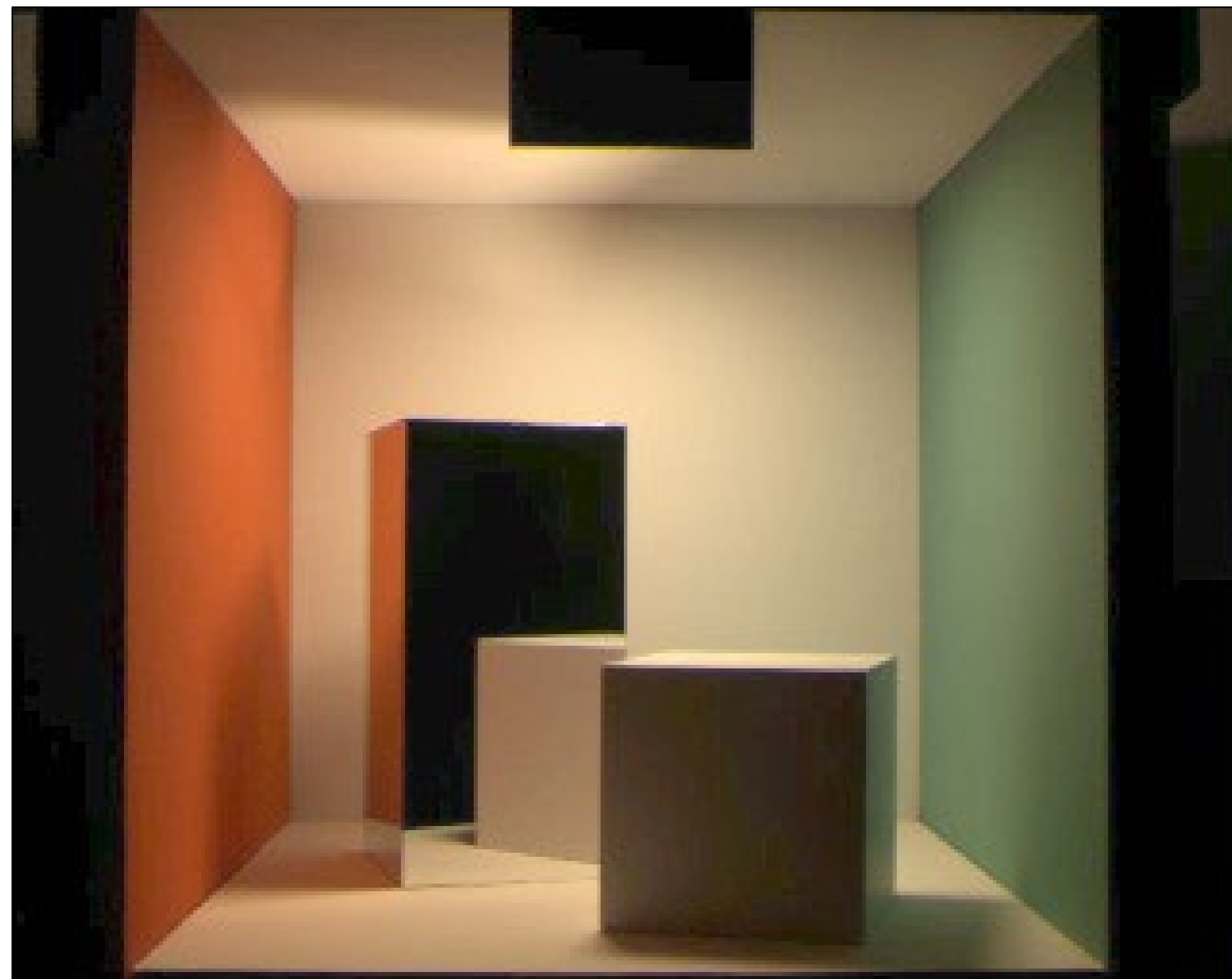


Rendering equation

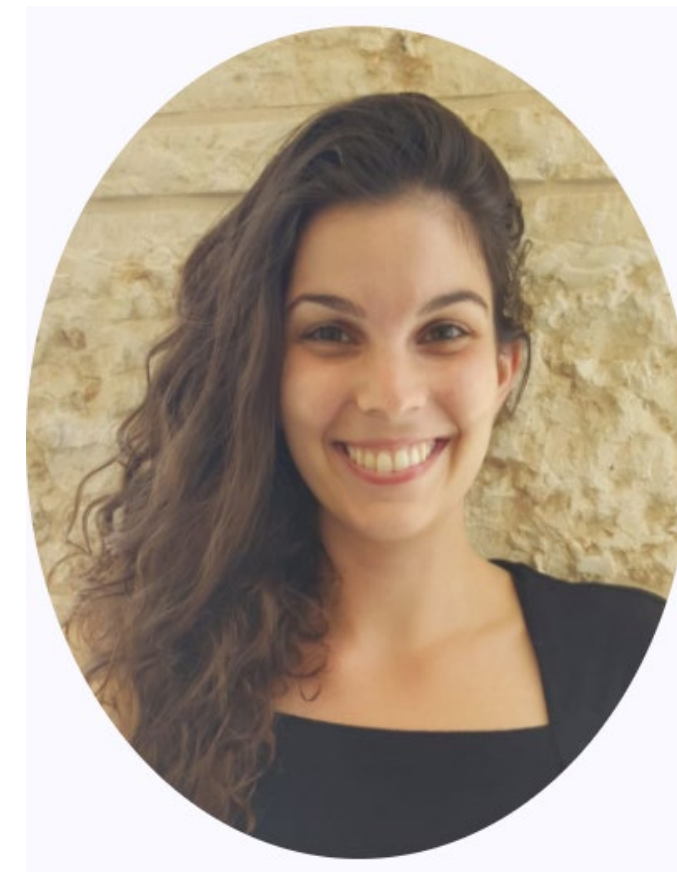


15-468, 15-668, 15-868
Physics-based Rendering
Spring 2021, Lecture 12

Course announcements

- Take-home quiz 4 due Tuesday 3/16 at 23:59.
 - Take-home quiz 5 will be posted tonight.
- Programming assignment 3 posted, due Friday 3/26 at 23:59.
 - How many of you have looked at/started/finished it?
 - Any questions?
- This week's reading group.
 - *Please* try and post suggested topics by Thursday early afternoon.
 - Suggest topics on Piazza.
- Vote to re-schedule lecture of 3/25.

Graphics faculty candidate talk



- Speaker: **Rana Hanocka** (Tel Aviv University)
- Title: **Artificial Intelligence for Geometry Processing**
- Abstract: Demand for geometry processing is higher than ever, given the continuously and exponentially growing amount of captured 3D data (with depth-sensing cameras now prevalent in smartphones, robots, drones, and cars). Yet, in practice, current geometry processing techniques struggle to automatically and robustly analyze real-world data, even in small volumes. Deep learning, the most popular form of artificial intelligence, has been remarkably effective in extracting patterns from voluminous data, thus generating significant scientific interest in its applicability to 3D geometric data. However, despite the inspiring success of deep learning on large sets of Euclidean data (such as text, images, and video), extending deep neural networks to non-Euclidean, irregular 3D data has proven to be both ambiguous and highly challenging.

This talk will present my research into developing deep learning techniques that enable effective operation on irregular geometric data. I will demonstrate how we can leverage the representational power of neural networks to solve complex geometry processing problems, including surface reconstruction and geometric modeling/synthesis. I will conclude by highlighting open research directions aligned with my focus on designing 3D machine learning techniques that can both facilitate the robust processing of real-world geometric data and improve ease-of-use in downstream applications.

Overview of today's lecture

- Leftover from previous lecture: light sources, mixture sampling, multiple importance sampling.
- Rendering equation.
- Path tracing with next-event estimation.

Slide credits

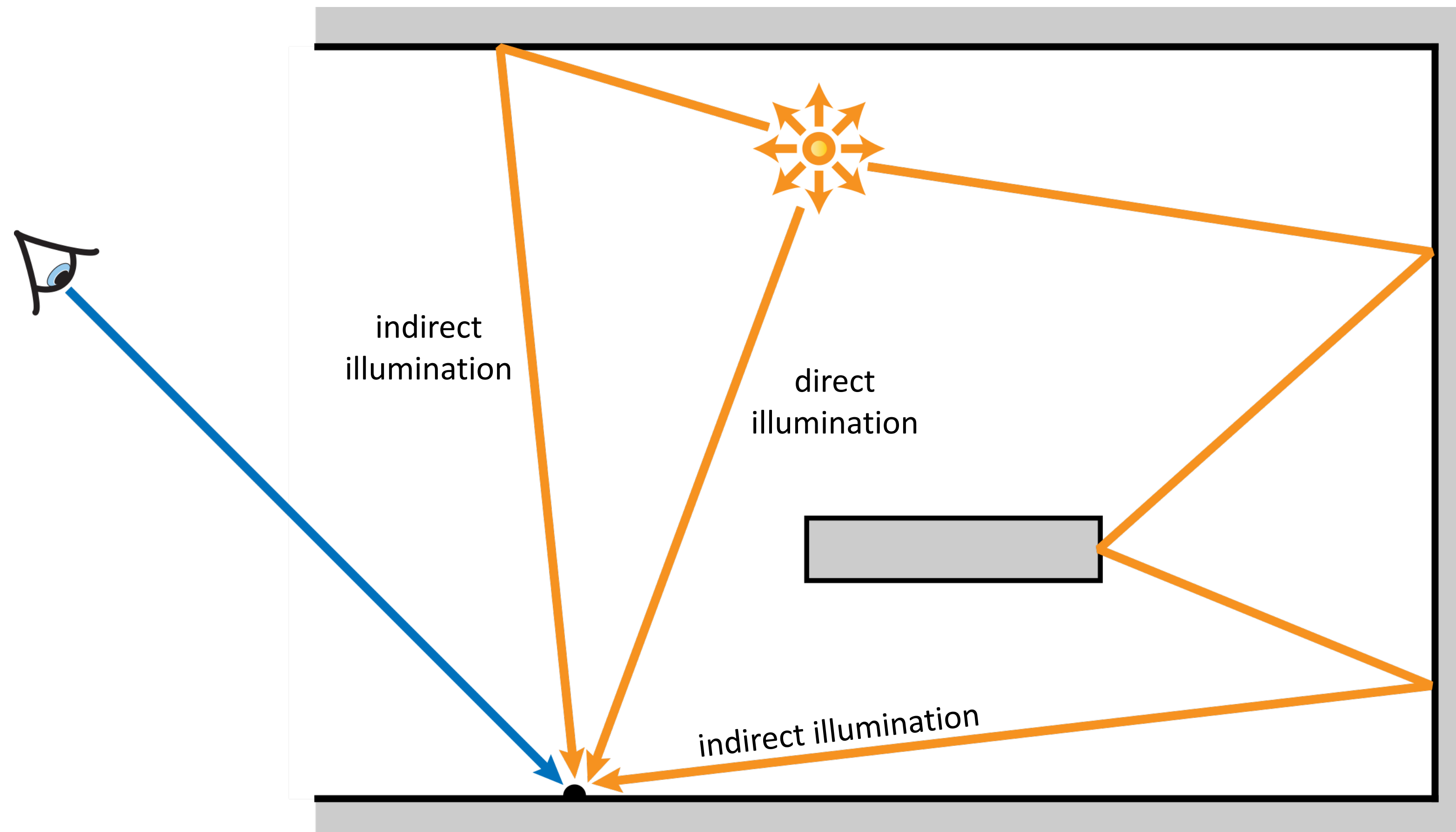
Most of these slides were directly adapted from:

- Wojciech Jarosz (Dartmouth).

Direct vs. Indirect Illumination

Where does L_i
“come from”?

$$L_r(\mathbf{x}, \vec{\omega}_r) = \int_{H^2} f_r(\mathbf{x}, \vec{\omega}_i, \vec{\omega}_r) L_i(\mathbf{x}, \vec{\omega}_i) \cos \theta_i \, d\vec{\omega}_i$$



Direct vs. Indirect Illumination

Direct illumination



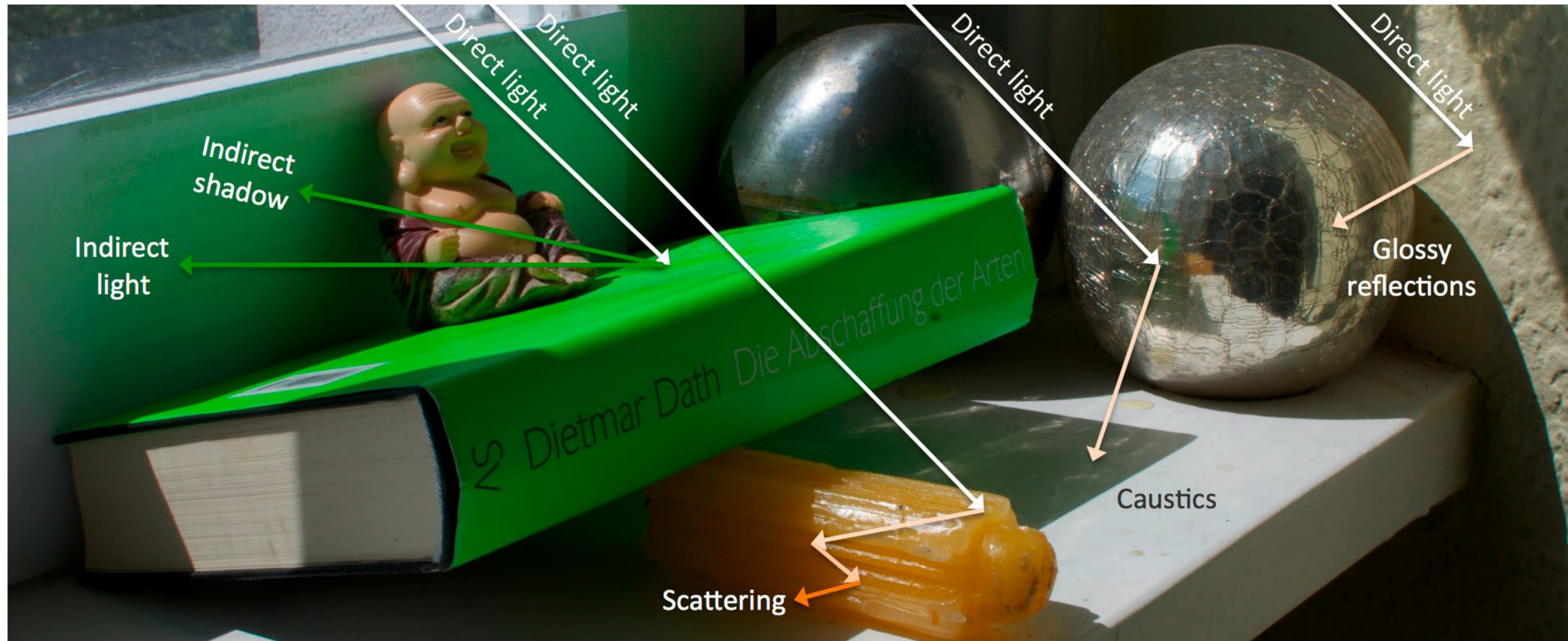
Indirect illumination



Direct + indirect illumination

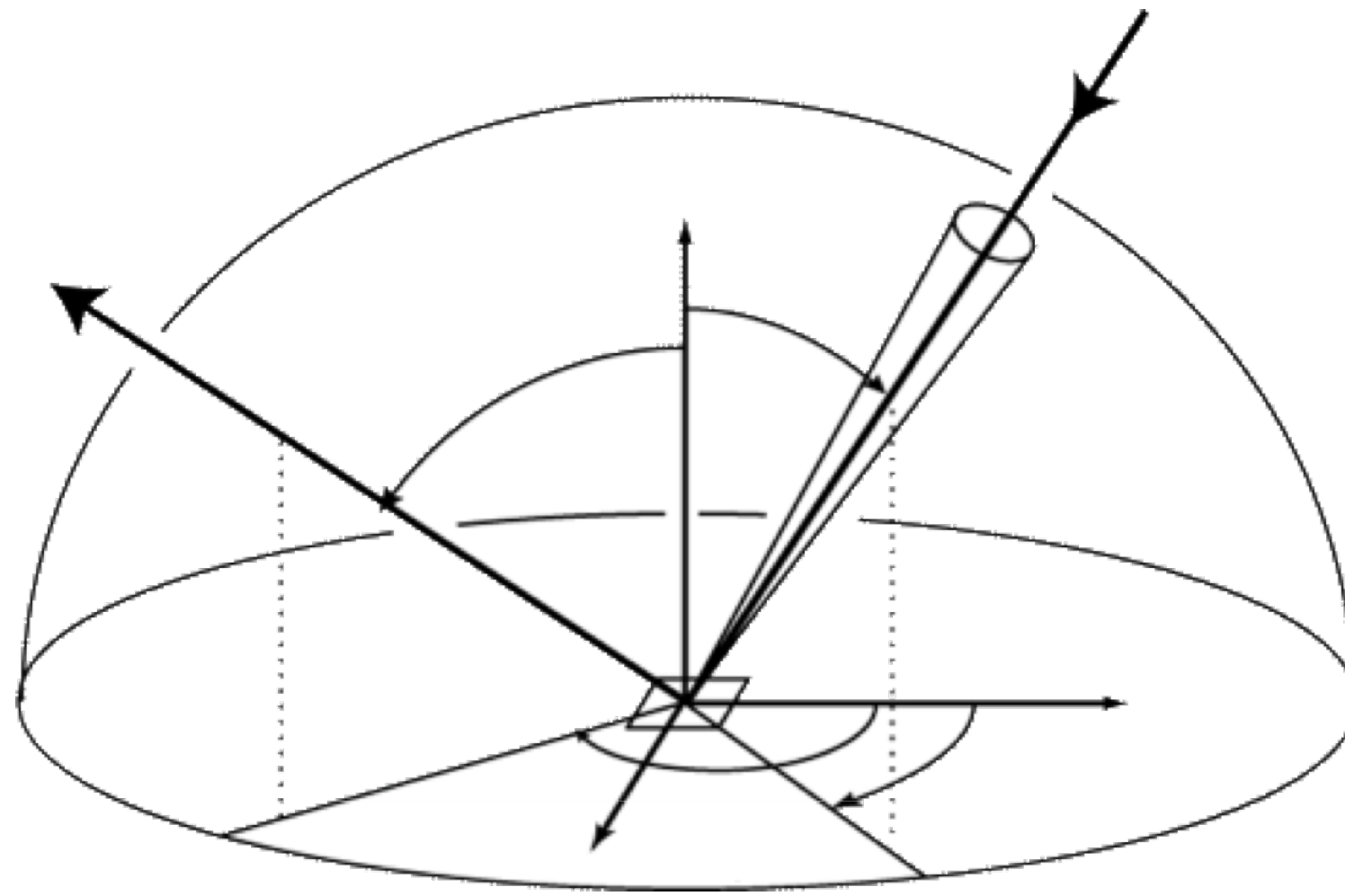


All-in-One!



Reflection Equation

Reflected radiance is the weighted integral of incident radiance



$$L_r(\mathbf{x}, \vec{\omega}_r) = \int_{H^2} f_r(\mathbf{x}, \vec{\omega}_i, \vec{\omega}_r) L_i(\mathbf{x}, \vec{\omega}_i) \cos \theta_i \, d\vec{\omega}_i$$

Rendering Equation

James Kajiya, “The Rendering Equation.”
SIGGRAPH 1986.

Energy equilibrium:



$$L_o(\mathbf{x}, \vec{\omega}_o) = L_e(\mathbf{x}, \vec{\omega}_o) + L_r(\mathbf{x}, \vec{\omega}_o)$$

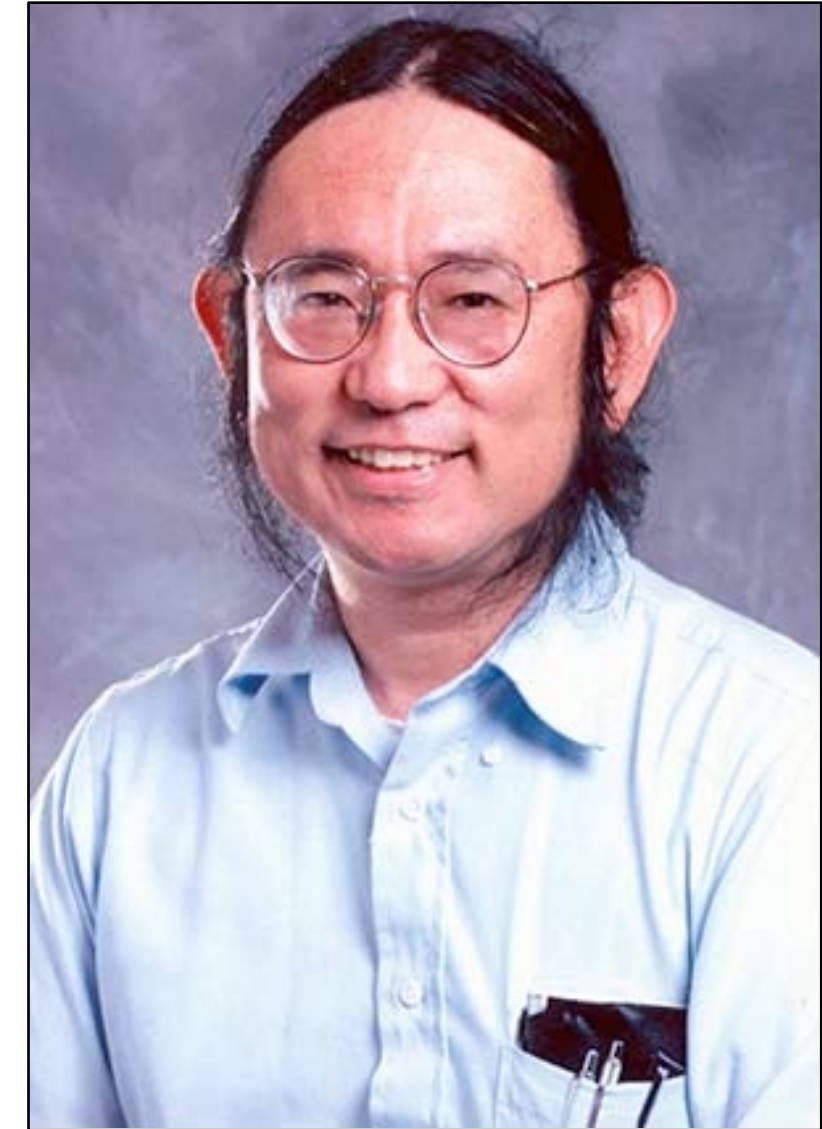
↑
outgoing

↑
emitted

↑
reflected

Rendering Equation

James Kajiya, “The Rendering Equation.”
SIGGRAPH 1986.



Energy equilibrium:

$$\boxed{L_o}(\mathbf{x}, \vec{\omega}_o) = L_e(\mathbf{x}, \vec{\omega}_o) + \int_{H^2} f_r(\mathbf{x}, \vec{\omega}_i, \vec{\omega}_o) \boxed{L_i}(\mathbf{x}, \vec{\omega}_i) \cos \theta_i \, d\vec{\omega}_i$$

Diagram illustrating the energy equilibrium equation:

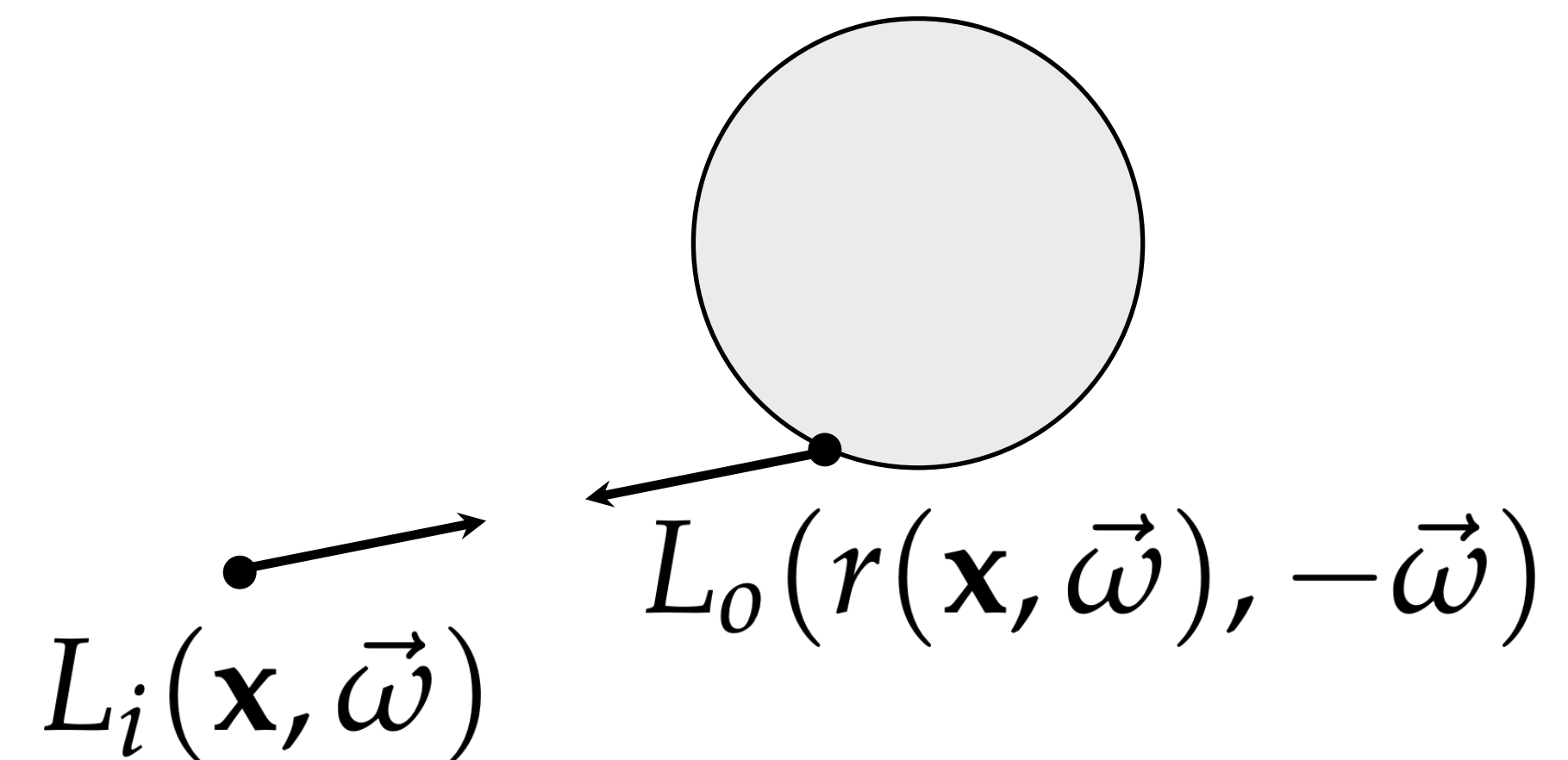
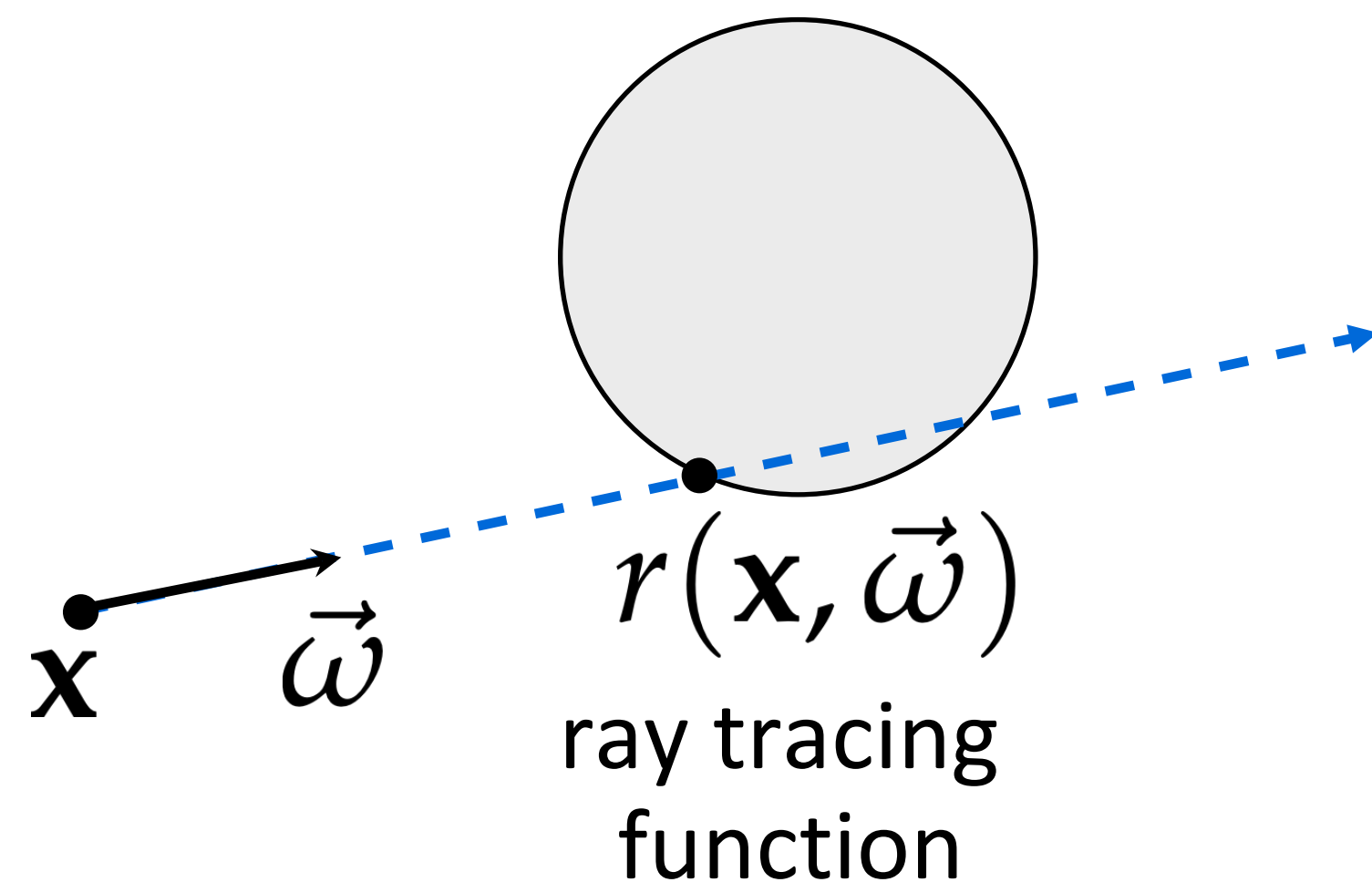
- $L_o(\mathbf{x}, \vec{\omega}_o)$ is labeled "outgoing".
- $L_e(\mathbf{x}, \vec{\omega}_o)$ is labeled "emitted".
- $L_i(\mathbf{x}, \vec{\omega}_i)$ is labeled "reflected".

Light Transport

In free-space/vacuum, radiance is constant along rays

We can relate incoming radiance to outgoing radiance

$$L_i(\mathbf{x}, \vec{\omega}) = L_o(r(\mathbf{x}, \vec{\omega}), -\vec{\omega})$$



Rendering Equation

ray tracing
function



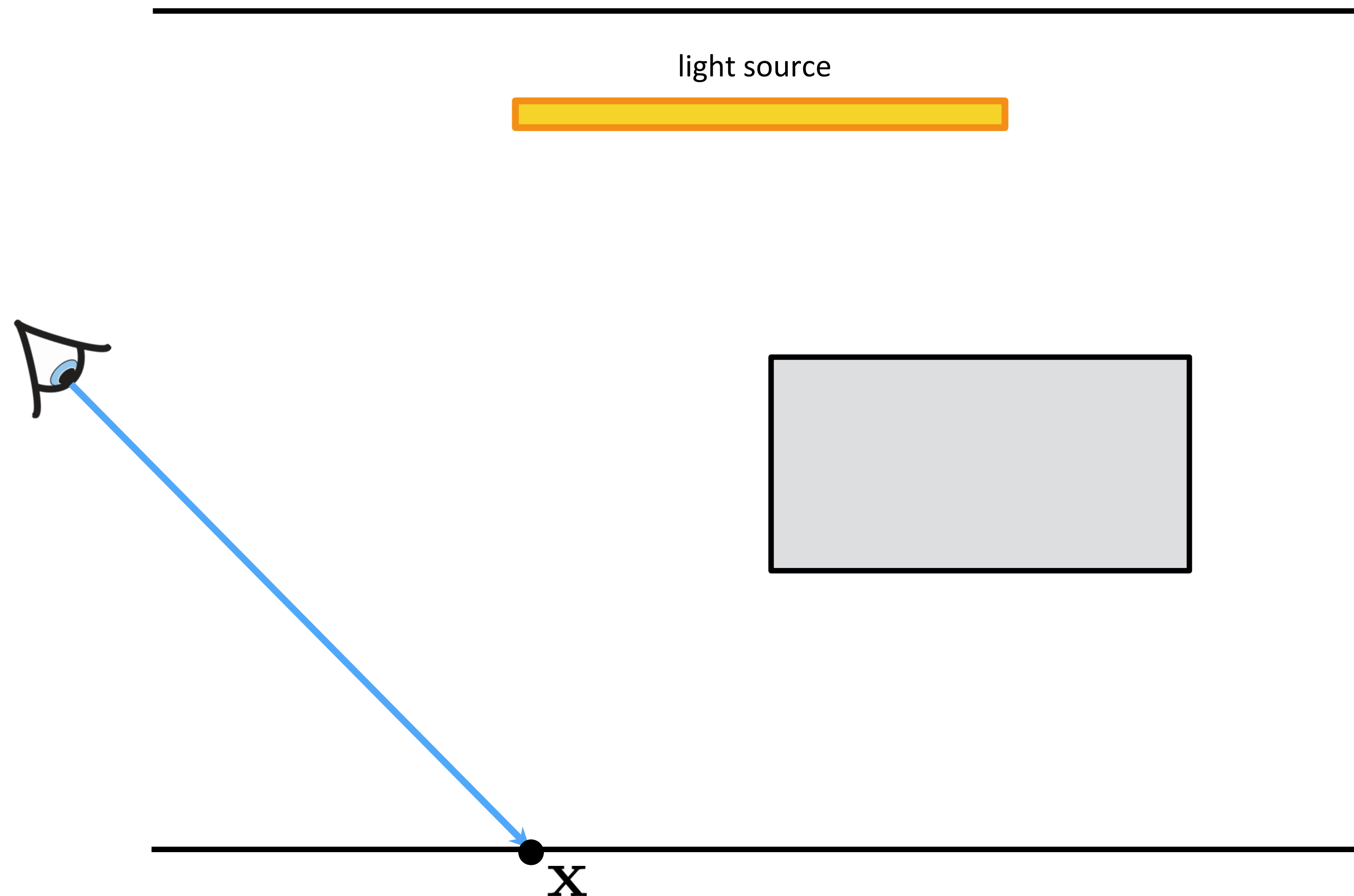
$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + \int_{H^2} f_r(\mathbf{x}, \vec{\omega}', \vec{\omega}) L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}') \cos \theta' d\vec{\omega}'$$

Only outgoing radiance on both sides

- we drop the “o” subscript
- Fredholm equation of the second kind (recursive)
- Extensive operator-theoretic study (that we will not cover here, but great reading group material)

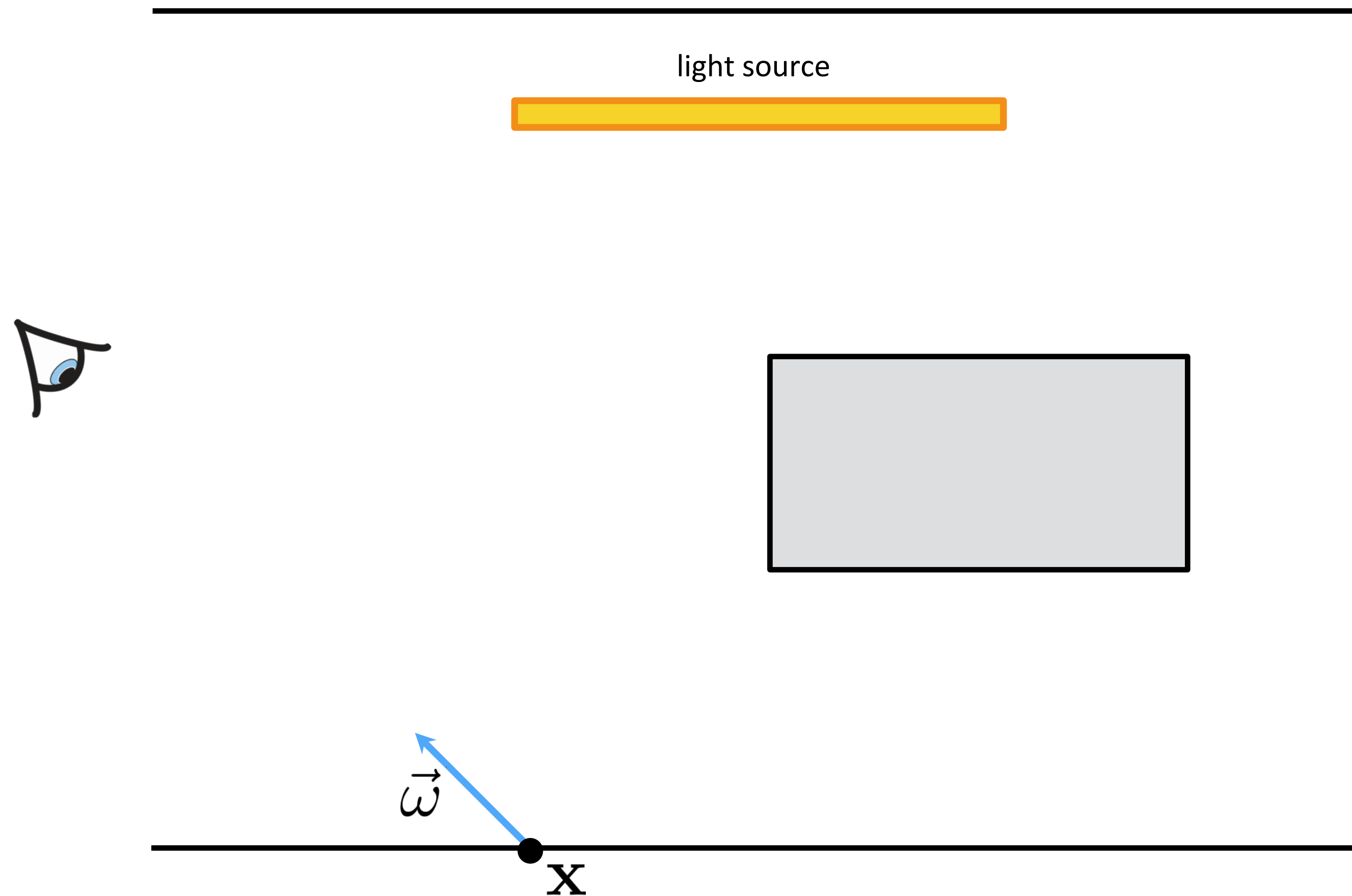
Rendering Equation

$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + \int_{H^2} f_r(\mathbf{x}, \vec{\omega}', \vec{\omega}) L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}') \cos \theta' d\vec{\omega}'$$



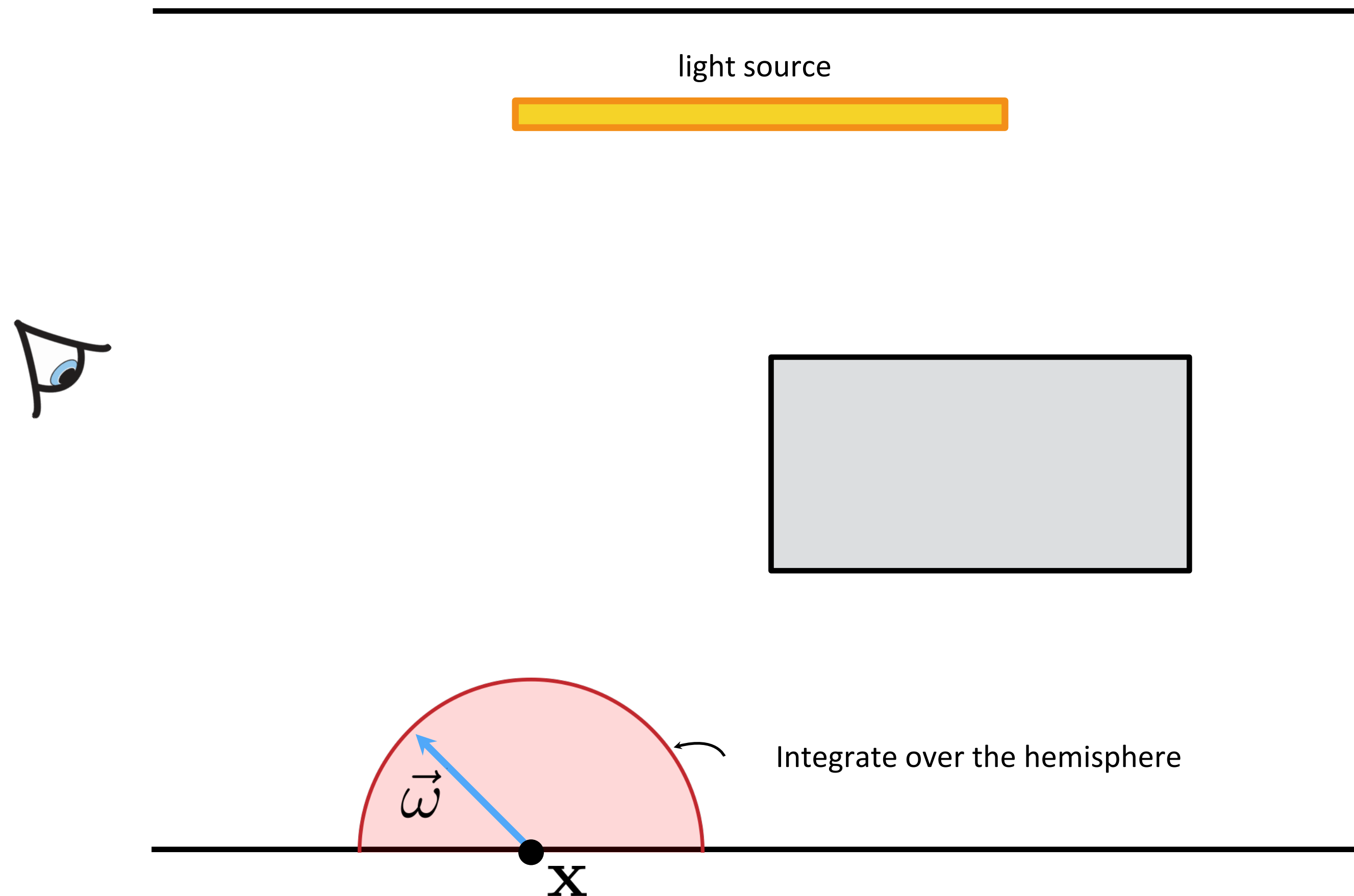
Rendering Equation

$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + \int_{H^2} f_r(\mathbf{x}, \vec{\omega}', \vec{\omega}) L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}') \cos \theta' d\vec{\omega}'$$



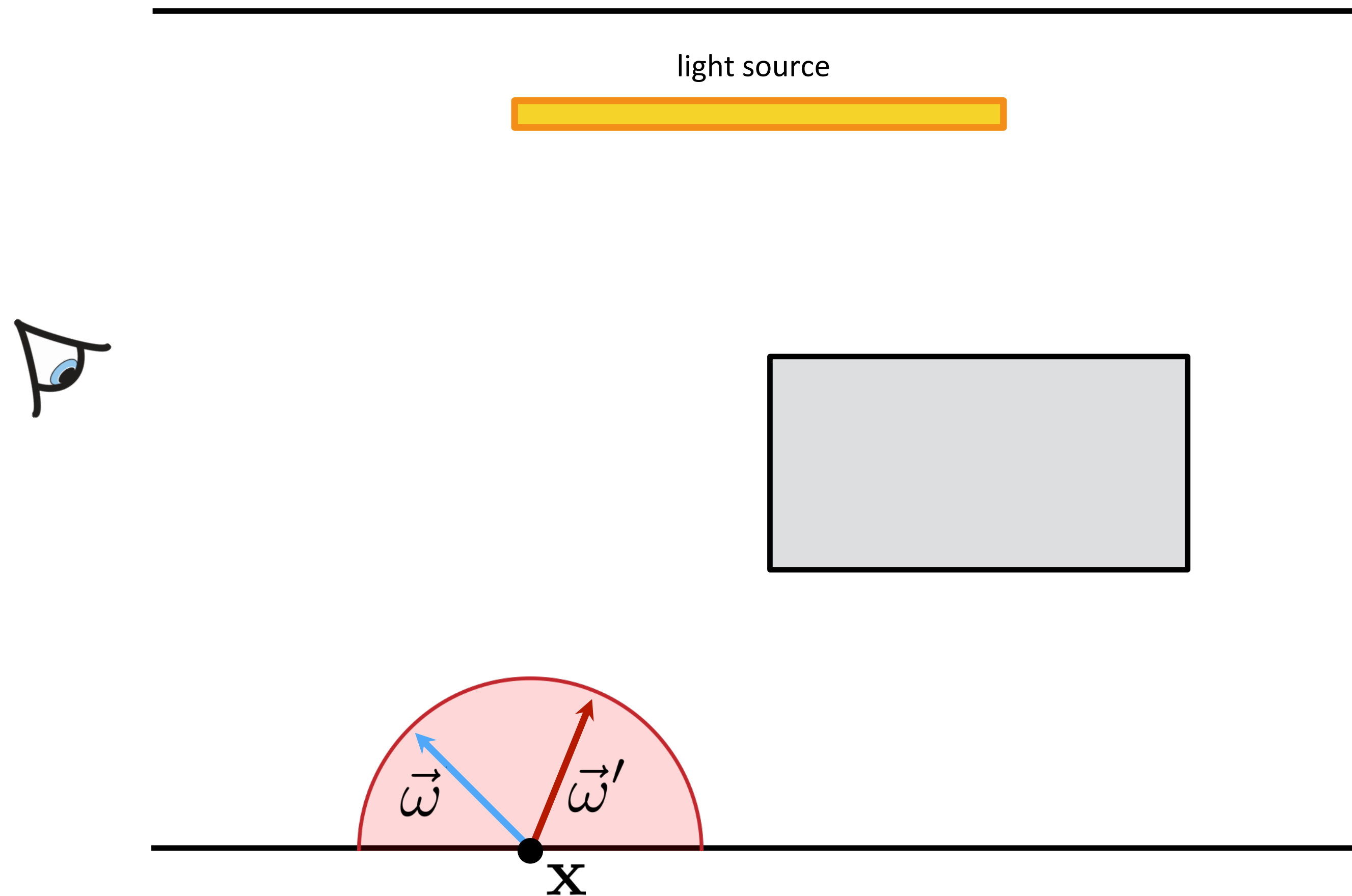
Rendering Equation

$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + \int_{H^2} f_r(\mathbf{x}, \vec{\omega}', \vec{\omega}) L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}') \cos \theta' d\vec{\omega}'$$



Rendering Equation

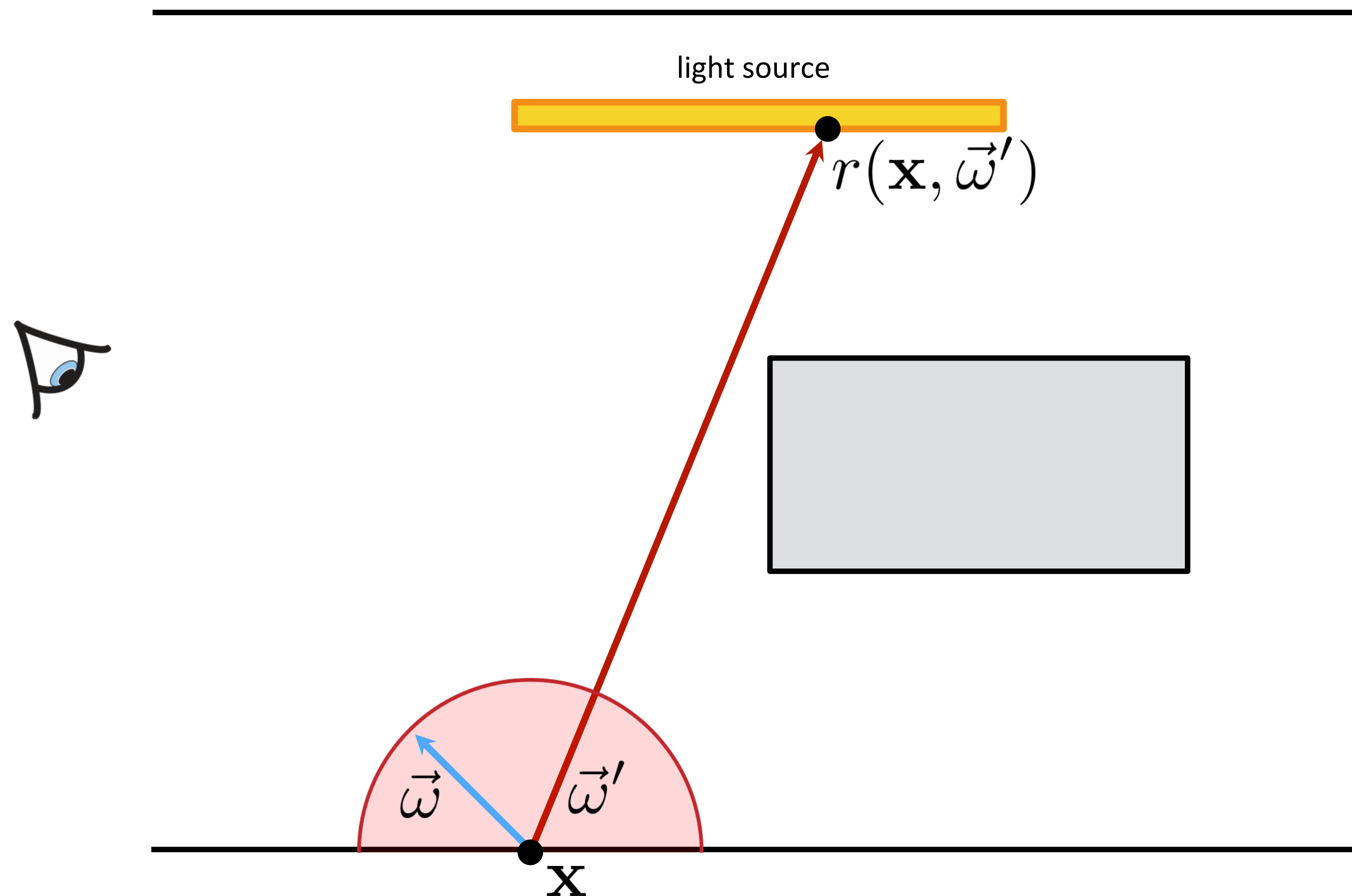
$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + \int_{H^2} f_r(\mathbf{x}, \vec{\omega}', \vec{\omega}) L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}') \cos \theta' d\vec{\omega}'$$



Rendering Equation

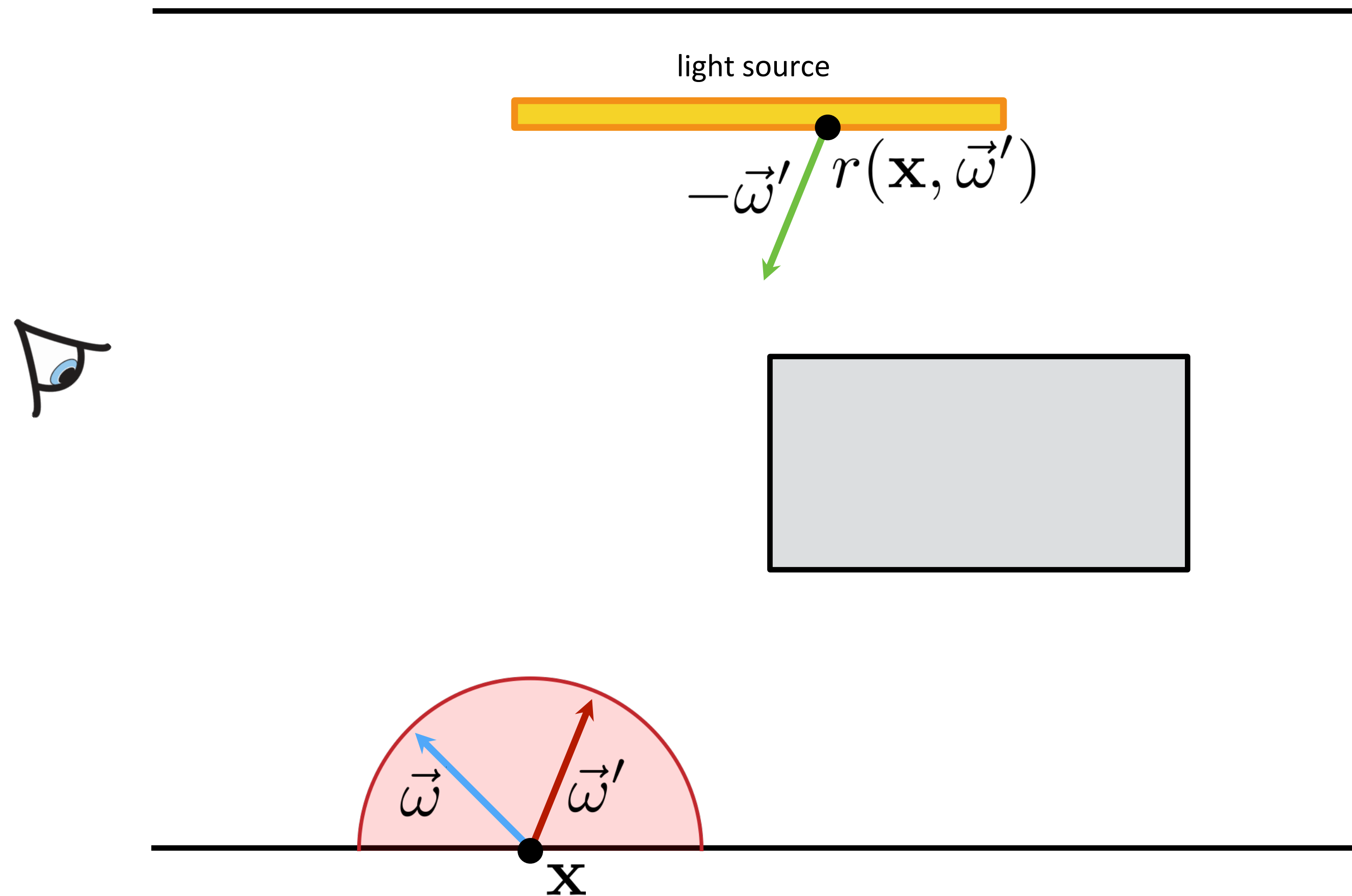
$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + \int_{H^2} f_r(\mathbf{x}, \vec{\omega}', \vec{\omega}) L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}') \cos \theta' d\vec{\omega}'$$

ray tracing
function



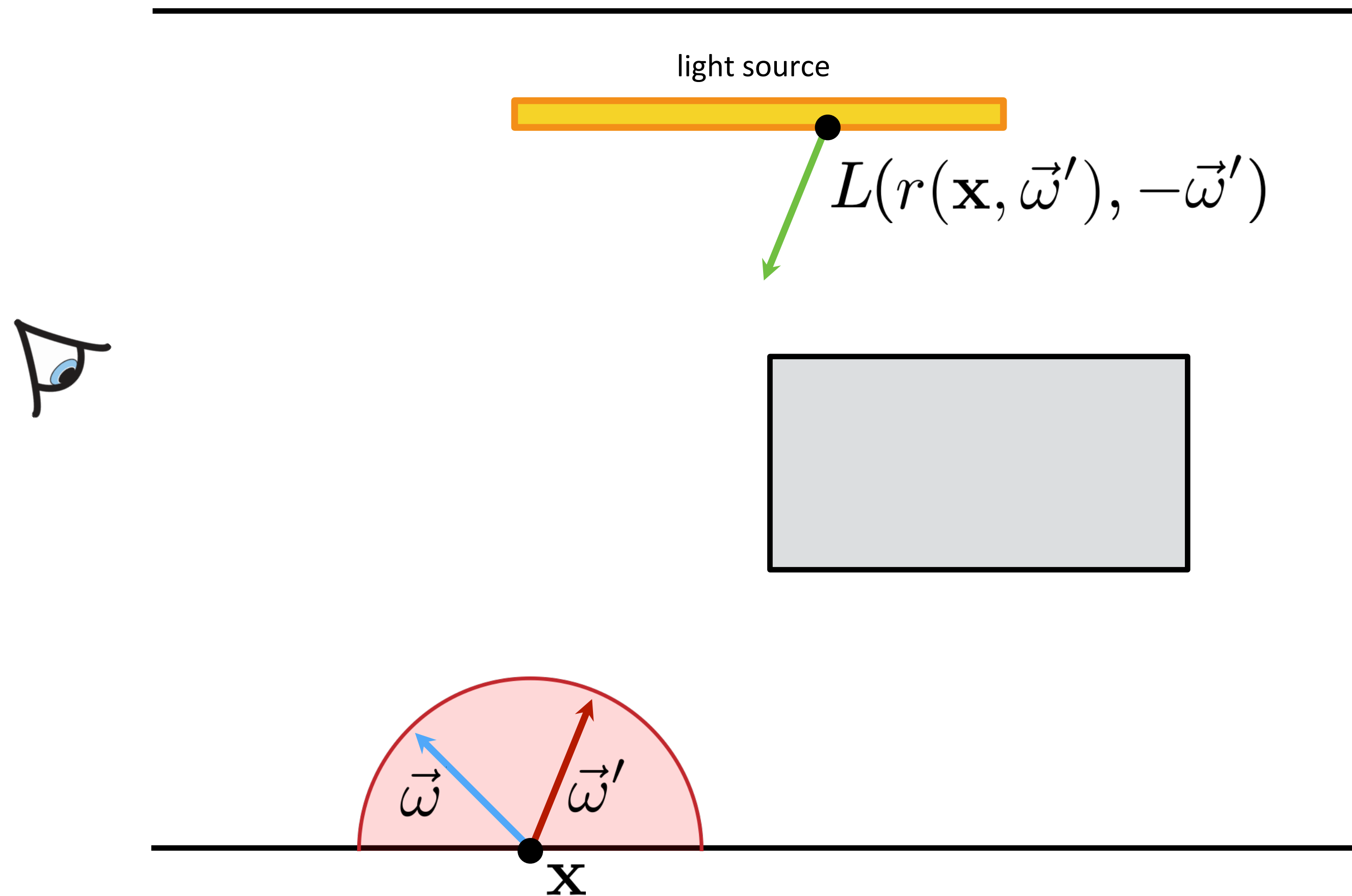
Rendering Equation

$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + \int_{H^2} f_r(\mathbf{x}, \vec{\omega}', \vec{\omega}) L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}') \cos \theta' d\vec{\omega}'$$



Rendering Equation

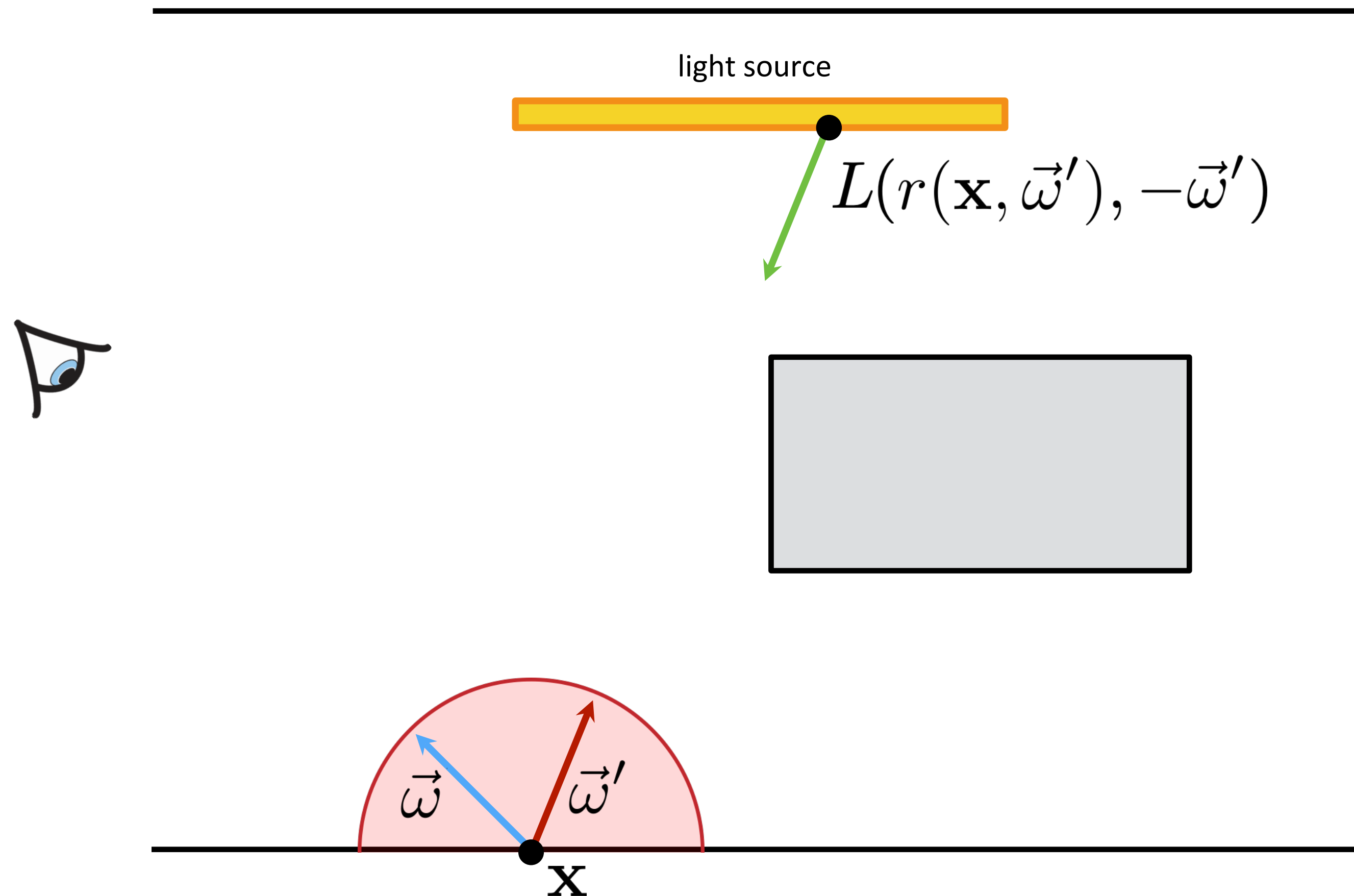
$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + \int_{H^2} f_r(\mathbf{x}, \vec{\omega}', \vec{\omega}) L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}') \cos \theta' d\vec{\omega}'$$



Rendering Equation

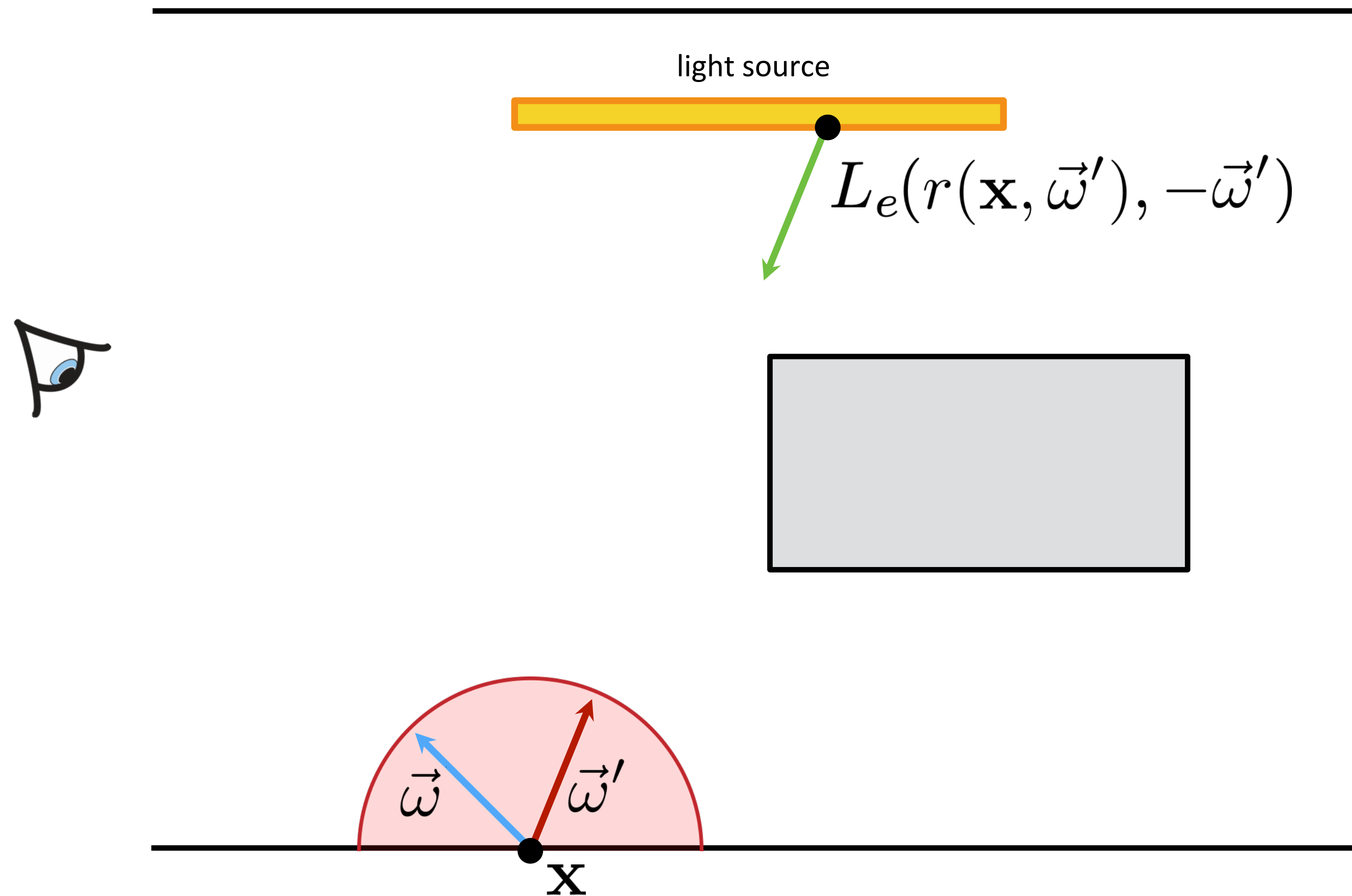
$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + \int_{H^2} f_r(\mathbf{x}, \vec{\omega}', \vec{\omega}) L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}') \cos \theta' d\vec{\omega}'$$

recursion



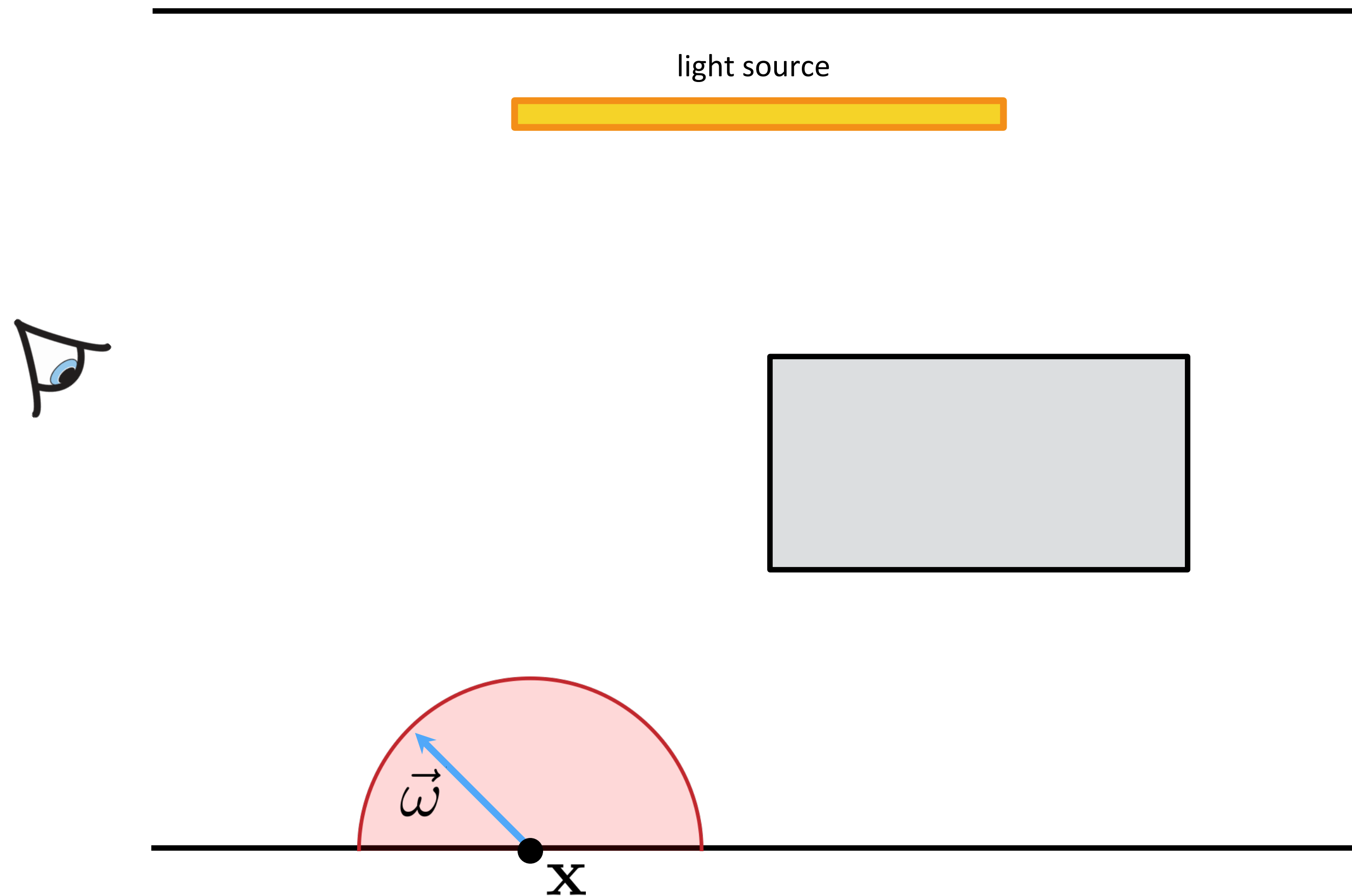
Rendering Equation

$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + \int_{H^2} f_r(\mathbf{x}, \vec{\omega}', \vec{\omega}) \boxed{L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}')} \cos \theta' d\vec{\omega}'$$



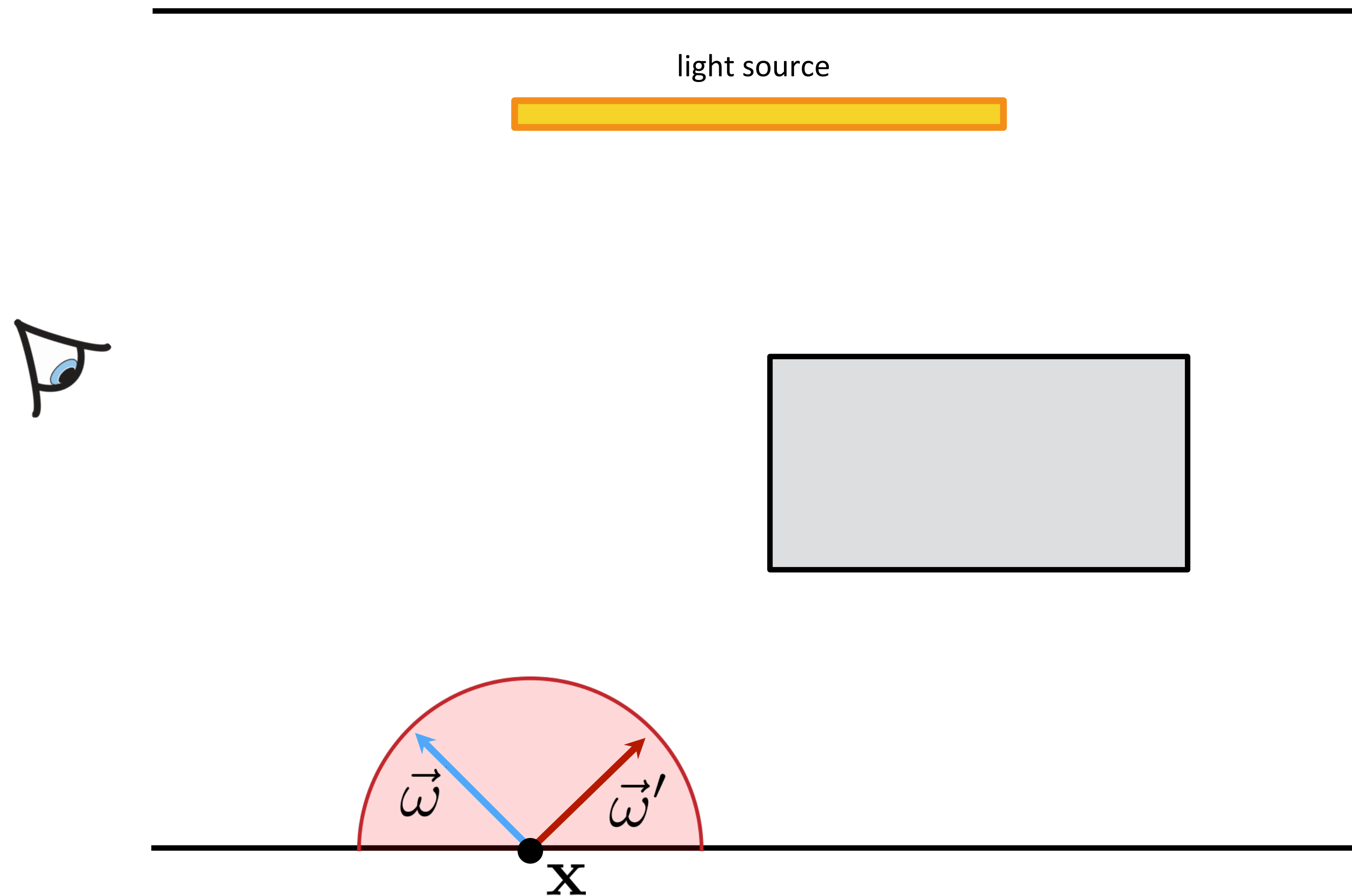
Rendering Equation

$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + \int_{H^2} f_r(\mathbf{x}, \vec{\omega}', \vec{\omega}) L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}') \cos \theta' d\vec{\omega}'$$



Rendering Equation

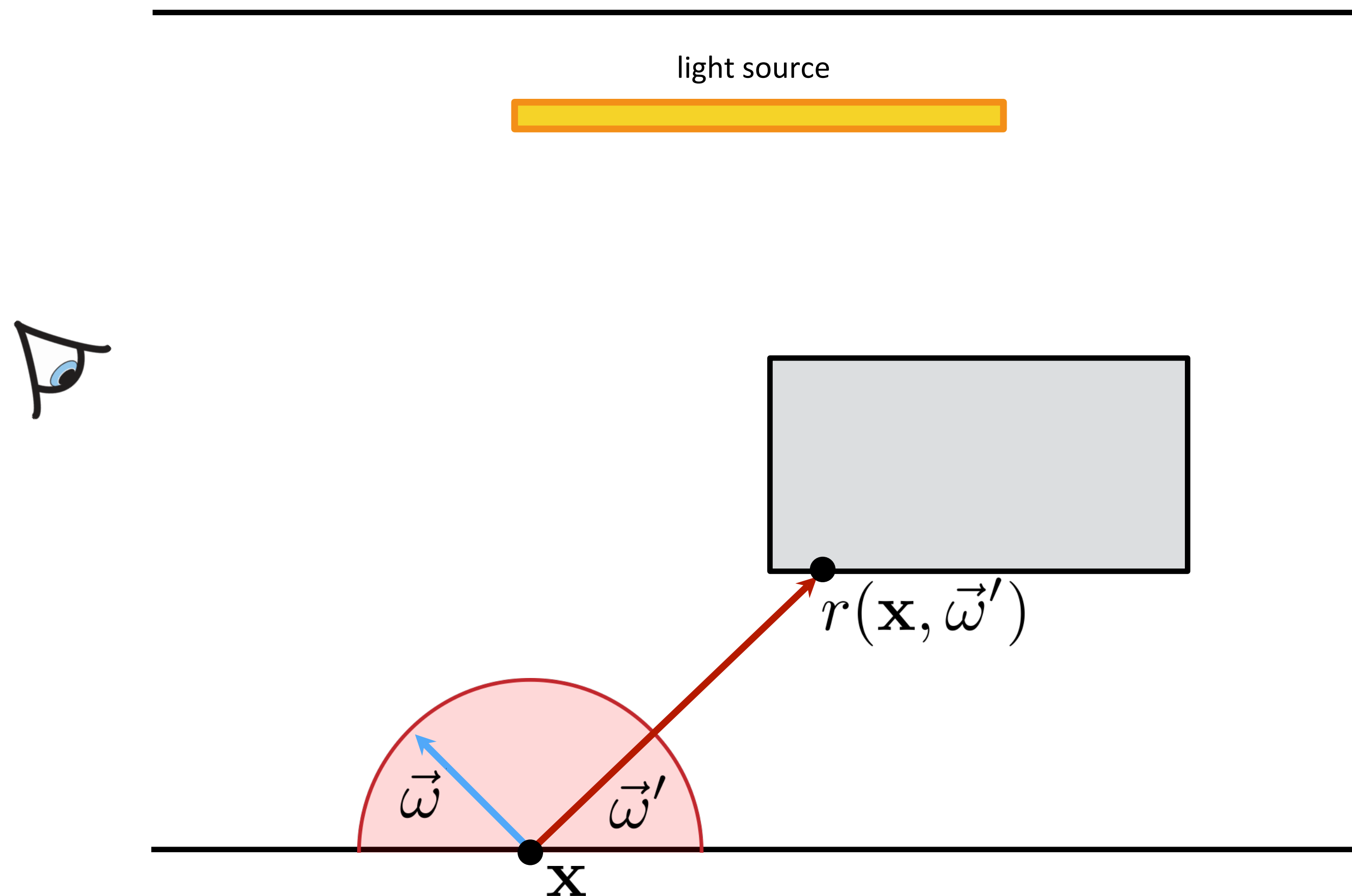
$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + \int_{H^2} f_r(\mathbf{x}, \vec{\omega}', \vec{\omega}) L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}') \cos \theta' d\vec{\omega}'$$



Rendering Equation

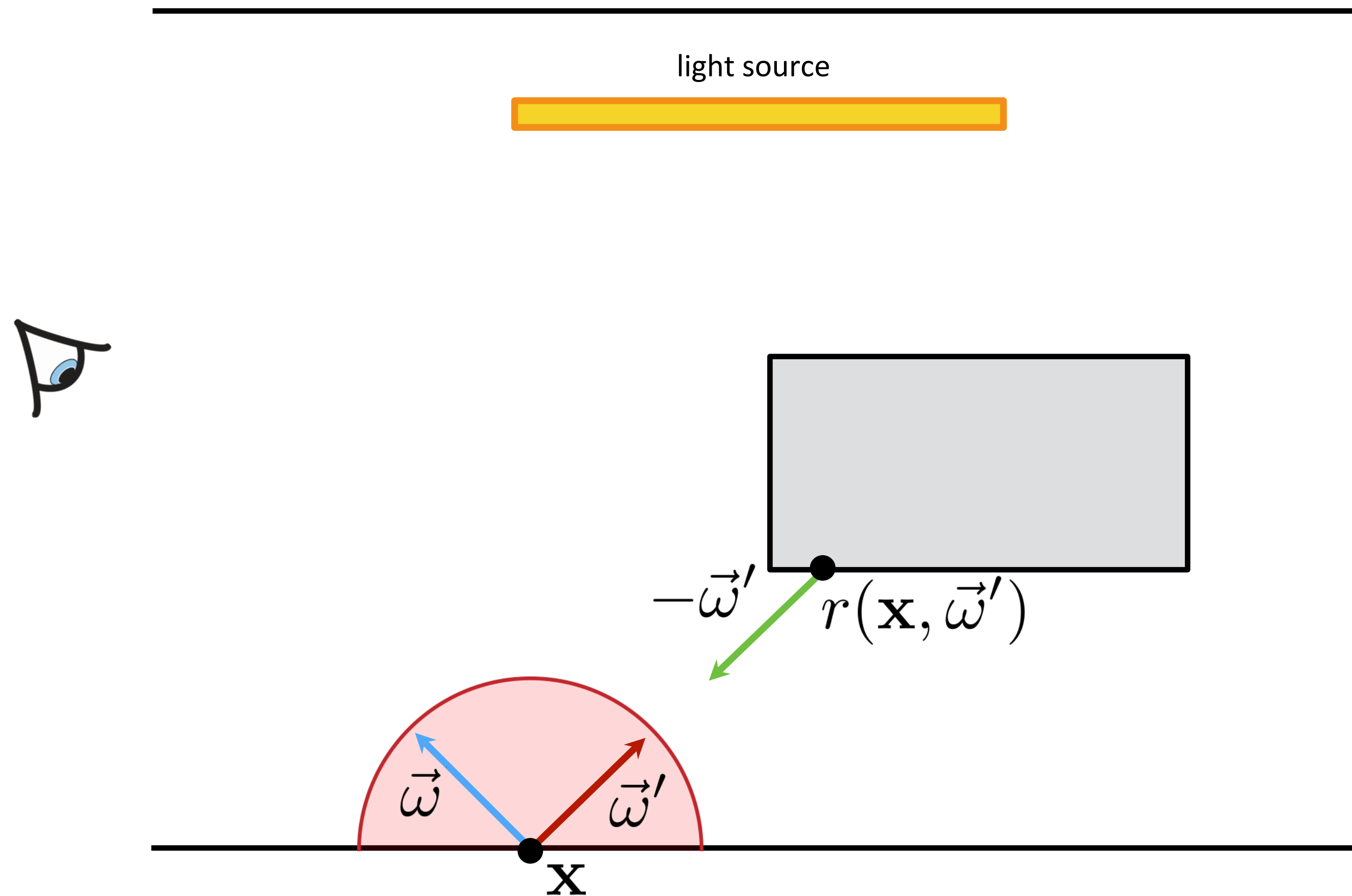
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ray tracing
function



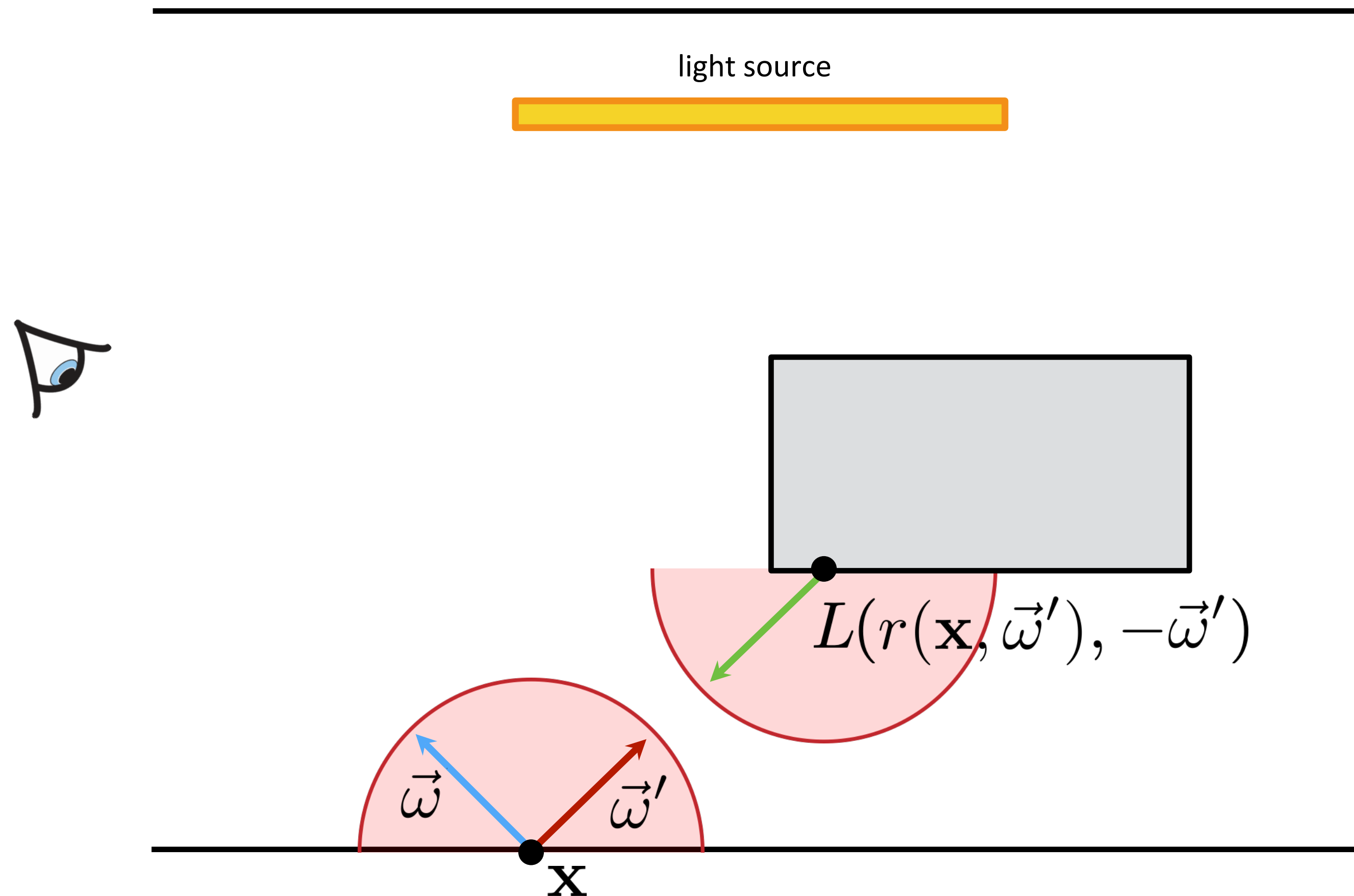
Rendering Equation

$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + \int_{H^2} f_r(\mathbf{x}, \vec{\omega}', \vec{\omega}) L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}') \cos \theta' d\vec{\omega}'$$



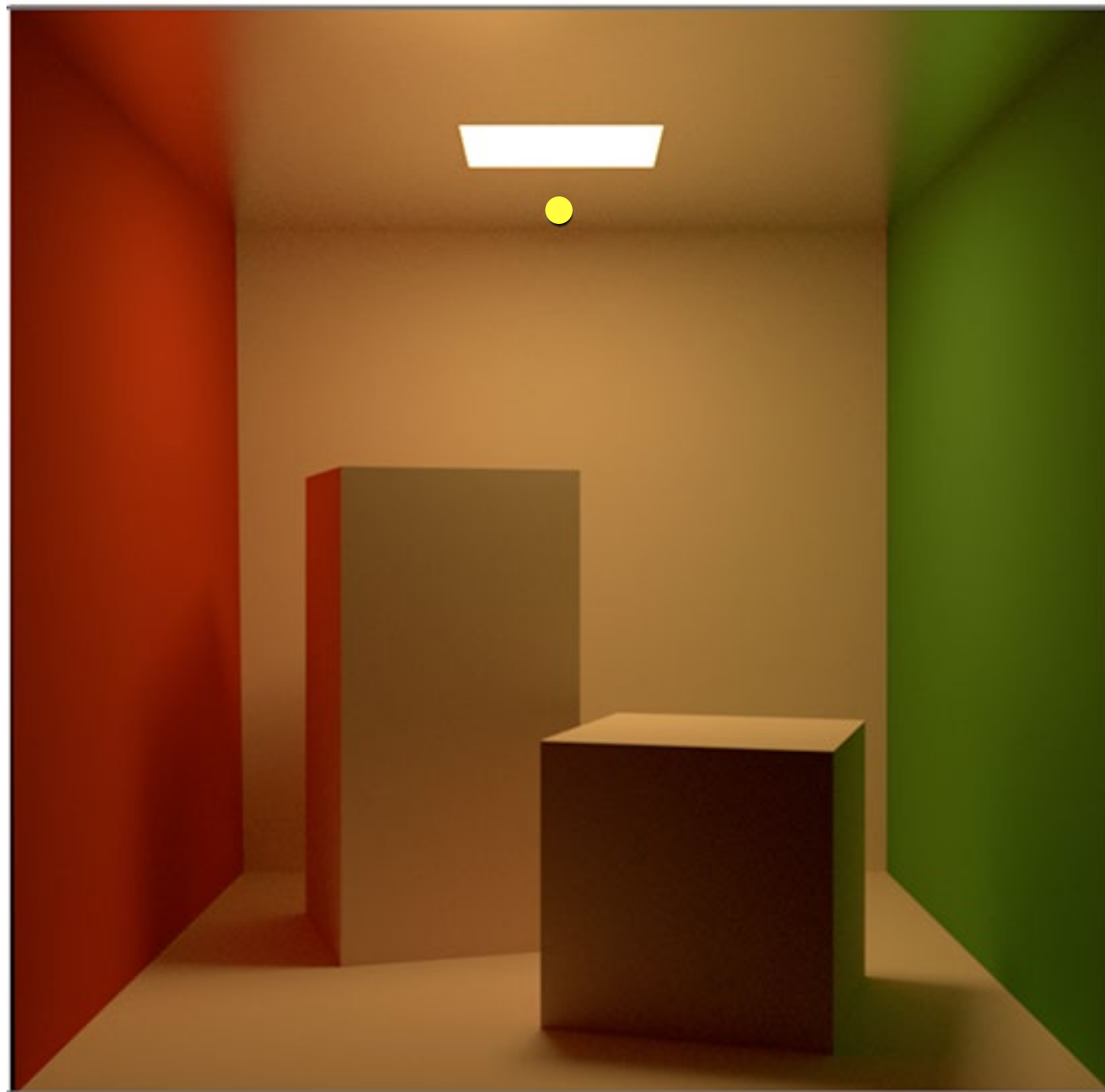
Rendering Equation

$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + \int_{H^2} f_r(\mathbf{x}, \vec{\omega}', \vec{\omega}) \underbrace{L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}')}_{\text{recursion}} \cos \theta' d\vec{\omega}'$$



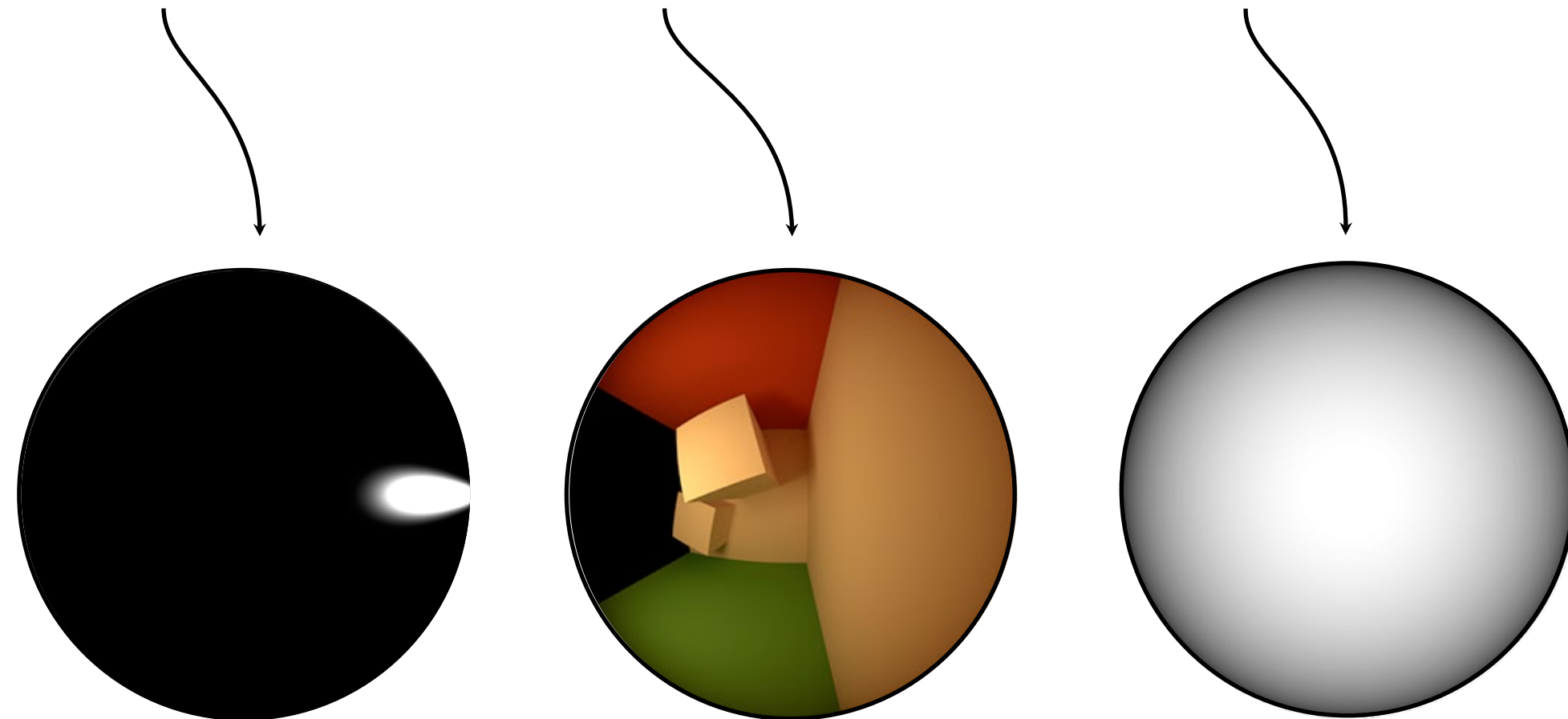
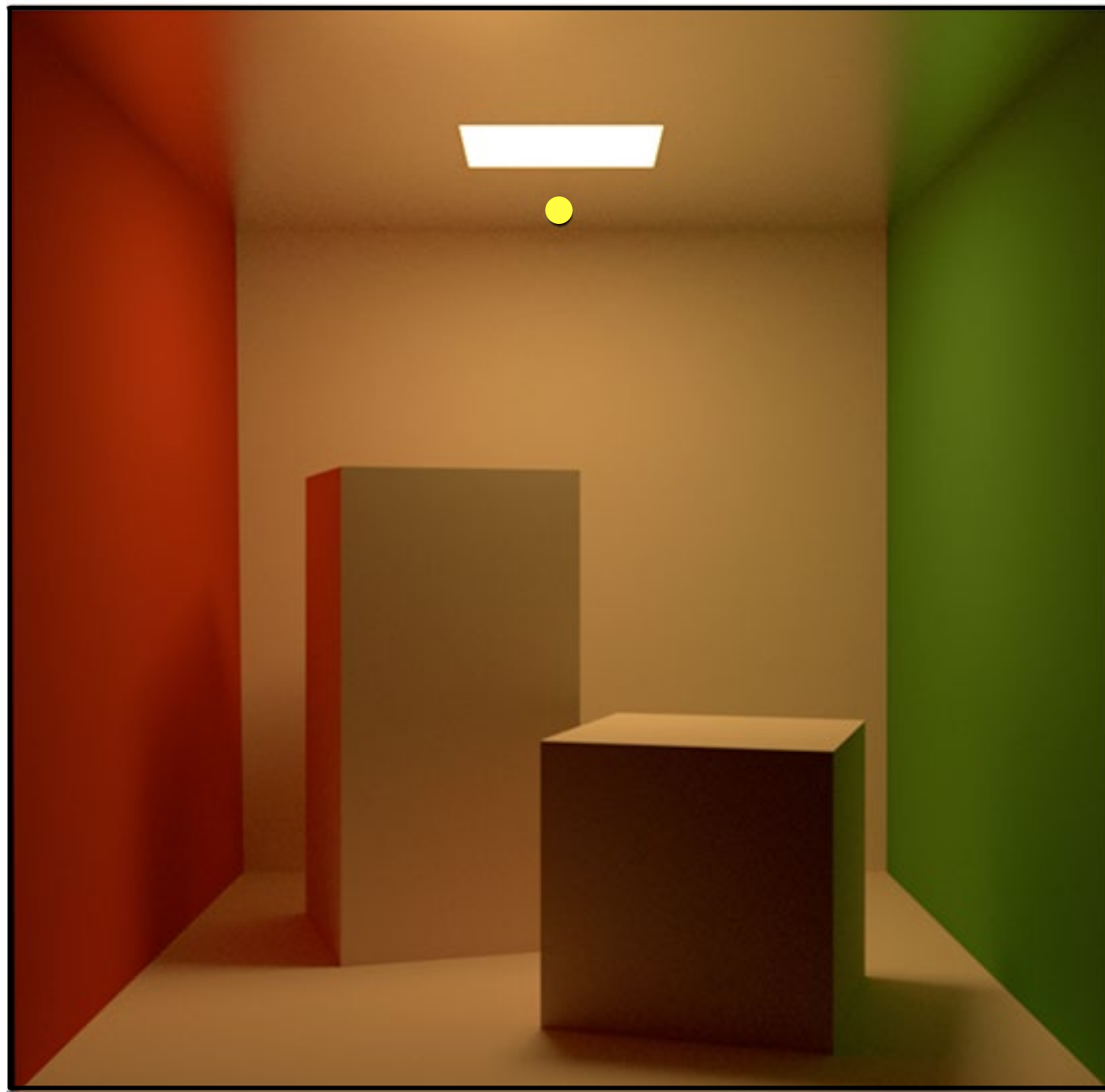
Rendering Equation

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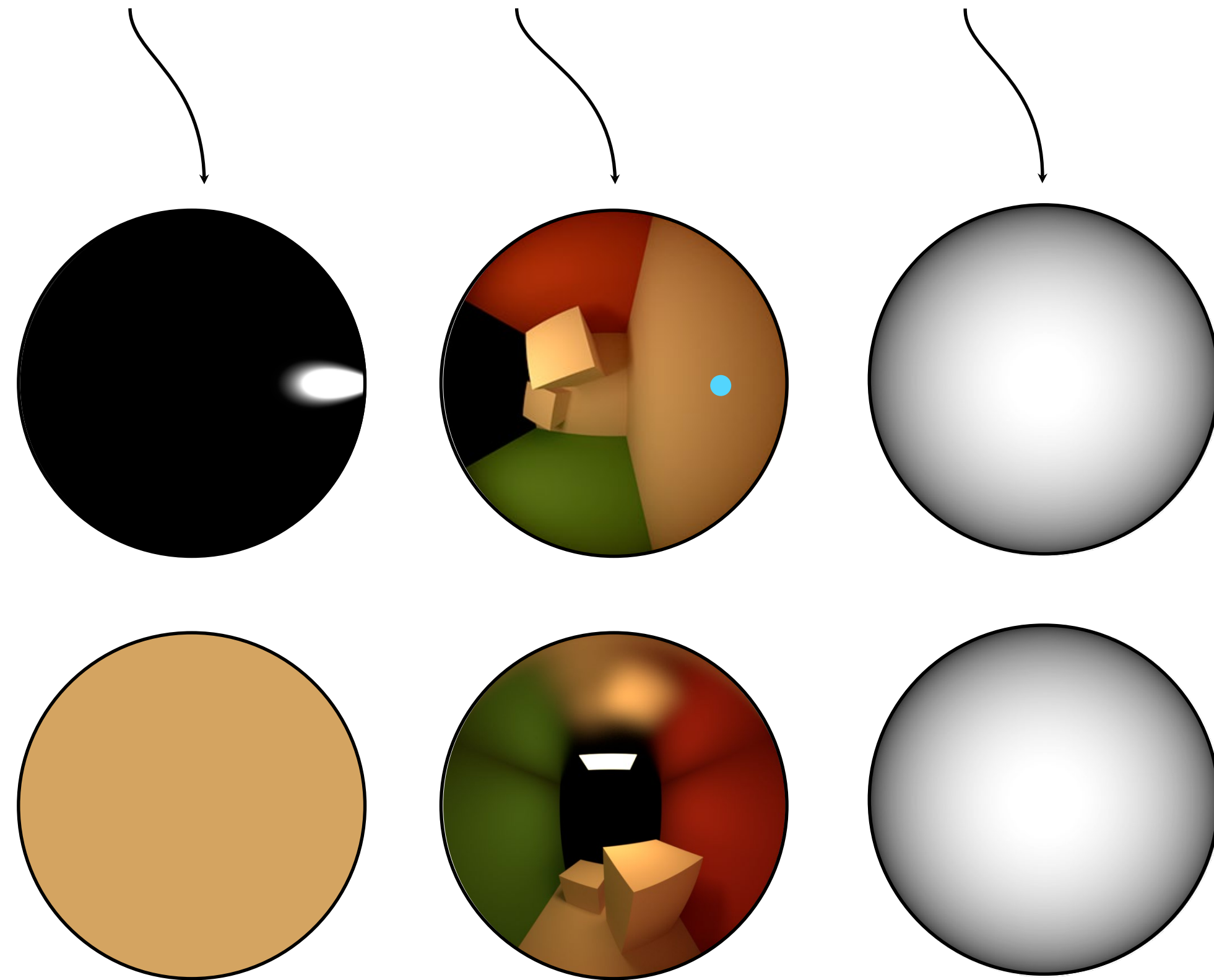
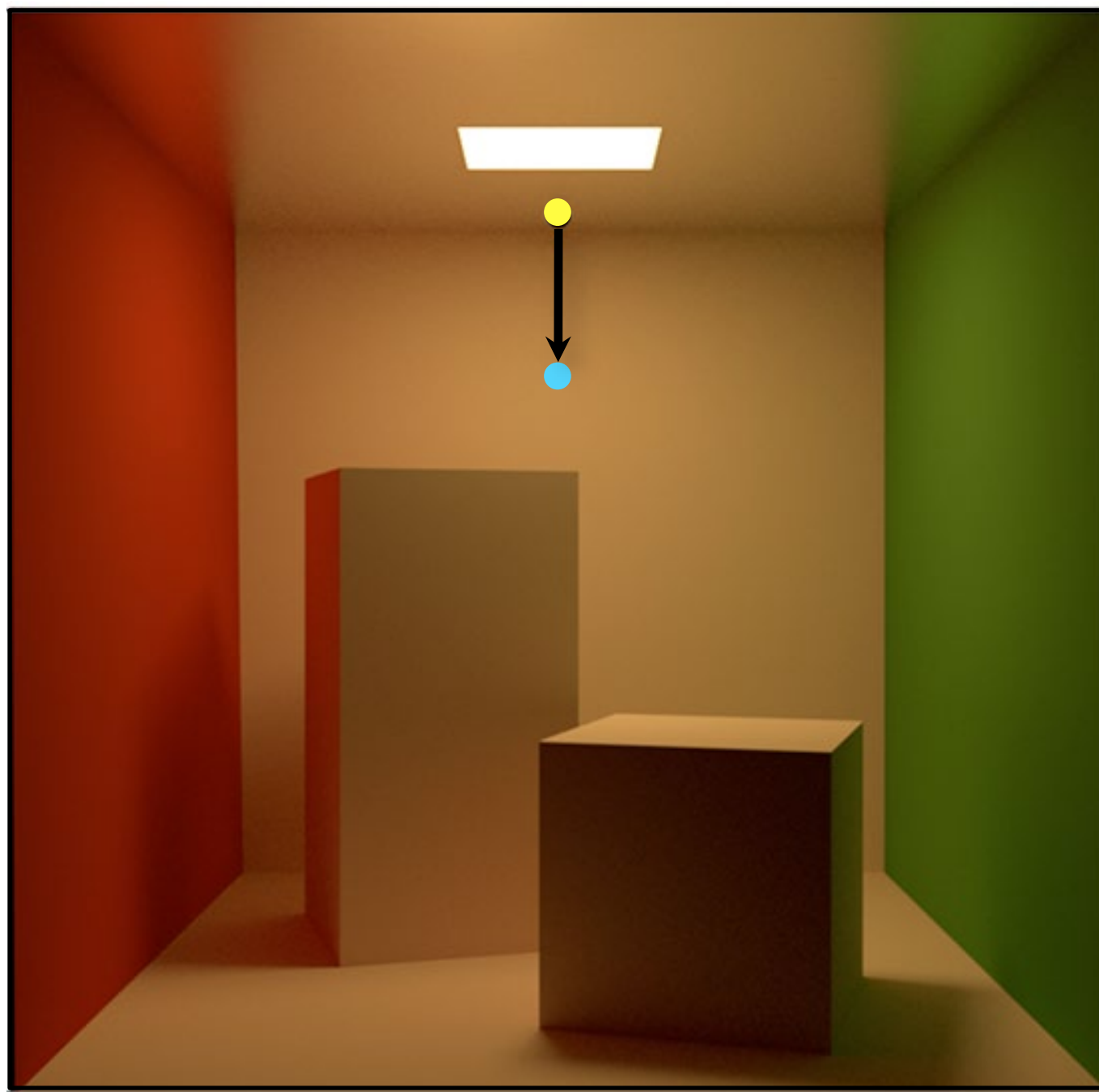
Rendering Equation

$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + \int_{H^2} f_r(\mathbf{x}, \vec{\omega}', \vec{\omega}) L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}') \cos \theta' d\vec{\omega}'$$



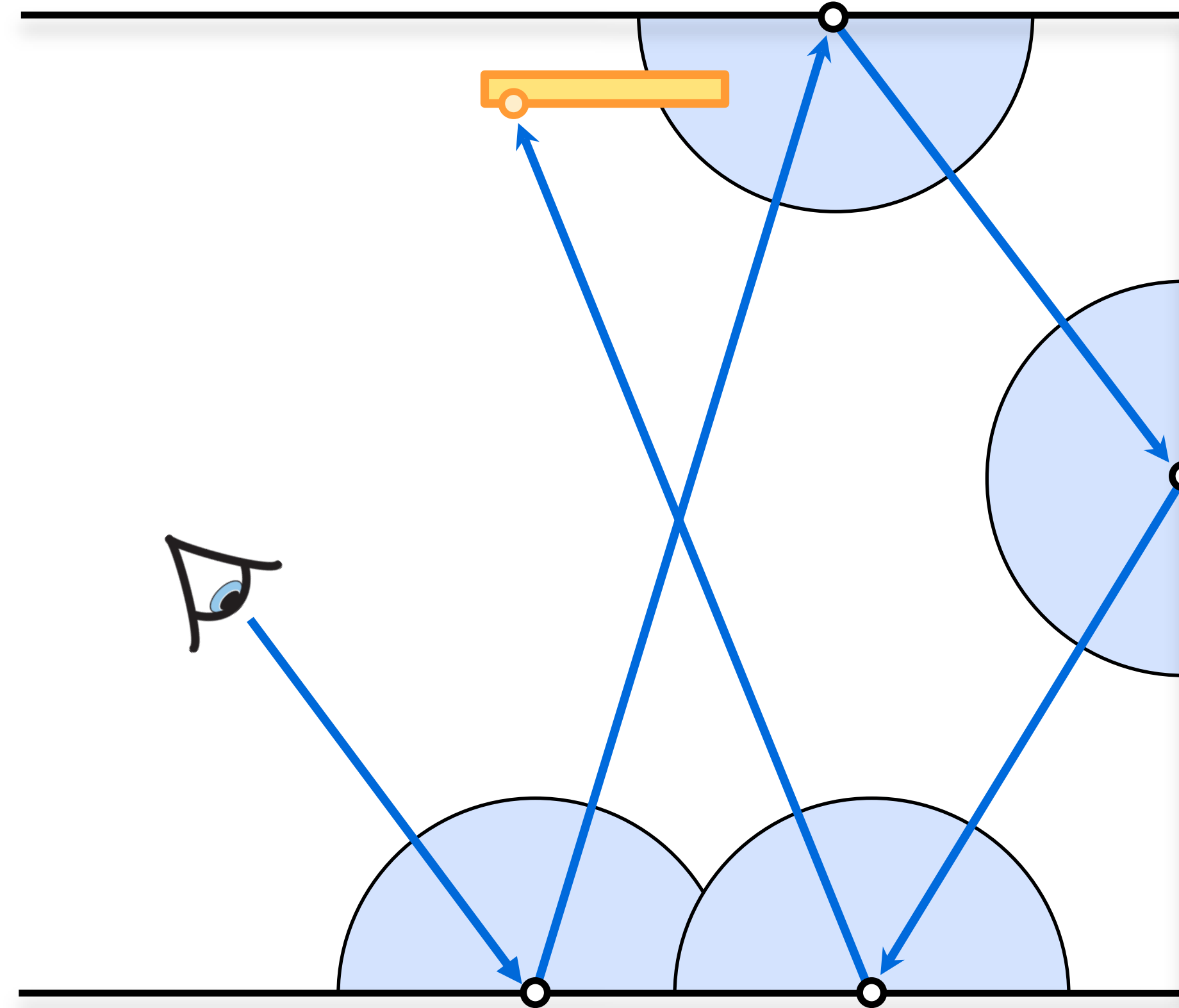
Rendering Equation

$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + \int_{H^2} f_r(\mathbf{x}, \vec{\omega}', \vec{\omega}) L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}') \cos \theta' d\vec{\omega}'$$



Path Tracing

Path Tracing



$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + \int_{H^2} f_r(\vec{\mathbf{x}}, \vec{\omega}', \vec{\omega}) L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}') \cos \theta' d\vec{\omega}'$$

$$L(\mathbf{x}, \vec{\omega}) \approx L_e(\mathbf{x}, \vec{\omega}) + \frac{f_r(\vec{\mathbf{x}}, \vec{\omega}', \vec{\omega}) L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}') \cos \theta'}{p(\vec{\omega}')}$$

Path Tracing Algorithm

$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + L_r(\mathbf{x}, \vec{\omega})$$

Color color(**Point** \mathbf{x} , **Direction** ω , **int** moreBounces):

if not moreBounces:

return $L_e(\mathbf{x}, -\omega)$

// sample recursive integral

ω' = sample from BRDF

return $L_e(\mathbf{x}, -\omega) + \text{BRDF} * \text{color}(\text{trace}(\mathbf{x}, \omega'), \text{moreBounces}-1) * \text{dot}(\mathbf{n}, \omega') / \text{pdf}(\omega')$

Partitioning the Integrand

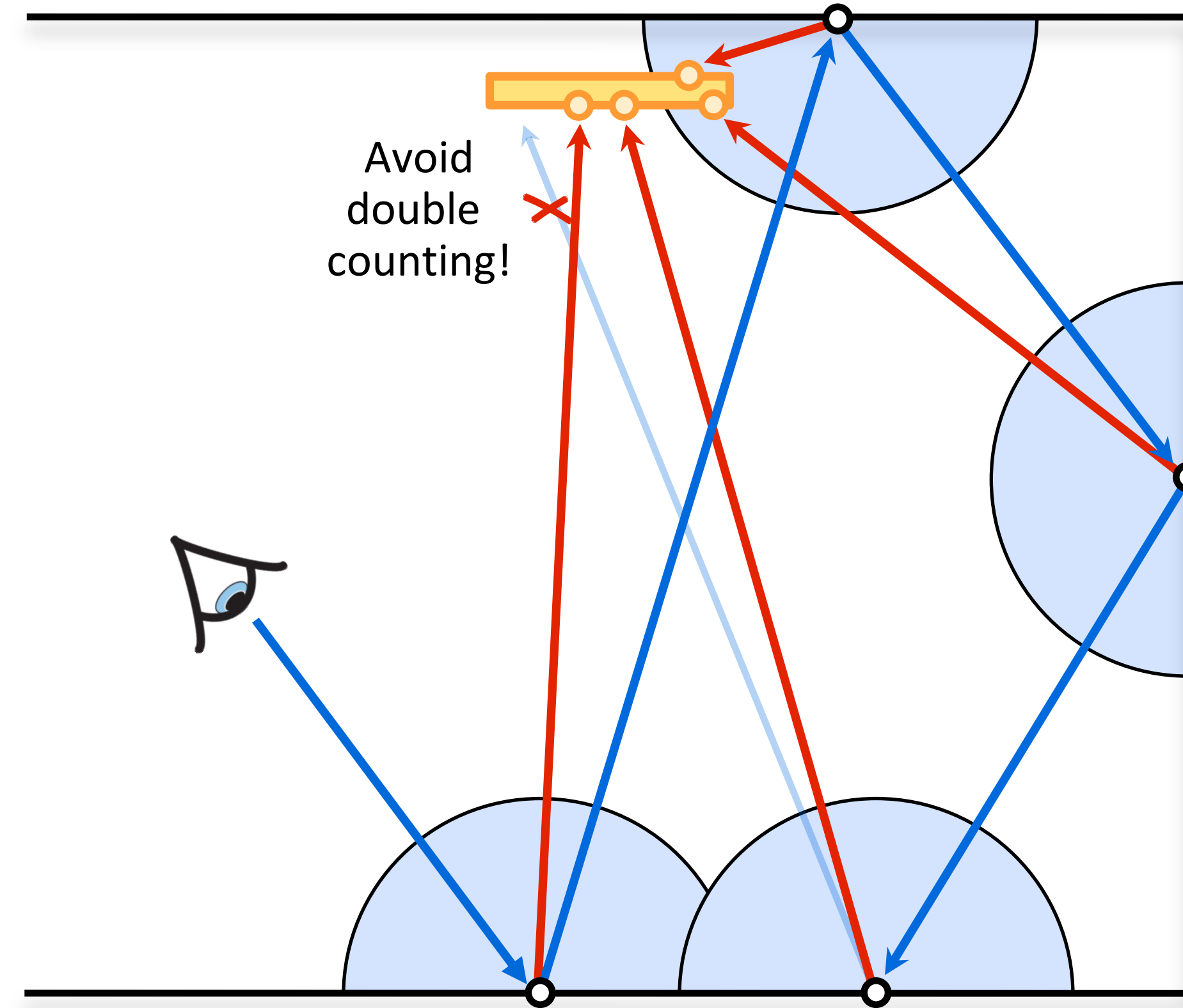
Direct illumination: sometimes better estimated by sampling emissive surfaces

Let's estimate direct illumination separately from indirect illumination, then add the two

- i.e. shoot shadow rays (direct) and gather rays (indirect)
- be careful not to double-count!

Also known as ***next-event estimation (NEE)***

Path Tracing with NEE



$$L(\mathbf{x}, \vec{\omega}) = L_e + \int_{A_e} \cdots L_e(\mathbf{x} \leftarrow \mathbf{x}') \cdots dA_e(\mathbf{x}') + \int_{H^2 \setminus A_e} \cdots L(\mathbf{x}, \vec{\omega}') \cdots d\vec{\omega}'$$

Path Tracing Algorithm with NEE

$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + L_{\text{dir}}(\mathbf{x}, \vec{\omega}) + L_{\text{ind}}(\mathbf{x}, \vec{\omega})$$

Color color(**Point** \mathbf{x} , **Direction** ω , **int** moreBounces):

if not moreBounces:
 return L_e ;

double counting!

// next-event estimation: compute L_{dir} by sampling the light

ω_1 = sample from light

$L_{\text{dir}} = \text{BRDF} * \text{color}(\text{trace}(\mathbf{x}, \omega_1), 0) * \text{dot}(\mathbf{n}, \omega_1) / \text{pdf}(\omega_1)$

// compute L_{ind} by sampling the BSDF

ω_2 = sample from BSDF;

$L_{\text{ind}} = \text{BSDF} * \text{color}(\text{trace}(\mathbf{x}, \omega_2), \text{moreBounces}-1) * \text{dot}(\mathbf{n}, \omega_2) / \text{pdf}(\omega_2)$

return $L_e + L_{\text{dir}} + L_{\text{ind}}$

Path Tracing Algorithm with NEE

$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + L_{\text{dir}}(\mathbf{x}, \vec{\omega}) + L_{\text{ind}}(\mathbf{x}, \vec{\omega})$$

Color color(**Point** \mathbf{x} , **Direction** ω , **int** moreBounces, **bool** includeLe):

$L_e = \text{includeLe} ? L_e(\mathbf{x}, -\omega) : \text{black}$

if not moreBounces:
 return L_e

// next-event estimation: compute L_{dir} by sampling the light

$\omega_1 = \text{sample from light}$

$L_{\text{dir}} = \text{BRDF} * \text{color}(\text{trace}(\mathbf{x}, \omega_1), 0, \text{true}) * \text{dot}(\mathbf{n}, \omega_1) / \text{pdf}(\omega_1)$

// compute L_{ind} by sampling the BSDF

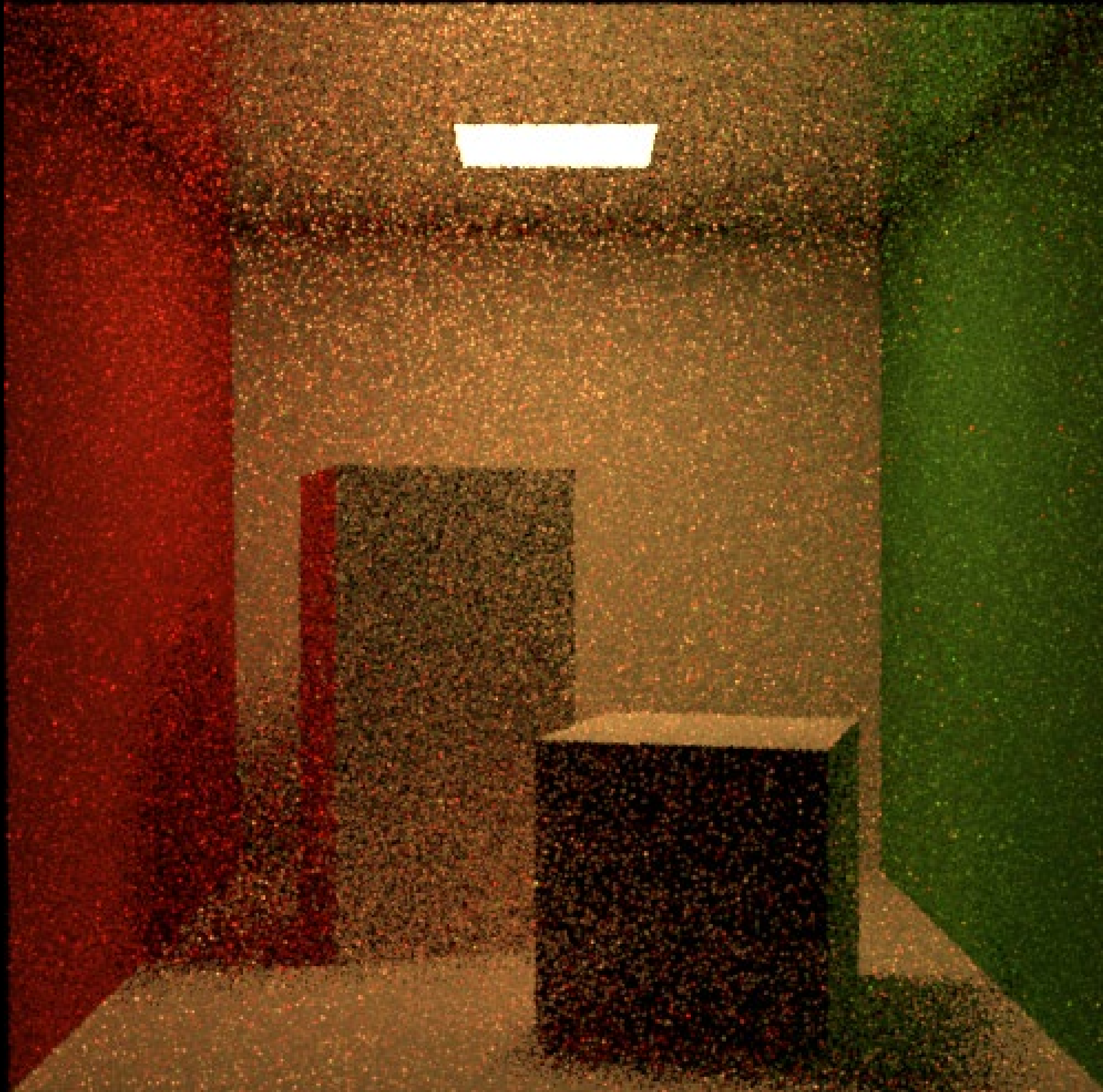
$\omega_2 = \text{sample from BSDF}$

$L_{\text{ind}} = \text{BSDF} * \text{color}(\text{trace}(\mathbf{x}, \omega_2), \text{moreBounces}-1, \text{false}) * \text{dot}(\mathbf{n}, \omega_2) / \text{pdf}(\omega_2)$

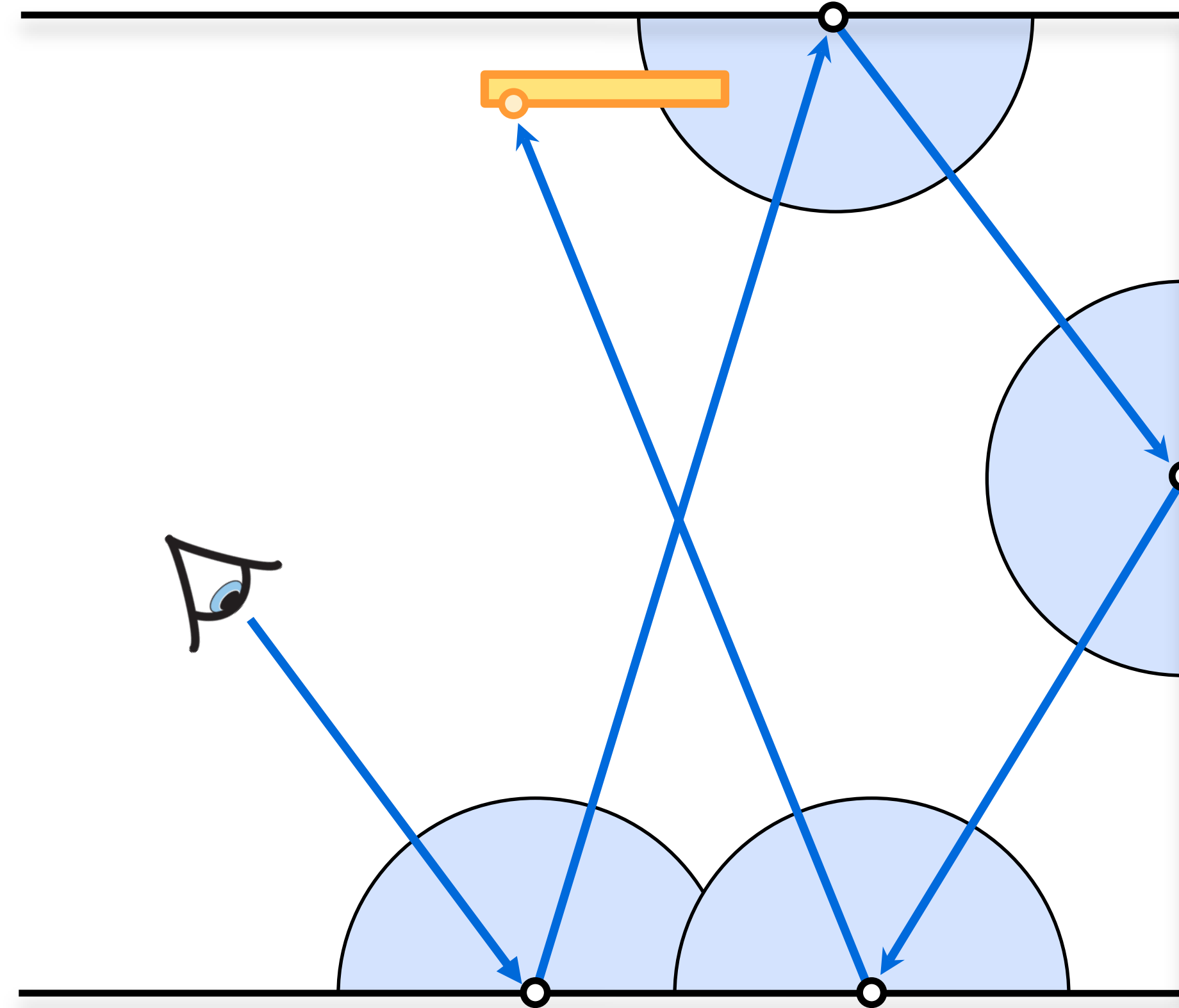
return $L_e + L_{\text{dir}} + L_{\text{ind}}$

Path Tracing with Shadow Rays

1 path/pixel



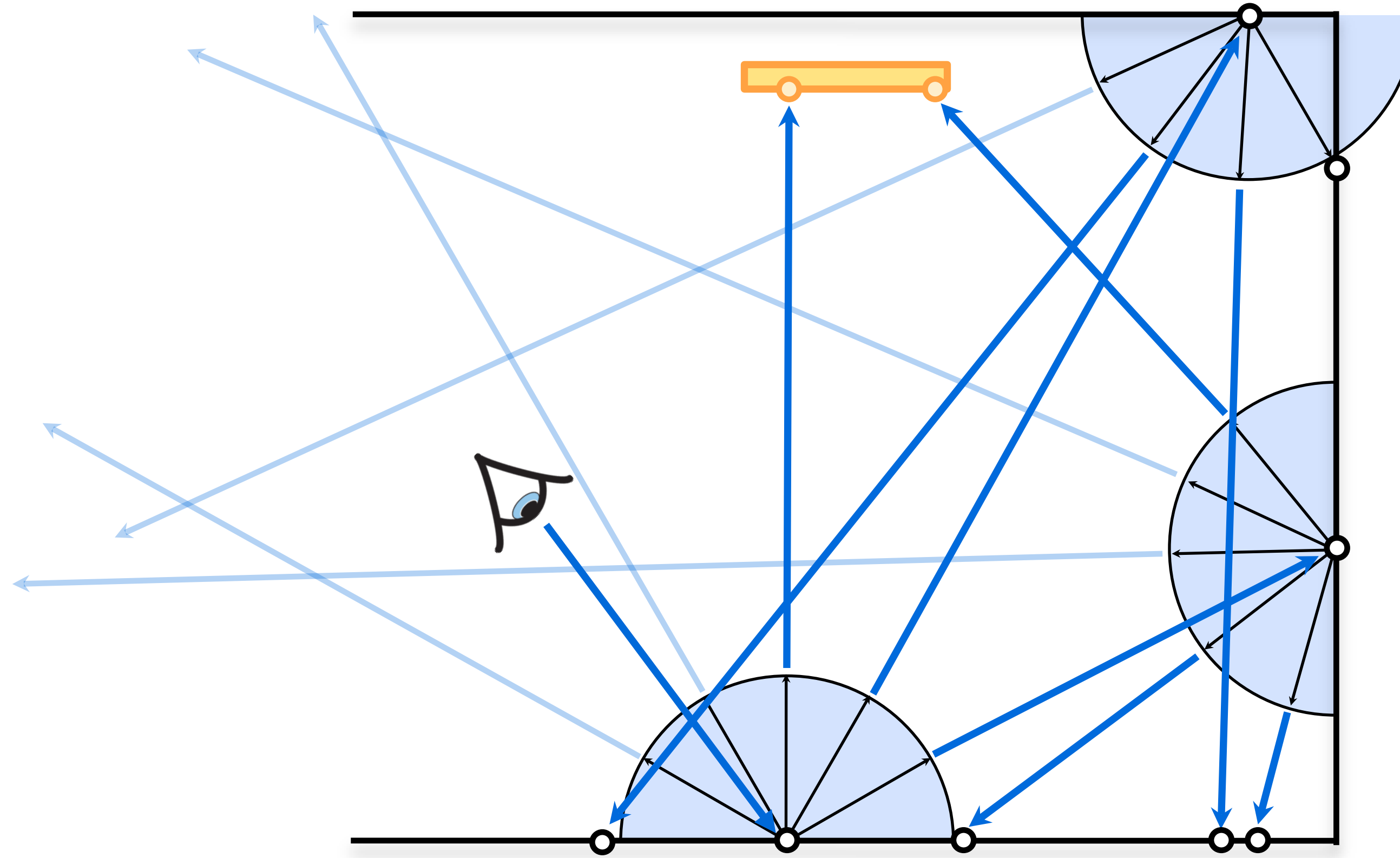
Path Tracing



$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + \int_{H^2} f_r(\vec{\mathbf{x}}, \vec{\omega}', \vec{\omega}) L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}') \cos \theta' d\vec{\omega}'$$

$$L(\mathbf{x}, \vec{\omega}) \approx L_e(\mathbf{x}, \vec{\omega}) + \frac{f_r(\vec{\mathbf{x}}, \vec{\omega}', \vec{\omega}) L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}') \cos \theta'}{p(\vec{\omega}')}$$

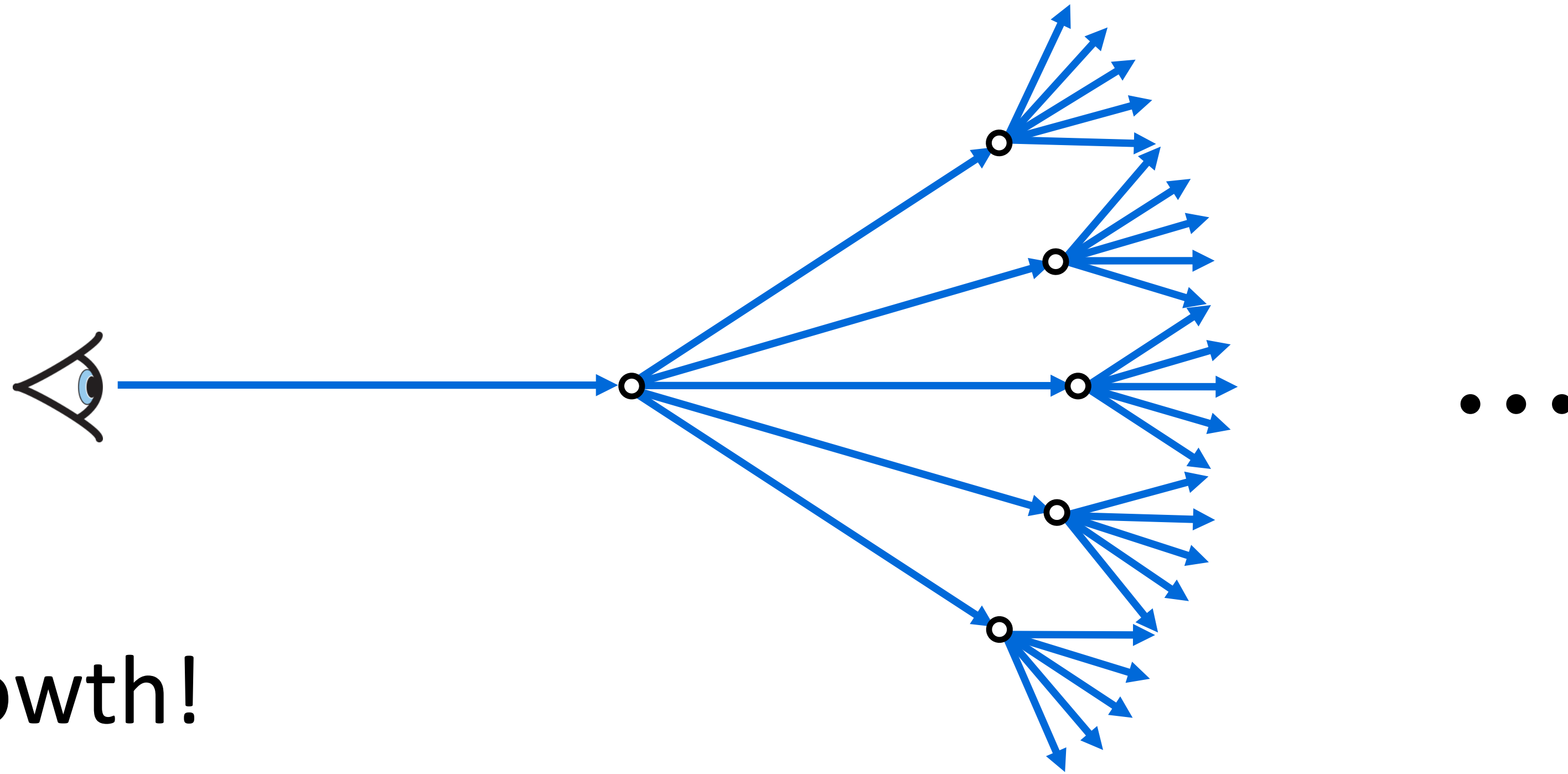
Improving quality: the wrong way



$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + \int_{H^2} f_r(\vec{\mathbf{x}}, \vec{\omega}', \vec{\omega}) L(r(\mathbf{x}, \vec{\omega}'), -\vec{\omega}') \cos \theta' d\vec{\omega}'$$

$$L(\mathbf{x}, \vec{\omega}) \approx L_e(\mathbf{x}, \vec{\omega}) + \frac{1}{N} \sum_{k=1}^N \frac{f_r(\vec{\mathbf{x}}, \vec{\omega}'_k, \vec{\omega}) L(r(\mathbf{x}, \vec{\omega}'_k), -\vec{\omega}'_k) \cos \theta'_k}{p(\vec{\omega}'_k)}$$

The problem



Exponential growth!

3-bounce contributes less than 1-bounce transport, but we estimate it with 25× as many samples!

Improving quality

Just shoot more rays/pixel

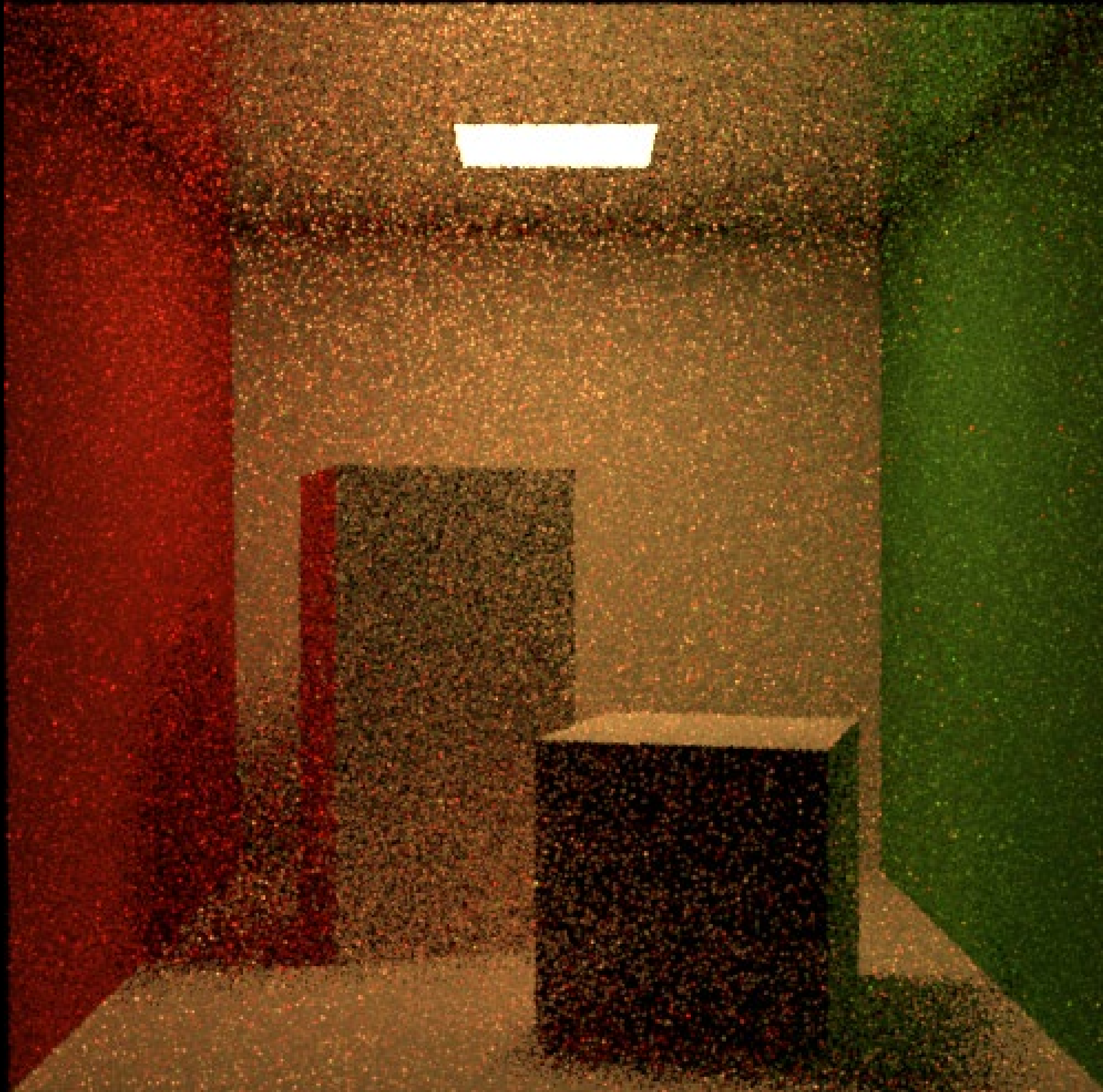
- avoid exponential growth: make sure not to branch!

Each ray will start a new **path**

We can achieve antialiasing/depth of field/motion blur at the same time “for free”!

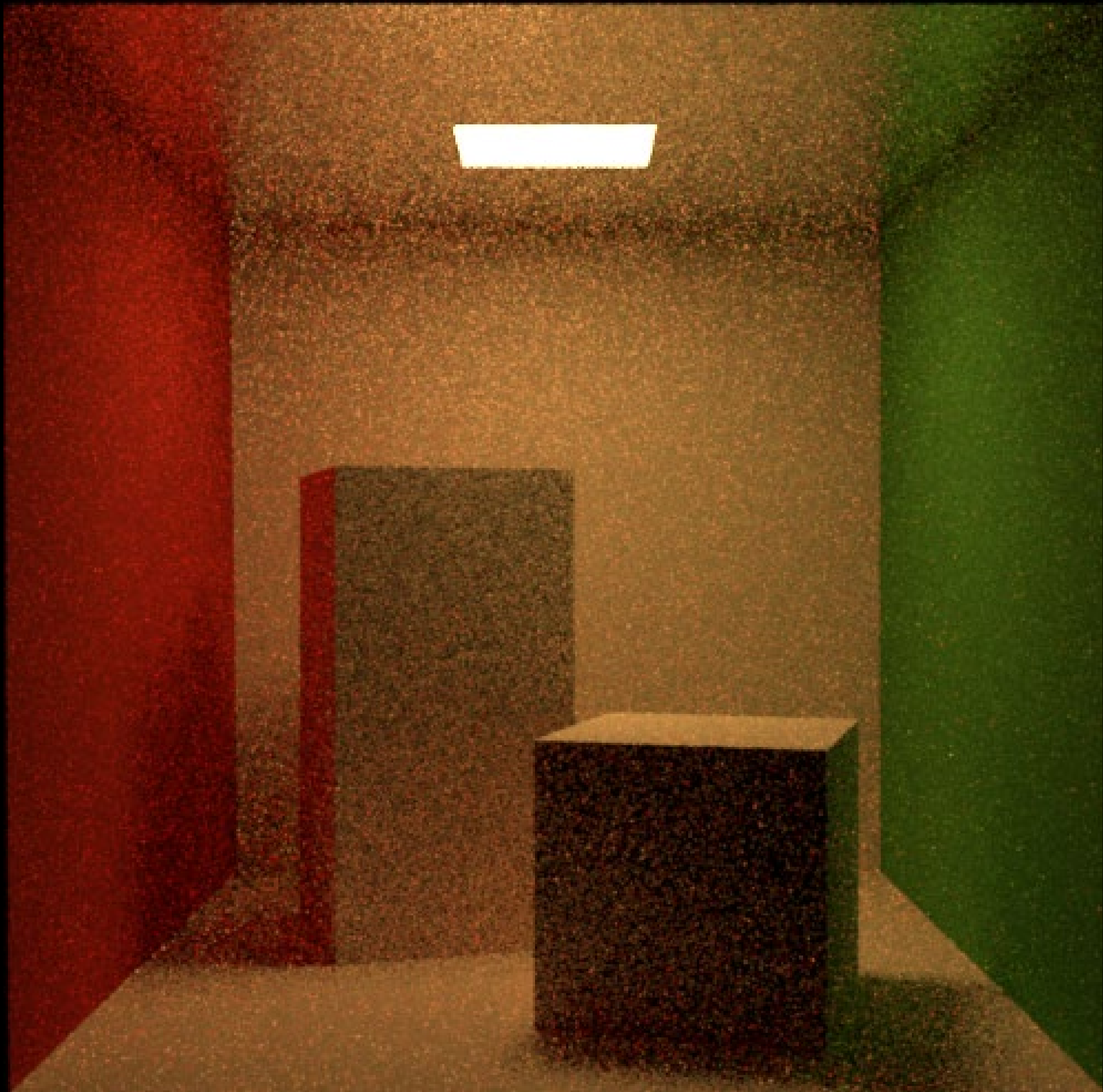
Path Tracing with Shadow Rays

1 path/pixel



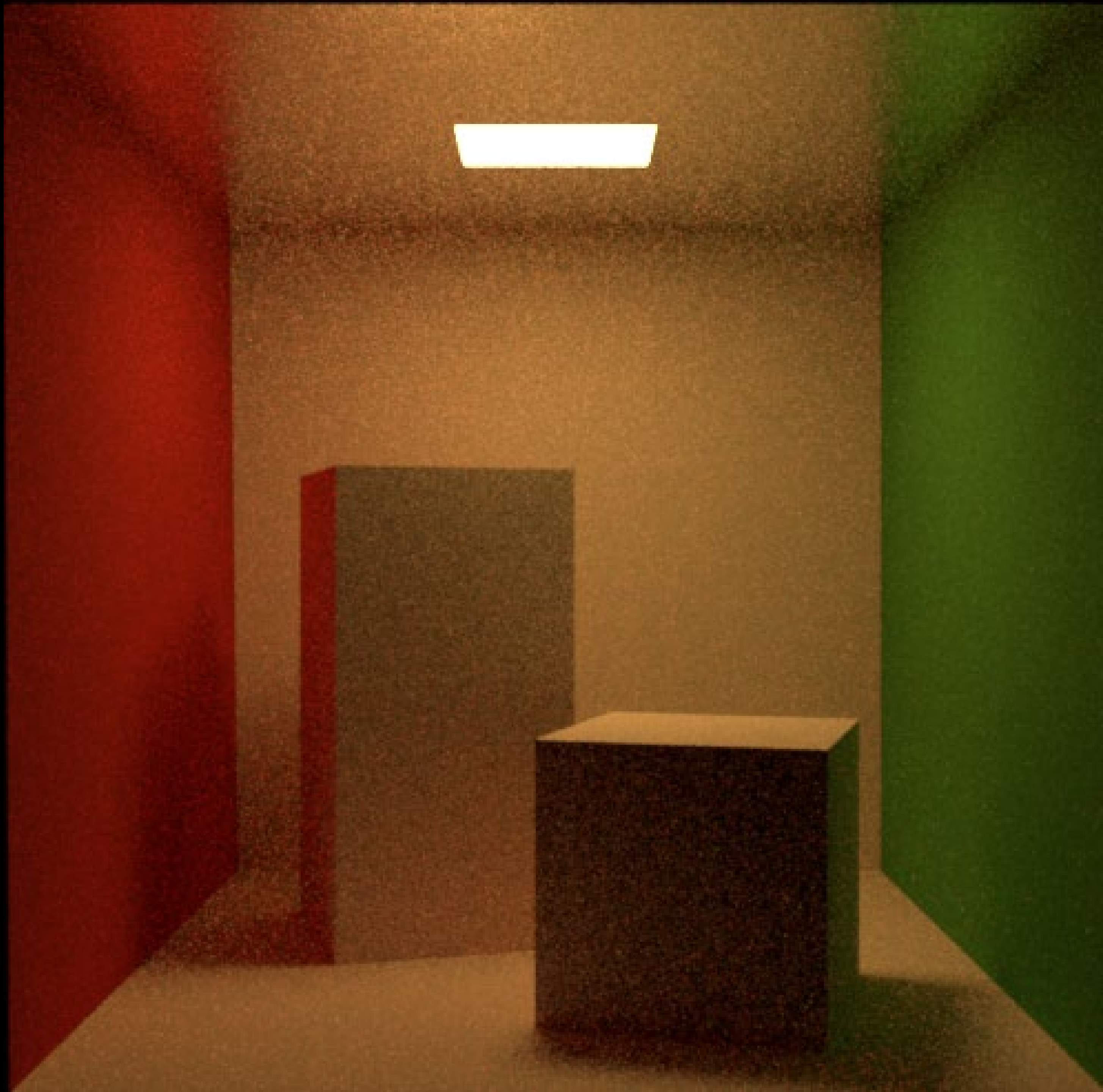
Path Tracing with Shadow Rays

4 paths/pixel



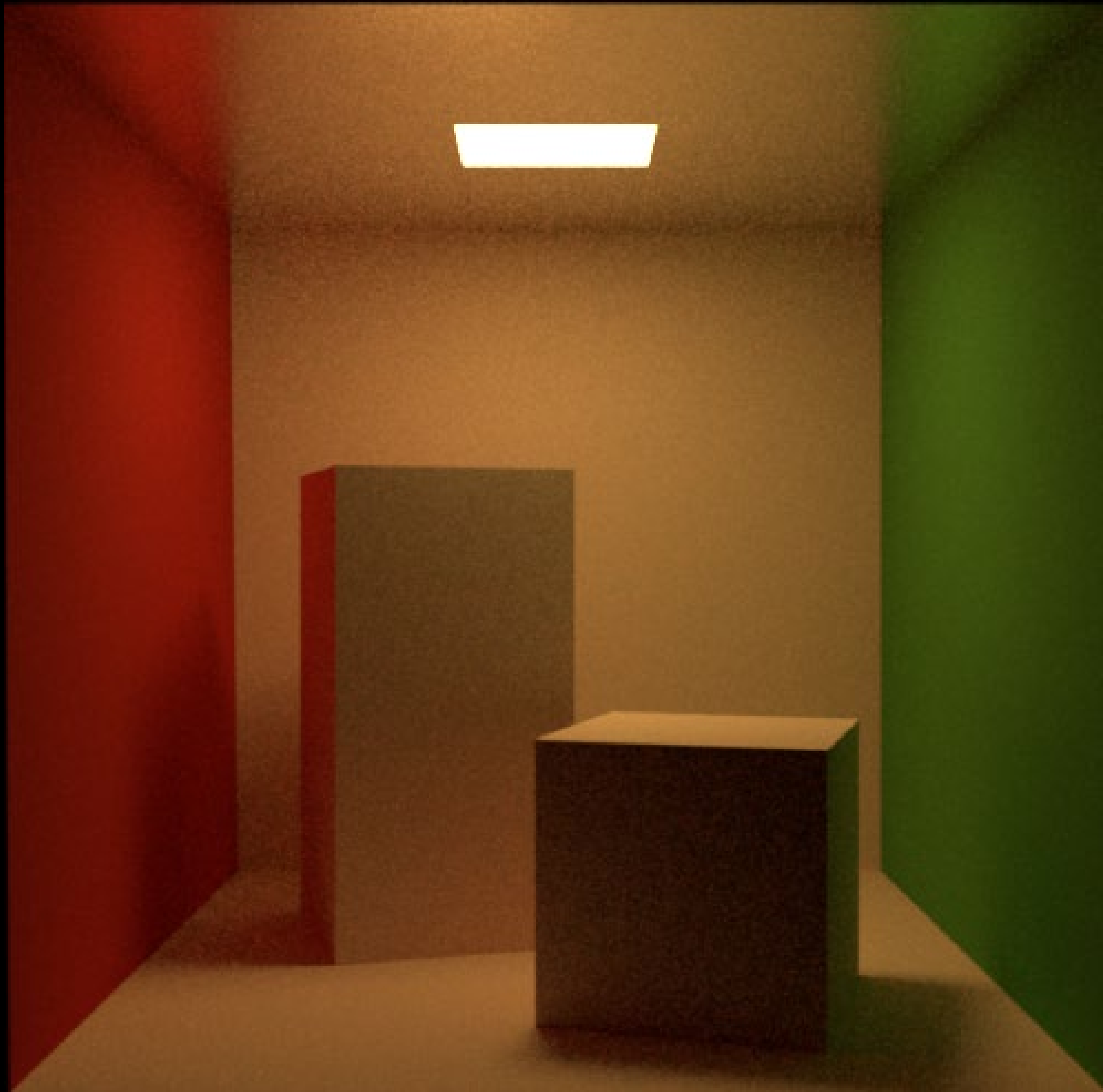
Path Tracing with Shadow Rays

16 paths/pixel



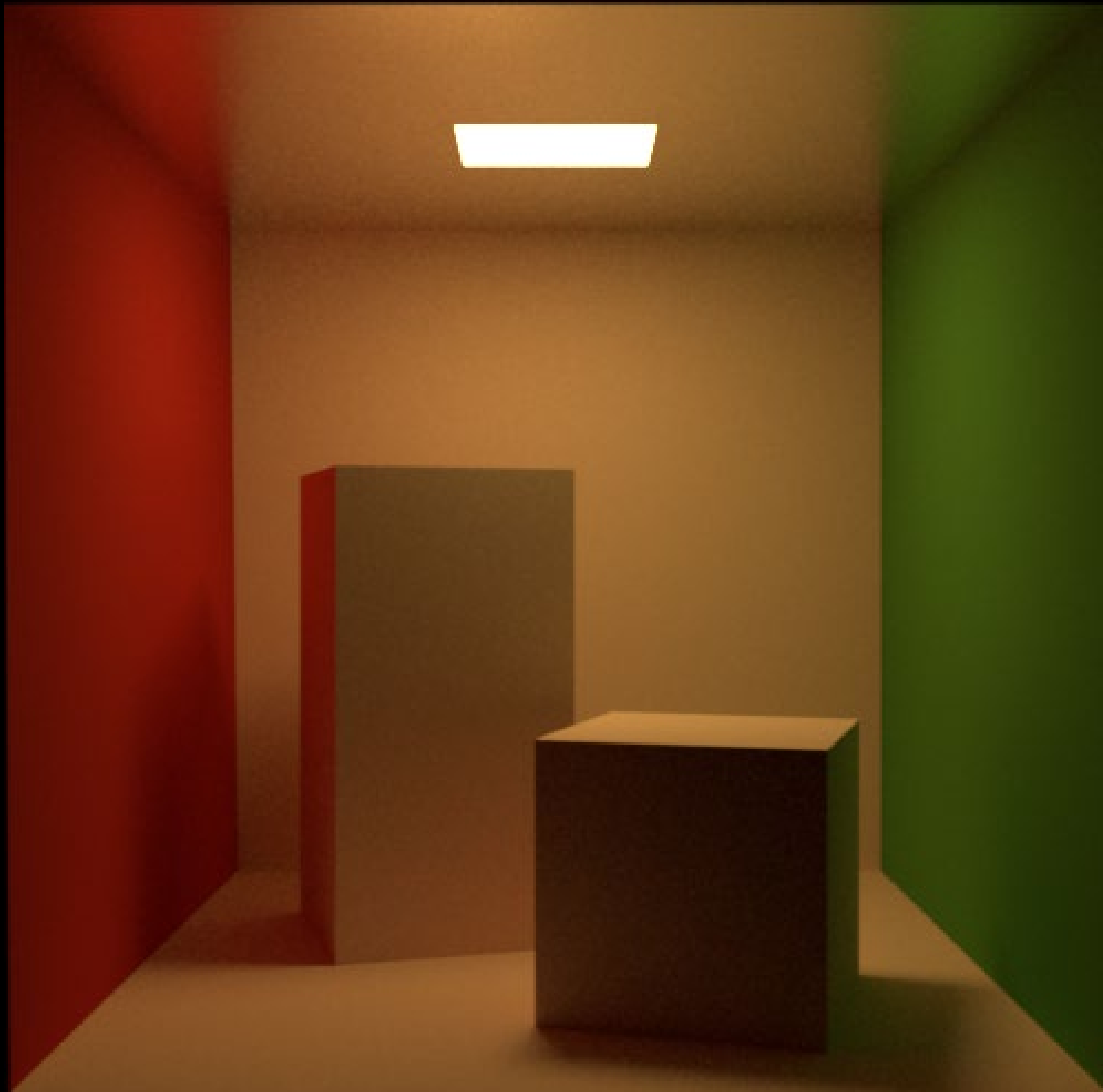
Path Tracing with Shadow Rays

64 paths/pixel



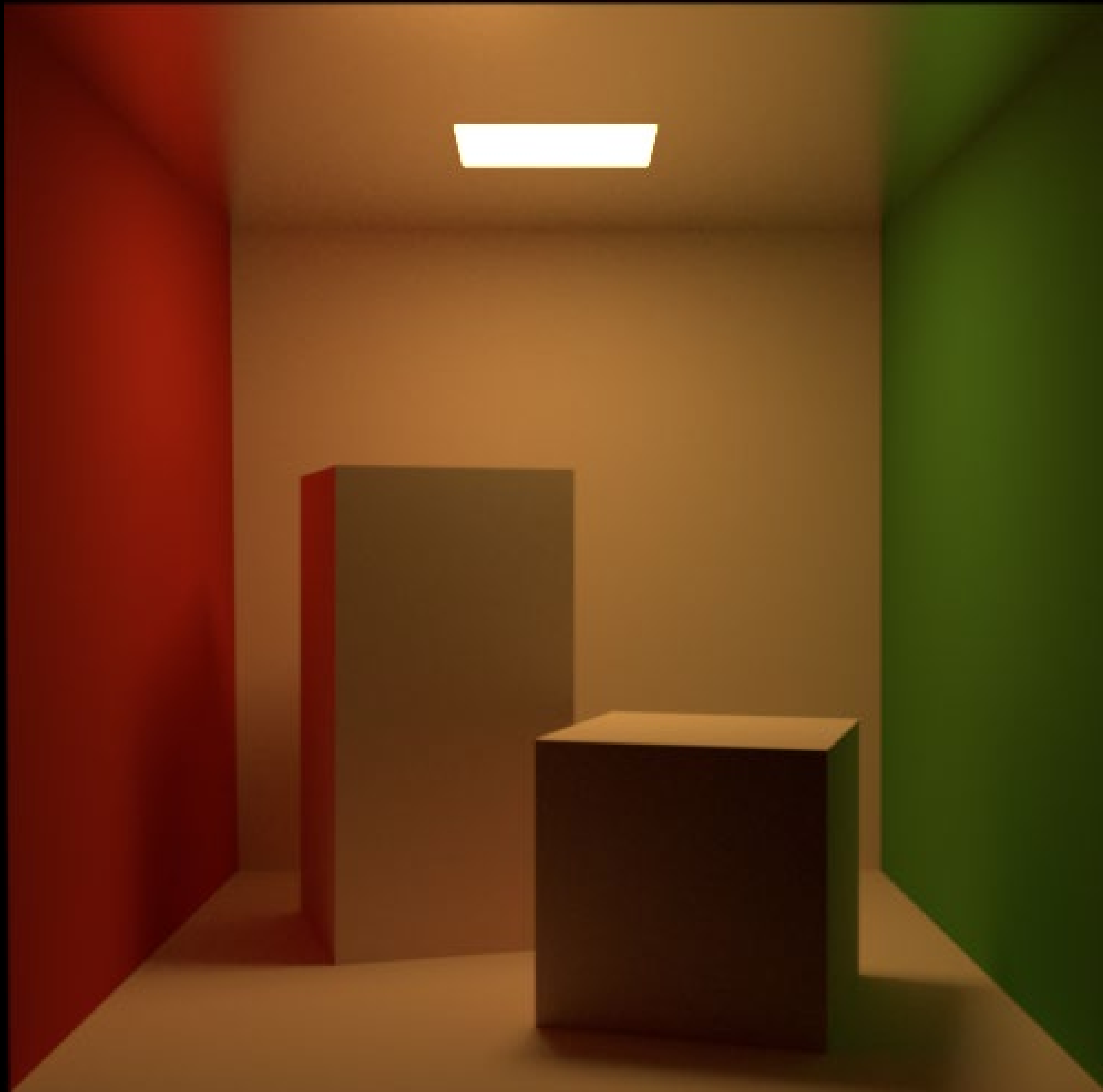
Path Tracing with Shadow Rays

256 paths/pixel



Path Tracing with Shadow Rays

1024 paths/pixel



When do we stop recursion?

Truncating at some fixed depth introduces ***bias***

Solution: Russian roulette

Russian Roulette

Probabilistically terminate the recursion

New estimator: evaluate original estimator X with probability P (but reweighted), otherwise return zero:

$$X_{\text{rr}} = \begin{cases} \frac{X}{P} & \xi < P \\ 0 & \text{otherwise} \end{cases}$$

Unbiased: same expected value as original estimator:

$$E[X_{\text{rr}}] = P \cdot \left(\frac{E[X]}{P} \right) + (1 - P) \cdot 0 = E[X]$$

Russian Roulette

This will actually increase variance!

- but it will improve efficiency if P is chosen so that samples that are expensive, but are likely to make a small contribution, are skipped

You are already doing this

- probabilistic absorption in BSDF (instead of scattering)

Questions?

We should really be using MIS or mixture sampling

Naive Path Tracing

$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + L_r(\mathbf{x}, \vec{\omega})$$

Color color(**Point** \mathbf{x} , **Direction** ω , **int** moreBounces):

if not moreBounces:

 return $L_e(\mathbf{x}, -\omega)$

// sample recursive integral

ω' = sample from BRDF

return $L_e(\mathbf{x}, -\omega) + \text{BRDF} * \text{color}(\text{trace}(\mathbf{x}, \omega'), \text{moreBounces}-1) * \text{dot}(\mathbf{n}, \omega') / \text{pdf}(\omega')$

Path Tracing with mixture sampling

$$L(\mathbf{x}, \vec{\omega}) = L_e(\mathbf{x}, \vec{\omega}) + L_r(\mathbf{x}, \vec{\omega})$$

Color color(**Point** \mathbf{x} , **Direction** ω , **int** moreBounces):

if not moreBounces:

return $L_e(\mathbf{x}, -\omega)$

// sample recursive integral

ω' = sample from mixture PDF

return $L_e(\mathbf{x}, -\omega) + \text{BRDF} * \text{color}(\text{trace}(\mathbf{x}, \omega'), \text{moreBounces}-1) * \text{dot}(\mathbf{n}, \omega') / \text{pdf}(\omega')$

Path Tracing Algorithm with NEE

```
color trace(Point x, Direction  $\omega$ , int moreBounces, bool includeLe):
```

```
    get scene intersection  $\mathbf{x}$ , and normal  $\mathbf{n}$ 
```

```
     $L_e$  = includeLe ?  $L_e(\mathbf{x}, -\omega)$  : black
```

```
    if not moreBounces:
```

```
        return  $L_e$ 
```

```
    // next-event estimation: compute  $L_{dir}$  by sampling the light
```

```
     $\omega_1$  = sample from light
```

```
     $L_{dir}$  = BRDF * trace( $\mathbf{x}$ ,  $\omega_1$ , 0, true) * dot( $\mathbf{n}$ ,  $\omega_1$ ) / pdf( $\omega_1$ )
```

```
    // compute  $L_{ind}$  by sampling the BSDF
```

```
     $\omega_2$  = sample from BSDF
```

```
     $L_{ind}$  = BSDF * trace( $\mathbf{x}$ ,  $\omega_2$ , moreBounces-1, false) * dot( $\mathbf{n}$ ,  $\omega_2$ ) / pdf( $\omega_2$ )
```

```
    return  $L_e$  +  $L_{dir}$  +  $L_{ind}$ 
```

Path Tracing Algorithm with NEE+MIS

```
color trace(Point x, Direction  $\omega$ , int moreBounces, float Leweight):
```

```
    get scene intersection  $\mathbf{x}$ , and normal  $\mathbf{n}$ 
```

```
     $L_e = \text{Leweight} * L_e(\mathbf{x}, -\omega)$ 
```

```
    if not moreBounces:
```

```
        return  $L_e$ 
```

```
    // next-event estimation: compute  $L_{\text{dir}}$  by sampling the light
```

```
     $\omega_1$  = sample from light
```

```
     $L_{\text{dir}} = \text{BRDF} * \text{trace}(\mathbf{x}, \omega_1, 0, \text{mis-weight}_1) * \text{dot}(\mathbf{n}, \omega_1) / \text{pdf}(\omega_1)$ 
```

```
    // compute  $L_{\text{ind}}$  by sampling the BSDF
```

```
     $\omega_2$  = sample from BSDF
```

```
     $L_{\text{ind}} = \text{BSDF} * \text{trace}(\mathbf{x}, \omega_2, \text{moreBounces}-1, \text{mis-weight}_2) * \text{dot}(\mathbf{n}, \omega_2) / \text{pdf}(\omega_2)$ 
```

```
    return  $L_e + L_{\text{dir}} + L_{\text{ind}}$ 
```

Path Tracing on 99 Lines of C++

```
1.  #include <math.h>    // smallpt, a Path Tracer by Kevin Beason, 2008
2.  #include <stdlib.h>  // Make : g++ -O3 -fopenmp smallpt.cpp -o smallpt
3.  #include <stdio.h>   // Remove "-fopenmp" for g++ version < 4.2
4.  struct Vec {        // Usage: time ./smallpt 5000 && xv image.ppm
5.      double x, y, z;    // position, also color (r,g,b)
6.      Vec(double x_=0, double y_=0, double z_=0){ x=x_; y=y_; z=z_; }
7.      Vec operator+(const Vec &b) const { return Vec(x+b.x,y+b.y,z+b.z); }
8.      Vec operator-(const Vec &b) const { return Vec(x-b.x,y-b.y,z-b.z); }
9.      Vec operator*(double b) const { return Vec(x*b,y*b,z*b); }
10.     Vec mult(const Vec &b) const { return Vec(x*b.x,y*b.y,z*b.z); }
11.     Vec& norm(){ return *this = *this * (1/sqrt(x*x+y*y+z*z)); }
12.     double dot(const Vec &b) const { return x*b.x+y*b.y+z*b.z; } // cross:
13.     Vec operator%(Vec&b){return Vec(y*b.z-z*b.y,z*b.x-x*b.z,x*b.y-y*b.x);}
14. };
15. struct Ray { Vec o, d; Ray(Vec o_, Vec d_) : o(o_), d(d_) {} };
16. enum Refl_t { DIFF, SPEC, REFR }; // material types, used in radiance()
17. struct Sphere {
18.     double rad; // radius
19.     Vec p, e, c; // position, emission, color
20.     Refl_t refl; // reflection type (DIFFuse, SPECular, REFRactive)
21.     Sphere(double rad_, Vec p_, Vec e_, Vec c_, Refl_t refl_):
22.         rad(rad_), p(p_), e(e_), c(c_), refl(refl_) {}
23.     double intersect(const Ray &r) const { // returns distance, 0 if nohit
24.         Vec op = p-r.o; // Solve t^2*d.d + 2*t*(o-p).d + (o-p).(o-p)-R^2 = 0
25.         double t, eps=1e-4, b=op.dot(r.d), det=b*b-op.dot(op)+rad*rad;
26.         if (det<0) return 0; else det=sqrt(det);
27.         return (t=b-det)>eps ? t : ((t=b+det)>eps ? t : 0);
28.     }
29. };
30. Sphere spheres[] = { //Scene: radius, position, emission, color, material
31.     Sphere(1e5, Vec( 1e5+1,40.8,81.6), Vec(),Vec(.75,.25,.25),DIFF), //Left
32.     Sphere(1e5, Vec(-1e5+99,40.8,81.6),Vec(),Vec(.25,.25,.75),DIFF), //Rght
33.     Sphere(1e5, Vec(50,40.8, 1e5), Vec(),Vec(.75,.75,.75),DIFF), //Back
34.     Sphere(1e5, Vec(50,40.8,-1e5+170), Vec(),Vec(), DIFF), //Frnt
35.     Sphere(1e5, Vec(50, 1e5, 81.6), Vec(),Vec(.75,.75,.75),DIFF), //Botm
36.     Sphere(1e5, Vec(50,-1e5+81.6,81.6),Vec(),Vec(.75,.75,.75),DIFF), //Top
37.     Sphere(16.5,Vec(27,16.5,47), Vec(),Vec(1,1,1)*.999, SPEC), //Mirr
38.     Sphere(16.5,Vec(73,16.5,78), Vec(),Vec(1,1,1)*.999, REFR), //Glas
39.     Sphere(600, Vec(50,681.6-.27,81.6),Vec(12,12,12), Vec(), DIFF) //Lite
40. };
41. inline double clamp(double x){ return x<0 ? 0 : x>1 ? 1 : x; }
42. inline int toInt(double x){ return int(pow(clamp(x),1/2.2)*255+.5); }
43. inline bool intersect(const Ray &r, double &t, int &id){
44.     double n=sizeof(spheres)/sizeof(Sphere), d, inf=t=1e20;
45.     for(int i=int(n);i--;) if((d=spheres[i].intersect(r))&&d<t){t=d;id=i;}
46.     return t<inf;
47. }
```

```
48. Vec radiance(const Ray &r, int depth, unsigned short *Xi){
49.     double t; // distance to intersection
50.     int id=0; // id of intersected object
51.     if (!intersect(r, t, id)) return Vec(); // if miss, return black
52.     const Sphere &obj = spheres[id]; // the hit object
53.     Vec x=r.o+r.d*t, n=(x-obj.p).norm(), nl=n.dot(r.d)<0?n:n*-1, f=obj.c;
54.     double p = f.x>f.y && f.x>f.z ? f.x : f.y>f.z ? f.y : f.z; // max refl
55.     if (++depth>5) if (erand48(Xi)<p) f=f*(1/p); else return obj.e; //R.R.
56.     if (obj.refl == DIFF){ // Ideal DIFFUSE reflection
57.         double r1=2*M_PI*erand48(Xi), r2=erand48(Xi), r2s=sqrt(r2);
58.         Vec w=nl, u=((fabs(w.x)>.1?Vec(0,1):Vec(1))%w).norm(), v=w%u;
59.         Vec d = (u*cos(r1)*r2s + v*sin(r1)*r2s + w*sqrt(1-r2)).norm();
60.         return obj.e + f.mult(radiance(Ray(x,d),depth,Xi));
61.     } else if (obj.refl == SPEC) // Ideal SPECULAR reflection
62.         return obj.e + f.mult(radiance(Ray(x,r.d-n*2*n.dot(r.d)),depth,Xi));
63.     Ray reflRay(x, r.d-n*2*n.dot(r.d)); // Ideal dielectric REFRACTION
64.     bool into = n.dot(nl)>0; // Ray from outside going in?
65.     double nc=1, nt=1.5, nnt=into?nc/nt:nt/nc, ddn=r.d.dot(nl), cos2t;
66.     if ((cos2t=1-nnt*nnt*(1-ddn*ddn))<0) // Total internal reflection
67.         return obj.e + f.mult(radiance(reflRay,depth,Xi));
68.     Vec tdir = (r.d*nnt - n*((into?-1:1)*(ddn*nnt+sqrt(cos2t)))).norm();
69.     double a=nt-nc, b=nt+nc, R0=a*a/(b*b), c = 1-(into?-ddn:tdir.dot(n));
70.     double Re=R0+(1-R0)*c*c*c*c*c, Tr=1-Re, P=.25+.5*Re, RP=Re/P, TP=Tr/(1-P);
71.     return obj.e + f.mult(depth>2 ? (erand48(Xi)<P ? // Russian roulette
72.         radiance(reflRay,depth,Xi)*RP:radiance(Ray(x,tdir),depth,Xi)*TP) :
73.         radiance(reflRay,depth,Xi)*Re+radiance(Ray(x,tdir),depth,Xi)*Tr);
74. }
75. int main(int argc, char *argv[]){
76.     int w=1024, h=768, samps = argc==2 ? atoi(argv[1])/4 : 1; // # samples
77.     Ray cam(Vec(50,52,295.6), Vec(0,-0.042612,-1).norm()); // cam pos, dir
78.     Vec cx=Vec(w*.5135/h), cy=(cx%cam.d).norm()**.5135, r, *c=new Vec[w*h];
79.     #pragma omp parallel for schedule(dynamic, 1) private(r) // OpenMP
80.     for (int y=0; y<h; y++){ // Loop over image rows
81.         fprintf(stderr, "\rRendering (%d spp) %5.2f%%", samps*4, 100.*y/(h-1));
82.         for (unsigned short x=0, Xi[3]={0,0,y*y*y}; x<w; x++) // Loop cols
83.             for (int sy=0, i=(h-y-1)*w+x; sy<2; sy++) // 2x2 subpixel rows
84.                 for (int sx=0; sx<2; sx++, r=Vec()){ // 2x2 subpixel cols
85.                     for (int s=0; s<samps; s++){
86.                         double r1=2*erand48(Xi), dx=r1<1 ? sqrt(r1)-1: 1-sqrt(2-r1);
87.                         double r2=2*erand48(Xi), dy=r2<1 ? sqrt(r2)-1: 1-sqrt(2-r2);
88.                         Vec d = cx*( ( (sx+.5 + dx)/2 + x)/w - .5) +
89.                             cy*( ( (sy+.5 + dy)/2 + y)/h - .5) + cam.d;
90.                         r = r + radiance(Ray(cam.o+d*140,d.norm()),0,Xi)*(1./samps);
91.                     } // Camera rays are pushed ^^^^ forward to start in interior
92.                     c[i] = c[i] + Vec(clamp(r.x),clamp(r.y),clamp(r.z))**.25;
93.                 }
94.             }
95.         FILE *f = fopen("image.ppm", "w"); // Write image to PPM file.
96.         fprintf(f, "P3\n%d %d\n%d\n", w, h, 255);
97.         for (int i=0; i<w*h; i++)
98.             fprintf(f,"%d %d %d ", toInt(c[i].x), toInt(c[i].y), toInt(c[i].z));
99.     }
```


directions for making pictures using numbers
(explained using only the ten hundred words people use most often)

the light that comes from
an interesting direction
towards the position on the
stuff

direction towards
the eye

position on
the stuff

light made by the stuff
(sometimes because
it is very hot)

the answer to how much light from an
interesting direction that will keep going
in the direction towards the eye, after
hitting stuff at the position (this is easy
for mirrors, not so easy for everything else)

how much the light
becomes less bright
because the stuff leans
away from the
interesting direction

$$L_o(x, \omega_o) = L_e(x, \omega_o) + \int_{\Omega} f_r(x, \omega_i \rightarrow \omega_o) L_i(x, \omega_i) (\omega_i \cdot n) d\omega_i$$

light that leaves the
position on the stuff and
reaches the eye

light can be added
said a man who sat under
a tree many years ago

for lots of interesting directions
inside half a ball facing up
from the stuff, add up all the
answers in between