#### Wrap-up and discussion



15-463, 15-663, 15-862 Computational Photography Fall 2021, Lecture 22

#### http://graphics.cs.cmu.edu/courses/15-463

#### Course announcements

- Homework assignment 6 is due on <u>12/5</u>.
  - Any questions about the homework?
  - You can use any remaining late days for the last homework assignment.
- Final project presentations on <u>Thursday 12/9</u>.
  Detailed logistics posted on Piazza.
- Final project reports due on <u>Tuesday 12/14, midnight</u>.

### Class evaluation\*s\* – please take them!

- CMU's Faculty Course Evaluations (FCE): <u>https://cmu.smartevals.com/</u>
- TA evaluation: <u>https://www.ugrad.cs.cmu.edu/ta/F21/feedback/</u>
- 15-463/663/862 end-of-semester survey: <u>https://docs.google.com/forms/d/e/1FAIpQLSc6eXw\_tbcxIF7-fm882V\_7g80Q-l\_34oObpITMCqOUgMcEkw/viewform</u>
- Please take all three of them, super helpful for developing future offerings of the class.
- Thanks in advance!

#### Overview of today's lecture

• Class wrap-up and discussion.

#### Course overview

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- 1. Photographic optics and pipeline.  $\leftarrow$
- 2. Exposure, HDR, and noise.
- 3. Color and image editing.
- 4. Focus and coded photography.
- 5. Radiometry and photometric stereo.
- 6. Geometry and stereo.
- 7. Computational light transport.

- Lectures 2 4.
- Lectures 5 7.
- Lectures 8 10.
  - Lectures 11 13.
  - Lectures 14 15.
  - Lectures 16 18.
    - Lectures 19 21.

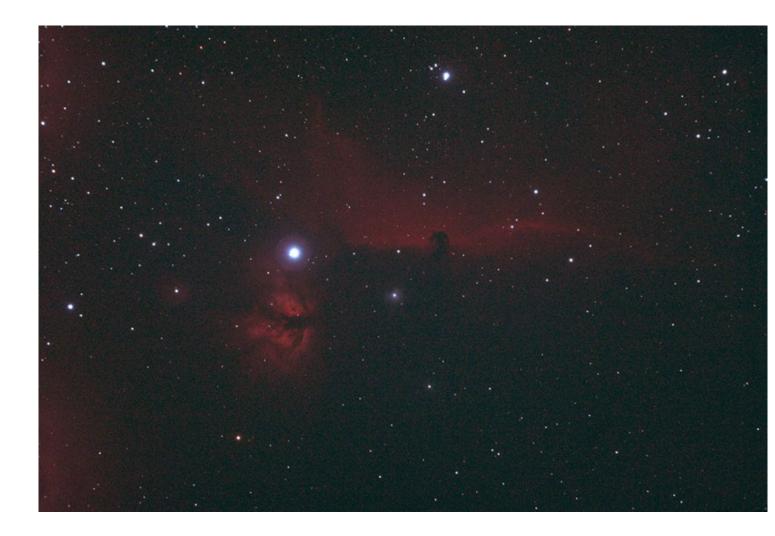
### Photographic optics and pipeline

- pinhole and lens cameras
- lenses and other optical elements
- paraxial optics
- aperture
- image processing pipeline



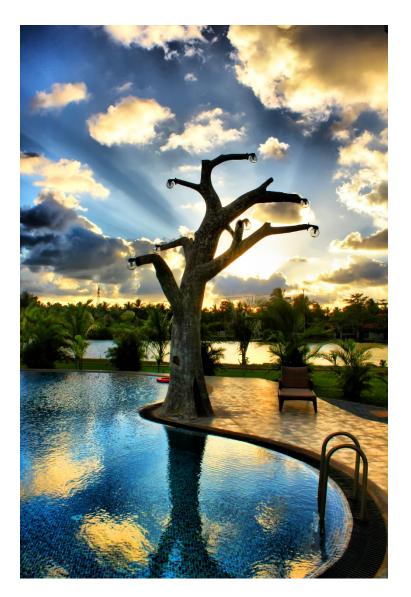
#### Exposure, HDR, and noise

- exposure control
- high-dynamic-range imaging
- radiometric calibration
- noise modeling
- noise calibration



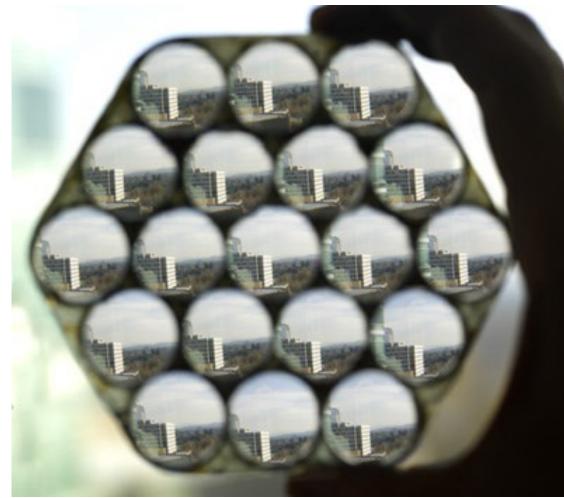
## Color and image editing

- tonemapping
- color processing
- color calibration
- edge-aware and bilateral filtering
- gradient-domain processing
- Poisson integration



# Focus and coded photography

- focal stacks
- depth from (de)focus and confocal stereo
- lightfields and lightfield processing
- plenoptic camera
- deconvolution and motion deblurring
- coded aperture
- coded exposure



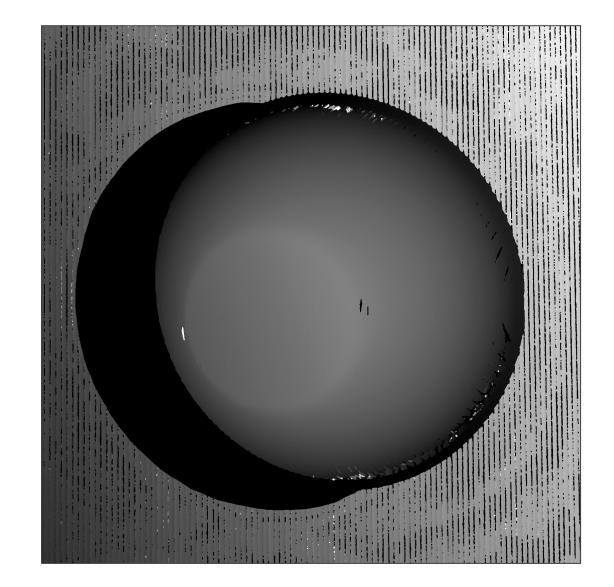
# Radiometry and photometric stereo

- radiometry
- reflectance equation
- BRDF models
- illumination models
- calibrated photometric stereo
- uncalibrated photometric stereo



### Geometry and stereo

- geometric camera models
- geometric camera calibration
- triangulation
- epipolar geometry
- stereo and disparity
- depth from lightfields
- structured light scanning



# Computational light transport

- time-of-flight imaging
- direct and global illumination
- light transport matrices
- dual photography
- optical computing
- probing and epipolar imaging



# Things you should know how to do

1. Build simple pinhole cameras, use DSLR cameras and modern lenses.

- 2. Write your own LDR and HDR image processing pipelines.
- 3. Calibrate the radiometric, color, noise, and geometric properties of a camera.
- 4. Fuse images and perform flash/no-flash photography.
- 5. Use bilateral and gradient-domain filtering for image editing tasks.
- 6. Capture and refocus your own lightfields and focal stacks.
- 7. Build three different types of depth and shape sensing systems: depth-from-defocus, photometric stereo, structured light.

# Do you plan on taking any other vision/graphics courses?

If you are an undergraduate, check out the graphics concentration.

Background courses (ideally you should take both):

- 15-462 computer graphics.
- 16-385 computer vision.

More advanced courses directly relevant for computational photography and imaging:

- <u>15-468 physics-based rendering modeling, simulating, and inverting light transport.</u>  $\leftarrow$  Spring 2022, offered by Yannis
- 15-458 discrete differential geometry background for 3D geometry processing and geometric optics.
- 16-822 geometry-based methods in vision all about epipolar geometry.
- 16-726 learning-based image synthesis learning-based variants of computational photography algorithms.
- 16-722 sensing and sensors background on vision and other sensors and noise modeling.
- 16-866 sensor systems similar to above, background on vision and other sensors and noise modeling.
- 33-353 intermediate optics wave optics, hands-on experience with optical components.
- 18-416 nano-bio-photonics modern photonics systems and applications to biology.

More general vision (left) and graphics (right):

- 16-824 visual learning and recognition
- 10-703 deep reinforcement learning
- 16-831 statistical techniques in robotics
- 16-833 robot localization and mapping
- 16-881 deep Reinforcement Learning for Robotics

- 15-365 experimental animation
- 15-464 technical animation
- 15-465 animation art and technology
- 15-466 computer game programming
- 15-469 algorithmic textiles design

# Interested in doing research in computational imaging or rendering? Talk to me!

Many, many possible projects, including:

- Projects on rendering and inverse rendering.
- Projects on theory of light transport.
- Projects on coherent imaging and optical coherence tomography.
- Projects on material inference (reflectance, scattering, refractive fields, particle sizing).
- Projects on tissue imaging.
- Projects on non-line-of-sight imaging.
- Projects on combining physics (rendering) and deep learning.
- Projects on data-driven optimization of imaging systems.
- Projects derived from your final project for a paper publication.

Many 15-463/663/862 alumni have worked on various research projects in my group.

Ideal background:

- Knowledge of (at least one of) graphics, vision, physics, numerical computing.
- If you've taken 15-463, you have the background.









Srinivasa

Narasimhan

Faculty

Arjun Teh

PhD Student

ateh@andrew.cmu.edu

Adithya Pediredla

Bakari Hassan

PhD Student

bhassan@andrew.cmu.edu

Aswin Sankaranarayanan Faculty saswin@andrew.cmu.edu

Ioannis Gkioulekas Faculty igktoule@andrew.cmu.edu

Faculty Igaleott@andrew.cmu.edu

John Galeotti

Faculty mpotoole@cmu.edu

Matthew O'Toole

Alankar Kotwal

PhD Student

aloo@cmu.edu

**Dinesh Reddy** 

PhD Student

Jiatian (Caroline)

Sun

Undergraduate

Student jlatlans@andrew.cmu.edu

PostDoc apedired@andrew.cmu.edu srinivas@andrew.cmu.edu

20

19



Wave-based Non-Line-of-Sight Imaging using Fast f-k Migration

David B. Lindell, Gordon Wetzstein, Matthew O'Toole. ACM SIGGRAPH 2019.

Ellipsoidal Path Connections for Time-gated Rendering Adithya Pediredla, Ashok Veeraraghavan, and Ioannis Gkioulekas. ACM SIGGRAPH 2019.

A Differential Theory of Radiative Transfer



A Monte Carlo Framework for Rendering Speckle Statistics in Scattering Media

Convolutional Approximations to the General Non-Line-of-Sight Imaging Operator

Cheng Zhang, Lifan Wu, Changxi Zheng, Ioannis Gkioulekas, Ravi Ramamoorthi, and Shuang Zhao. ACM SIGGRAPH Asia 2019.

Byeongjoo Ahn, Akshat Dave, Ashok Veeraraghavan, Ioannis Gkioulekas, and Aswin C. Sankaranarayanan. ICCV 2019.

16



Chen Bar, Marina Alterman, Ioannis Gkioulekas, Anat Levin. ACM SIGGRAPH 2019.



A Theory of Fermat Paths for Non-Line-of-Sight Shape Reconstruction

Shumian Xin, Sotiris Nousias, Kiriakos N. Kutulakos, Aswin C. Sankaranarayanan, Srinivasa G. Narasimhan, and Ioannis Gkioulekas. CVPR 2019.



Multispectral Imaging for Fine-Grained Recognition of Powders on Complex Backgrounds





Beyond Volumetric Albedo—A Surface Optimization Framework for Non-Line-of-Sight Imaging

Chia-Yin Tsai, Aswin C. Sankaranarayanan, Ioannis Gkioulekas. CVPR 2019.



Non-Line-of-Sight Imaging with Partial Occluders and Surface Normals

Felix Heide, Matthew O'Toole, Kai Zang, David B. Lindell, Steven Diamond, Gordon Wetzstein. ACM Trans. on Graphics 2019.



Towards Multifocal Displays with Dense Focal Stacks

Rick Chang, Vijaya Kumar, Aswin C. Sankaranarayanan. ACM SIGGRAPH Asia 2018.

#### http://imaging.cs.cmu.edu/

Joe Bartels

PostDoc

josephba@andrew.cmu.edu





Vijay Rengarajan

PostDoc vangarat@andrew.cmu.edu





Mark Sheinin

PostDoc

marksheinin@gmail.com



Chao Liu PhD Student chao.liu@cs.cmu.edu

Che cche@andrew.cmu.edu

Chenggian (Bruce) PhD Student



Minh Vo PhD Student





Byeongjoo Ahn

PhD Student

bahn@andrew.cmu.edu

**Rick Chang** PhD Student rickchang@cmu.edu

Angi Yang

MS Student

angly1@andrew.cmu.edu



Bhargav Ghanekar

MS Student

bghaneka@andrew.cmu.edu

sxin@andrew.cmu.edu



Shumian Xin **Tiancheng Zhi** PhD Student PhD Student tzhi@cs.cmu.edu



**Roshan Sharma** 

MS Student

roshansh@andrew.cmu.edu

Vishwanath Saragadam PhD Student



yhua1@andrew.cmu.edu

Alumni













Yi Hua PhD Student











# This class is still evolving, your feedback is invaluable.

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#### Questions?