Wrap-up and discussion

http://graphics.cs.cmu.edu/courses/15-463

Course announcements

- Homework assignment 6 is due on <u>12/11</u> and optional assignment 7 is due on <u>12/18.</u>
  - Any questions about either homework?
  - You can use any remaining late days for the two homeworks.

- Final project presentations on <u>Thursday 12/17</u>.
  - Logistics will be posted on Piazza.

- Final project reports due on <u>Sunday 12/20, midnight</u>.

- One upcoming computational photography talk: - Tuesday 15th, 11 am – noon, Ricardo Martin-Brualla, "NeRF".

- Suggest topics for Friday's reading group on Piazza.

Class evaluation*s* – please take them!

- CMU's Faculty Course Evaluations (FCE): https://cmu.smartevals.com/

- TA evaluation: https://www.ugrad.cs.cmu.edu/ta/F20/feedback/

- 15-463/663/862 end-of-semester survey: https://docs.google.com/forms/d/e/1FAIpQLSew6XHzagr0KqWPFCmdoVmnHXQR5vfi4A6nEG0jMg6O1lBixA/viewform

- Please take all three of them, super helpful for developing future offerings of the class.

- Thanks in advance!

Overview of today's lecture

- Leftover from light transport matrices.

- Class wrap-up and discussion.

Course overview

1. Photographic optics and pipeline. ← Lectures 2 – 5.

2. Exposure, HDR, and noise. ← Lectures 6 – 7.

3. Color and image editing. ← Lectures 8 – 11.

4. Focus and coded photography. ← Lectures 12 – 16.

5. Radiometry and photometric stereo. ← Lectures 17 – 18.

6. Geometry and stereo. ← Lectures 19 – 22.

7. Computational light transport. ← Lectures 23 – 26.

8. Special topics. ← Reading groups.

Photographic optics and pipeline

- pinhole and lens cameras

- lenses and other optical elements

- paraxial optics

- aperture

- image processing pipeline

Exposure, HDR, and noise

- exposure control

- high-dynamic-range imaging

- radiometric calibration

- noise modeling

- noise calibration

Color and image editing

- tonemapping

- color processing

- color calibration

- edge-aware and bilateral filtering

- gradient-domain processing

- Poisson integration

Focus and coded photography

- focal stacks

- depth from (de)focus and confocal stereo

- lightfields and lightfield processing

- plenoptic camera

- deconvolution and motion deblurring

- coded aperture

- coded exposure
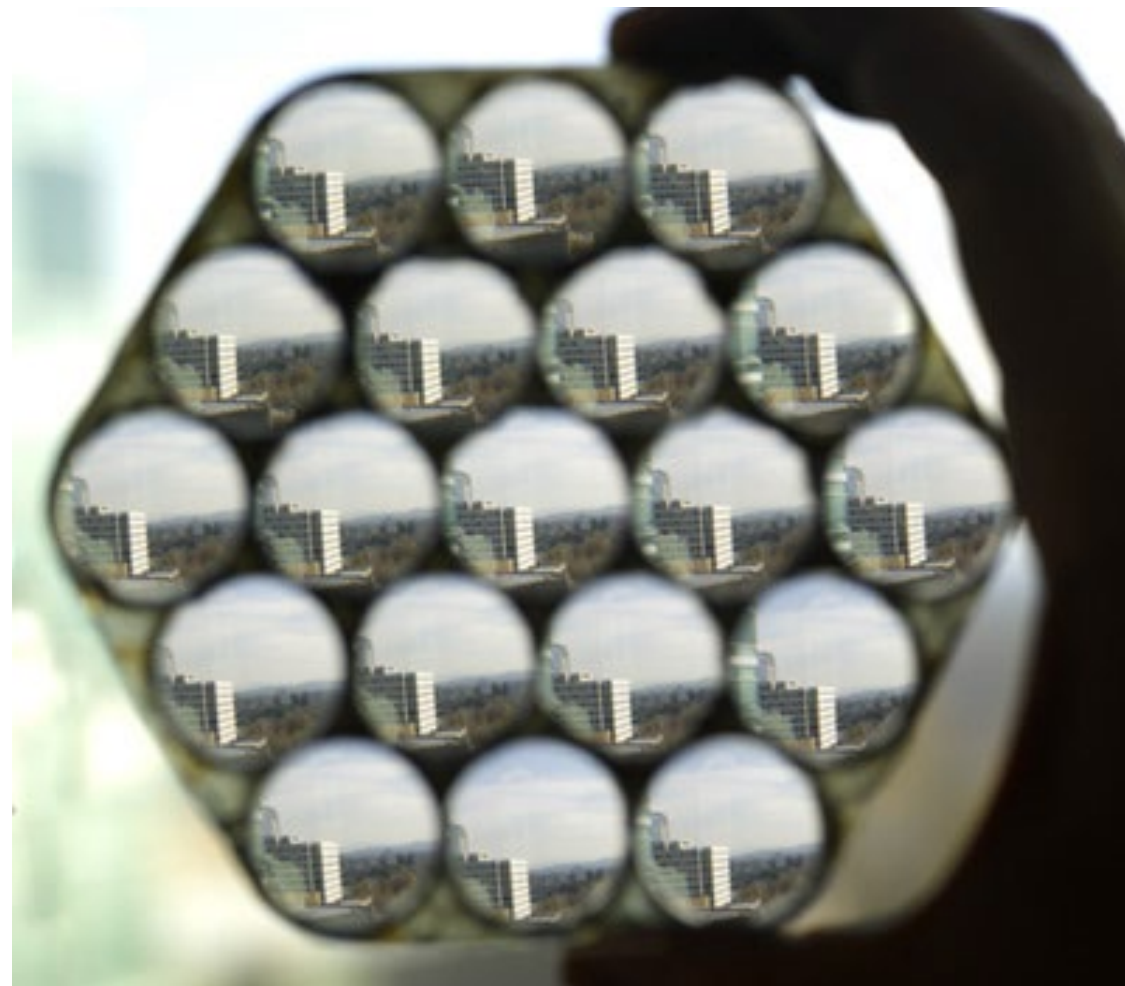
Radiometry and photometric stereo

- radiometry

- reflectance equation

- BRDF models

- illumination models

- calibrated photometric stereo

- uncalibrated photometric stereo

Geometry and stereo

- geometric camera models

- geometric camera calibration

- triangulation

- epipolar geometry

- stereo and disparity

- depth from lightfields
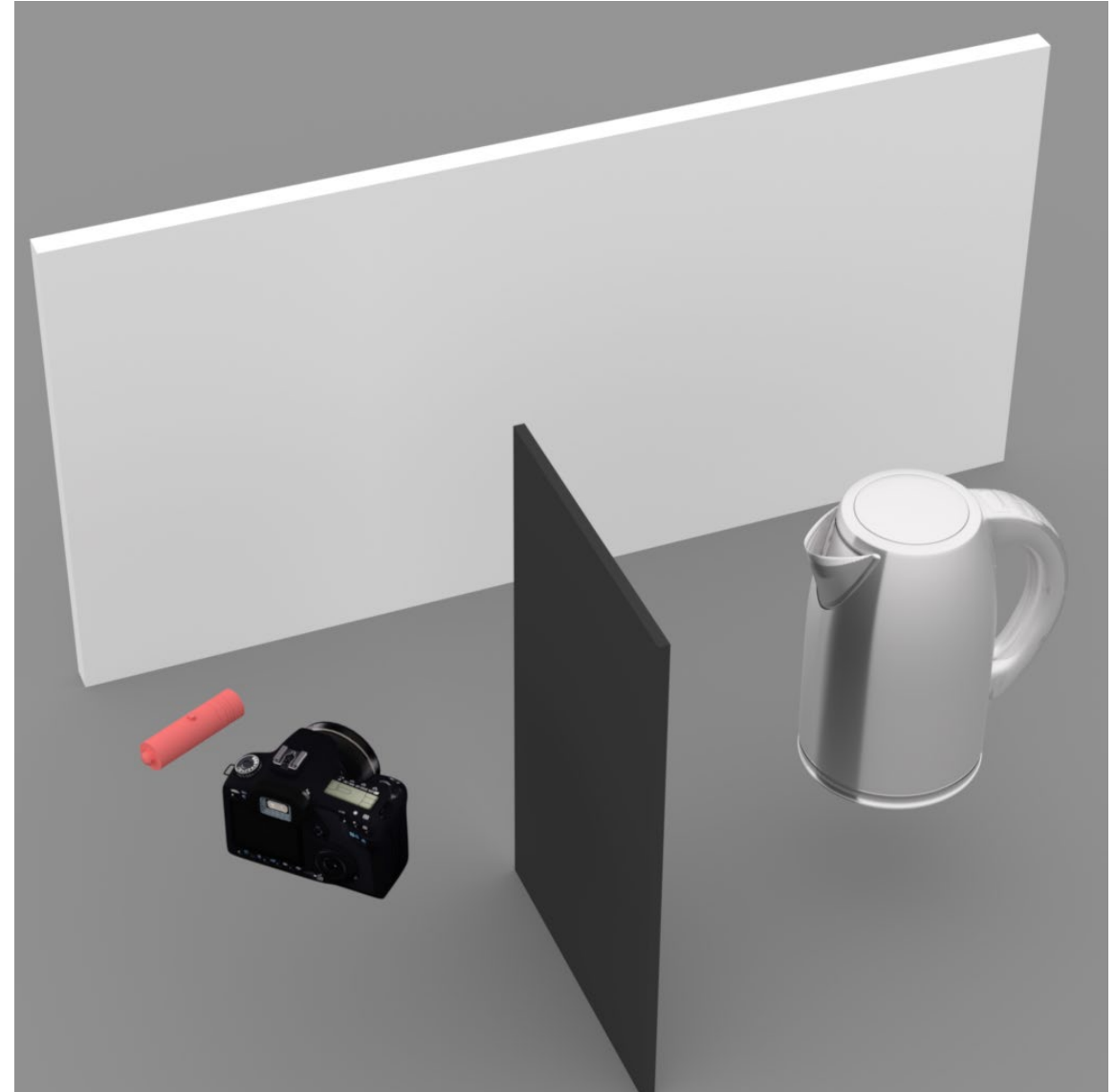
- structured light scanning
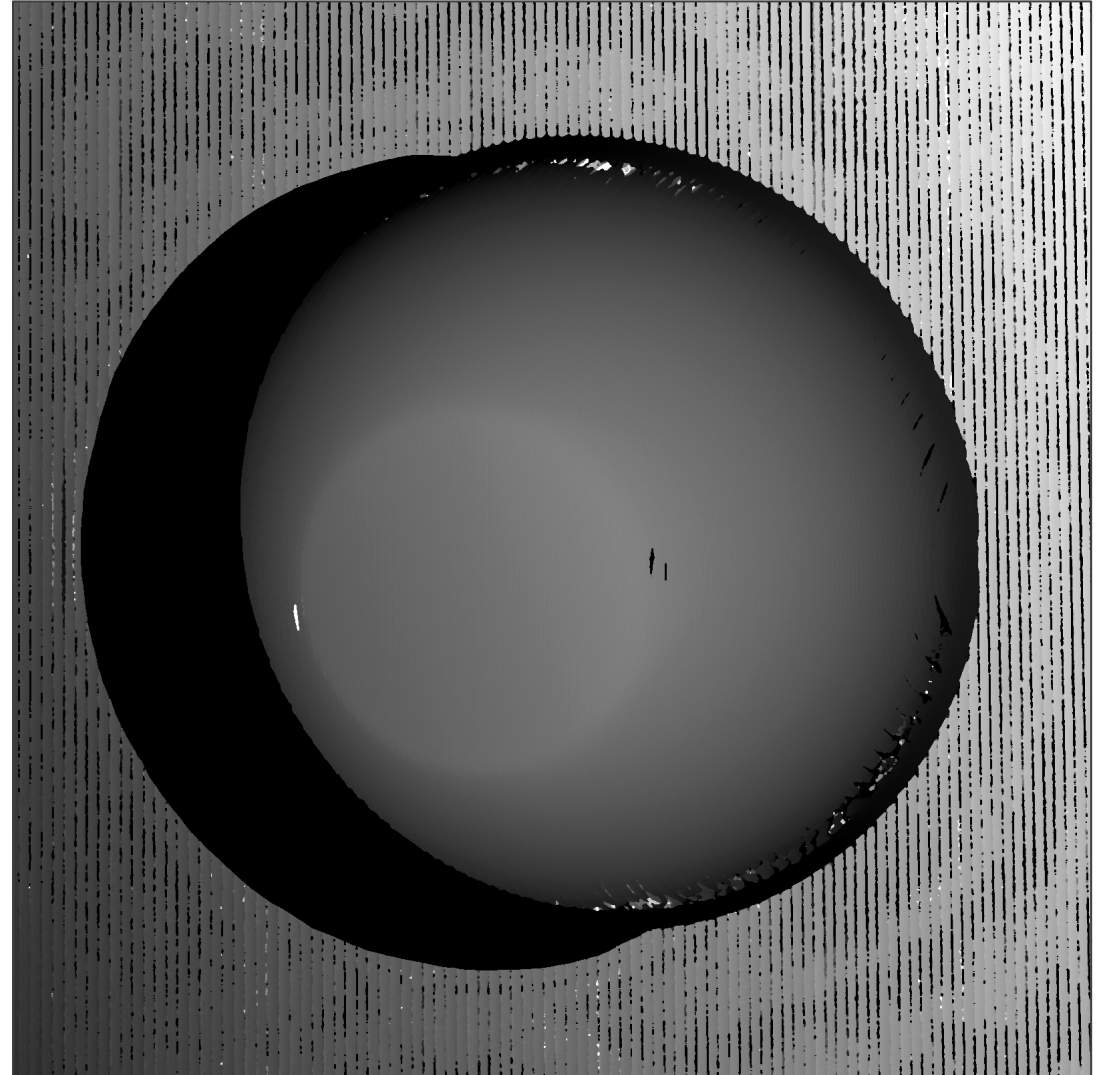
Computational light transport

- time-of-flight imaging

- direct and global illumination

- light transport matrices

- dual photography

- optical computing

- probing and epipolar imaging
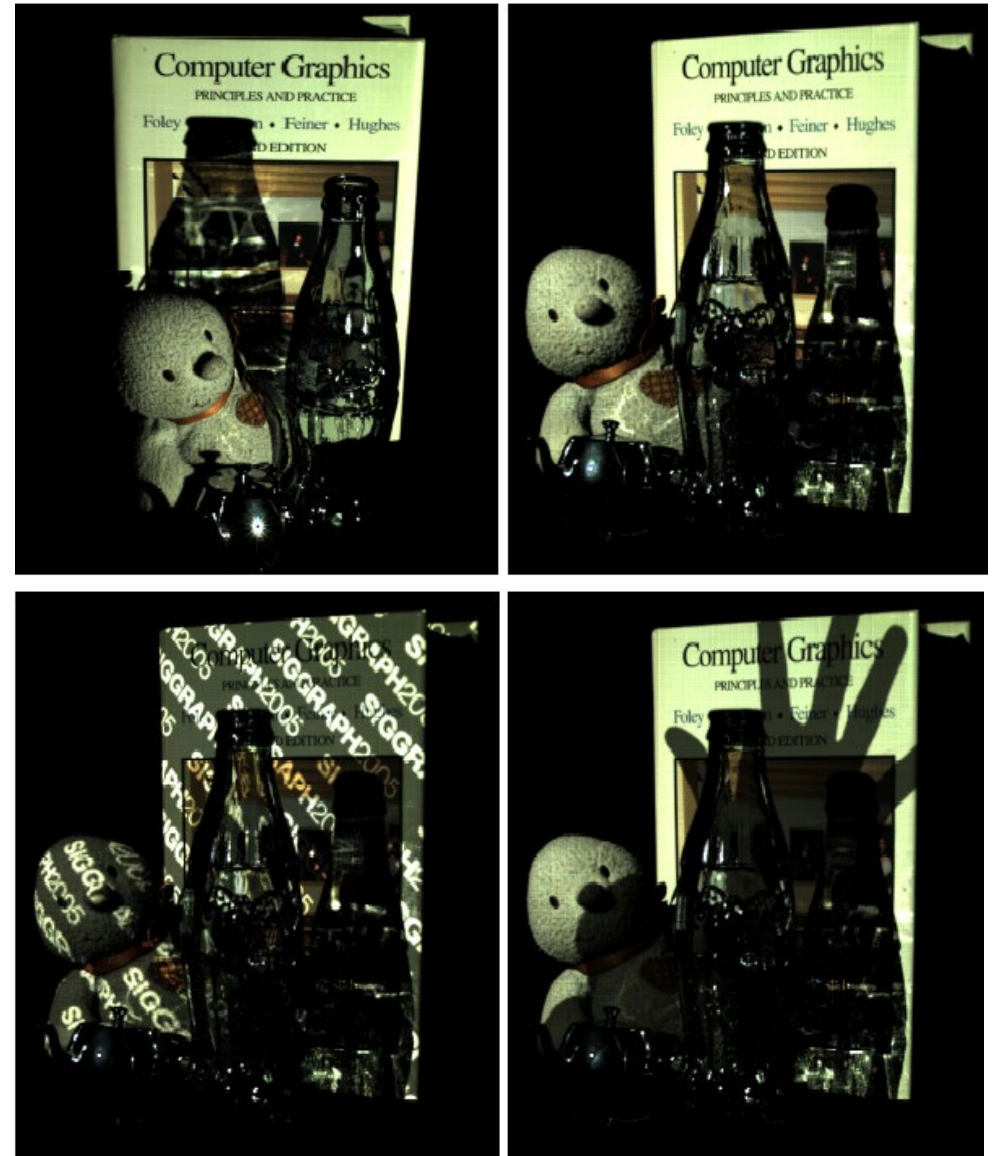
Special topics

- non-line-of-sight imaging

- Fermat paths

- geometric optics

- Helmholtz stereopsis

- reciprocity in light transport

- TBD for Friday 12/11!

Things you should know how to do

1. Build simple pinhole cameras, use DSLR cameras and modern lenses.

2. Write your own LDR and HDR image processing pipelines.

3. Calibrate the radiometric, color, noise, and geometric properties of a camera.

4. Fuse images and perform flash/no-flash photography.

5. Use bilateral and gradient-domain filtering for image editing tasks.

6. Capture and refocus your own lightfields and focal stacks.

7. Build three different types of depth and shape sensing systems: depth-from-defocus, photometric stereo, structured light.

Do you plan on taking any other vision/graphics courses?

If you are an undergraduate, check out the new **graphics concentration**.

Background courses (ideally you should take both):
- 15-462 computer graphics.
- 16-385 computer vision.

More advanced courses directly relevant for computational photography and imaging:
- <u>15-468 physics-based rendering – modeling, simulating, and inverting light transport.</u> ← new in Spring 2021, offered by Yannis
- 15-458 discrete differential geometry – background for 3D geometry processing and geometric optics.
- 16-822 geometry-based methods in vision – all about epipolar geometry.
- 16-726 learning-based image synthesis – learning-based variants of computational photography algorithms.
- 16-722 sensing and sensors – background on vision and other sensors and noise modeling.
- 16-866 sensor systems – similar to above, background on vision and other sensors and noise modeling.
- 33-353 intermediate optics – wave optics, hands-on experience with optical components.
- 18-416 nano-bio-photonics – modern photonics systems and applications to biology.

More general vision (left) and graphics (right):
- 16-824 visual learning and recognition
- 10-703 deep reinforcement learning
- 16-831 statistical techniques in robotics
- 16-833 robot localization and mapping
- 16-881 deep Reinforcement Learning for Robotics

- 15-365 experimental animation
- 15-464 technical animation
- 15-465 animation art and technology
- 15-466 computer game programming
- 15-469 algorithmic textiles design

Interested in doing research in computational imaging or rendering? Talk to me!

Many, many possible projects, including:

- Projects on rendering and inverse rendering.
- Projects on theory of light transport.
- Projects on coherent imaging and optical coherence tomography.
- Projects on material inference (reflectance, scattering, refractive fields, particle sizing).
- Projects on tissue imaging.
- Projects on non-line-of-sight imaging.
- Projects on combining physics (rendering) and deep learning.
- Projects on data-driven optimization of imaging systems.
- Projects derived from your final project for a paper publication.

Many 15-463/663/862 alumni have worked on various research projects in my group.

Ideal background:
- Knowledge of (at least one of) graphics, vision, physics, numerical computing.
- If you've taken 15-463, you have the background.

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Convolutional Approximations to the General Non-Line-of-Sight Imaging Operator
Byeongjoo Ahn, Akshat Dave, Ashok Veeraraghavan, Ioannis Gkioulekas, and Aswin C. Sankaranarayanan. *ICCV 2019.*

A Differential Theory of Radiative Transfer
Cheng Zhang, Lifan Wu, Changxi Zheng, Ioannis Gkioulekas, Ravi Ramamoorthi, and Shuang Zhao. *ACM SIGGRAPH Asia 2019.*

Ellipsoidal Path Connections for Time-gated Rendering
Adithya Pediredla, Ashok Veeraraghavan, and Ioannis Gkioulekas. *ACM SIGGRAPH 2019.*

Wave-based Non-Line-of-Sight Imaging using Fast f-k Migration
David B. Lindell, Gordon Wetzstein, Matthew O'Toole. *ACM SIGGRAPH 2019.*

A Monte Carlo Framework for Rendering Speckle Statistics in Scattering Media
Chen Bar, Marina Alterman, Ioannis Gkioulekas, Anat Levin. *ACM SIGGRAPH 2019.*

A Theory of Fermat Paths for Non-Line-of-Sight Shape Reconstruction
Shumian Xin, Sotiris Nousias, Kiriakos N. Kutulakos, Aswin C. Sankaranarayanan, Srinivasa G. Narasimhan, and Ioannis Gkioulekas. *CVPR 2019.*

Multispectral Imaging for Fine-Grained Recognition of Powders on Complex Backgrounds
Tiancheng Zhi, Bernardo R. Pires, Martial Hebert, Srinivasa G. Narasimhan. *CVPR 2019.*

Beyond Volumetric Albedo—A Surface Optimization Framework for Non-Line-of-Sight Imaging
Chia-Yin Tsai, Aswin C. Sankaranarayanan, Ioannis Gkioulekas. *CVPR 2019.*

Non-Line-of-Sight Imaging with Partial Occluders and Surface Normals
Felix Heide, Matthew O'Toole, Kai Zang, David B. Lindell, Steven Diamond, Gordon Wetzstein. *ACM Trans. on Graphics 2019.*

Towards Multifocal Displays with Dense Focal Stacks
Rick Chang, Vijaya Kumar, Aswin C. Sankaranarayanan. *ACM SIGGRAPH Asia 2018.*

http://imaging.cs.cmu.edu/

This class is still evolving, so your feedback is invaluable.

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Questions?