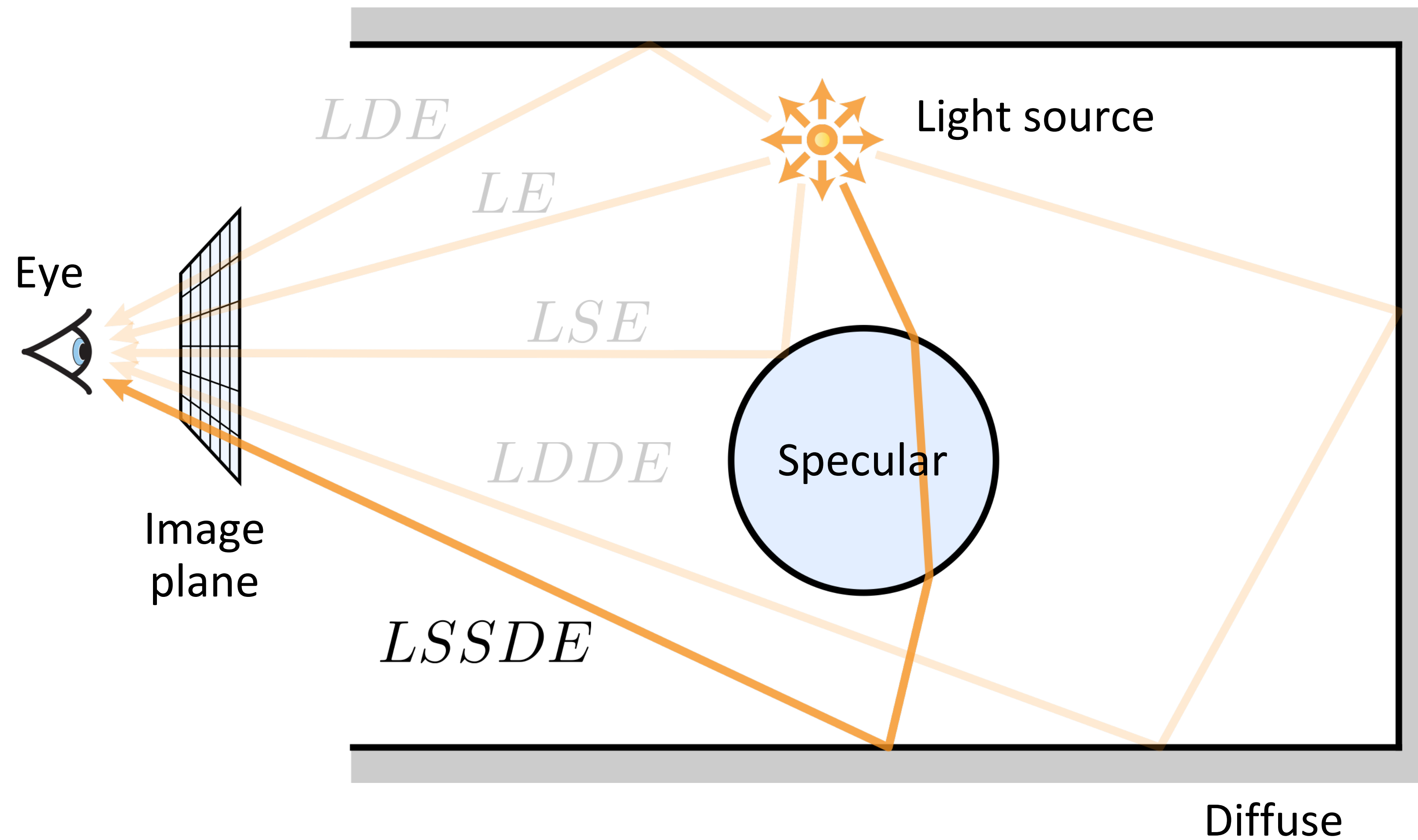
# Heckbert's Classification



# Heckbert's Classification



# Heckbert's Classification



# Heckbert's Classification

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Can express arbitrary classes of paths using a regular expression type syntax:

- $k^+$  : one or more of event  $k$
- $k^*$  : zero or more of event  $k$
- $k?$  : zero or one  $k$  events
- $(k|h)$  : a  $k$  or  $h$  event

# Heckbert's Classification

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Direct illumination:  $L(D|S)E$

Indirect illumination:  $L(D|S)(D|S)^+E$

# Heckbert's Classification

---

Direct illumination:  $L(D|S)E$

Indirect illumination:  $L(D|S)(D|S)^+E$

Full global illumination:  $L(D|S)^*E$

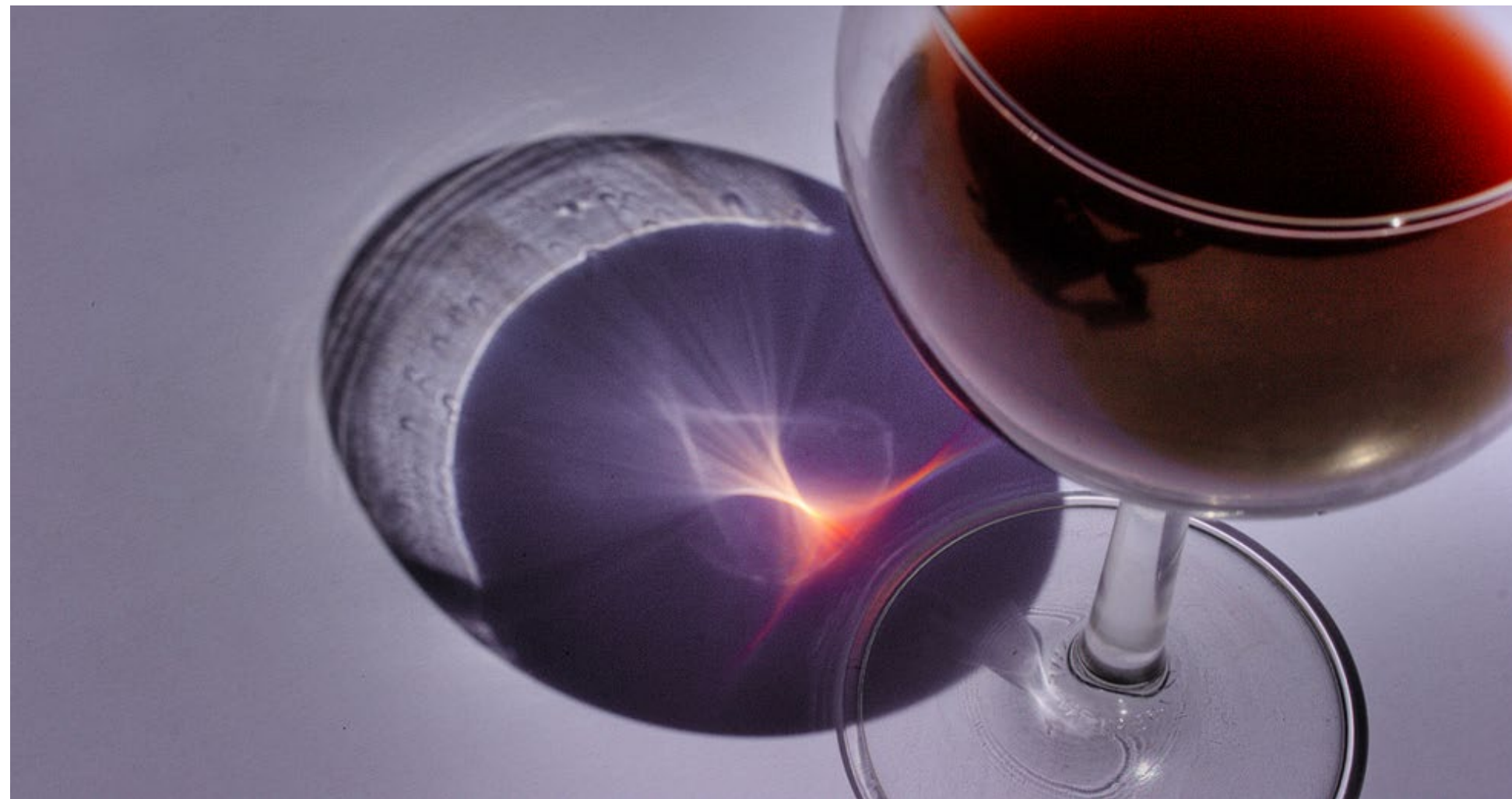


# Diffuse inter-reflections: $LDD^+E$

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# Caustics: $LS+DE$



# Subsurface Scattering

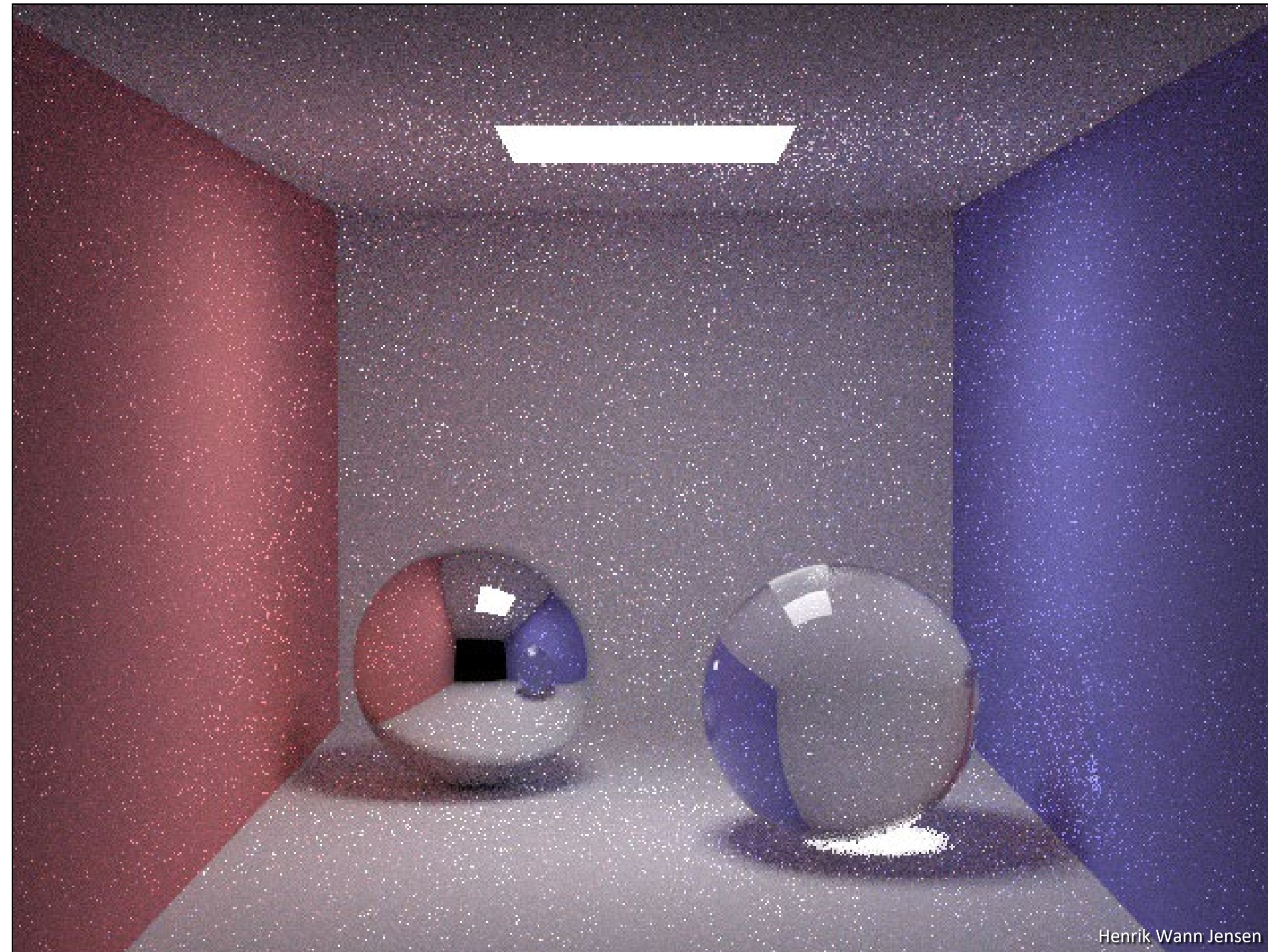
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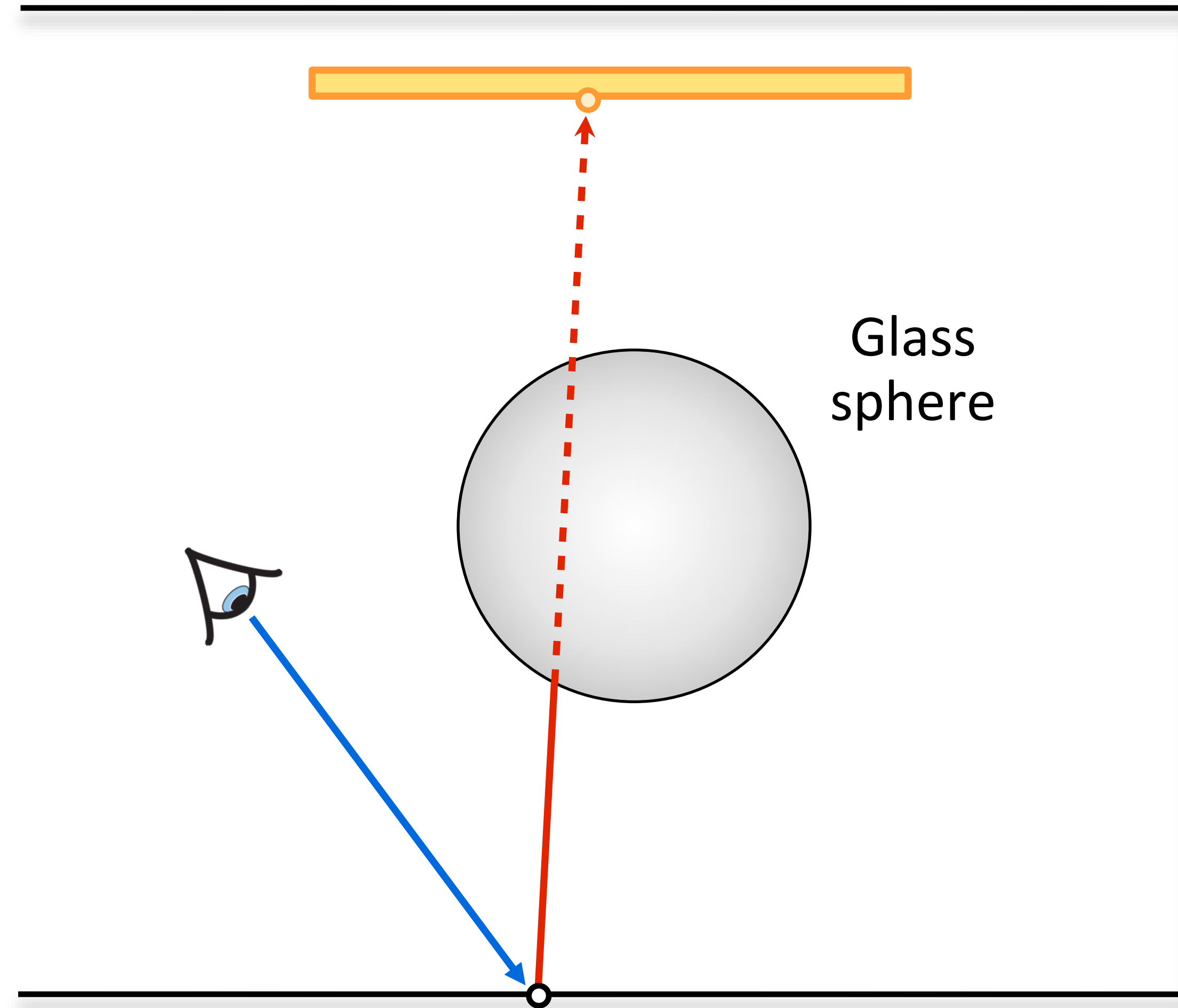
# + Glass/Mirror Material

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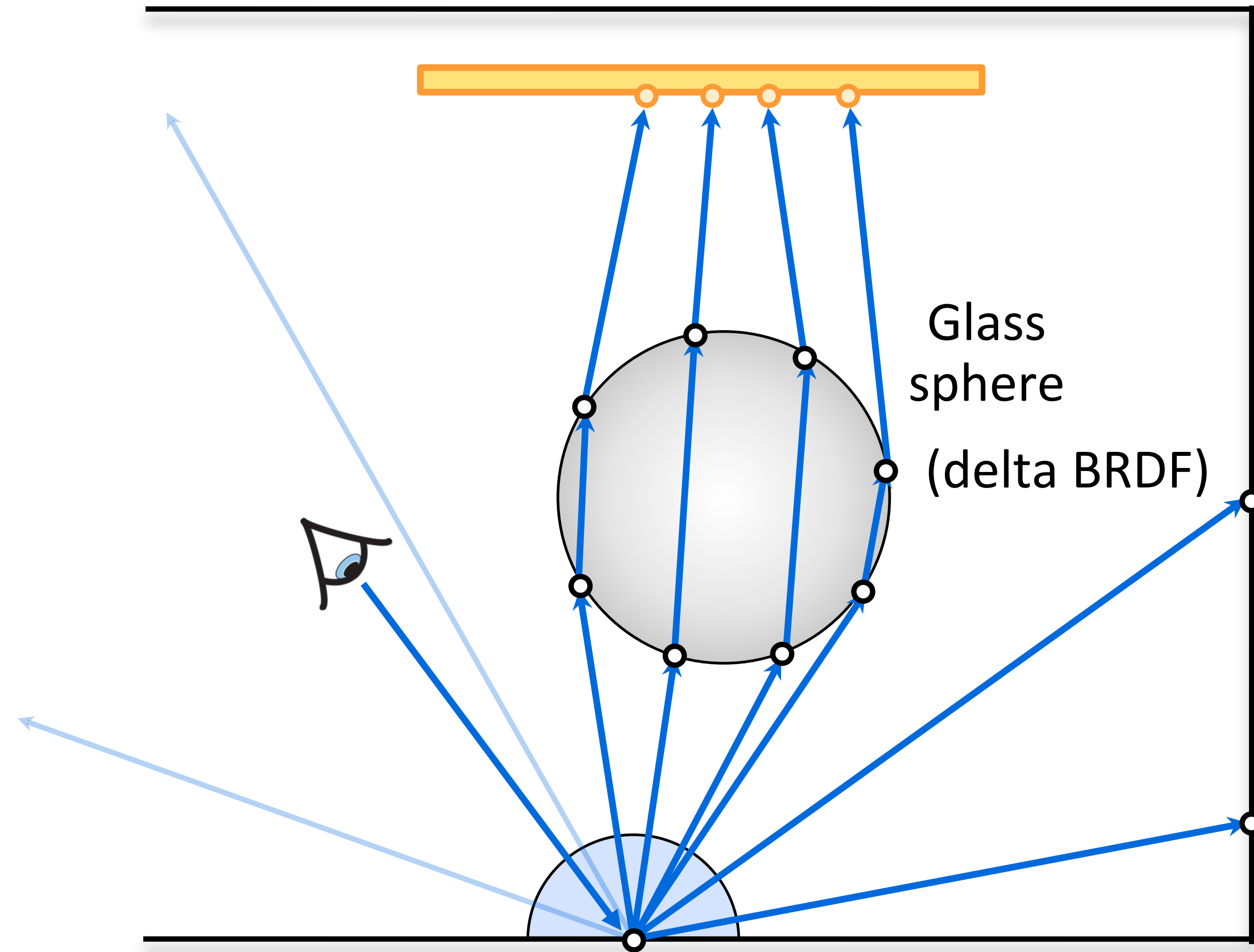


10 paths/pixel

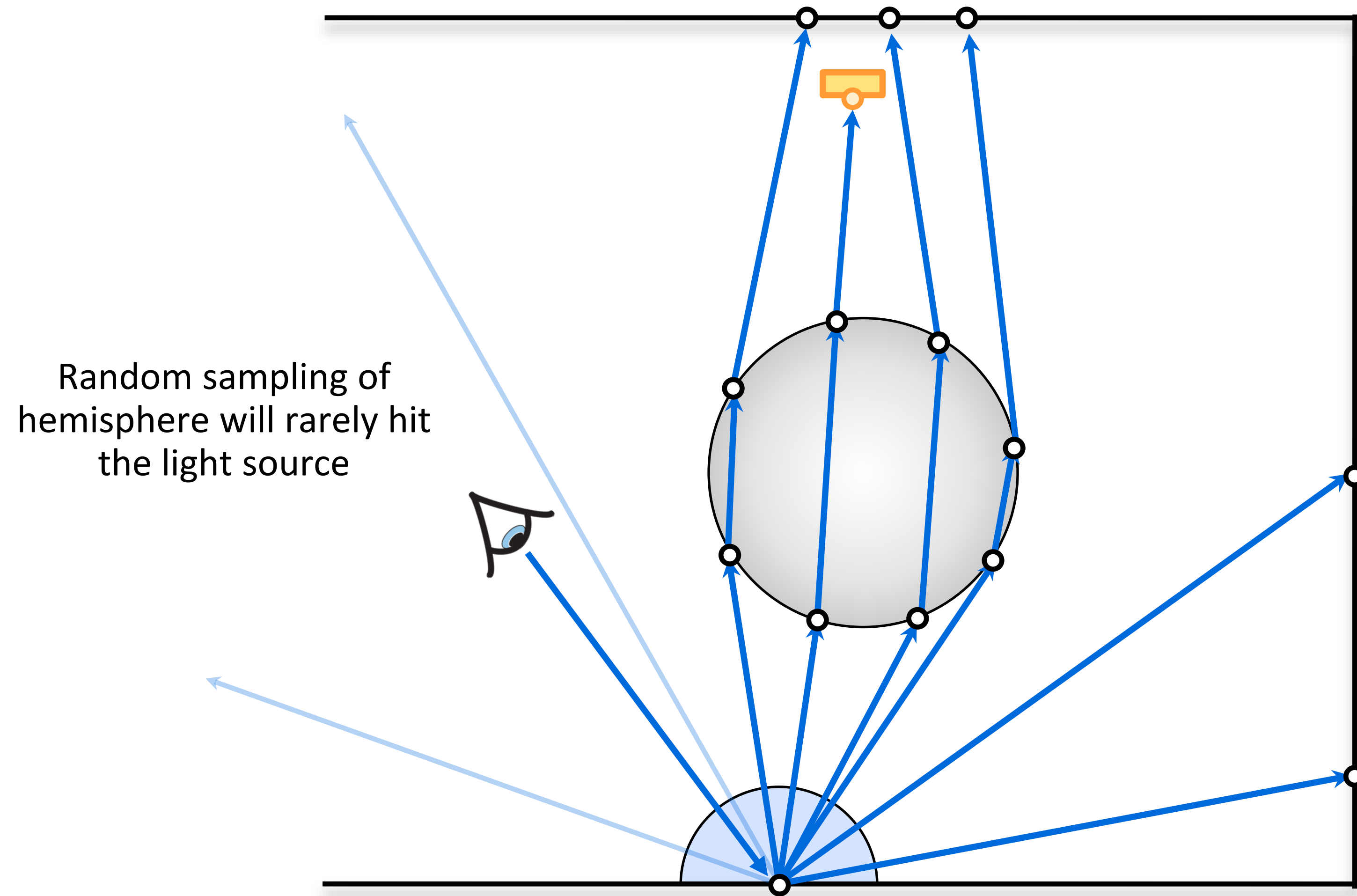
# Path Tracing Caustics



# Path Tracing Caustics

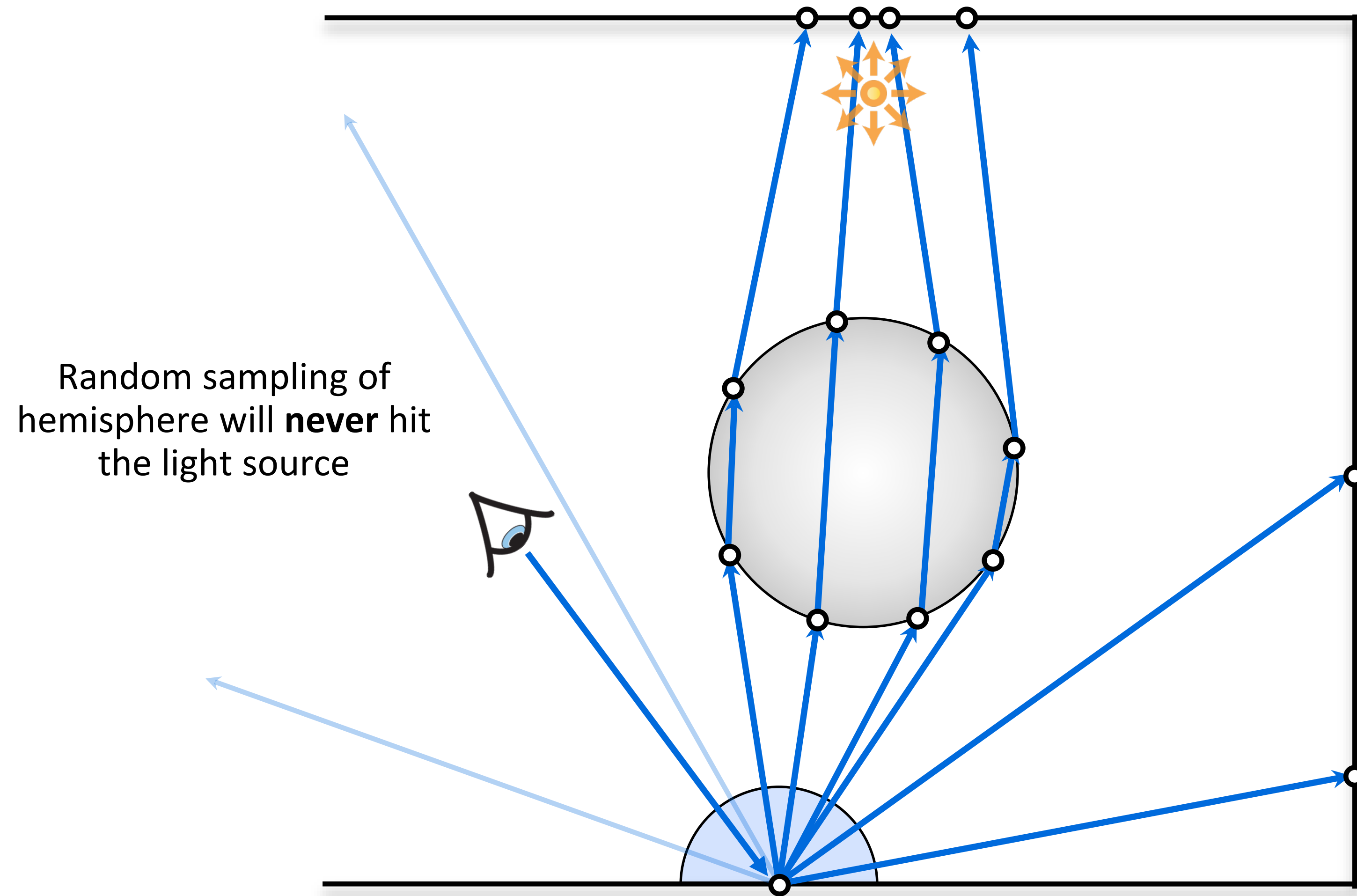


# Path Tracing Caustics





# Path Tracing Caustics



# Let's just give it more time...

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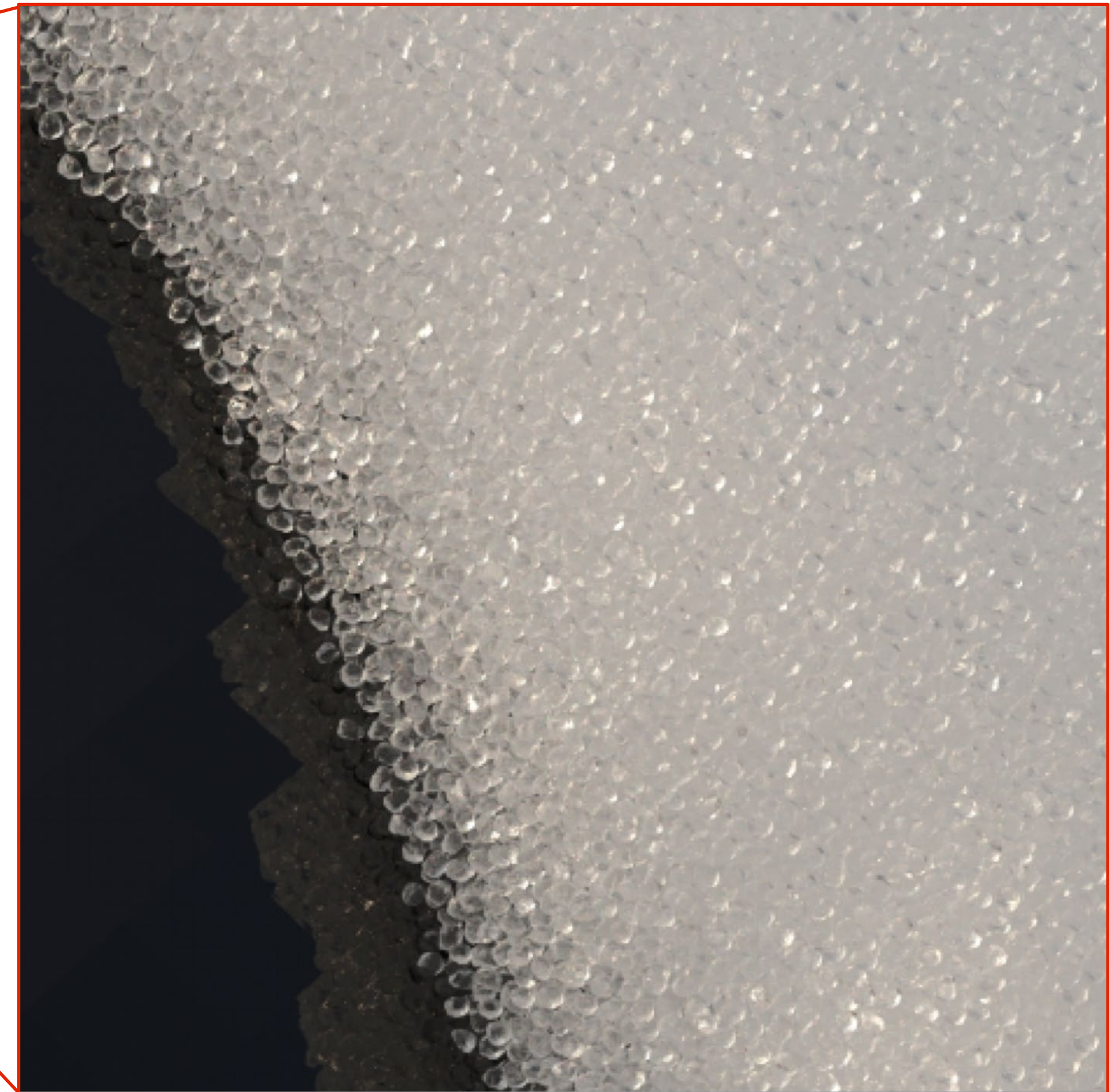
Nature  $\sim 2 \times 10^{33}$  / second

Fastest GPU ray tracer  $\sim 2 \times 10^8$  / second



Tim Webber, Gravity VFX supervisor

# Let's just give it more time...



1 image ~ 8 core years  
(parallelized on a cluster)

# Path Tracing - Summary

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- ✓ Full solution to the rendering equation
- ✓ Simple to implement
- ✗ Slow convergence
  - requires 4x more samples to half the error
- ✗ Robustness issues
  - does not handle some light paths well (or not at all), e.g. caustics ( $LS+DE$ )
- ✗ No reuse or caching of computation
- ✗ General sampling issue
  - makes only locally good decisions

# Today's agenda

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Measurement Equation

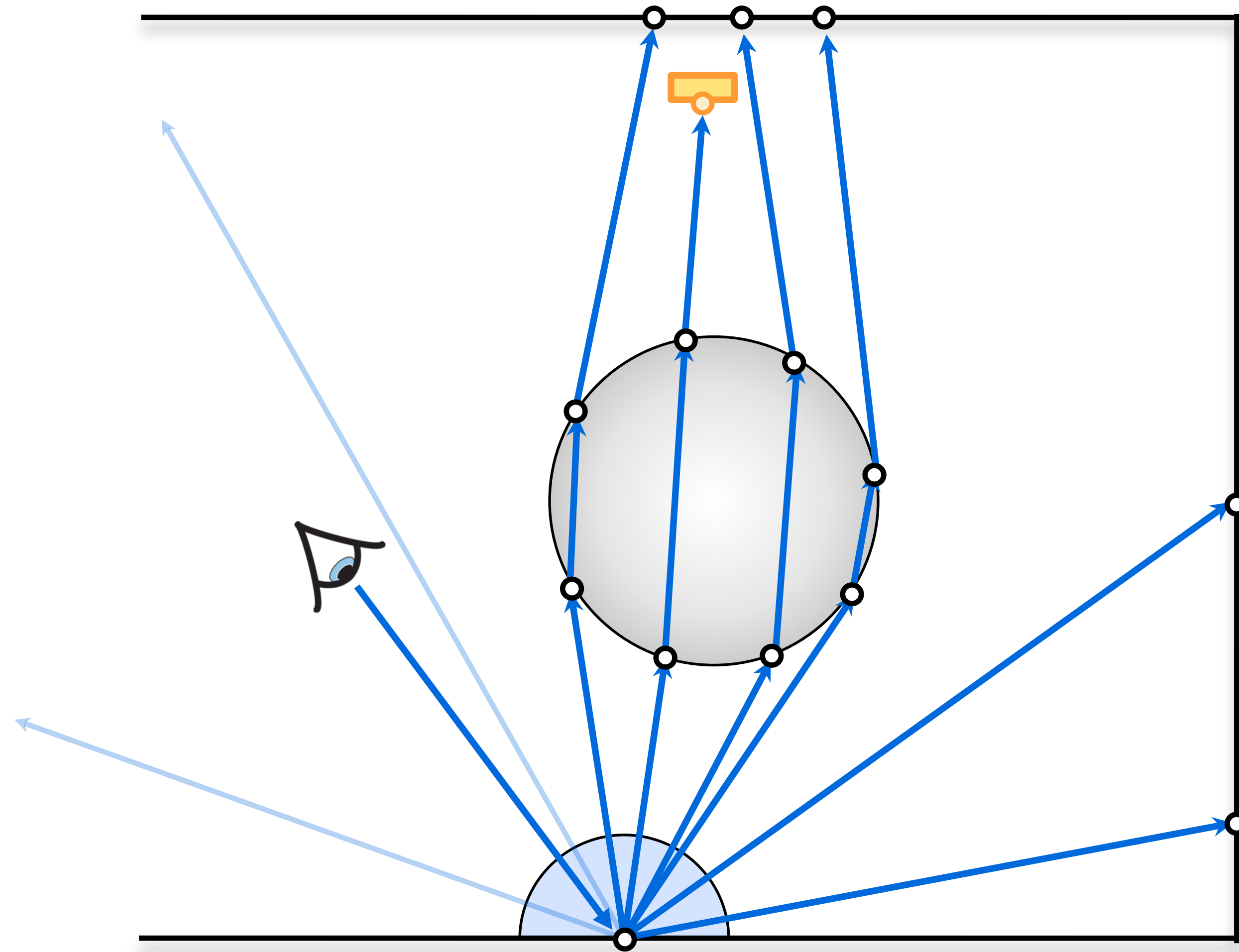
Path Integral Framework

Solving the Rendering Equation

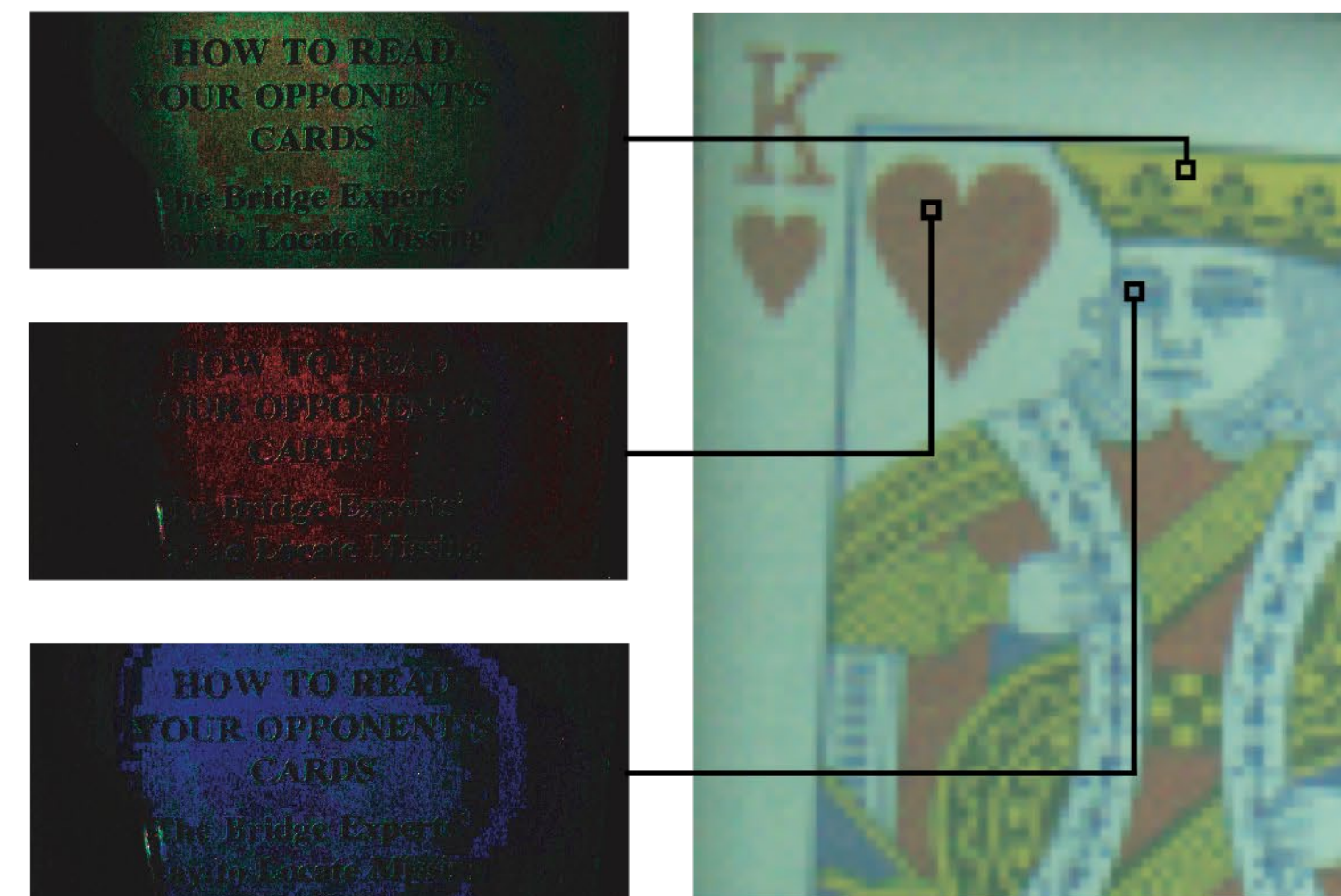
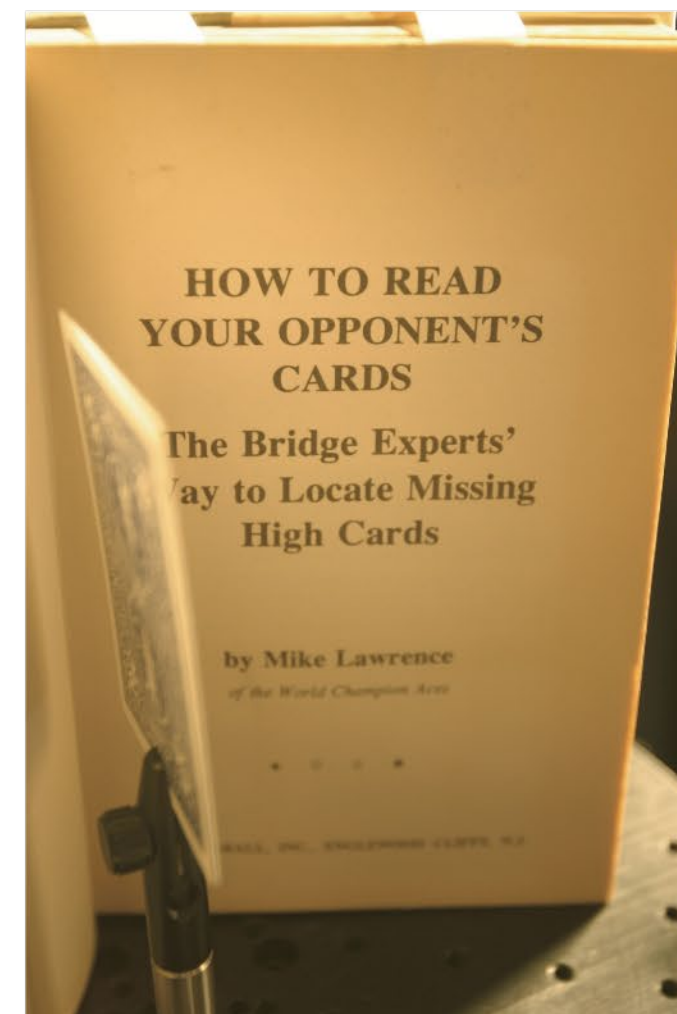
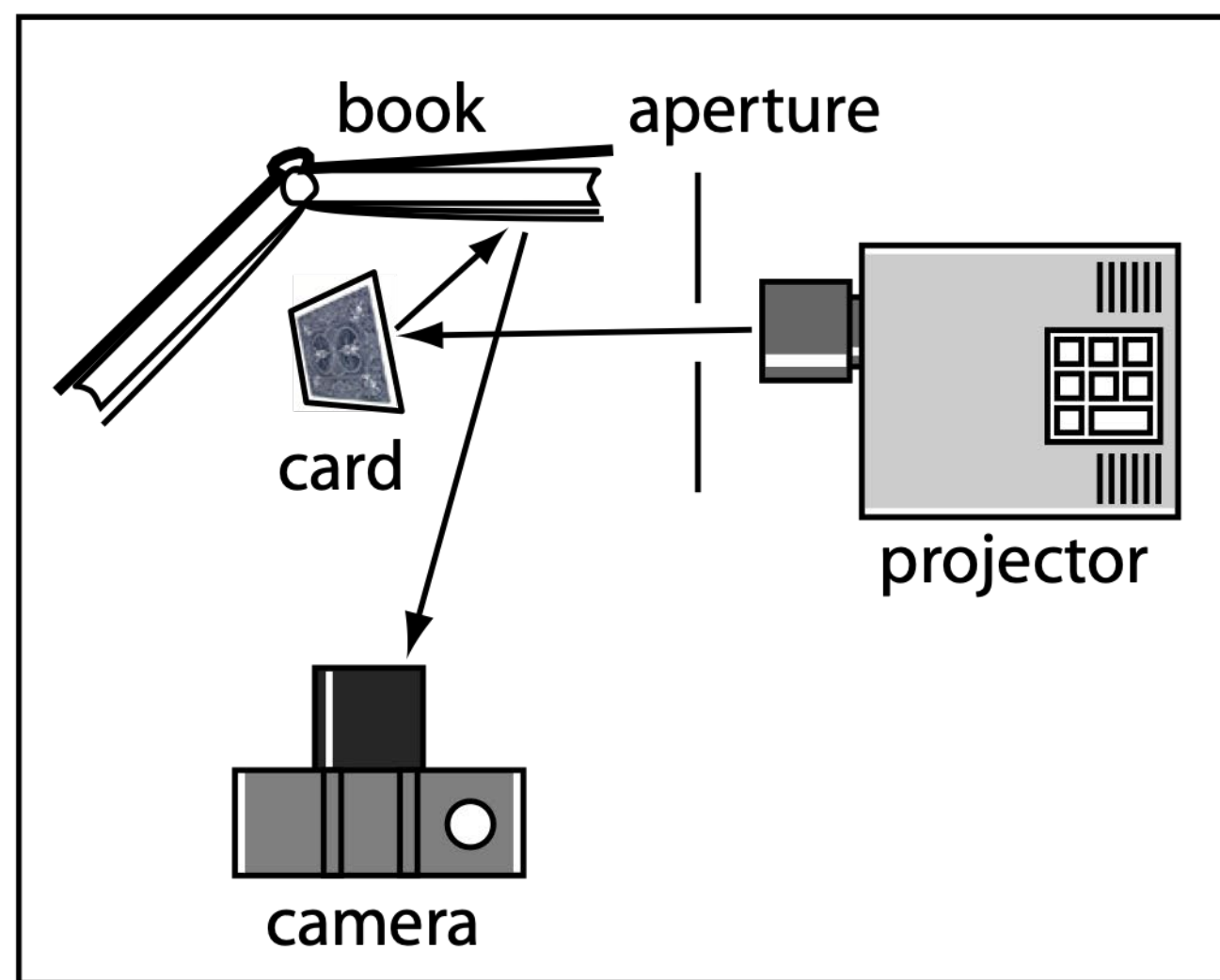
- Light tracing
- Bidirectional path tracing

# Can we simulate this better?

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# Light transport is symmetric



Dual Photography [Sen et al. 2005]

# Dual Photography

Pradeep Sen\*    Billy Chen\*    Gaurav Garg\*    Stephen R. Marschner†  
Mark Horowitz\*    Marc Levoy\*    Hendrik P.A. Lensch\*

\*Stanford University

†Cornell University

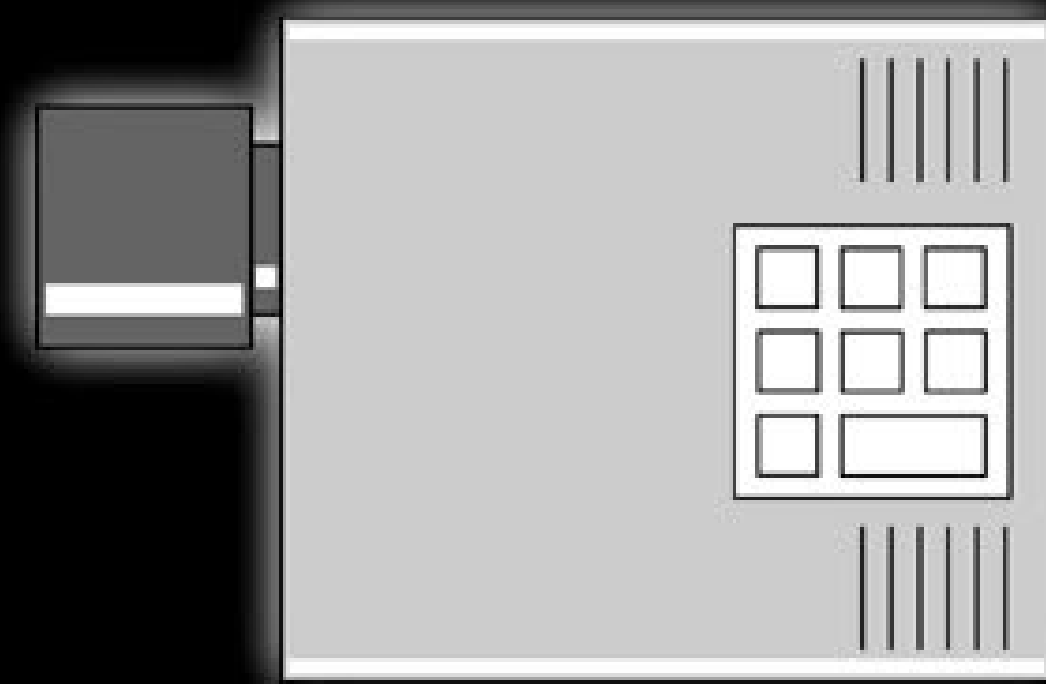


**SIGGRAPH2005**





card



projector

# Duality of Radiance and Importance

# Measurement Equation

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Rendering equation describes radiative equilibrium at point  $\mathbf{x}$ :

$$L_o(\mathbf{x}, \vec{\omega}_o) = L_e(\mathbf{x}, \vec{\omega}_o) + \int_{H^2} f_r(\mathbf{x}, \vec{\omega}_i, \vec{\omega}_o) L_i(\mathbf{x}, \vec{\omega}_i) \cos \theta_i d\vec{\omega}_i$$

We are interested in the total radiance contributing to pixel  $j$ :

$$I_j = \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta d\vec{\omega} d\mathbf{x}$$

*response* of the sensor at film location  $\mathbf{x}$   
to radiance arriving from direction  $\vec{\omega}$   
(often referred to as *emitted importance*)

# Radiometry as Measurements

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Weighted integral of 5D radiance function

$$\int_V \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L(\mathbf{x}, \vec{\omega}) d\vec{\omega} d\mathbf{x}$$

Other radiometric quantities are measurements

- expressing *irradiance* in terms of radiance:

$$\int_{H^2} L(\mathbf{x}, \vec{\omega}) \cos \theta d\vec{\omega} = E(\mathbf{x})$$

Integrate radiance over hemisphere

- expressing *flux/power* in terms of radiance:

$$\int_A \int_{H^2} L(\mathbf{x}, \vec{\omega}) \cos \theta d\vec{\omega} dA(\mathbf{x}) = \Phi(A)$$

Integrate radiance over hemisphere and area

# Radiance vs. Importance

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## Radiance

- emitted from light sources
- describes *amount of light* traveling within a differential beam

## Importance

- “emitted” from sensors
- describes the *response of the sensor* to radiance traveling within a differential beam

# Duality of Radiance & Importance

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$$I_j = \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{x}$$

# Duality of Radiance & Importance

---

$$\begin{aligned} I_j &= \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) L_o(\mathbf{y}, \mathbf{x}) \, d\mathbf{y} d\mathbf{x} \end{aligned}$$

outgoing quantities

Let's expand  $L_o$  and consider  
direct illumination only

# Duality of Radiance & Importance

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$$\begin{aligned} I_j &= \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) L_o(\mathbf{y}, \mathbf{x}) \, dy d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A \int_{A_{\text{light}}} W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) f(\mathbf{y}, \mathbf{z}, \mathbf{x}) G(\mathbf{y}, \mathbf{z}) L_e(\mathbf{z}, \mathbf{y}) \, dz dy d\mathbf{x} \end{aligned}$$

emitted quantities with  
identical measure

Let's swap the inner  
and outer integral



# Duality of Radiance & Importance

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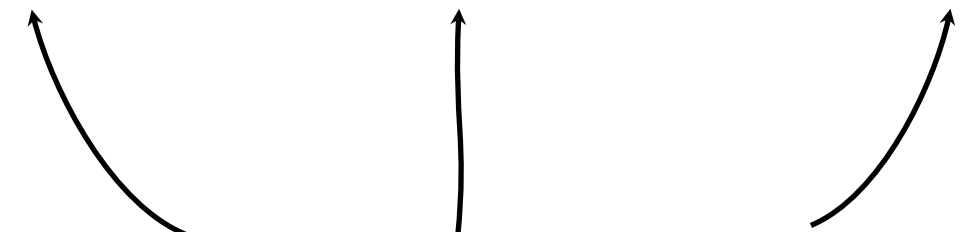
$$\begin{aligned} I_j &= \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) L_o(\mathbf{y}, \mathbf{x}) \, d\mathbf{y} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A \int_{A_{\text{light}}} W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) f(\mathbf{y}, \mathbf{z}, \mathbf{x}) G(\mathbf{y}, \mathbf{z}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{z} d\mathbf{y} d\mathbf{x} \\ &= \int_{A_{\text{light}}} \int_A \int_{A_{\text{film}}} W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) f(\mathbf{y}, \mathbf{z}, \mathbf{x}) G(\mathbf{y}, \mathbf{z}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{x} d\mathbf{y} d\mathbf{z} \end{aligned}$$

symmetric functions

# Duality of Radiance & Importance

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$$\begin{aligned} I_j &= \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) L_o(\mathbf{y}, \mathbf{x}) \, d\mathbf{y} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A \int_{A_{\text{light}}} W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) f(\mathbf{y}, \mathbf{z}, \mathbf{x}) G(\mathbf{y}, \mathbf{z}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{z} d\mathbf{y} d\mathbf{x} \\ &= \int_{A_{\text{light}}} \int_A \int_{A_{\text{film}}} W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{y}, \mathbf{x}) f(\mathbf{y}, \mathbf{x}, \mathbf{z}) G(\mathbf{z}, \mathbf{y}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{x} d\mathbf{y} d\mathbf{z} \end{aligned}$$

  
symmetric functions

# Duality of Radiance & Importance

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$$\begin{aligned} I_j &= \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) L_o(\mathbf{y}, \mathbf{x}) \, d\mathbf{y} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A \int_{A_{\text{light}}} W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) f(\mathbf{y}, \mathbf{z}, \mathbf{x}) G(\mathbf{y}, \mathbf{z}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{z} d\mathbf{y} d\mathbf{x} \\ &= \int_{A_{\text{light}}} \int_A \int_{A_{\text{film}}} W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{y}, \mathbf{x}) f(\mathbf{y}, \mathbf{x}, \mathbf{z}) G(\mathbf{z}, \mathbf{y}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{x} d\mathbf{y} d\mathbf{z} \\ &= \int_{A_{\text{light}}} \int_A W_o(\mathbf{y}, \mathbf{z}) G(\mathbf{z}, \mathbf{y}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{y} d\mathbf{z} \end{aligned}$$

# Duality of Radiance & Importance

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$$\begin{aligned} I_j &= \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) L_o(\mathbf{y}, \mathbf{x}) \, d\mathbf{y} d\mathbf{x} \\ &= \int_{A_{\text{film}}} \int_A \int_{A_{\text{light}}} W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{x}, \mathbf{y}) f(\mathbf{y}, \mathbf{z}, \mathbf{x}) G(\mathbf{y}, \mathbf{z}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{z} d\mathbf{y} d\mathbf{x} \\ &= \int_{A_{\text{light}}} \int_A \int_{A_{\text{film}}} W_e(\mathbf{x}, \mathbf{y}) G(\mathbf{y}, \mathbf{x}) f(\mathbf{y}, \mathbf{x}, \mathbf{z}) G(\mathbf{z}, \mathbf{y}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{x} d\mathbf{y} d\mathbf{z} \\ &= \int_{A_{\text{light}}} \int_A W_o(\mathbf{y}, \mathbf{z}) G(\mathbf{z}, \mathbf{y}) L_e(\mathbf{z}, \mathbf{y}) \, d\mathbf{y} d\mathbf{z} \\ &= \int_{A_{\text{light}}} \int_{H^2} W_i(\mathbf{z}, \vec{\omega}) L_e(\mathbf{z}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{z} \end{aligned}$$

# Duality of Radiance & Importance

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$$\begin{aligned} I_j &= \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{x} \\ &= \int_{A_{\text{light}}} \int_{H^2} W_i(\mathbf{z}, \vec{\omega}) L_e(\mathbf{z}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{z} \end{aligned}$$

emitted *importance*

incident *radiance*

emitted *radiance*

incident *importance*

# Duality of Radiance & Importance

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Path tracing

start from *film*, search for *radiance* at light

$$I_j = \int_{A_{\text{film}}} \int_{H^2} W_e(\mathbf{x}, \vec{\omega}) L_i(\mathbf{x}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{x}$$
$$= \int_{A_{\text{light}}} \int_{H^2} W_i(\mathbf{z}, \vec{\omega}) L_e(\mathbf{z}, \vec{\omega}) \cos \theta \, d\vec{\omega} d\mathbf{z}$$

Light tracing

start from *light*, search for *importance* at sensor

# Light Tracing

# Light Tracing

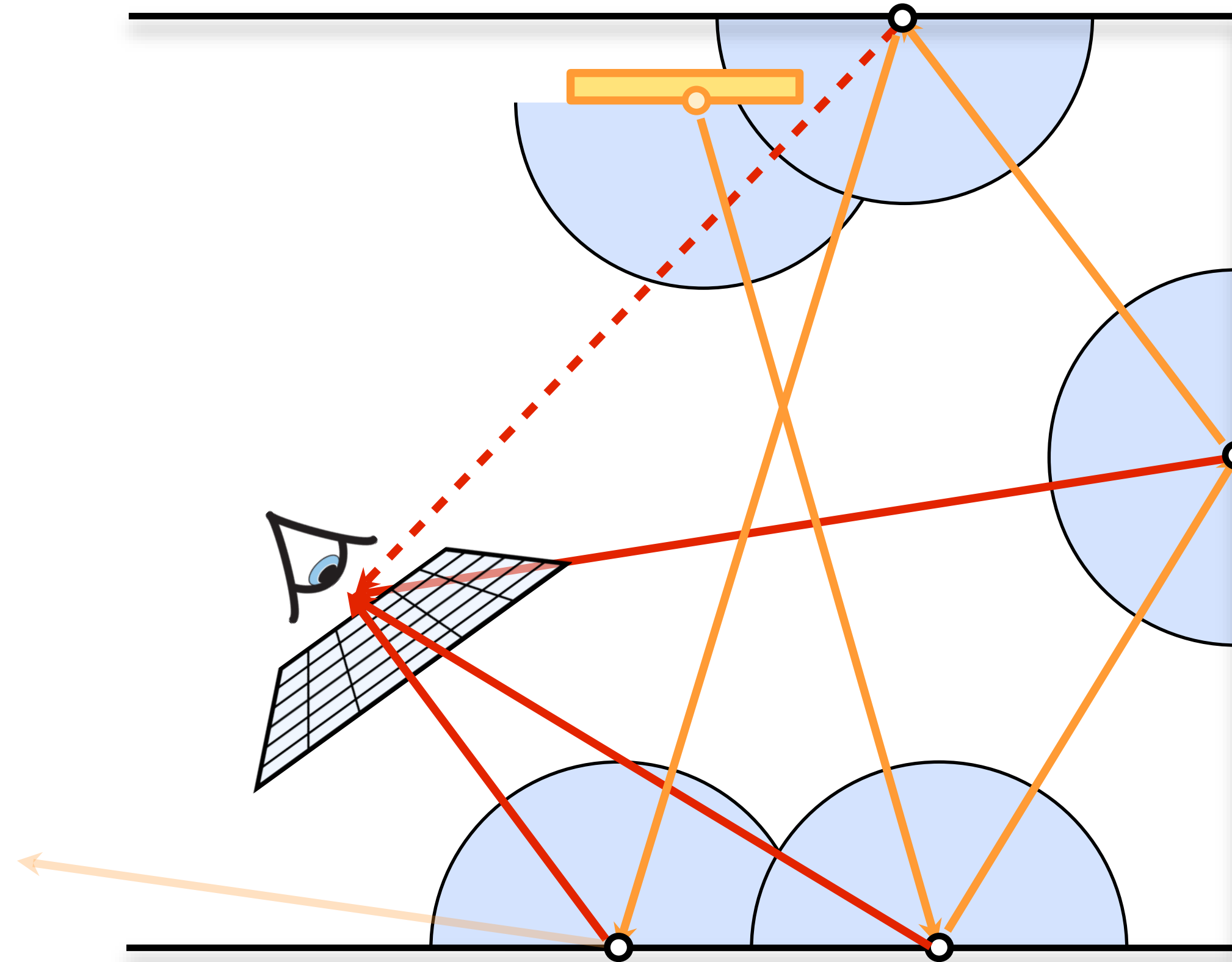
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Shoot multiple paths from light sources hoping to randomly hit the sensor

- Optionally: at each path vertex, connect to the image using next-event estimation (a.k.a. shadow rays in PT)

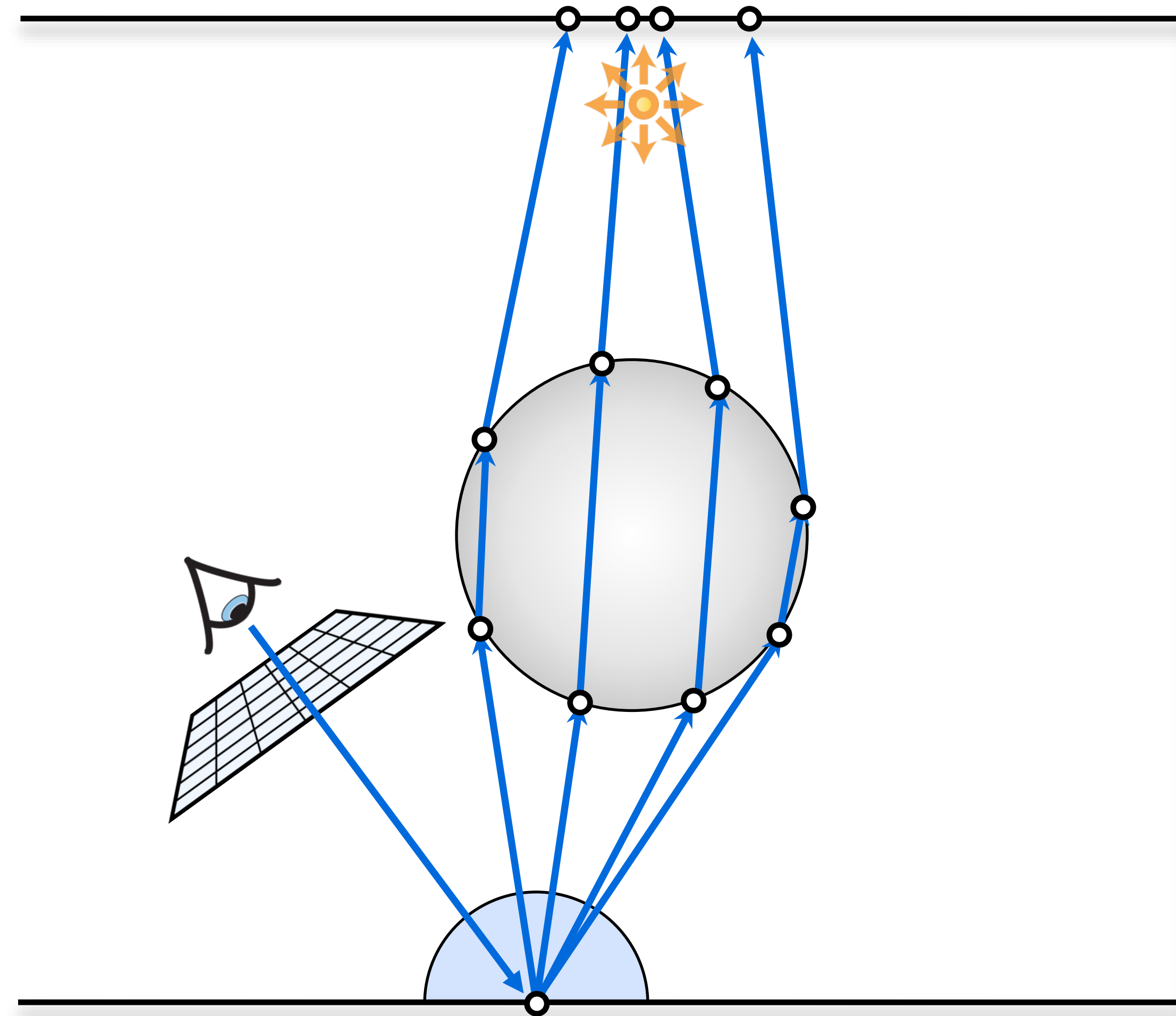


# Light Tracing with NEE



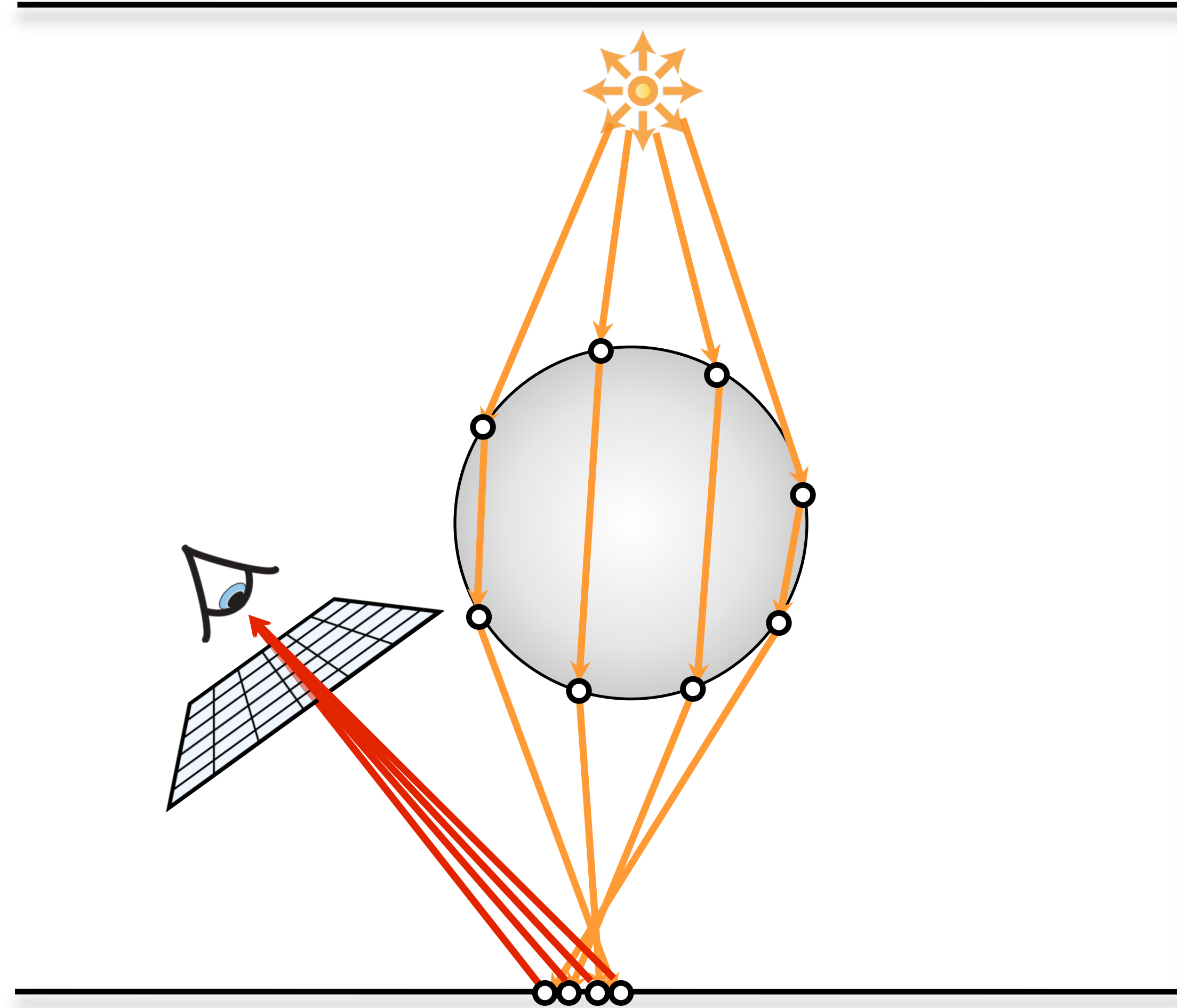
Splat to the image at each vertex

# Path Tracing Caustics



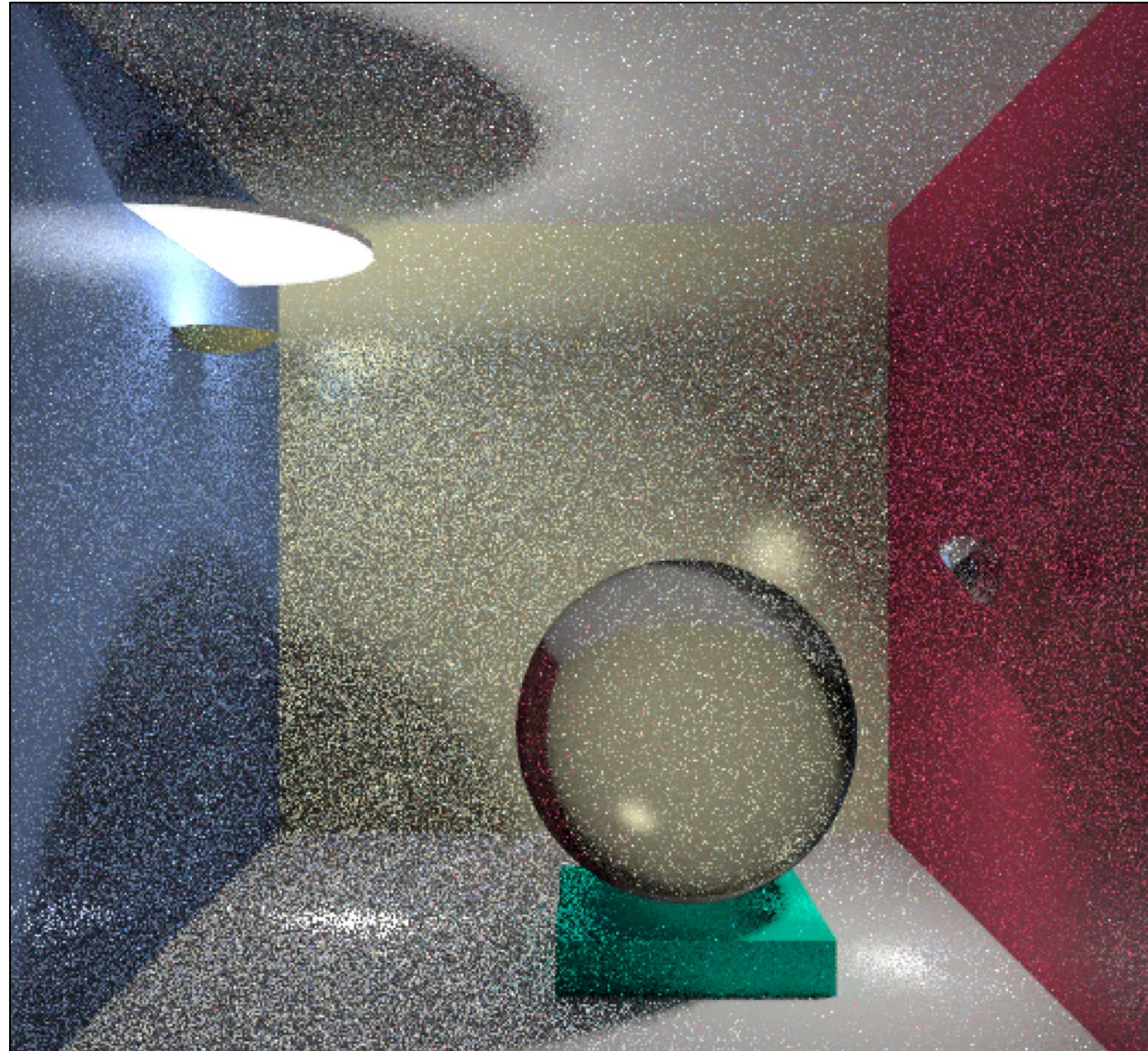
# Light Tracing Caustics

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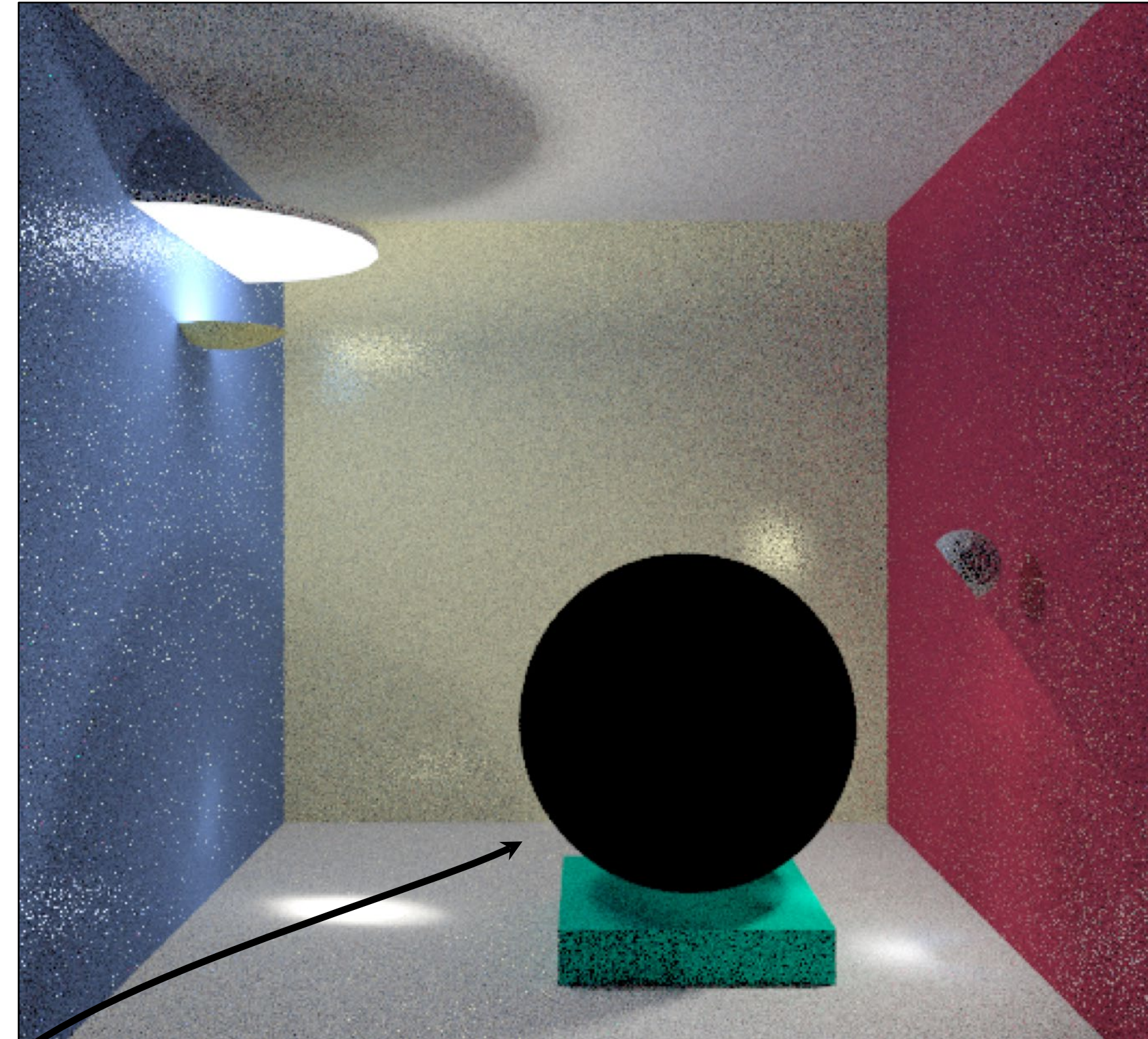


# Path vs. Light Tracing

Path tracing



Light tracing



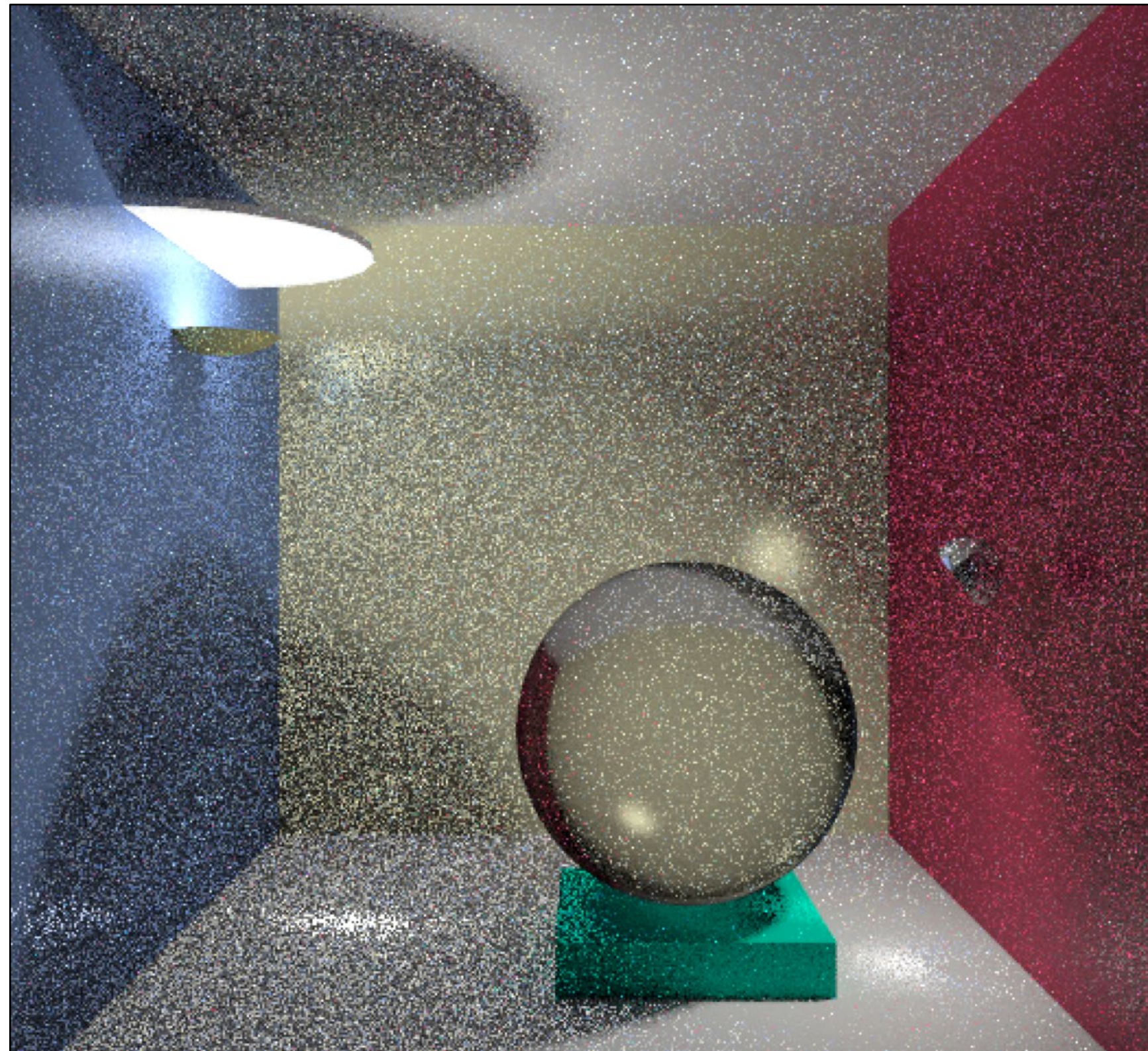
Images courtesy of F. Suykens

Why is this glass sphere black?

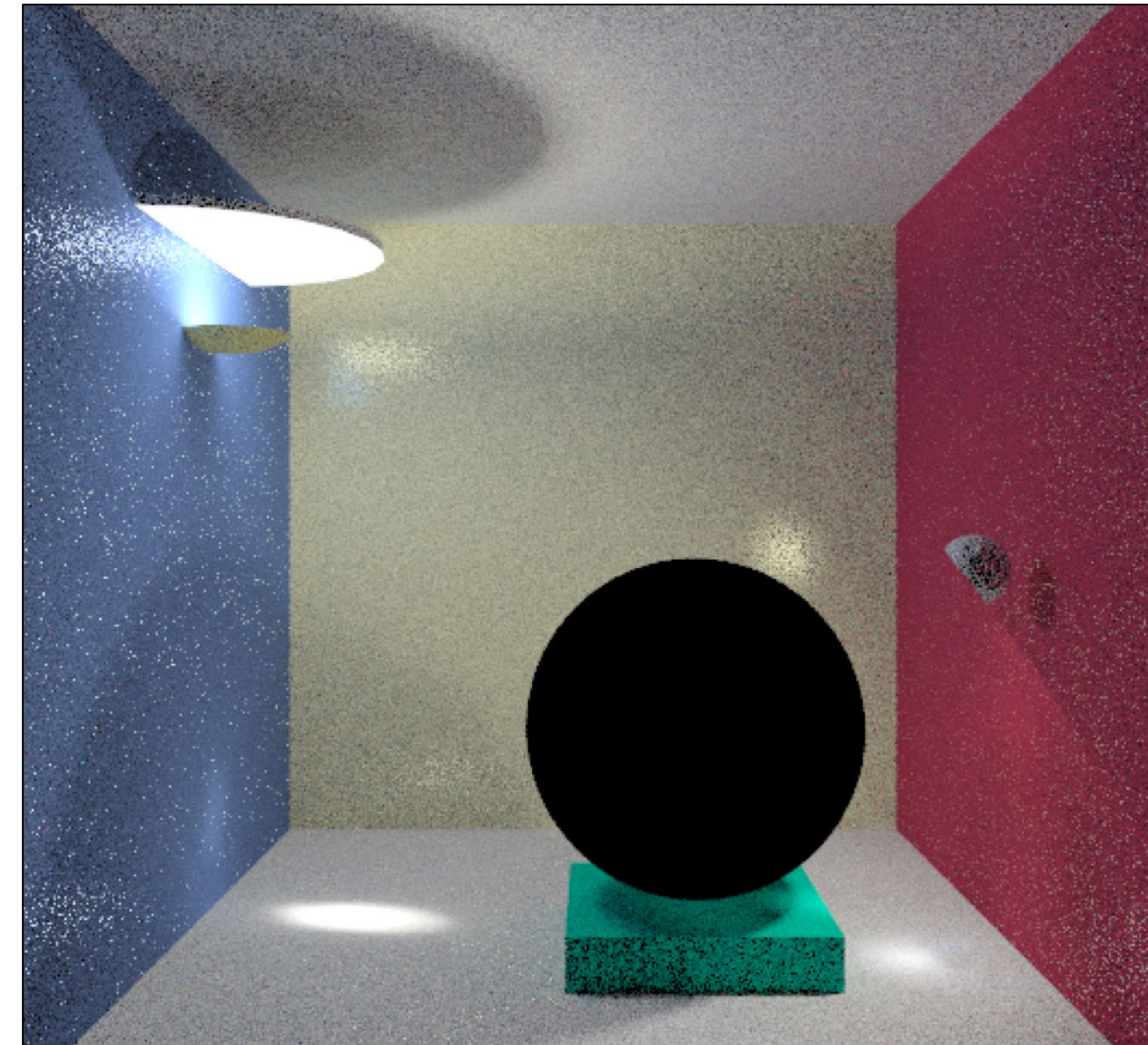
# Path vs. Light Tracing

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Path tracing



Light tracing



Images courtesy of F. Suykens

Can we combine them?

# Path Integral Framework

# Measurement Equation

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$$\begin{aligned} I_j &= \int_A \int_A W_e(\mathbf{x}_0, \mathbf{x}_1) G(\mathbf{x}_0, \mathbf{x}_1) L_o(\mathbf{x}_1, \mathbf{x}_0) d\mathbf{x}_1 d\mathbf{x}_0 \\ &= \int_A \int_A W_e(\mathbf{x}_0, \mathbf{x}_1) G(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_1, \mathbf{x}_0) + \int_A f(\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_0) G(\mathbf{x}_1, \mathbf{x}_2) L_o(\mathbf{x}_2, \mathbf{x}_1) d\mathbf{x}_2 d\mathbf{x}_1 d\mathbf{x}_0 \\ &= \int_A \int_A W_e(\mathbf{x}_0, \mathbf{x}_1) G(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_1, \mathbf{x}_0) + \int_A f(\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_0) G(\mathbf{x}_1, \mathbf{x}_2) L_e(\mathbf{x}_2, \mathbf{x}_1) + \int_A f(\mathbf{x}_2, \mathbf{x}_3, \mathbf{x}_1) G(\mathbf{x}_2, \mathbf{x}_3) L_e(\mathbf{x}_3, \mathbf{x}_2) + \int_A \cdots d\mathbf{x}_4 d\mathbf{x}_3 d\mathbf{x}_2 d\mathbf{x}_1 d\mathbf{x}_0 \end{aligned}$$

Hard to concisely express arbitrary light transport with all the nested integrals

Let's find a better way

# Path Integral Form of Measurement Eq.

$$\begin{aligned}
 I_j &= \int_A \int_A W_e(\mathbf{x}_0, \mathbf{x}_1) G(\mathbf{x}_0, \mathbf{x}_1) L_o(\mathbf{x}_1, \mathbf{x}_0) d\mathbf{x}_1 d\mathbf{x}_0 \\
 &= \iint_A W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_1, \mathbf{x}_0) G(\mathbf{x}_0, \mathbf{x}_1) d\mathbf{x}_1 d\mathbf{x}_0 \\
 &+ \iiint_A W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_2, \mathbf{x}_1) G(\mathbf{x}_0, \mathbf{x}_1) f(\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_0) G(\mathbf{x}_1, \mathbf{x}_2) d\mathbf{x}_2 d\mathbf{x}_1 d\mathbf{x}_0 + \dots \\
 &+ \int \dots \int_A W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_k, \mathbf{x}_{k-1}) G(\mathbf{x}_0, \mathbf{x}_1) \prod_{j=1}^{k-1} f(\mathbf{x}_j, \mathbf{x}_{j+1}, \mathbf{x}_{j-1}) G(\mathbf{x}_j, \mathbf{x}_{j+1}) d\mathbf{x}_k \dots d\mathbf{x}_0 + \dots
 \end{aligned}$$

introduce:  $\mathcal{P}_k = \{\bar{\mathbf{x}} = \mathbf{x}_0 \cdots \mathbf{x}_k; \mathbf{x}_0 \cdots \mathbf{x}_k \in A\}$

space of all paths with  $k$  segments



# Path Integral Form of Measurement Eq.

$$I_j = \int_A \int_A W_e(\mathbf{x}_0, \mathbf{x}_1) G(\mathbf{x}_0, \mathbf{x}_1) L_o(\mathbf{x}_1, \mathbf{x}_0) d\mathbf{x}_1 d\mathbf{x}_0$$

$$= \int_{\mathcal{P}_1} W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_1, \mathbf{x}_0) G(\mathbf{x}_0, \mathbf{x}_1) d\bar{\mathbf{x}}_1$$

$$+ \int_{\mathcal{P}_2} W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_2, \mathbf{x}_1) G(\mathbf{x}_0, \mathbf{x}_1) f(\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_0) G(\mathbf{x}_1, \mathbf{x}_2) d\bar{\mathbf{x}}_2 + \dots$$

$$+ \int_{\mathcal{P}_k} W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_k, \mathbf{x}_{k-1}) G(\mathbf{x}_0, \mathbf{x}_1) \prod_{j=1}^{k-1} f(\mathbf{x}_j, \mathbf{x}_{j+1}, \mathbf{x}_{j-1}) G(\mathbf{x}_j, \mathbf{x}_{j+1}) d\bar{\mathbf{x}}_k + \dots$$

introduce:  $T(\bar{\mathbf{x}}_k) = G(\mathbf{x}_0, \mathbf{x}_1) \prod_{j=1}^{k-1} f(\mathbf{x}_j, \mathbf{x}_{j+1}, \mathbf{x}_{j-1}) G(\mathbf{x}_j, \mathbf{x}_{j+1})$

throughput of path  $\bar{\mathbf{x}}_k$

# Path Integral Form of Measurement Eq.

$$I_j = \int_A \int_A W_e(\mathbf{x}_0, \mathbf{x}_1) G(\mathbf{x}_0, \mathbf{x}_1) L_o(\mathbf{x}_1, \mathbf{x}_0) d\mathbf{x}_1 d\mathbf{x}_0$$

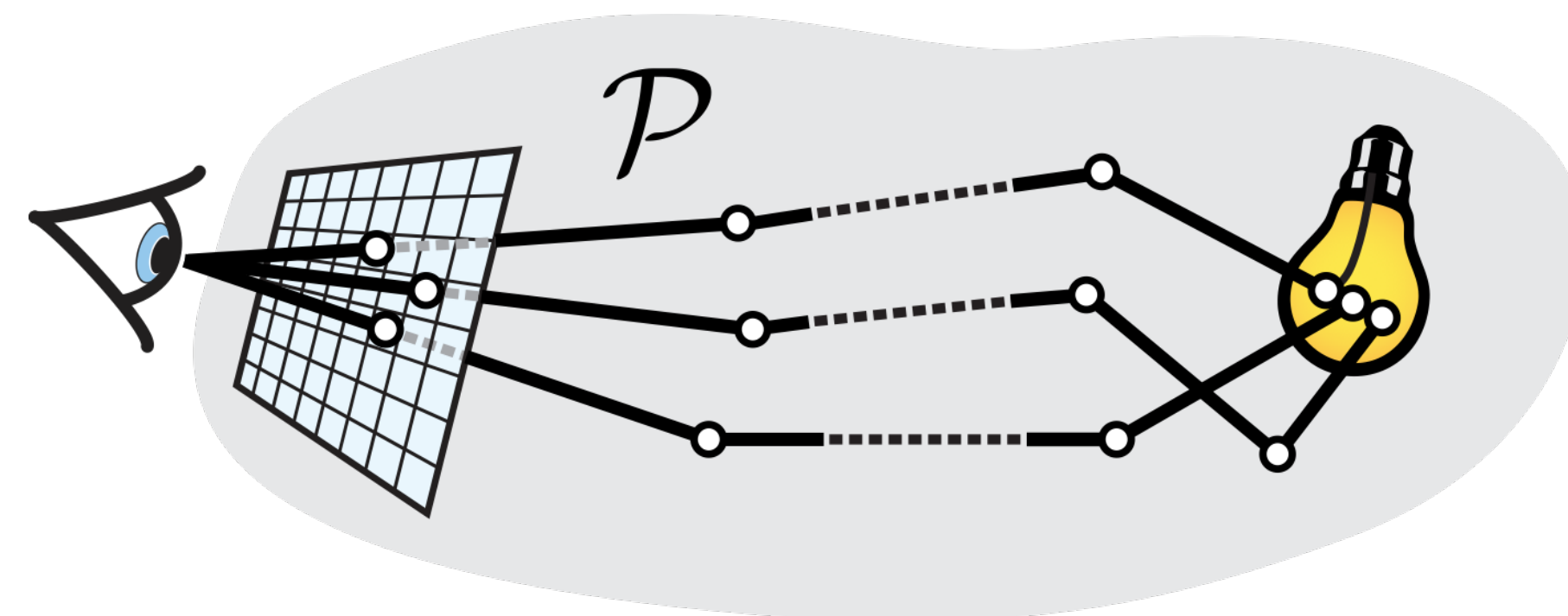
$$= \int_{\mathcal{P}_1} W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_1, \mathbf{x}_0) T(\bar{\mathbf{x}}_1) d\bar{\mathbf{x}}_1$$

$$+ \int_{\mathcal{P}_2} W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_2, \mathbf{x}_1) T(\bar{\mathbf{x}}_2) d\bar{\mathbf{x}}_2 + \dots$$

$$+ \int_{\mathcal{P}_k} W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_k, \mathbf{x}_{k-1}) T(\bar{\mathbf{x}}_k) d\bar{\mathbf{x}}_k + \dots$$

introduce:  $\mathcal{P} = \bigcup_{k=1}^{\infty} \mathcal{P}_k$

the *path space*, i.e. the space of all paths of all lengths



# Path Integral Form of Measurement Eq.

---

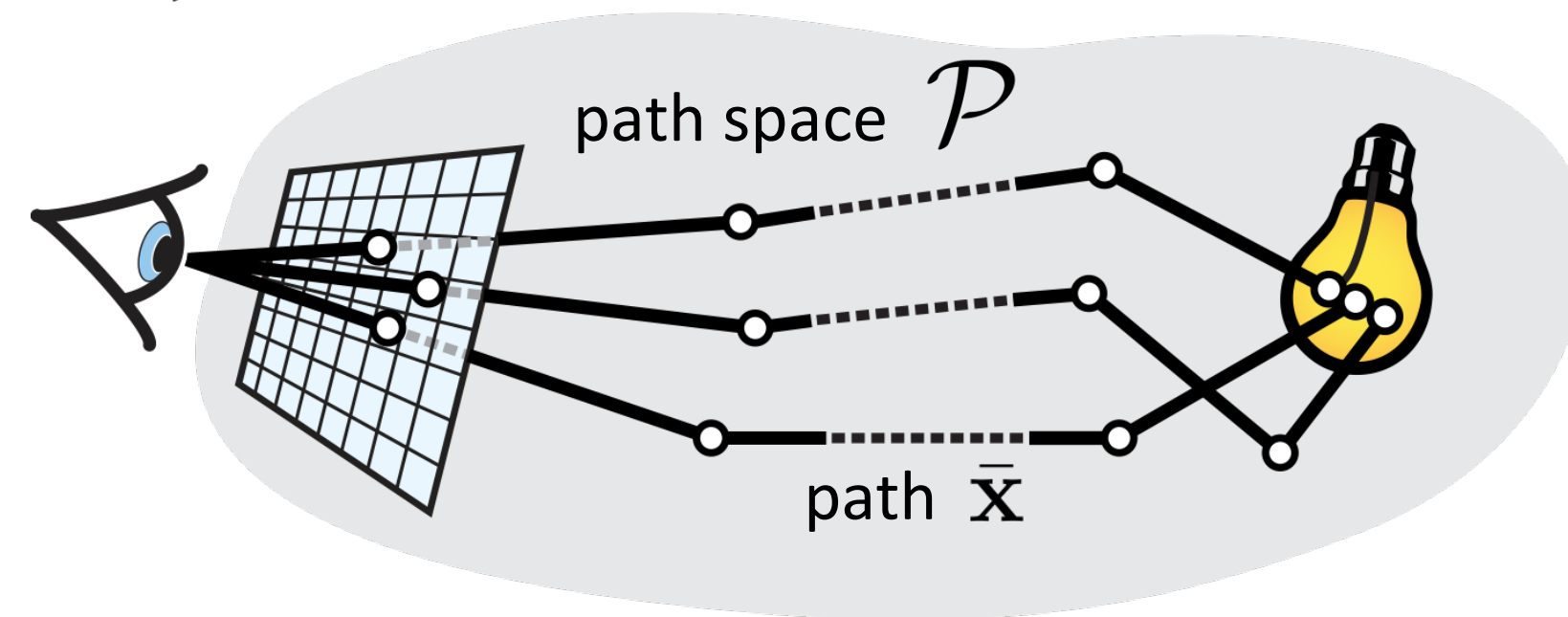
$$I_j = \int_A \int_A W_e(\mathbf{x}_0, \mathbf{x}_1) G(\mathbf{x}_0, \mathbf{x}_1) L_o(\mathbf{x}_1, \mathbf{x}_0) d\mathbf{x}_1 d\mathbf{x}_0$$

$$= \int_{\mathcal{P}} W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_k, \mathbf{x}_{k-1}) T(\bar{\mathbf{x}}) d\bar{\mathbf{x}}$$

global illumination (all paths of all lengths)

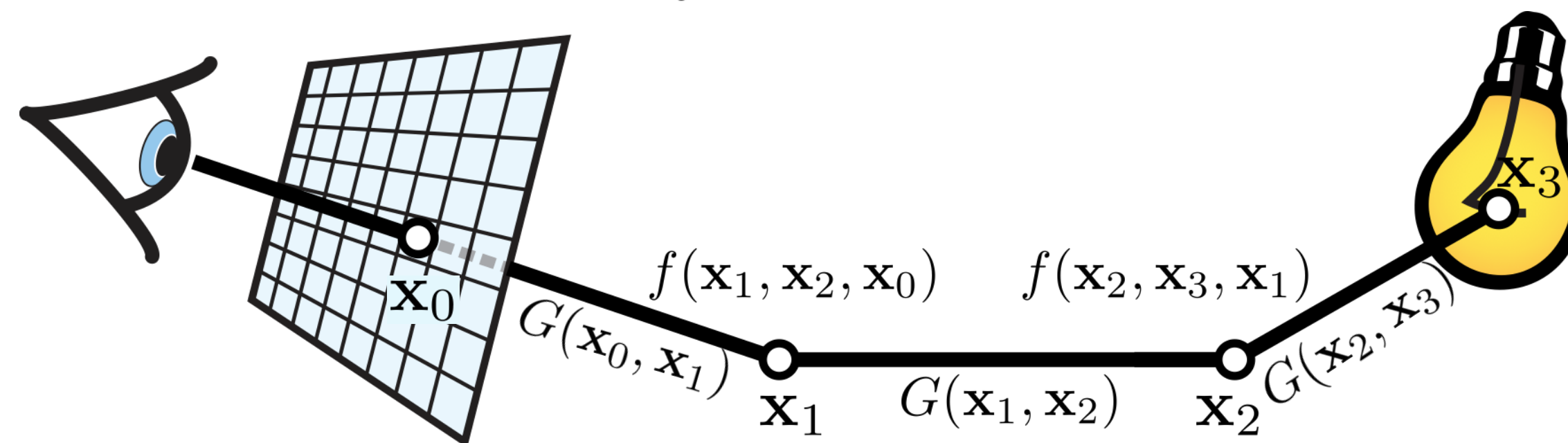
# Path Integral Form of Measurement Eq.

$$I_j = \int_{\mathcal{P}} W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_k, \mathbf{x}_{k-1}) T(\bar{\mathbf{x}}) d\bar{\mathbf{x}}$$



path throughput

$$T(\bar{\mathbf{x}}) = G(\mathbf{x}_0, \mathbf{x}_1) \prod_{j=1}^{k-1} f(\mathbf{x}_j, \mathbf{x}_{j+1}, \mathbf{x}_{j-1}) G(\mathbf{x}_j, \mathbf{x}_{j+1})$$



# Path Integral Form of Measurement Eq.

---

$$I_j = \int_{\mathcal{P}} W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_k, \mathbf{x}_{k-1}) T(\bar{\mathbf{x}}) d\bar{\mathbf{x}}$$

## Advantages:

- no recursion, no “nasty” nested integrals
- emphasizes symmetry of light transport
- easy to relate different rendering algorithms
- focuses on path geometry, independent of strategy for constructing paths
- MC estimator on path space looks much simpler

# Path Integral Form of Measurement Eq.

---

$$I_j = \int_{\mathcal{P}} W_e(\mathbf{x}_0, \mathbf{x}_1) L_e(\mathbf{x}_k, \mathbf{x}_{k-1}) T(\bar{\mathbf{x}}) d\bar{\mathbf{x}}$$

Monte Carlo estimator:

$$I_j \approx \frac{1}{N} \sum_{i=1}^N \frac{W_e(\mathbf{x}_{i,0}, \mathbf{x}_{i,1}) L_e(\mathbf{x}_{i,k}, \mathbf{x}_{i,k-1}) T(\bar{\mathbf{x}}_i)}{p(\bar{\mathbf{x}}_i)}$$

$$p(\bar{\mathbf{x}}) = p(\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{k-1}, \mathbf{x}_k)$$

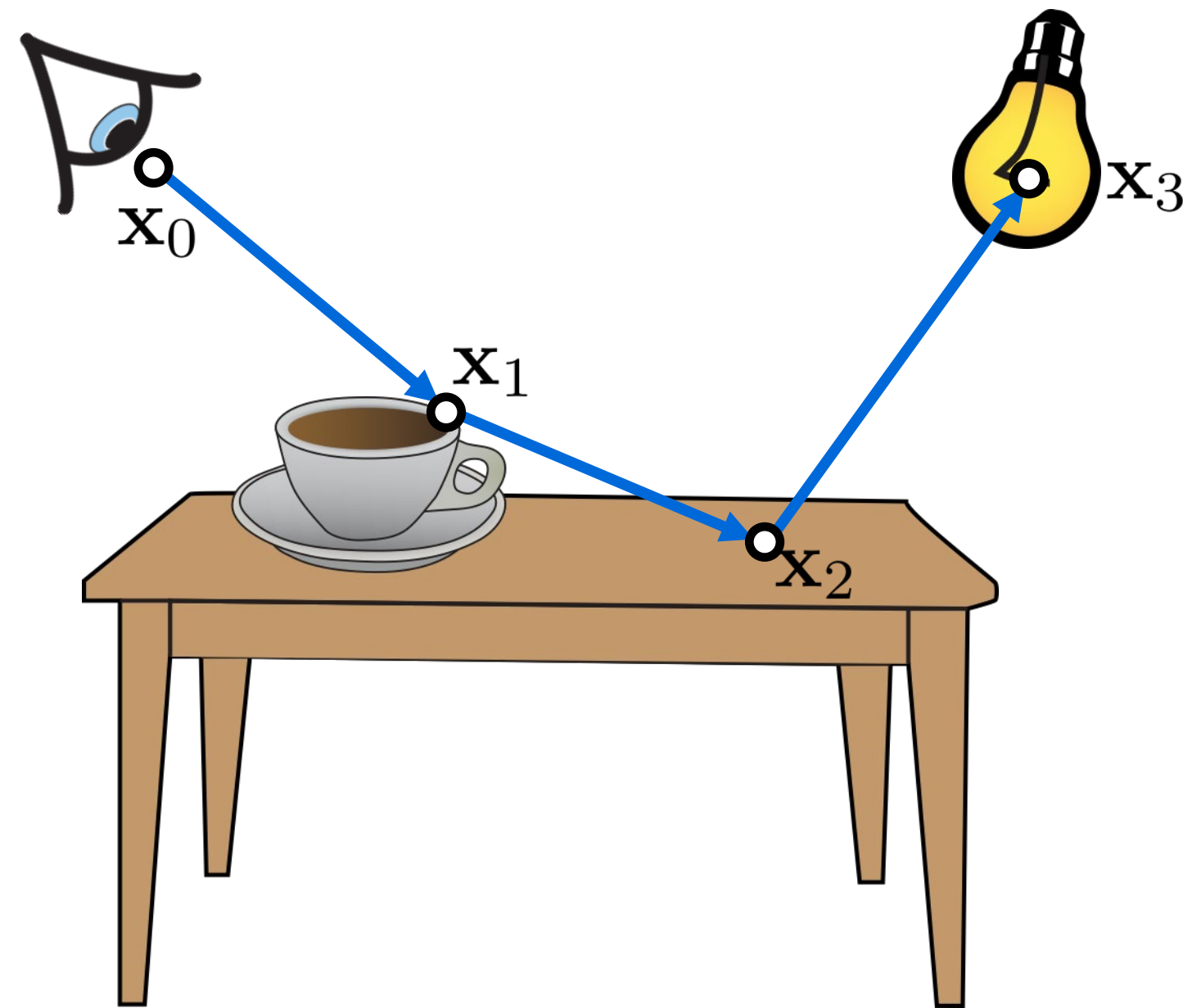
path PDF joint PDF of path vertices

# Path Construction

---

$$p(\bar{\mathbf{x}}) = p(\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{k-1}, \mathbf{x}_k)$$

Path tracing w/o NEE

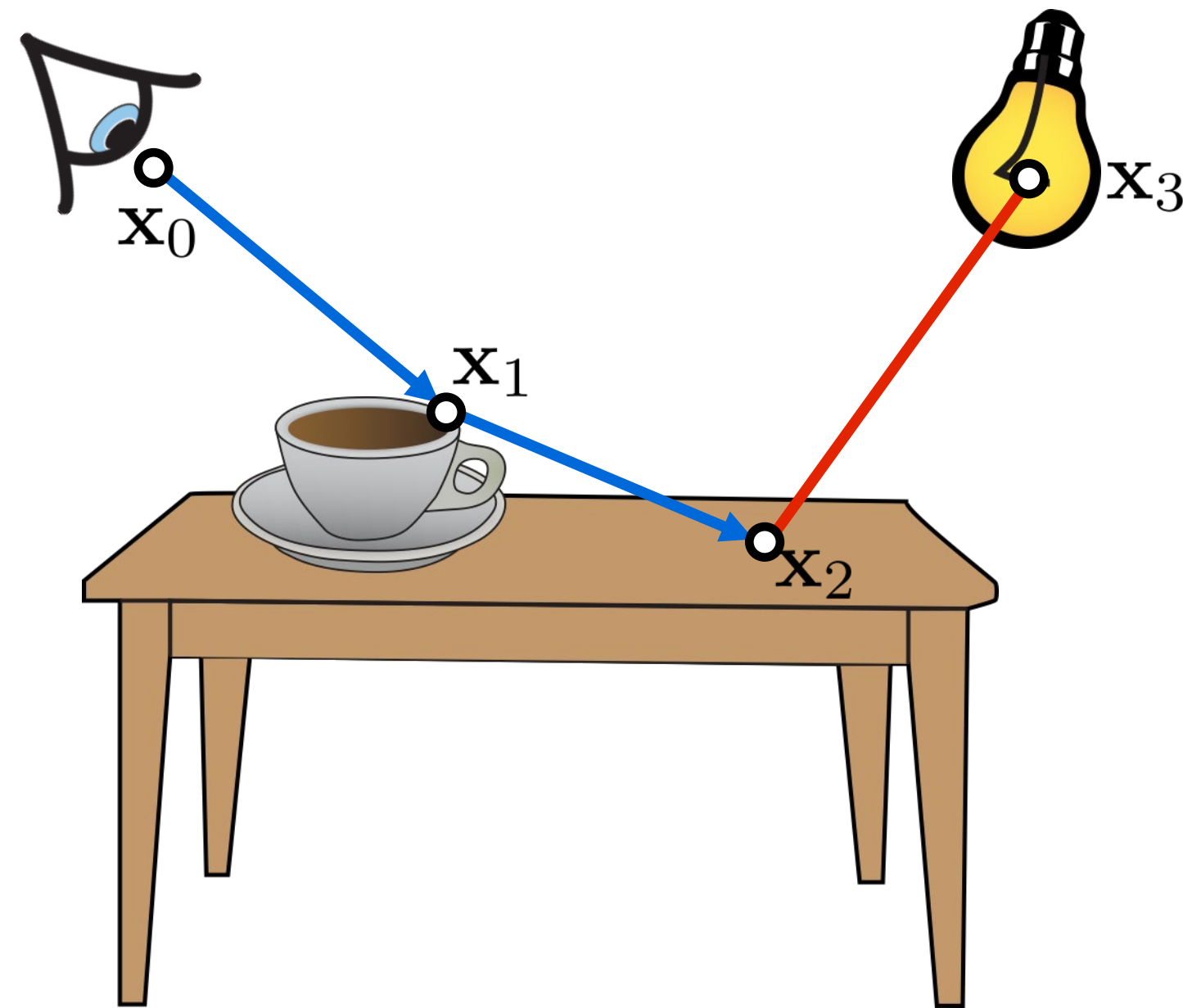


$$\begin{aligned} p(\bar{\mathbf{x}}) &= p(\mathbf{x}_0) \\ &\times p(\mathbf{x}_1 | \mathbf{x}_0) \\ &\times p(\mathbf{x}_2 | \mathbf{x}_0 \mathbf{x}_1) \\ &\times p(\mathbf{x}_3 | \mathbf{x}_0 \mathbf{x}_1 \mathbf{x}_2) \end{aligned}$$

# Path Construction

$$p(\bar{\mathbf{x}}) = p(\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{k-1}, \mathbf{x}_k)$$

Path tracing with NEE



$$\begin{aligned} p(\bar{\mathbf{x}}) &= p(\mathbf{x}_0) \\ &\times p(\mathbf{x}_1 | \mathbf{x}_0) \\ &\times p(\mathbf{x}_2 | \mathbf{x}_0 \mathbf{x}_1) \\ &\times p(\mathbf{x}_3) \end{aligned}$$

assuming uniform  
area sampling

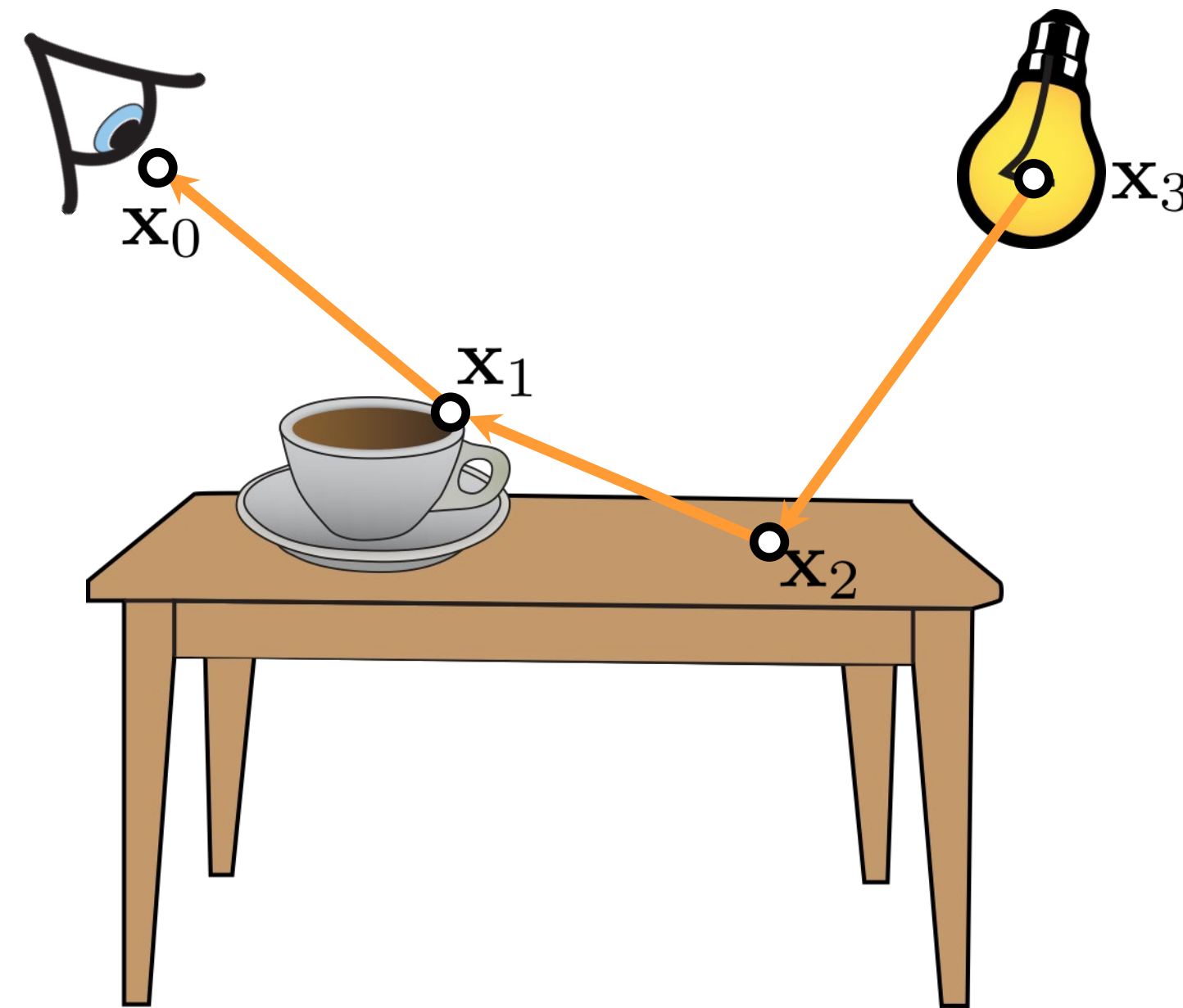


# Path Construction

---

$$p(\bar{\mathbf{x}}) = p(\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{k-1}, \mathbf{x}_k)$$

Light tracing

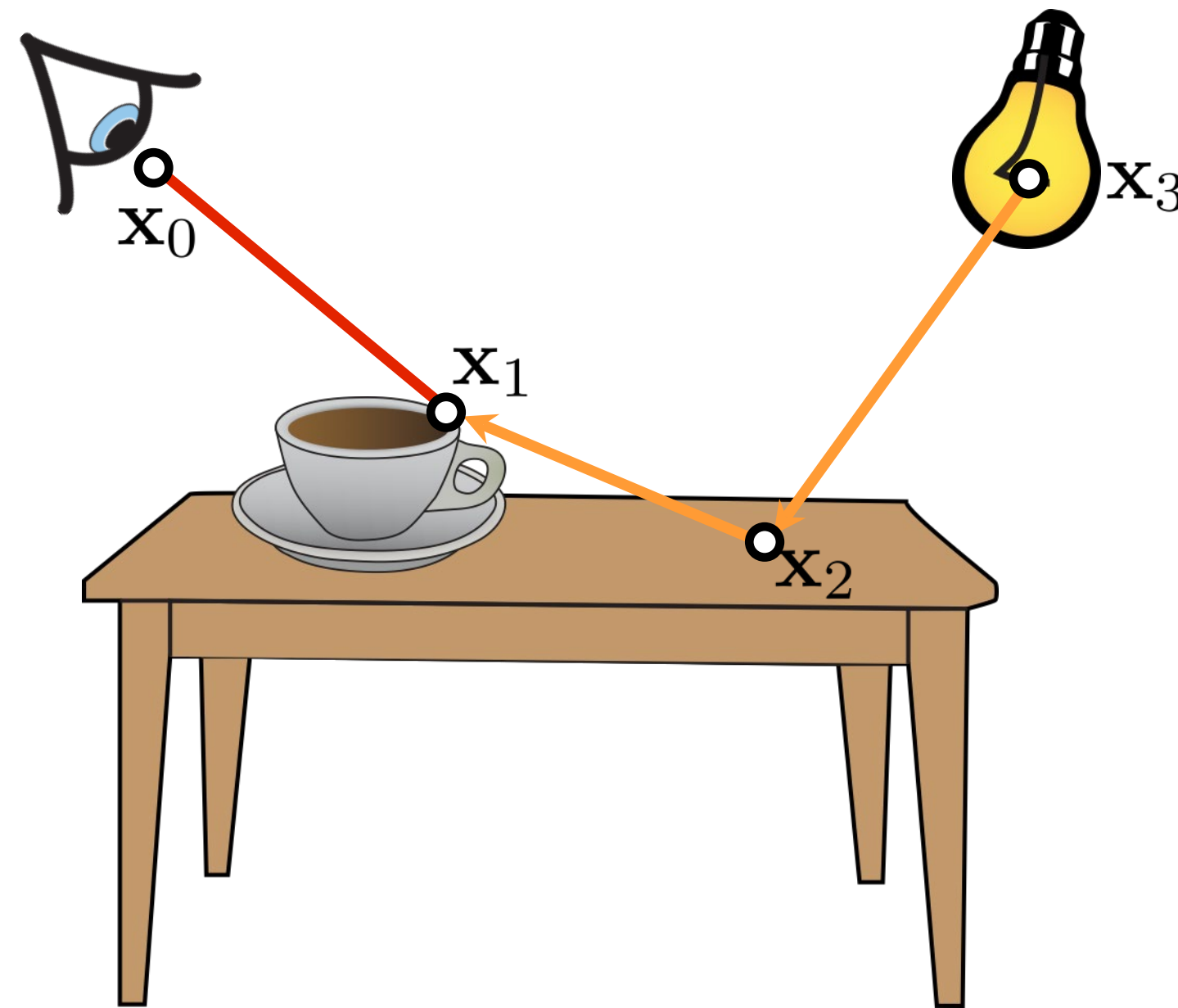


$$\begin{aligned} p(\bar{\mathbf{x}}) &= p(\mathbf{x}_0 | \mathbf{x}_3 \mathbf{x}_2 \mathbf{x}_1) \\ &\times p(\mathbf{x}_1 | \mathbf{x}_3 \mathbf{x}_2) \\ &\times p(\mathbf{x}_2 | \mathbf{x}_3) \\ &\times p(\mathbf{x}_3) \end{aligned}$$

# Path Construction

$$p(\bar{\mathbf{x}}) = p(\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{k-1}, \mathbf{x}_k)$$

Light tracing with NEE



assuming uniform aperture sampling

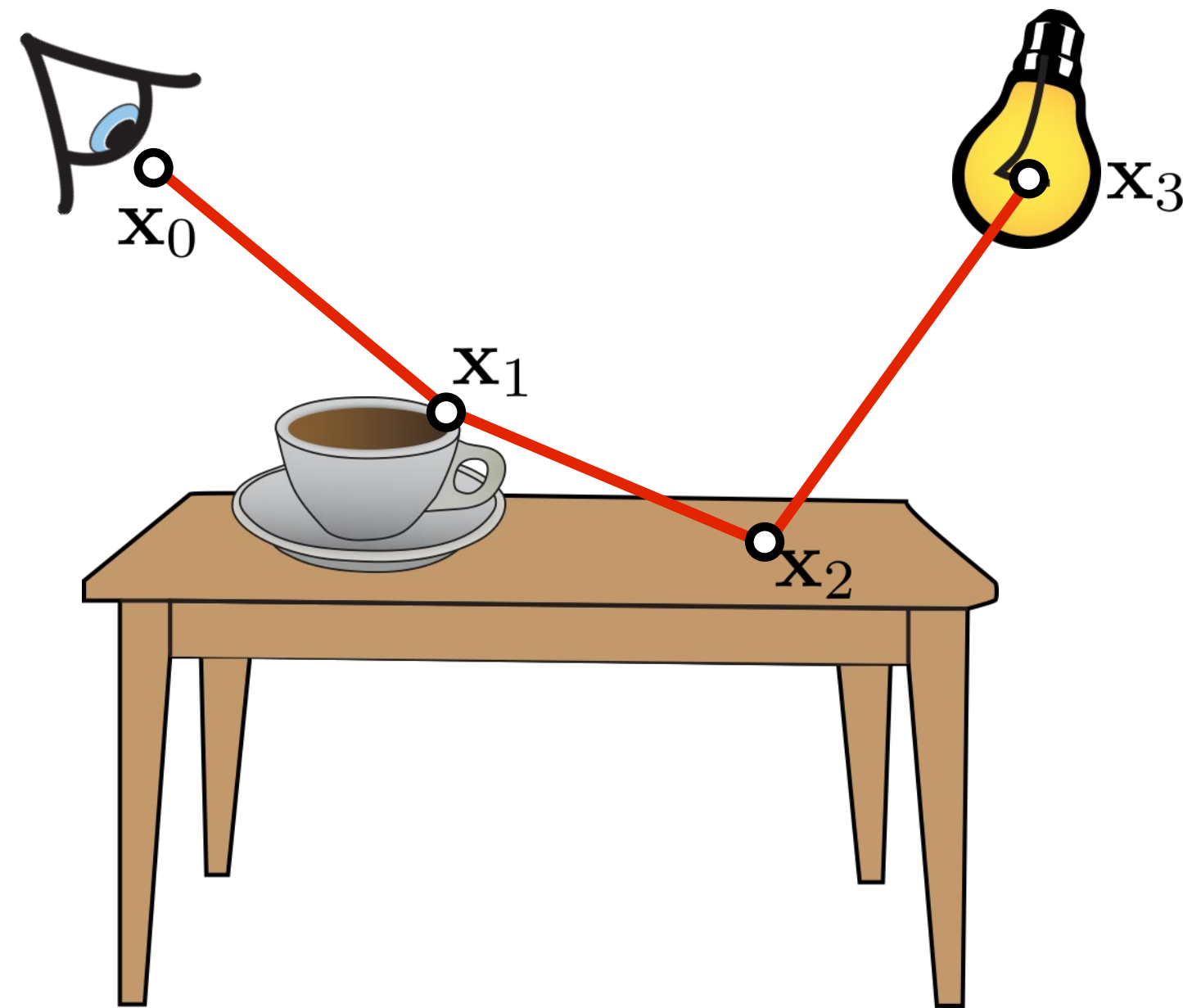
$$p(\bar{\mathbf{x}}) = p(\mathbf{x}_0) \times p(\mathbf{x}_1 | \mathbf{x}_3 \mathbf{x}_2) \times p(\mathbf{x}_2 | \mathbf{x}_3) \times p(\mathbf{x}_3)$$

# Path Construction

---

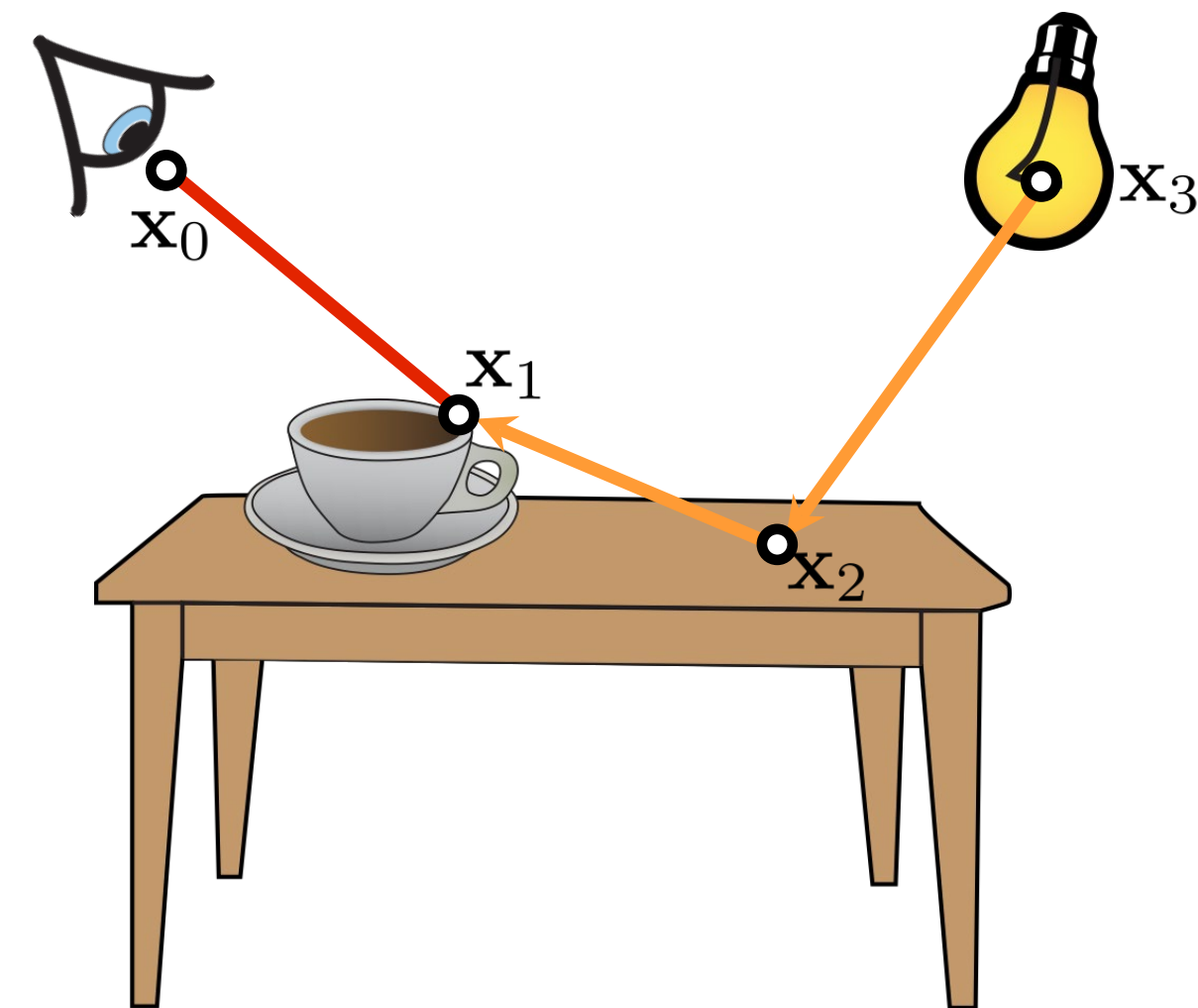
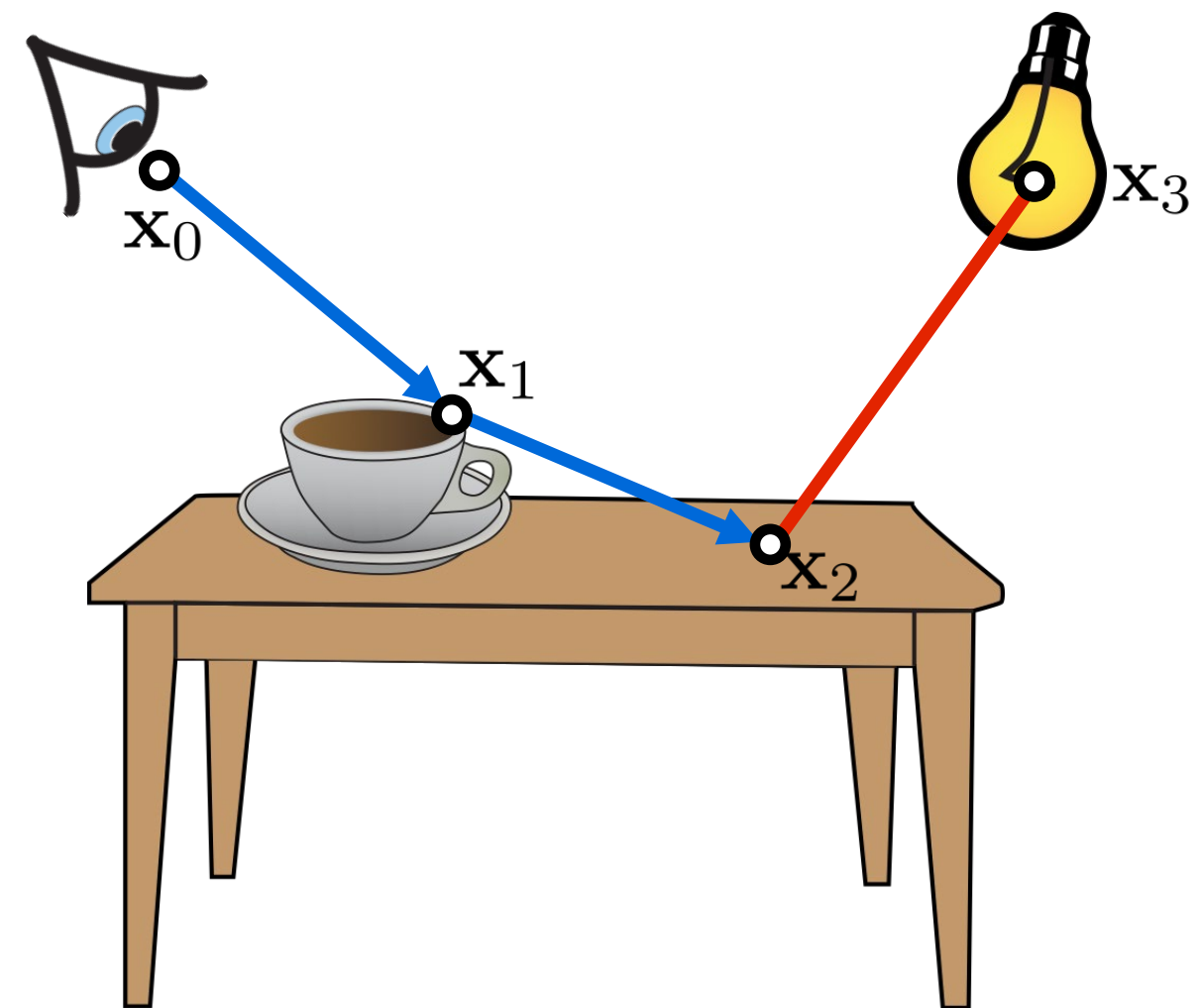
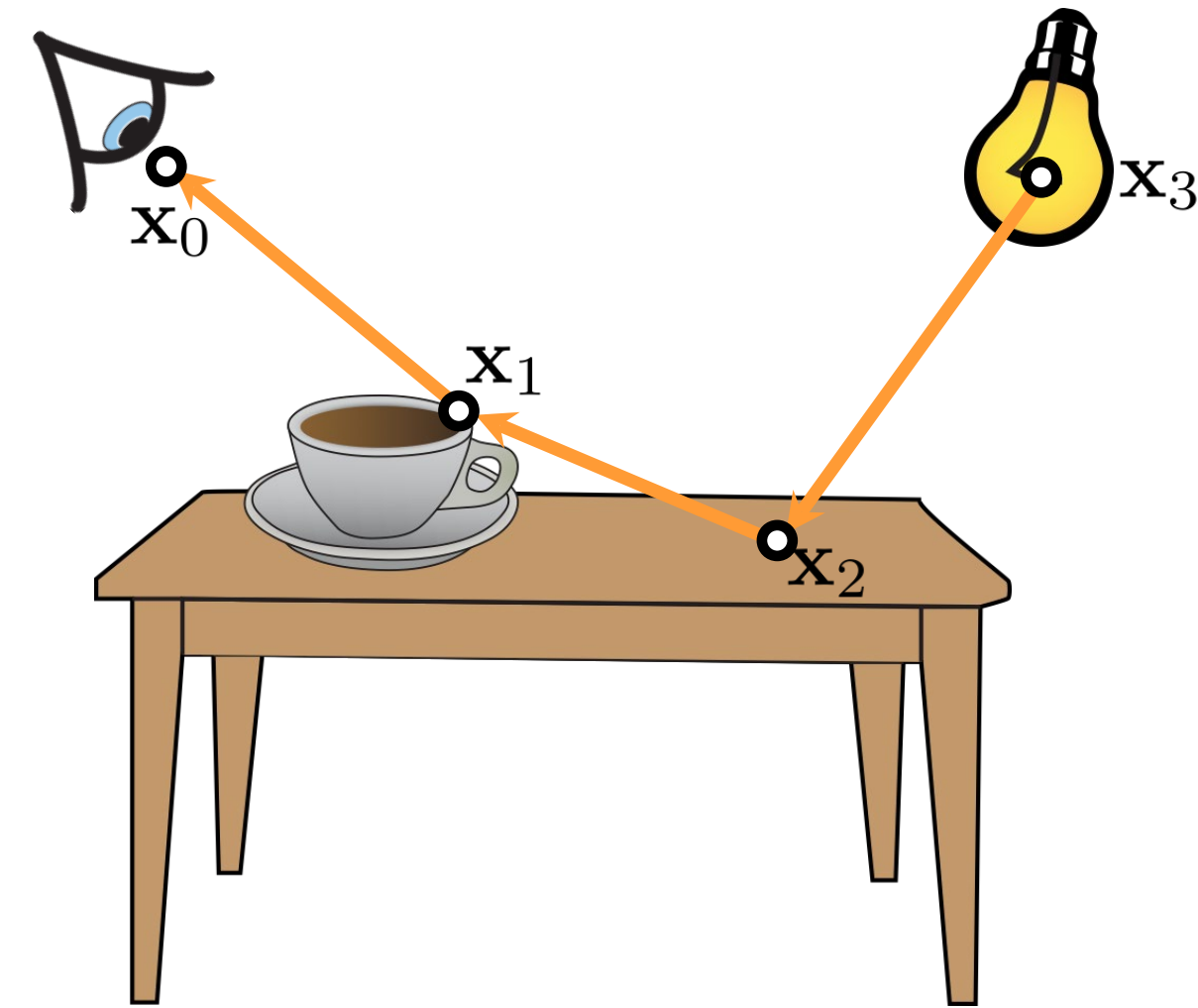
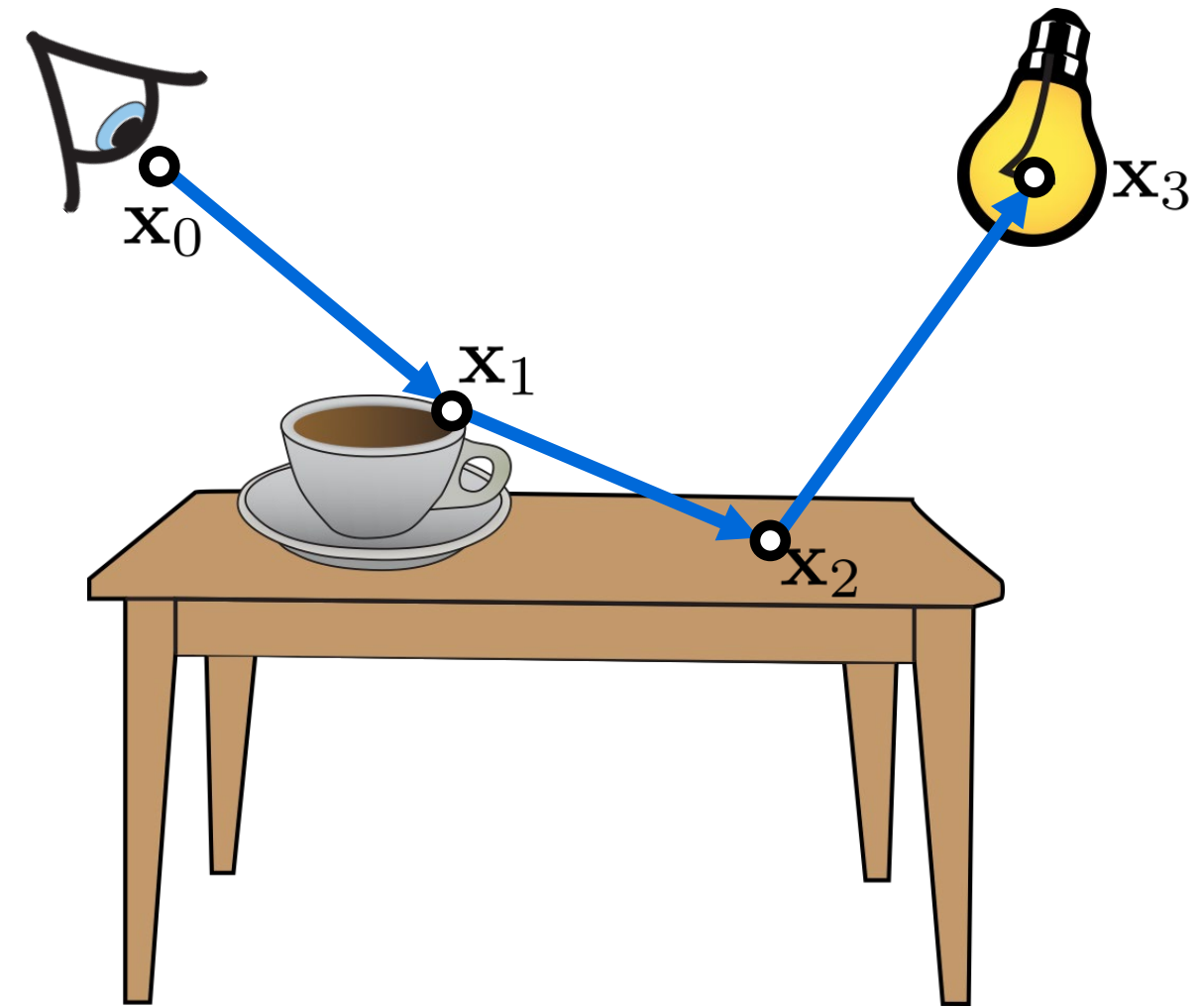
$$p(\bar{\mathbf{x}}) = p(\mathbf{x}_0, \mathbf{x}_1, \dots, \mathbf{x}_{k-1}, \mathbf{x}_k)$$

Independent sampling of path vertices  
(not very practical though)



$$\begin{aligned} p(\bar{\mathbf{x}}) &= p(\mathbf{x}_0) \\ &\times p(\mathbf{x}_1) \\ &\times p(\mathbf{x}_2) \\ &\times p(\mathbf{x}_3) \end{aligned}$$

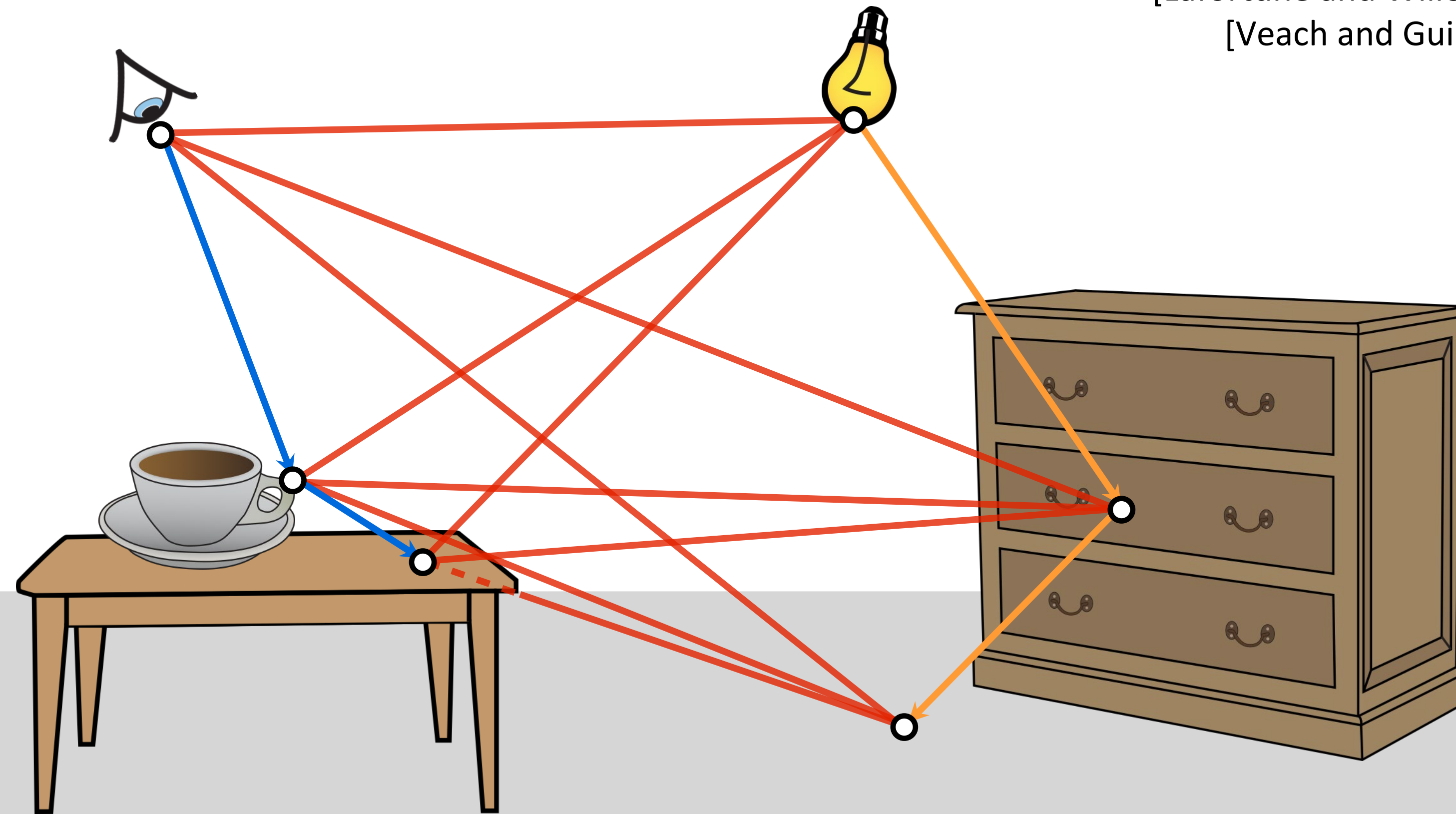
# Can we combine them?



# Bidirectional Path Tracing

# Bidirectional Path Tracing

[Lafortune and Willem's 1993]  
[Veach and Guibas 1994]



$t$  - # vertices on camera subpath  
 $s$  - # vertices on light subpath  
 $ts$  - # connections

# Bidirectional Path Tracing

---

```
color estimate ( point x )
{
    lp = sample light subpath
    cp = sample camera subpath for image point x

    for each vertex s in lp
        for each vertex t in cp
            fullPath = join( cp[ 0..s ], lp[ 0..t ] )
            splat ( fullPath.screenPos ,
fullPath.contrib )
}
```

# Bidirectional Path Tracing

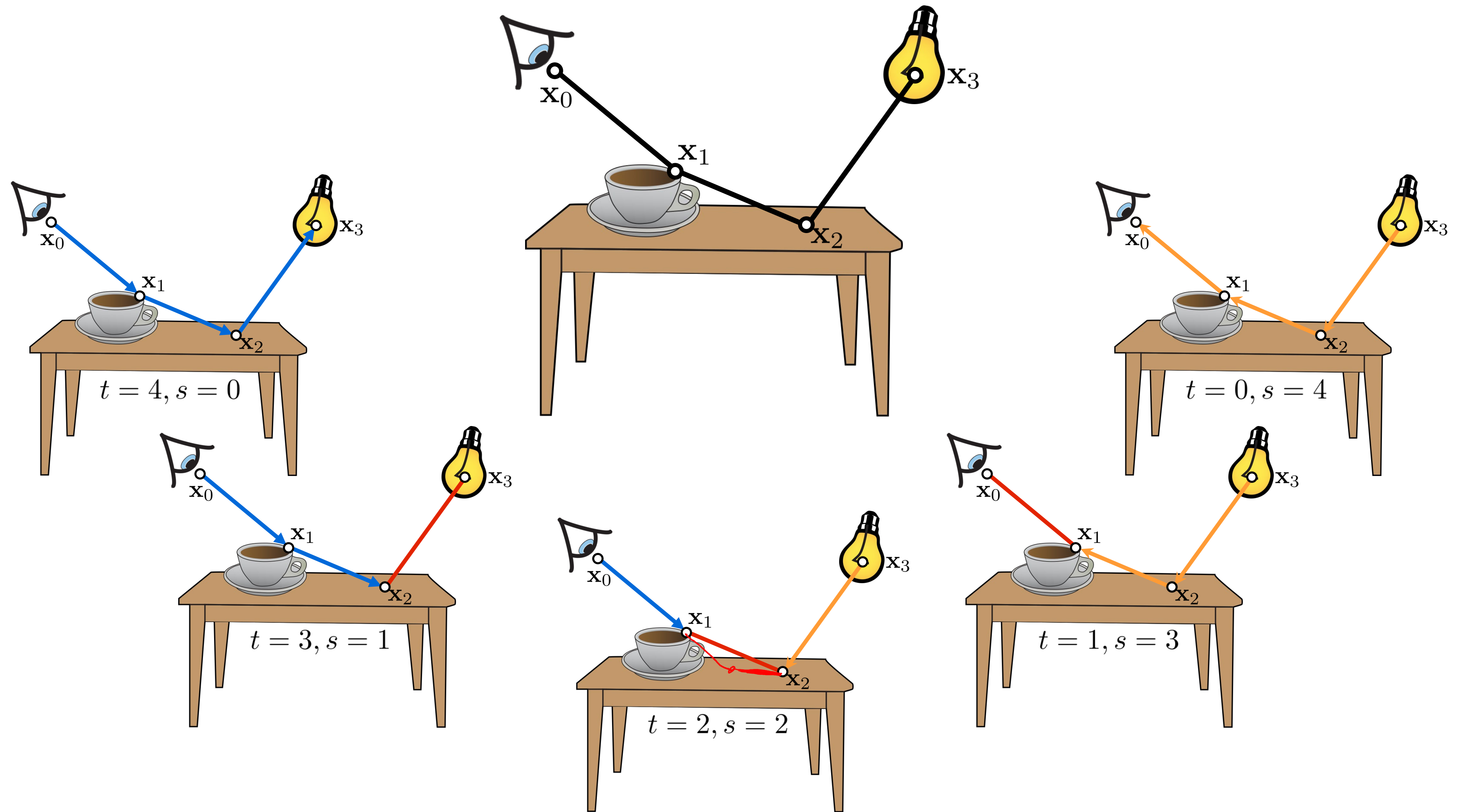
---

## Key observations:

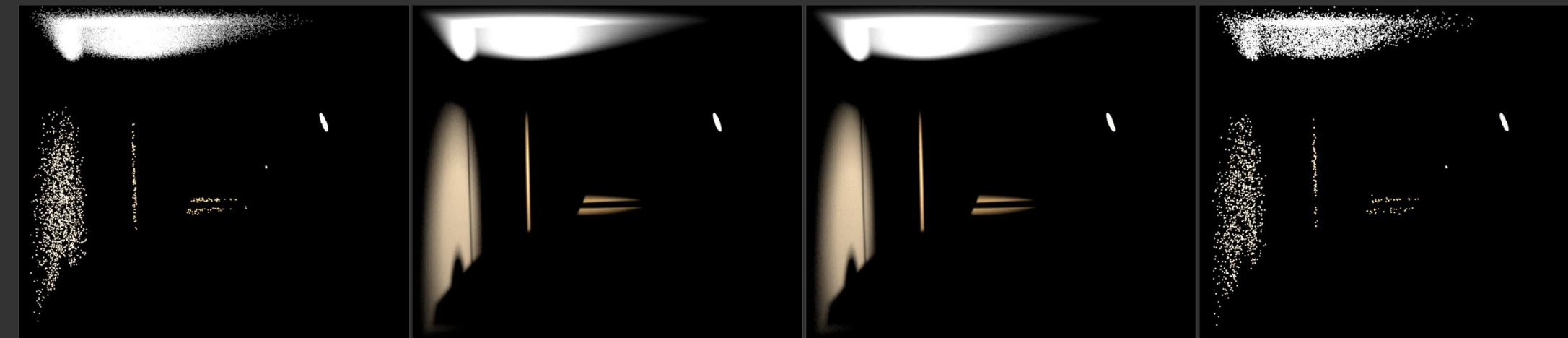
- Every path (formed by connecting camera sub-path to light sub-path) with  $k$  vertices can be constructed using  $k+1$  strategies
- For a particular path length, all strategies estimate the same integral
- Each strategy has a different PDF, i.e., each strategy has different strengths and weaknesses
- Let's combine them using MIS!



# Bidirectional Path Tracing



# Bidirectional Path Tracing



s=0, t=3

s=1, t=2

s=2, t=1

s=3, t=0



s=0, t=4

s=1, t=3

s=2, t=2

s=3, t=1

s=4, t=0



s=0, t=5

s=1, t=4

s=2, t=3

s=3, t=2

s=4, t=1

s=5, t=0



s=0, t=6

s=1, t=5

s=2, t=4

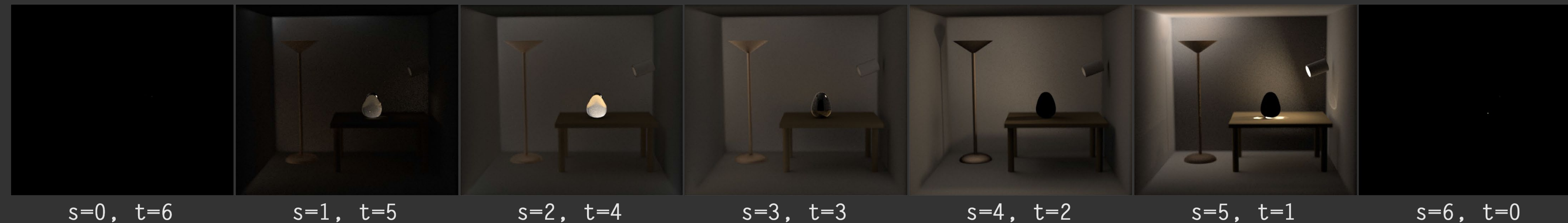
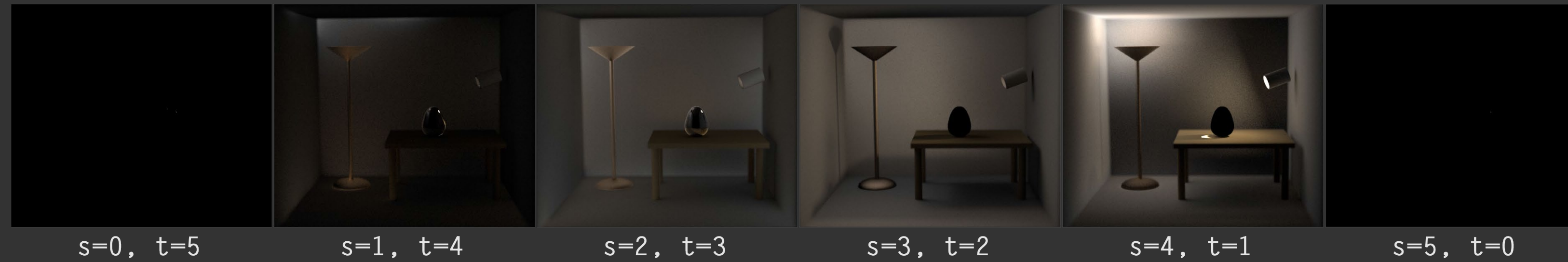
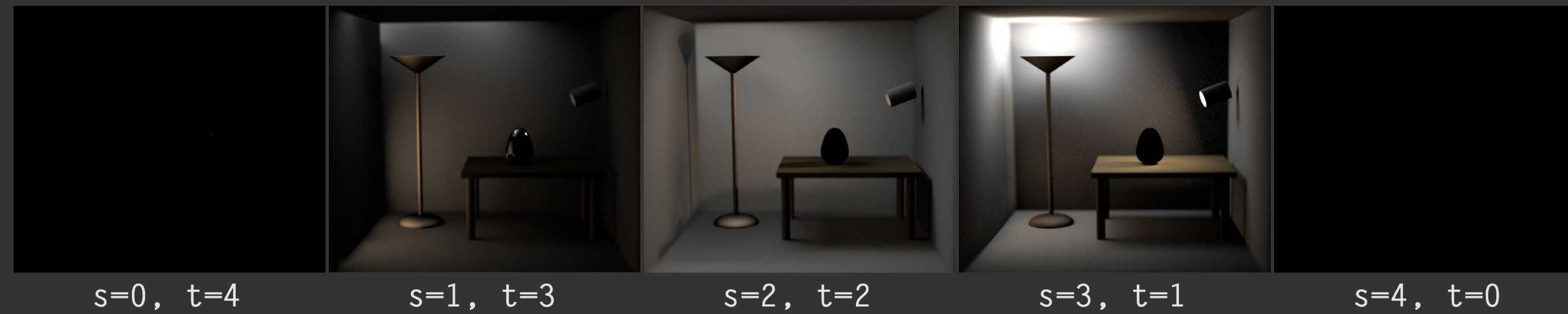
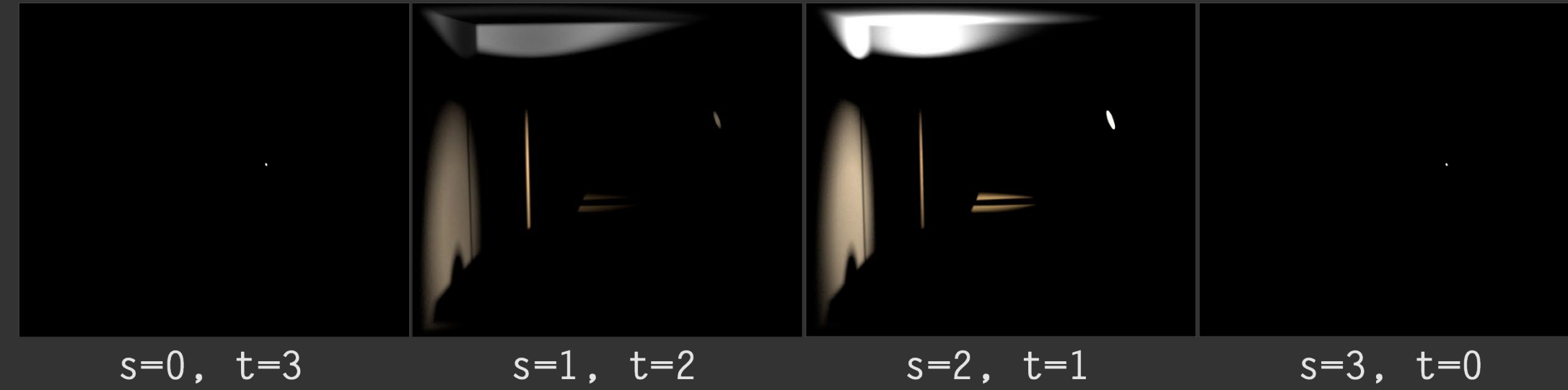
s=3, t=3

s=4, t=2

s=5, t=1

s=6, t=0

# Bidirectional Path Tracing (MIS)



# Bidirectional Path Tracing

(Unidirectional) path tracing

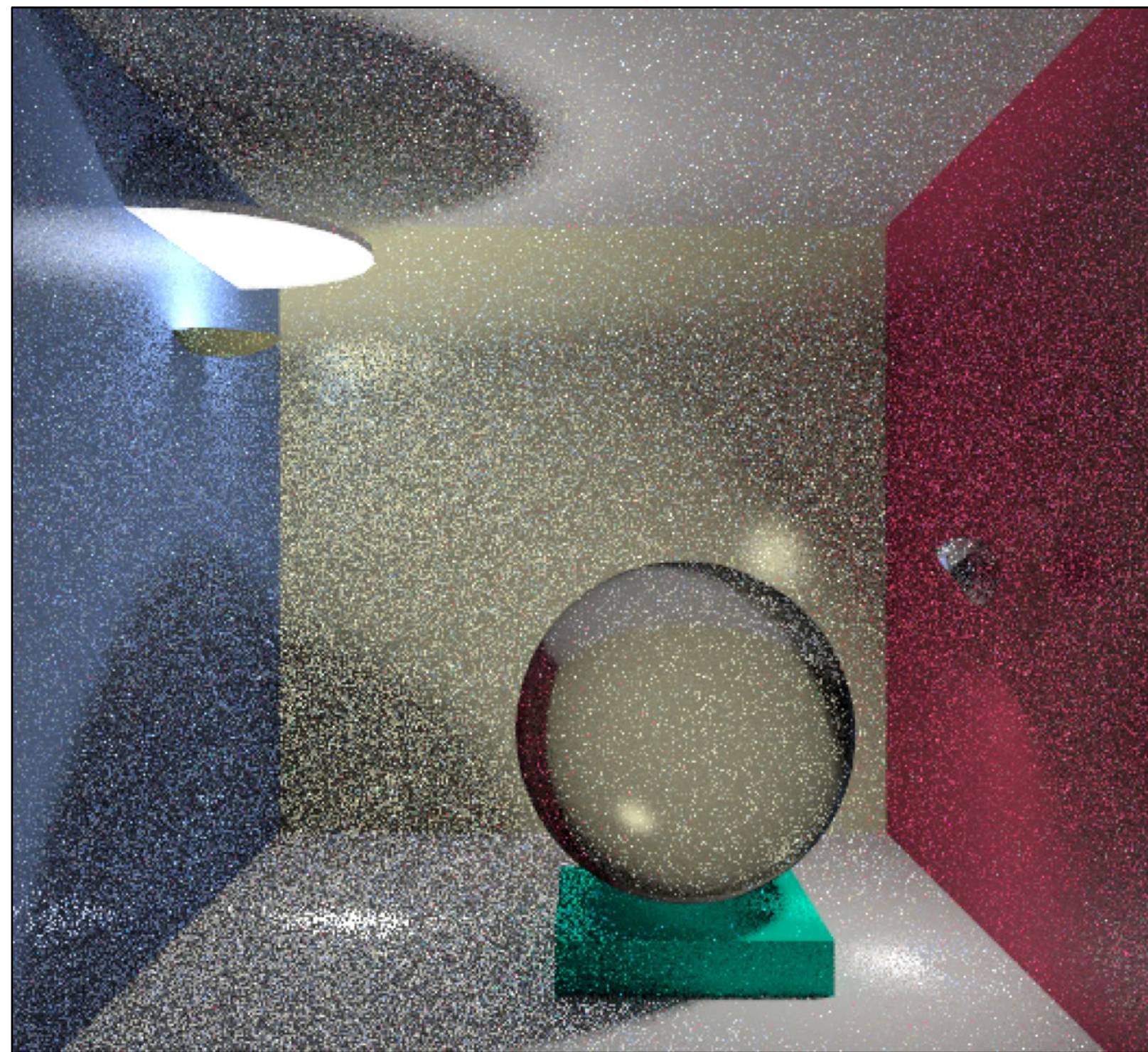


Bidirectional path tracing

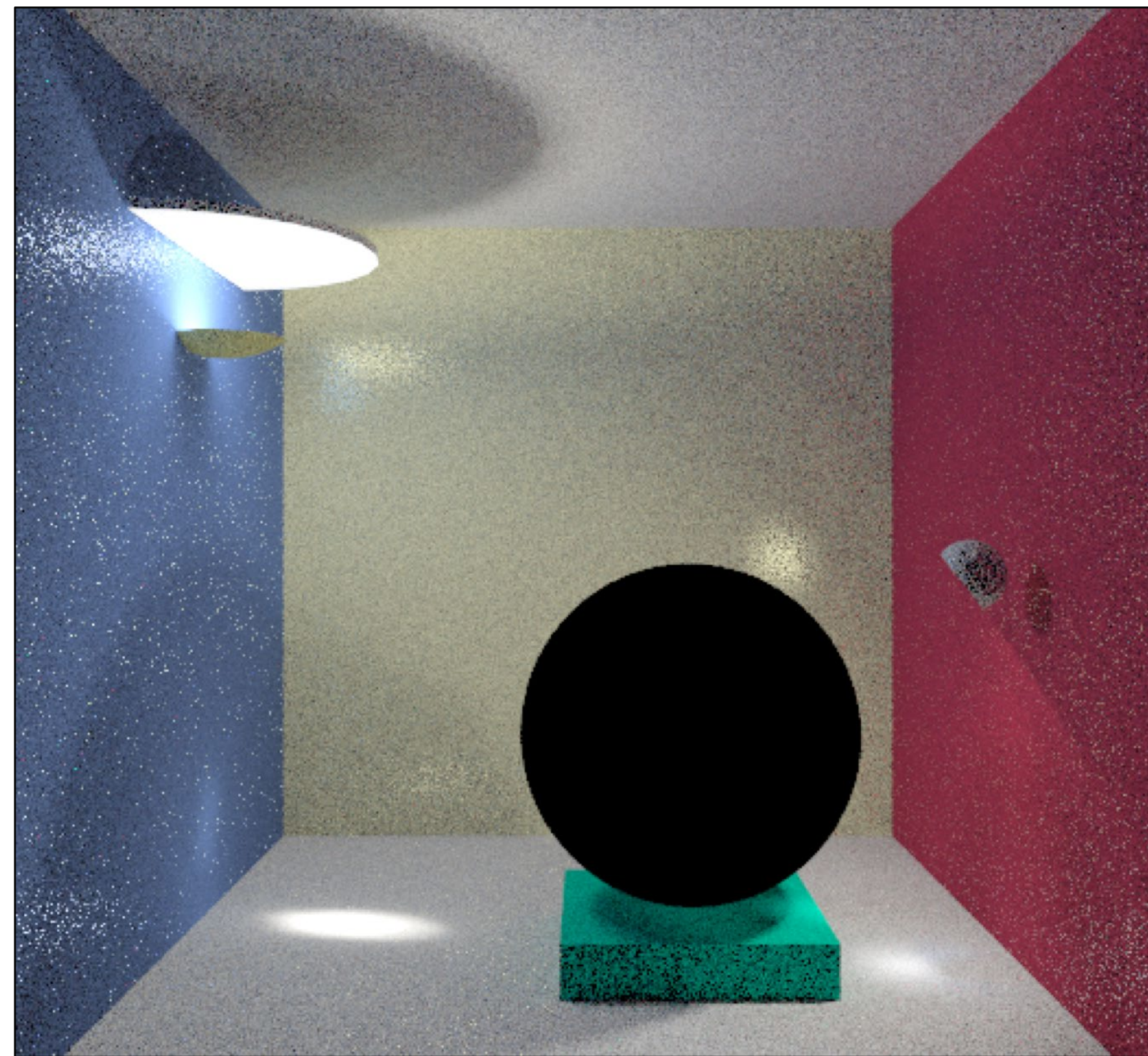


# Bidirectional Path Tracing

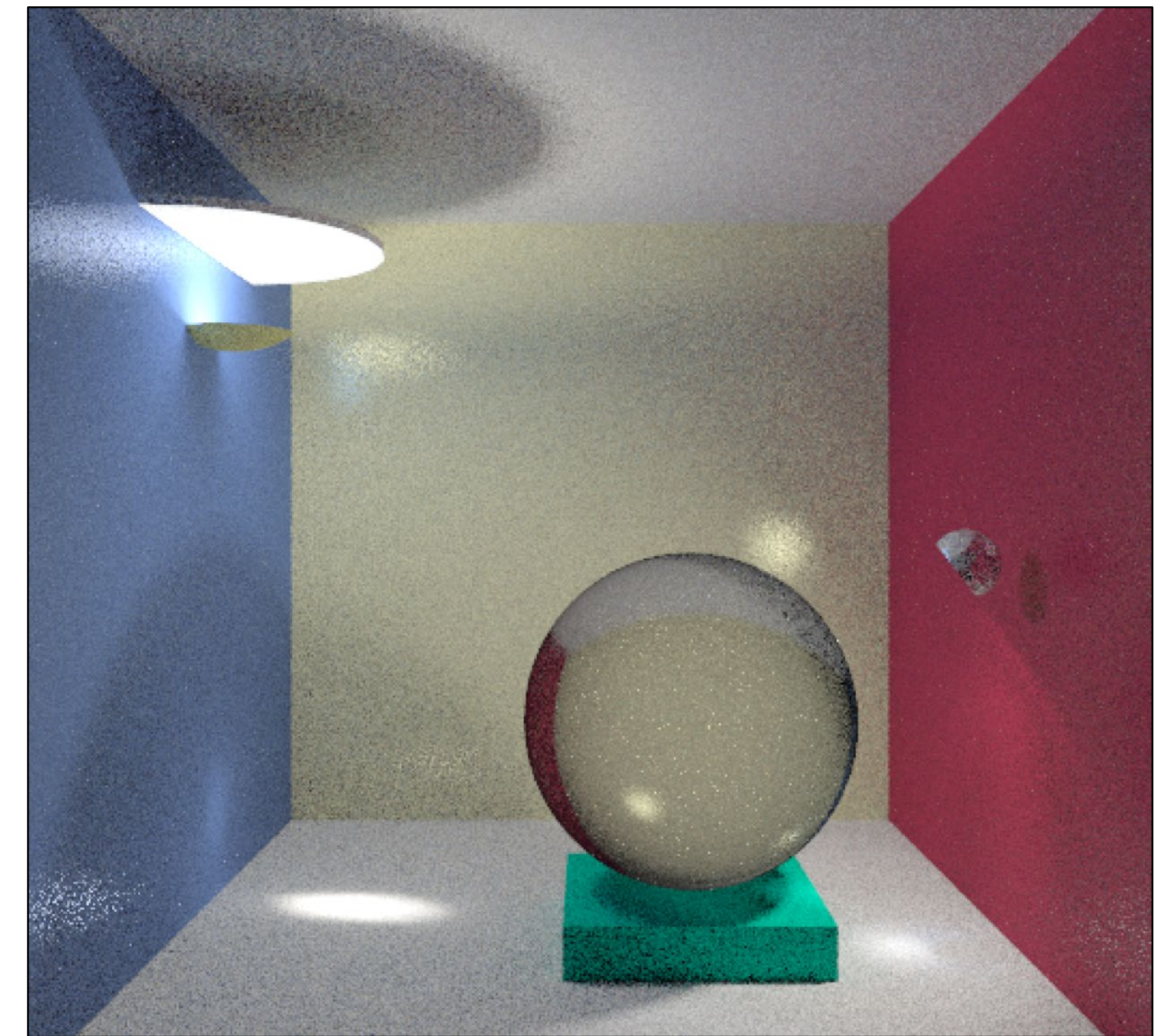
Path tracing



Light tracing



Bidirectional PT



# Still not robust enough...

Reference

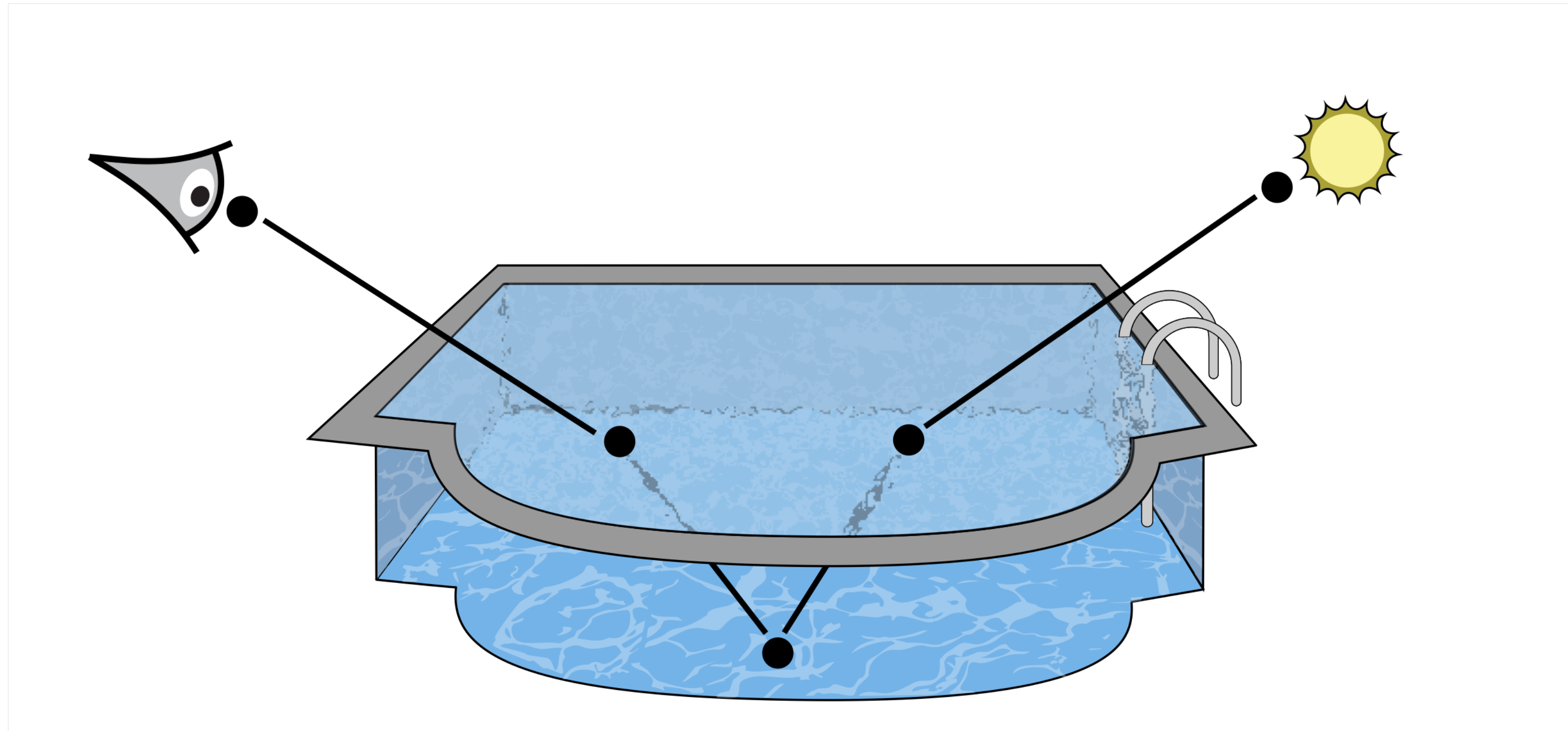
Bidirectional PT



$$L(DIS) \neq \sqrt{SDS}$$
$$(DIS)^* \in$$

# Still not robust enough...

---



*LSDSE* paths are difficult for any unbiased method

# Still not robust enough...

---

## Extensions

- Combination with photon mapping
  - Unified Path Sampling [Hachisuka et al. 2012]
  - Vertex Connection Merging [Georgiev et al. 2012]
- Metropolis sampling (global PDF)
- Path-space regularization [Kaplanyan et al. 2013]
- Path guiding (learn global PDF)