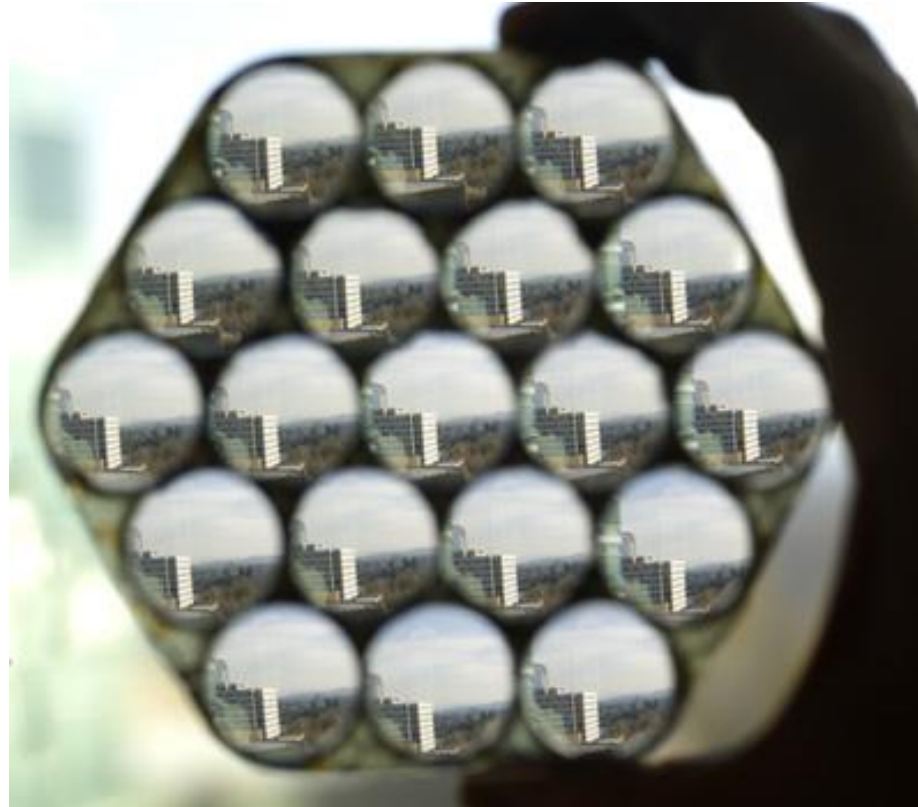


# Introduction



# Overview of today's lecture

- Teaching staff introductions
- What is computational photography?
- Course fast-forward and logistics

Teaching staff introductions

# Instructor: Ioannis (Yannis) Gkioulekas

I won't hold it against you if you mispronounce my last name



Originally from Greece



National Technical University of Athens (2004-09)



Harvard University (2009-17)



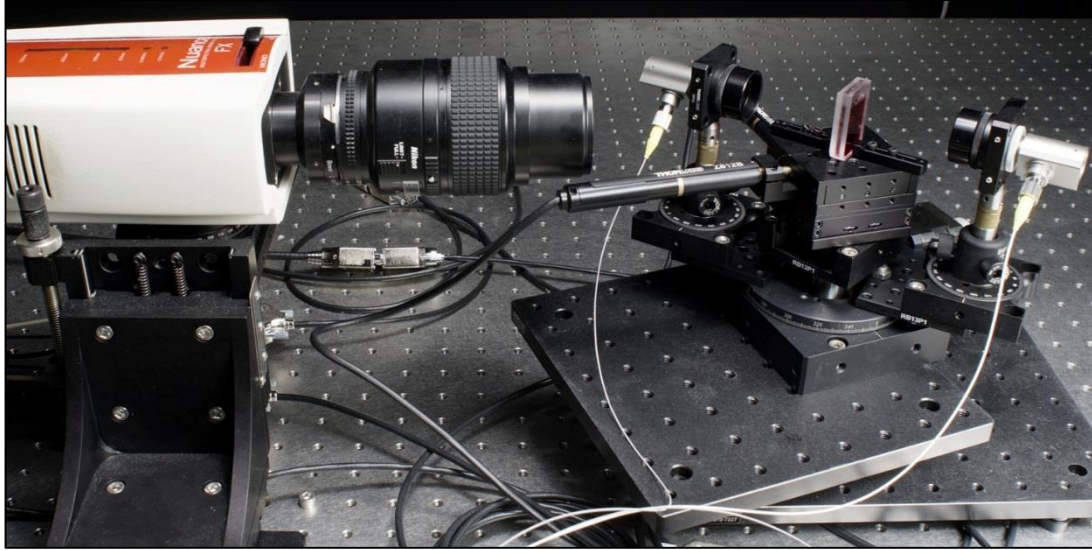
Carnegie Mellon University (2017-now)



me at Harvard in 2011  
(obviously need new photo)

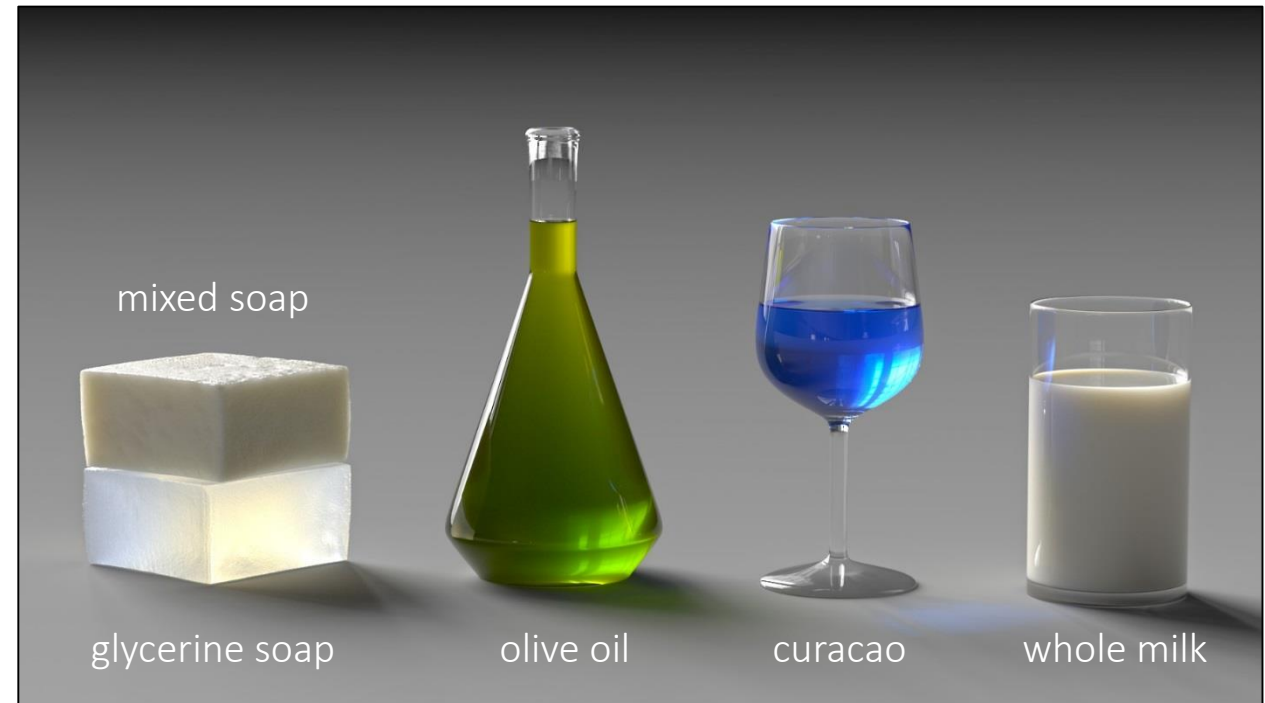
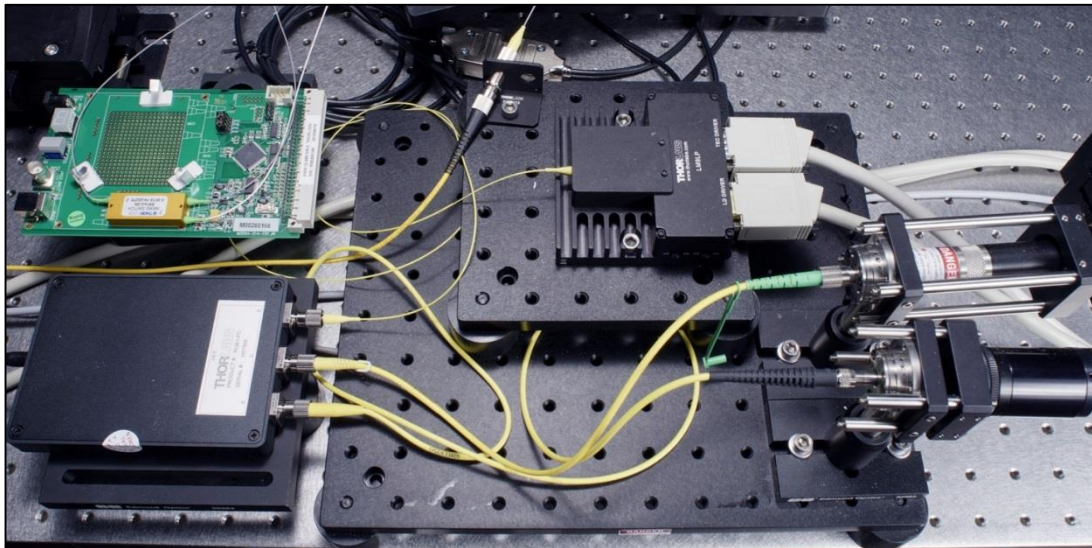
My website: <http://www.cs.cmu.edu/~igkioule>

# Building a scatterometer



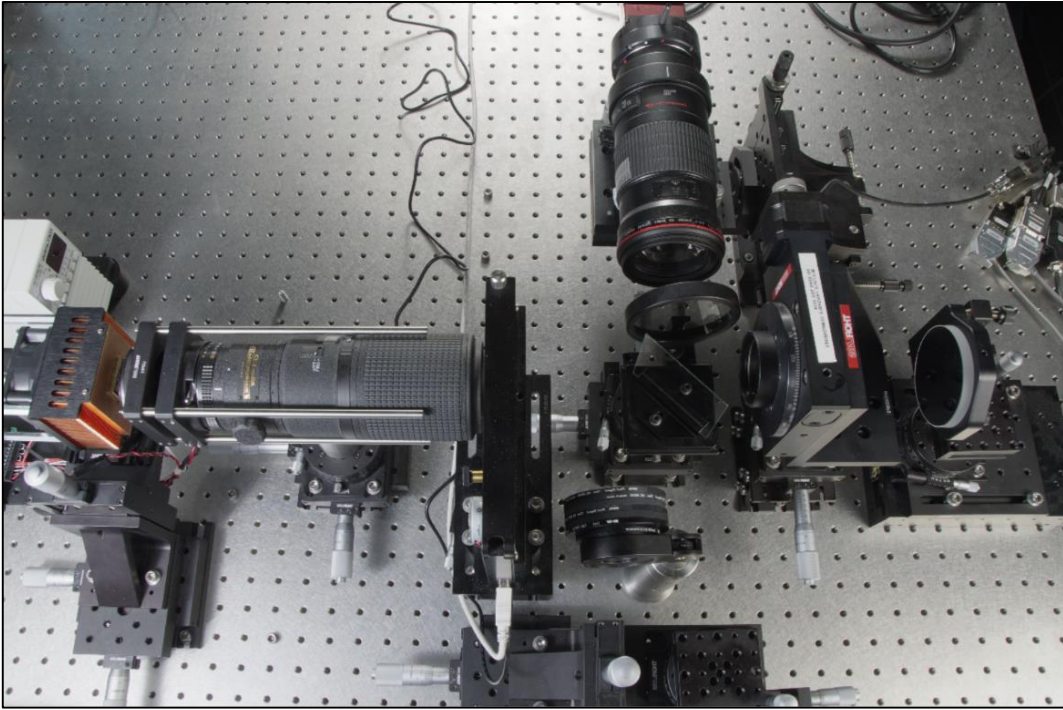
camera for measuring parameters  
of scattering materials

image synthesized from measurements

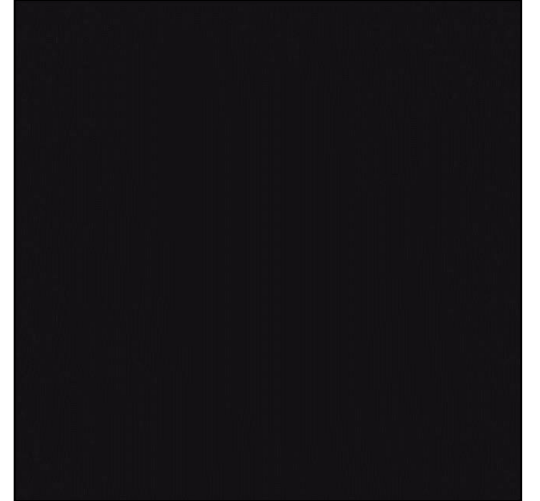




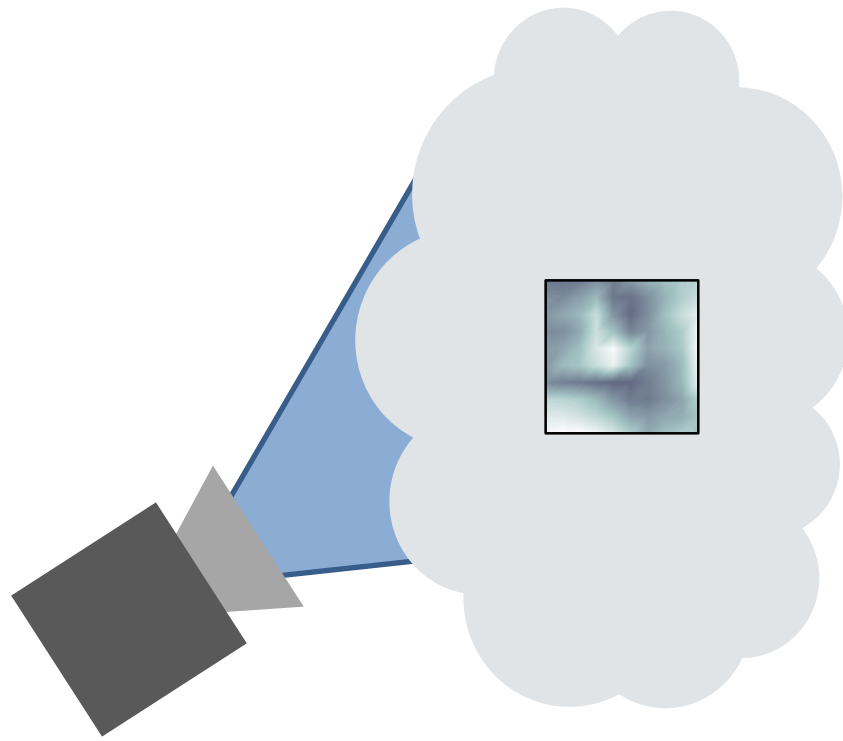
# Seeing light in flight



camera for capturing video at  $10^{15}$   
frames per second

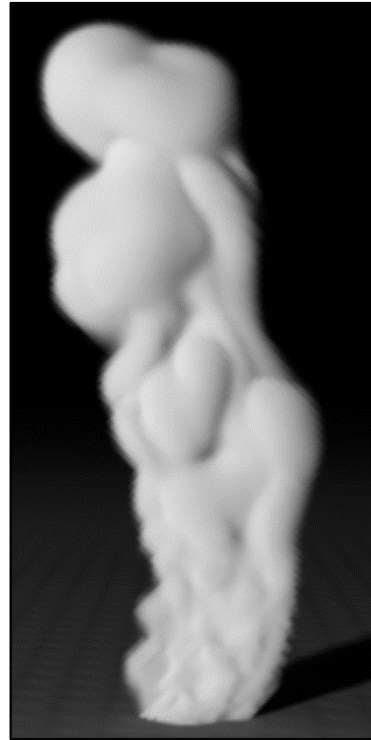


# Seeing inside objects



camera

thick smoke  
cloud



what a regular  
camera sees



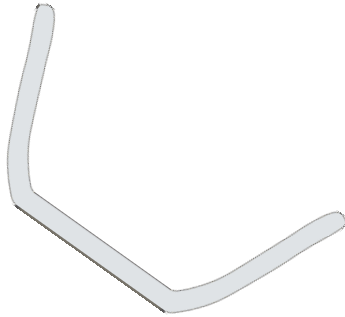
what our  
camera sees



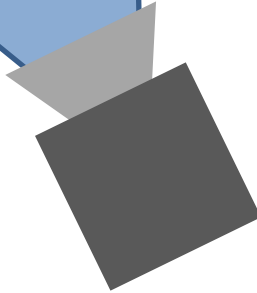
a slice through  
the cloud

# Seeing around walls

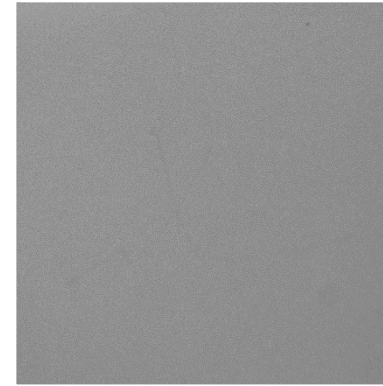
wall



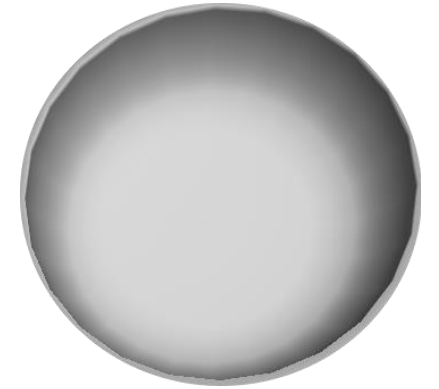
hidden object



camera



what a regular  
camera sees

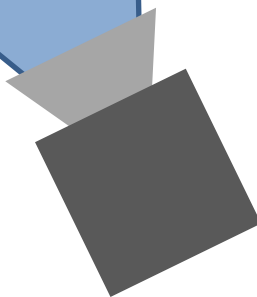


what shape our  
camera sees

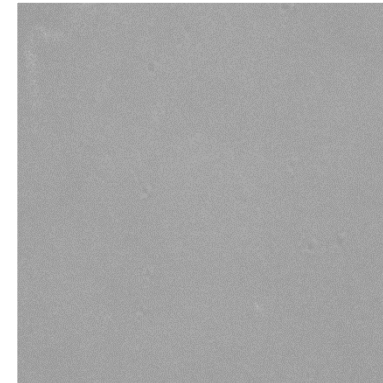
wall



hidden object



camera



what a regular  
camera sees



what depth our  
camera sees



# TA: Alankar Kotwal

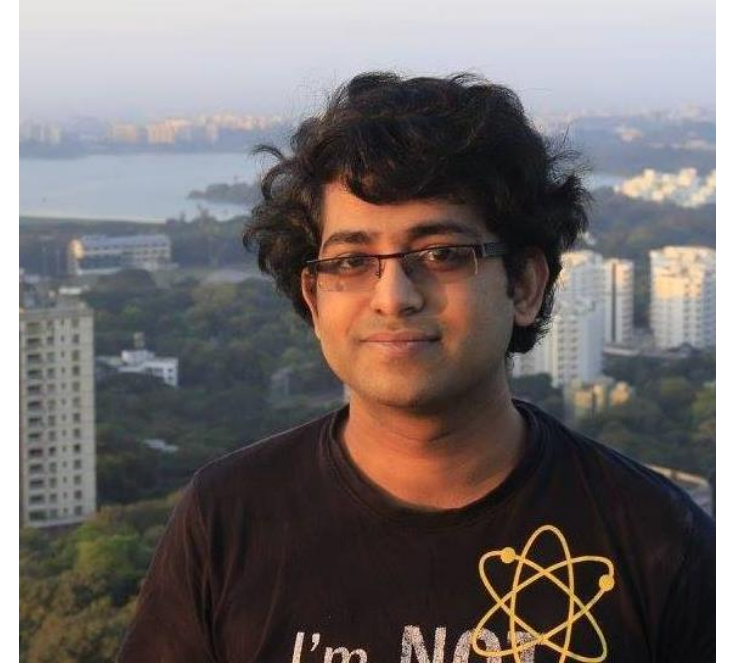
- RI PhD student
- Advisor: Yannis
- Research interests: seeing light in flight, seeing through objects
- Office Smith 220, usually found in lab Newell-Simon B526
- Education:



EE Undergrad + Masters: Indian Institute of Technology Bombay (July 2012-2017)

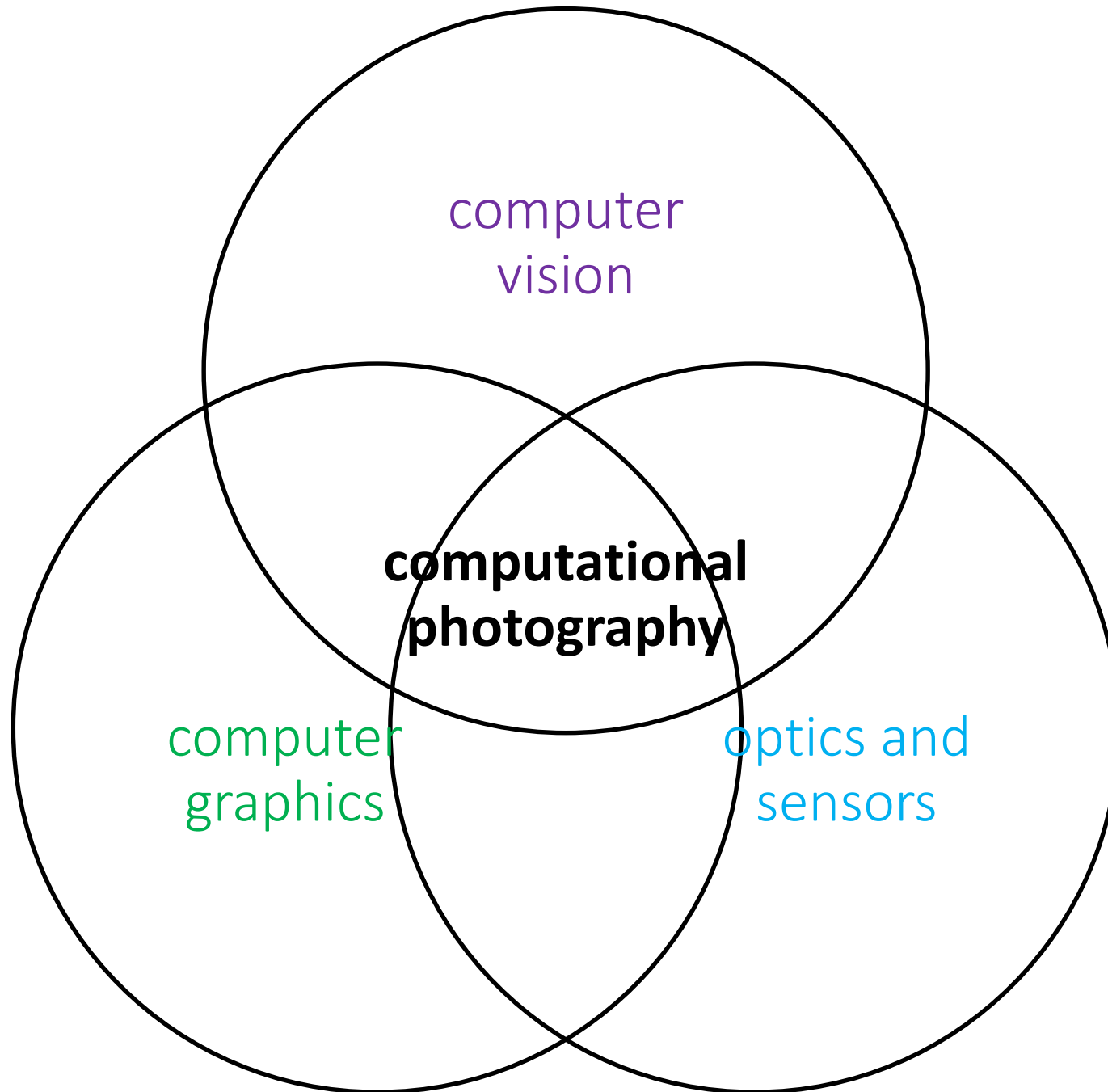


Robotics PhD: Carnegie Mellon University (Aug 2017-now)



My website: [alankarkotwal.github.io](https://alankarkotwal.github.io), email: [aloo@cmu.edu](mailto:aloo@cmu.edu)

What is computational photography?



# Analog photography



optics to focus light on  
an image plane



film to capture focused light  
(chemical process)



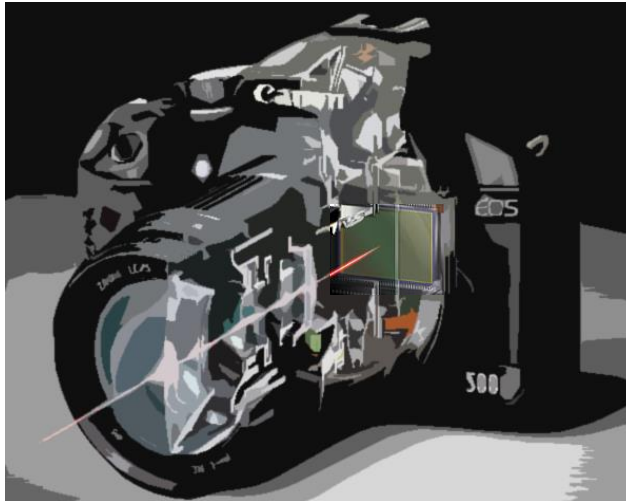
dark room for limited post-  
processing (chemical process)



# Digital photography



optics to focus light on  
an image plane



digital sensor to capture focused  
light (electrical process)



on-board processor for post-  
processing (digital process)

# Computational photography



optics to focus light on  
an image plane



digital sensor to capture focused  
light (electrical process)



arbitrary computation  
between sensor and image

# Overcome limitations of digital photography

Image enhancement and photographic look



camera output



image after stylistic tonemapping

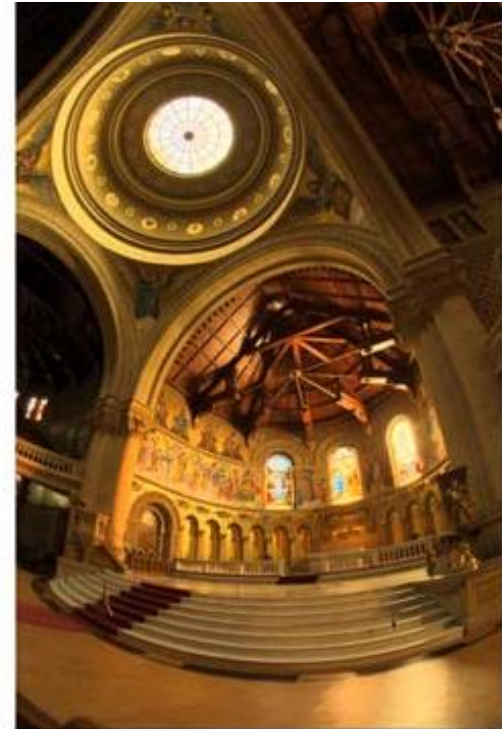
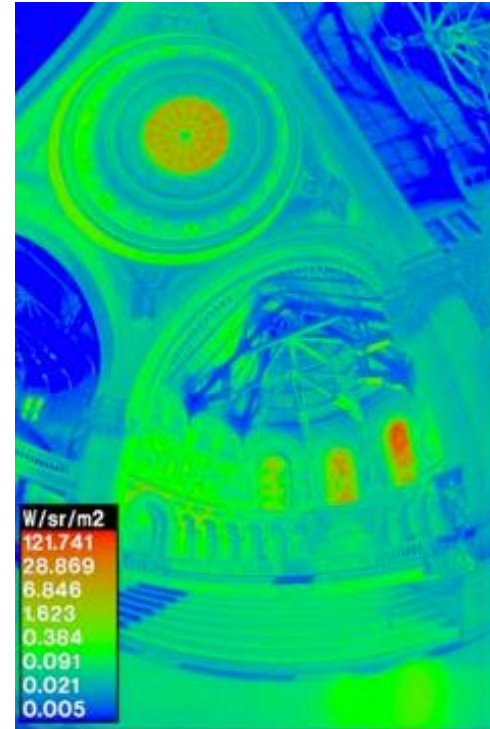
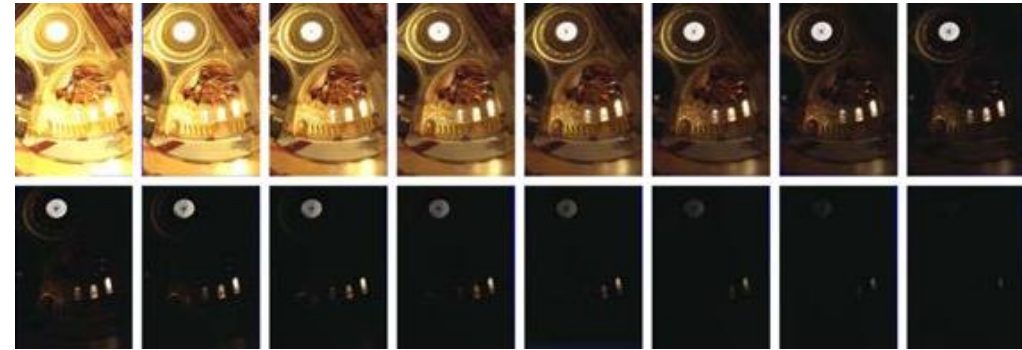


# Overcome limitations of digital photography

High dynamic range (HDR) imaging



One of your  
homeworks!

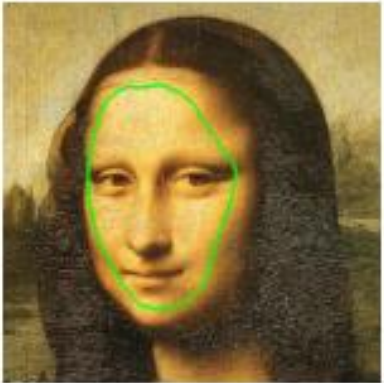


[example from [www.dpreview.com](http://www.dpreview.com)] [Debevec and Malik, SIGGRAPH 1997]



# Create realistic new imagery

Image blending and harmonization



# Post-capture image compositing

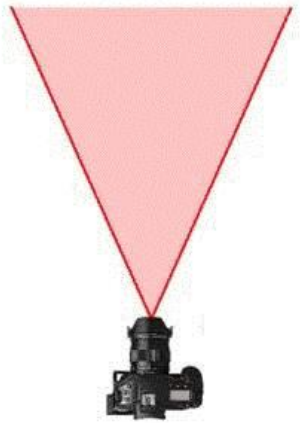
## Computational zoom



images captured at three zoom settings



post-capture synthesis of new zoom views

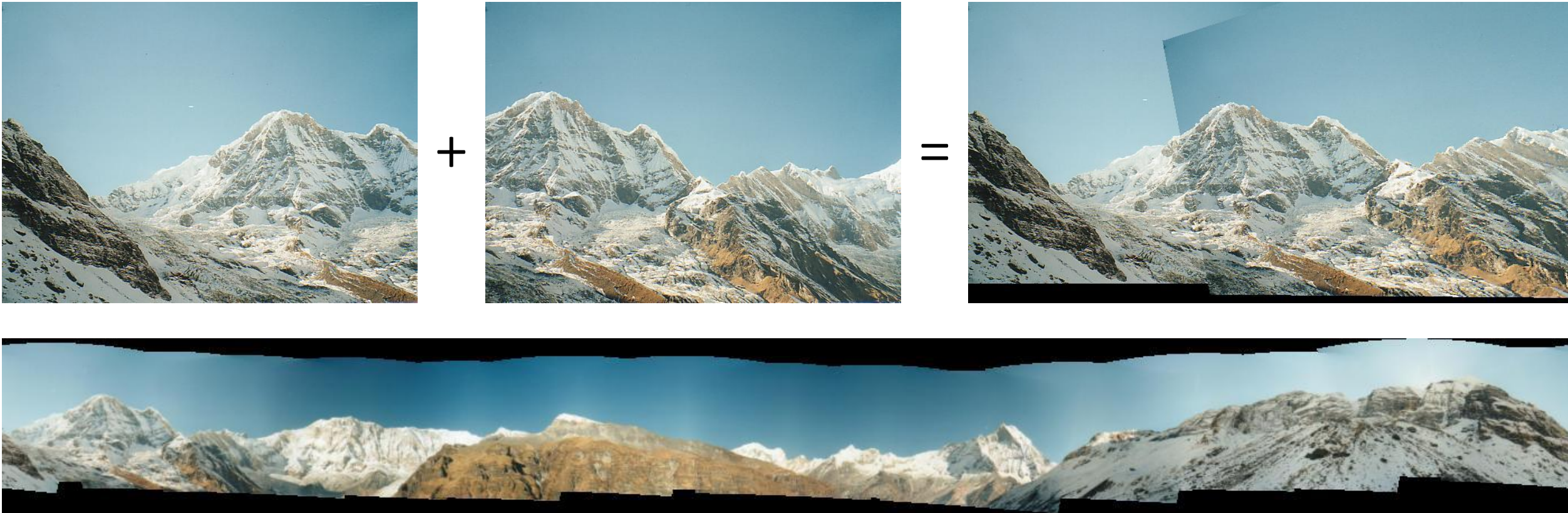


One of your  
homeworks!



# Process image collections

Auto-stitching images into panoramas



# Process (very) large image collections

Using the Internet as your camera



reconstructing cities from Internet photos



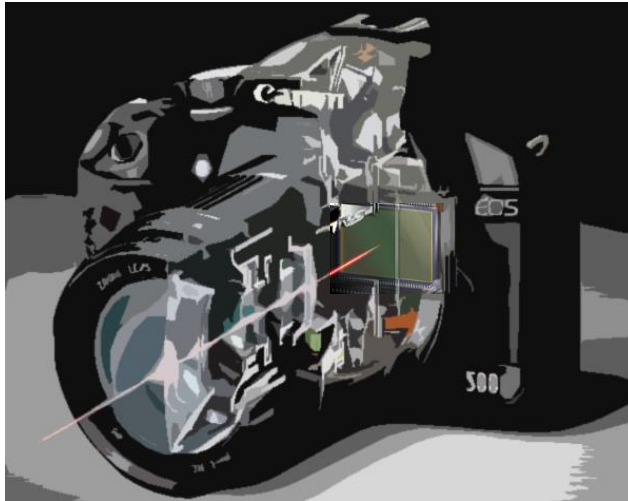
time-lapse from Internet photos



# Computational photography



optics to focus light on  
an image plane



digital sensor to capture focused  
light (electrical process)



arbitrary computation  
between sensor and image

# Computational photography



generalized optics  
between scene and sensor



digital sensor to capture focused  
light (electrical process)



arbitrary computation  
between sensor and image

\*Sometimes people discriminate between *computational photography* and *computational imaging*. We use them interchangeably.

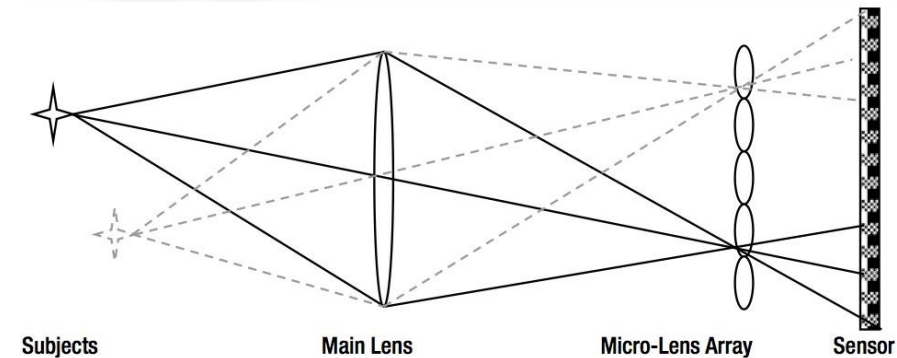
# Capture more than 2D images

Lightfield cameras for plenoptic imaging



post-capture refocusing

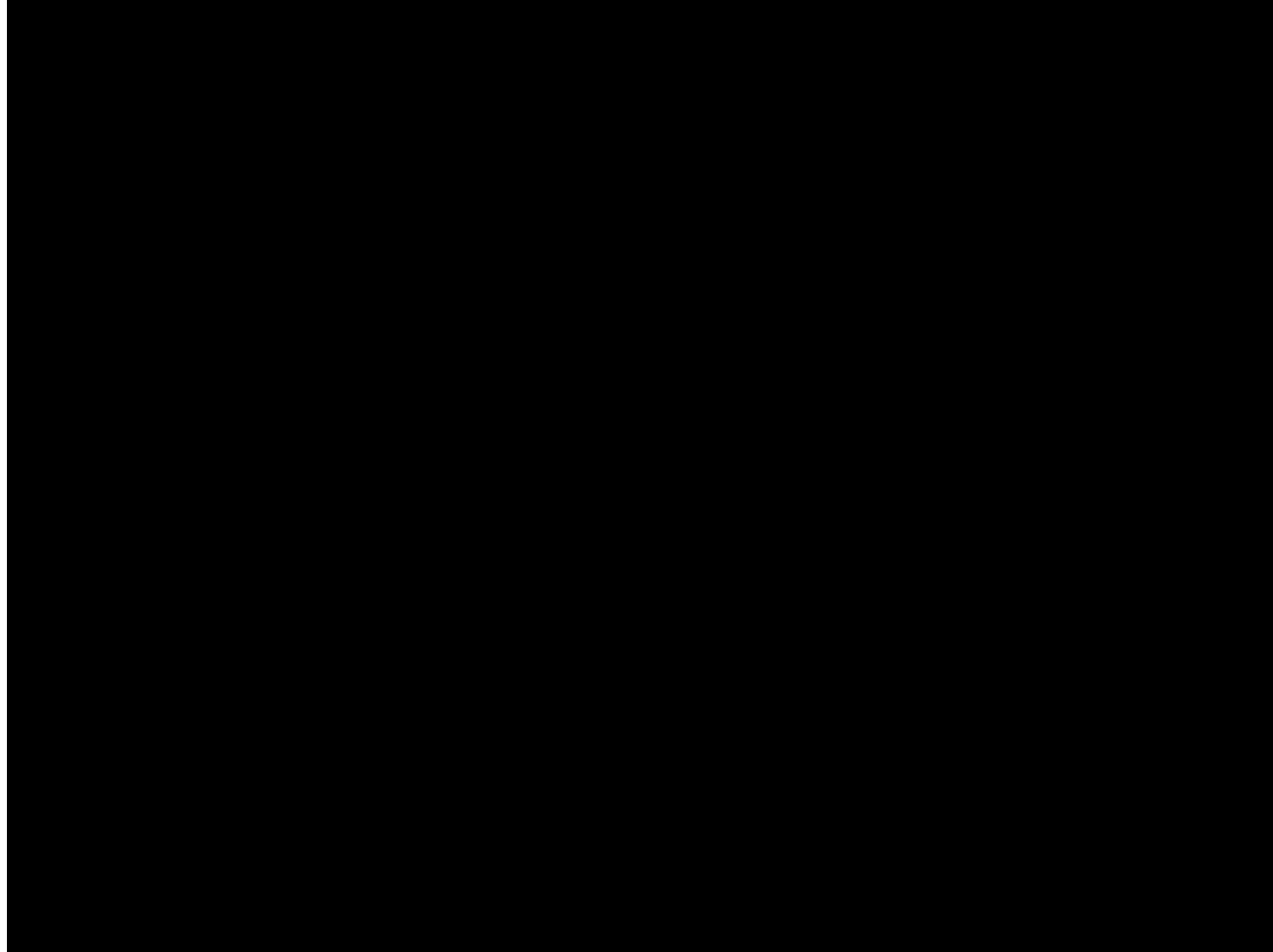
One of your  
homeworks!



[Ng et al., SIGGRAPH 2005] [Lytro Inc.]

# Capture more than 2D images

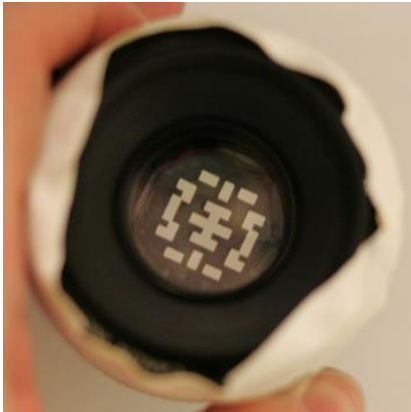
Lightfield cameras for plenoptic imaging



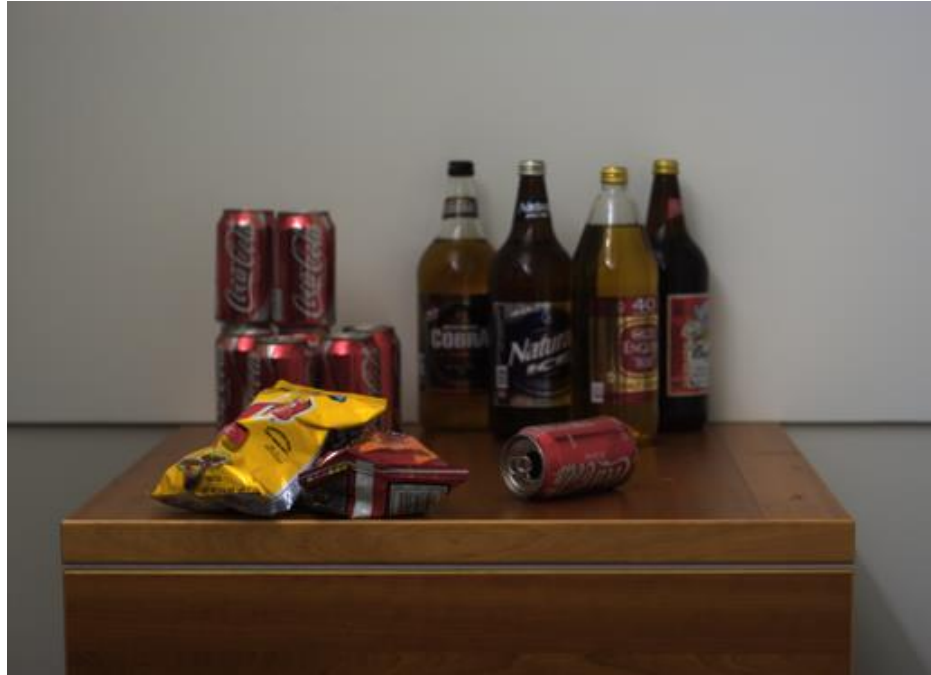


# Measure 3D from a single 2D image

Coded aperture for single-image depth and refocusing



conventional vs  
coded lens



input image



inferred depth

# Measure 3D from a single 2D image

Coded aperture for single-image depth and refocusing



## Image and Depth from a Conventional Camera with a Coded Aperture

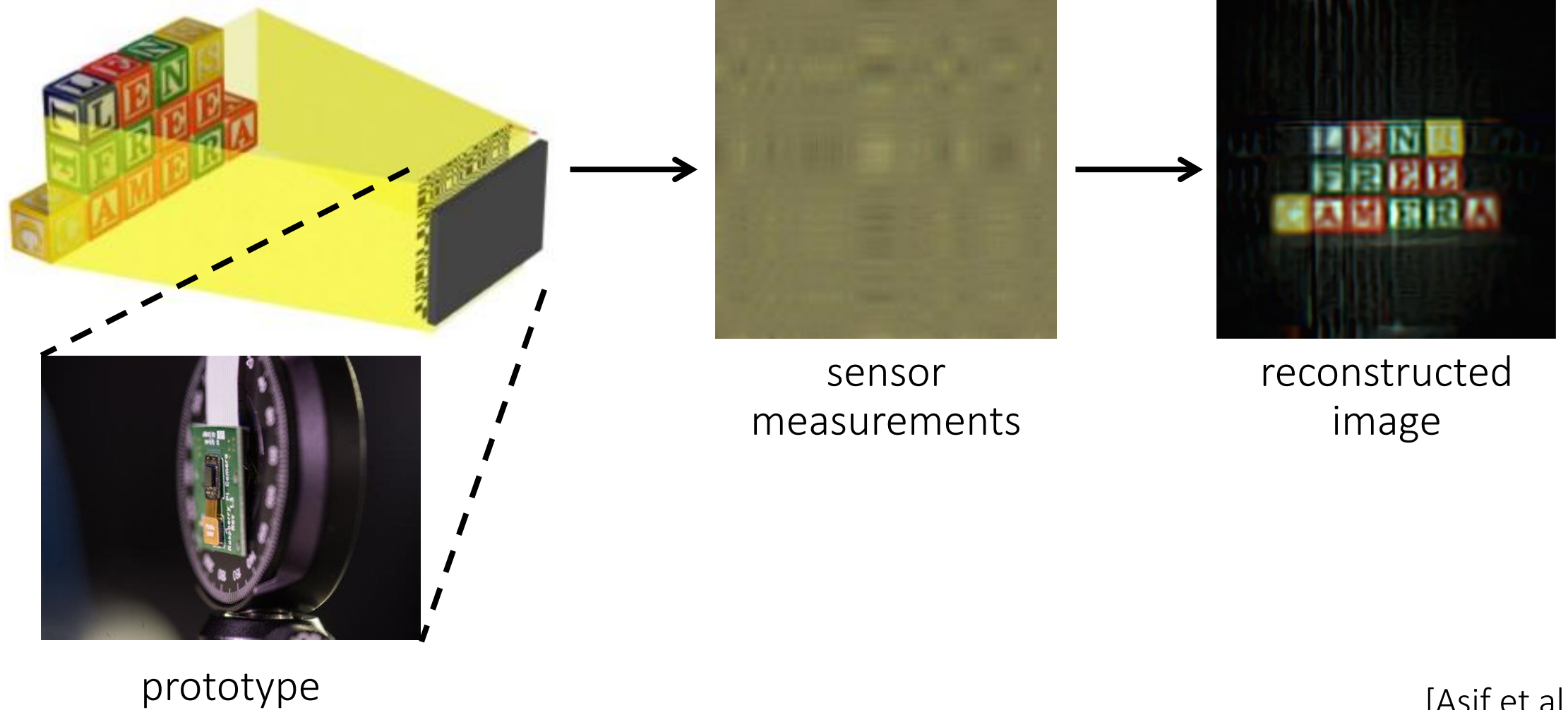
Novel view synthesis

Anat Levin, Rob Fergus,  
Fredo Durand, William Freeman

MIT CSAIL

# Remove lenses altogether

FlatCam: replacing lenses with masks





# Computational photography



generalized optics  
between scene and sensor



digital sensor to capture focused  
light (electrical process)

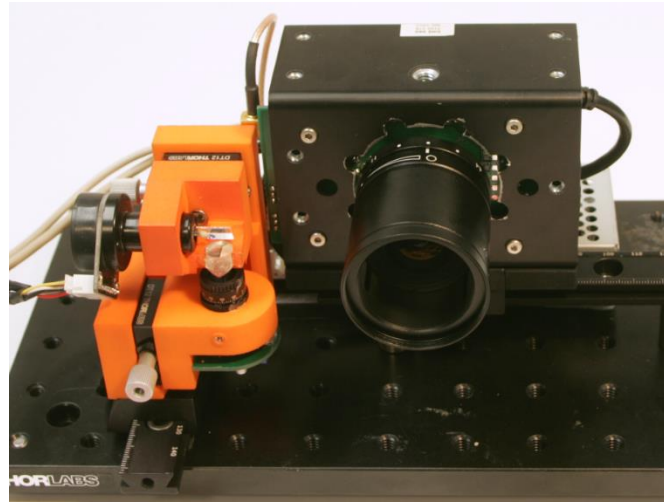


arbitrary computation  
between sensor and image

# Computational photography



generalized optics  
between scene and sensor



unconventional sensing  
and illumination

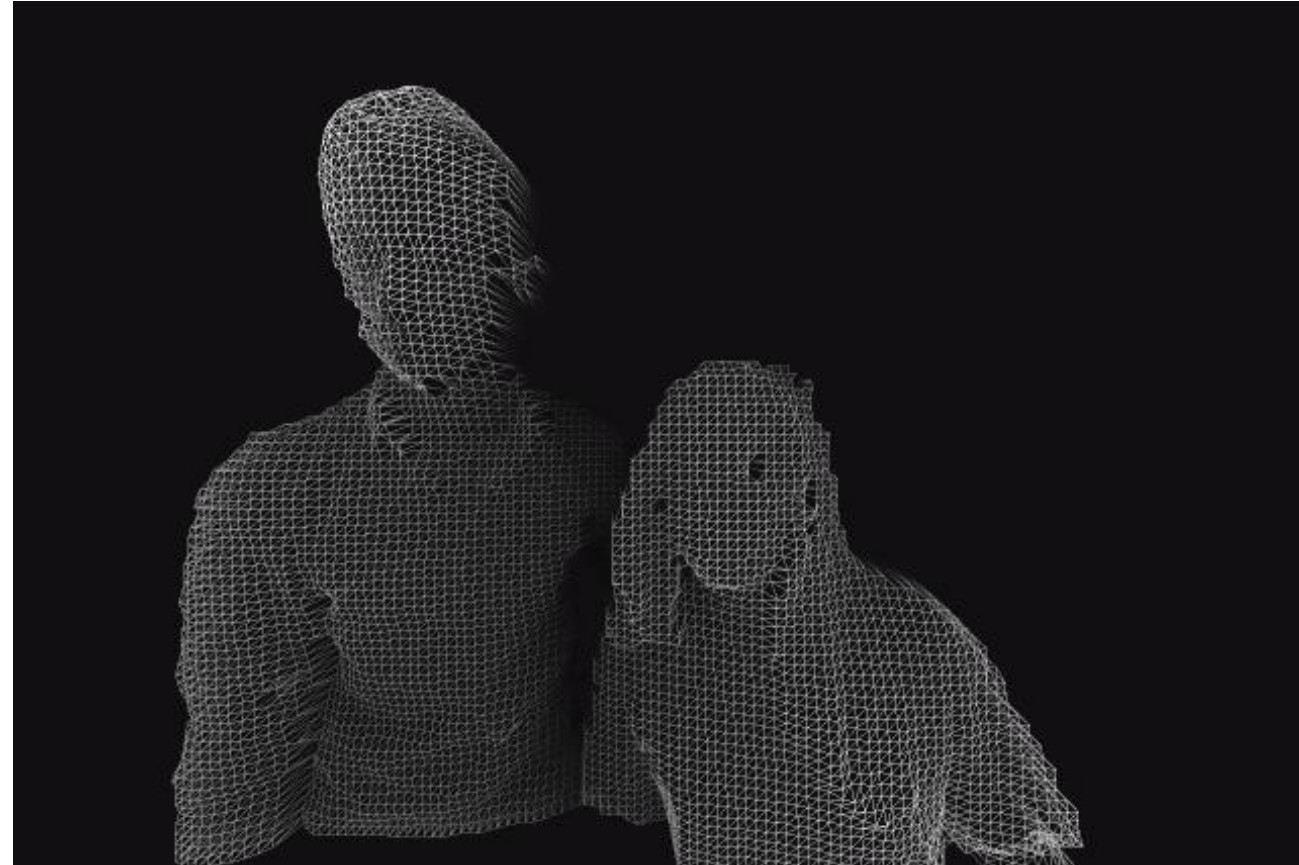


arbitrary computation  
between sensor and image



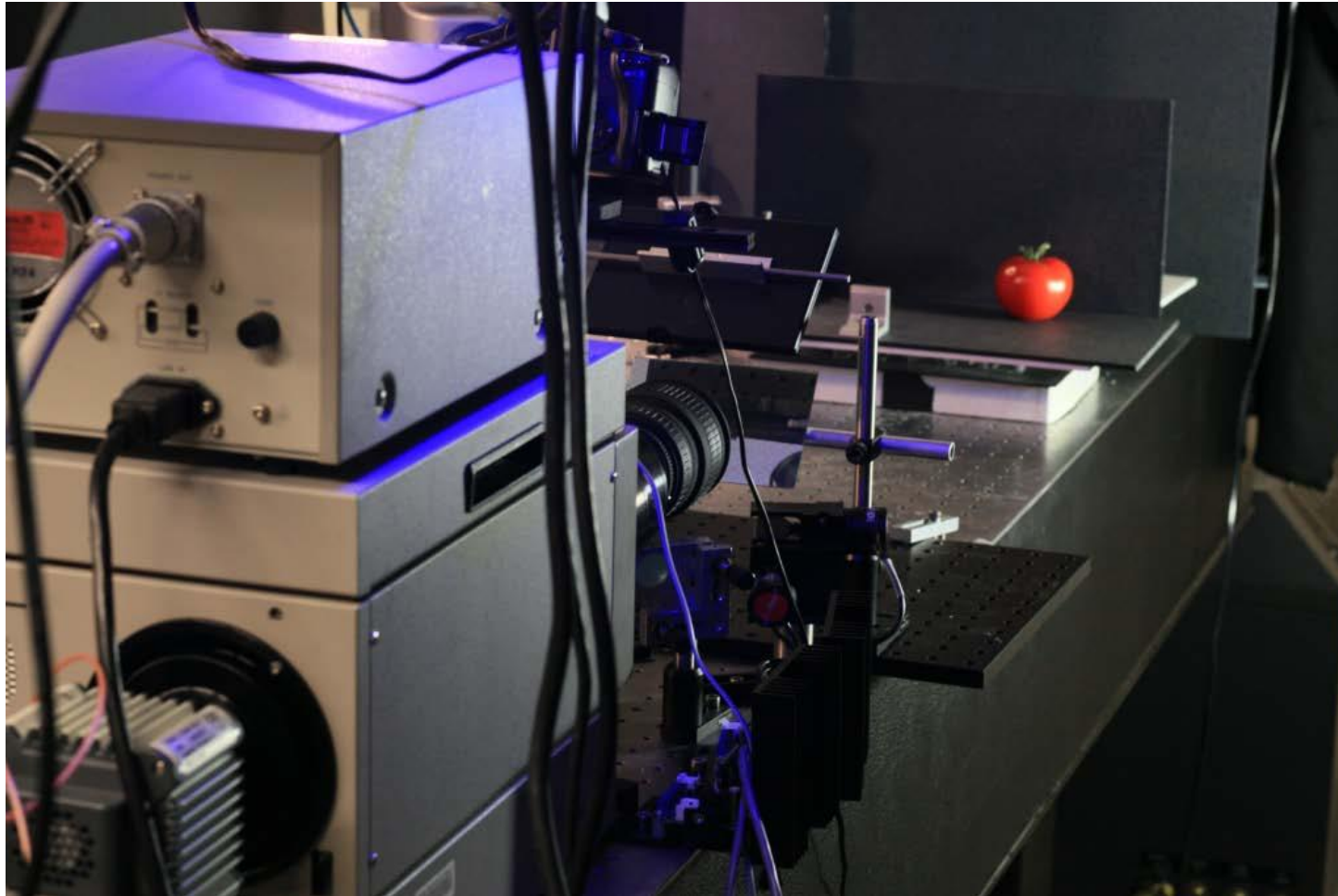
# Measure depth

Time-of-flight sensors for real-time depth sensing



# Measure light in flight

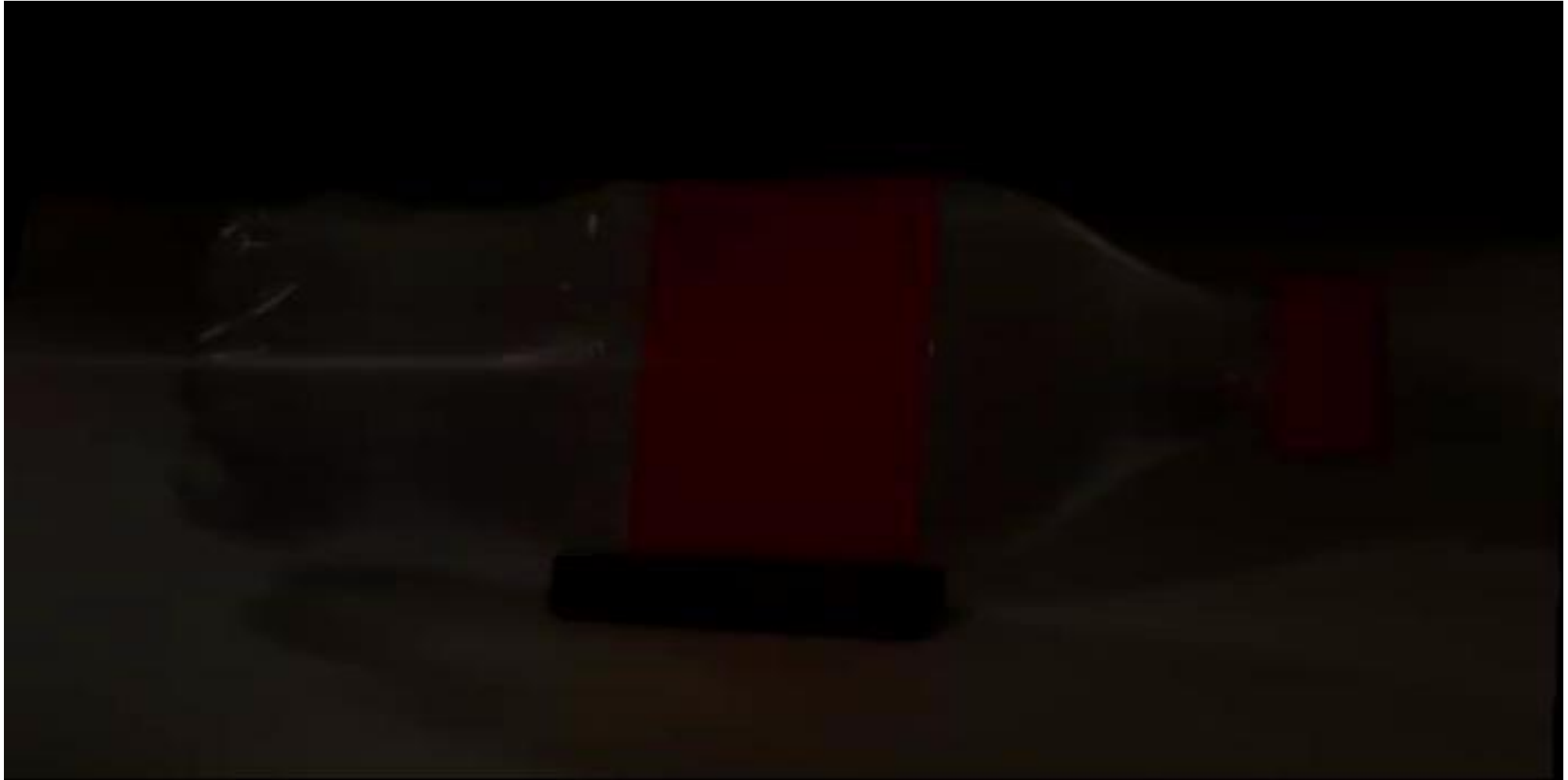
Streak camera for femtophotography



[Velten et al., SIGGRAPH 2013]

# Measure light in flight

Streak camera for femtophotography

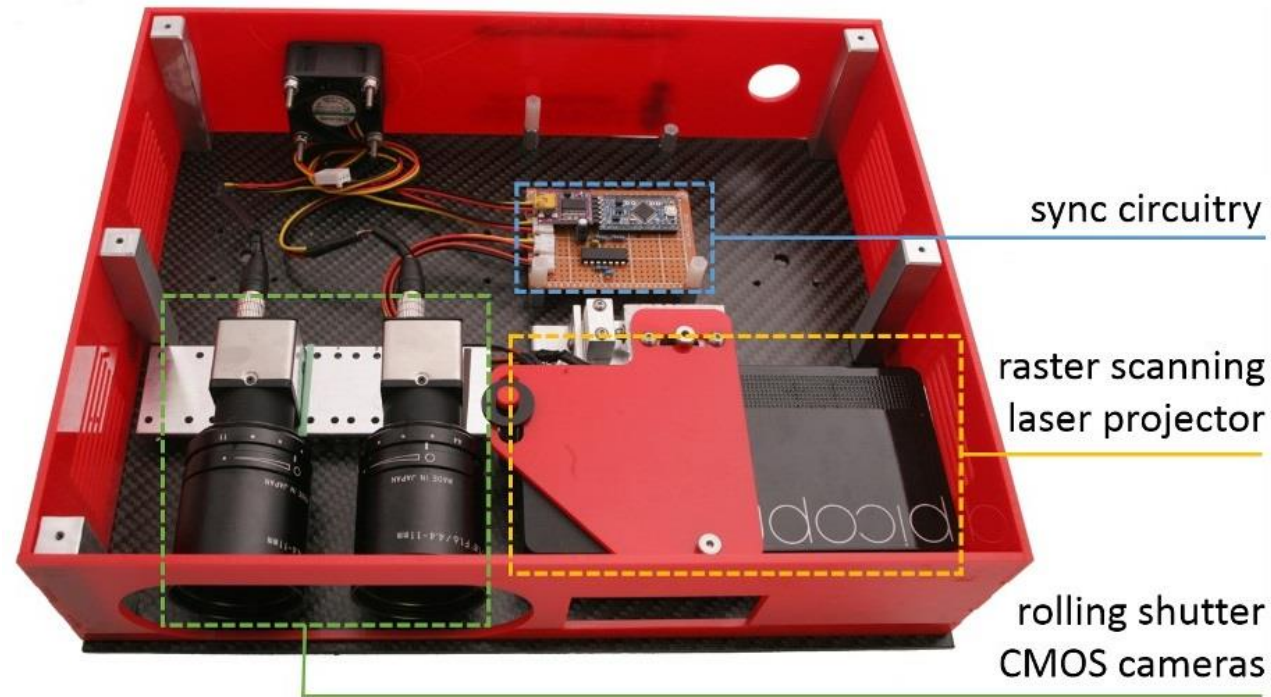


[Velten et al., SIGGRAPH 2013]



# Measure photons selectively

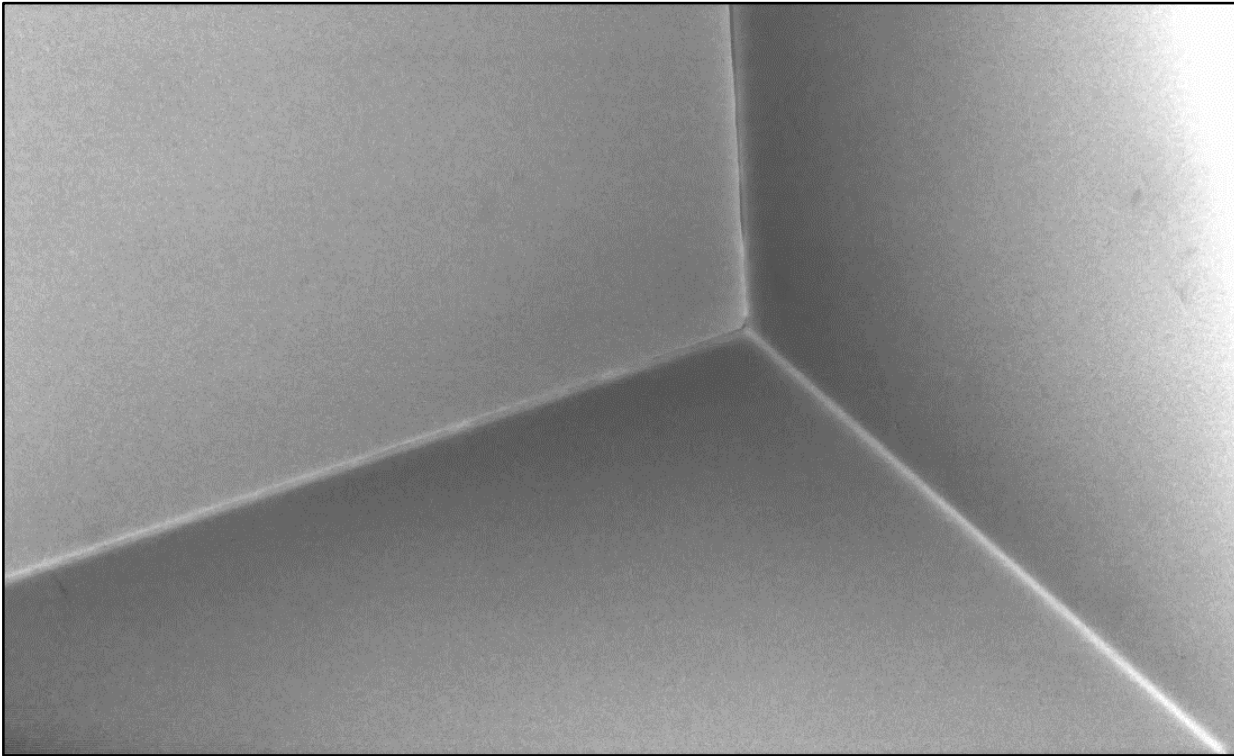
Structured light for epipolar imaging



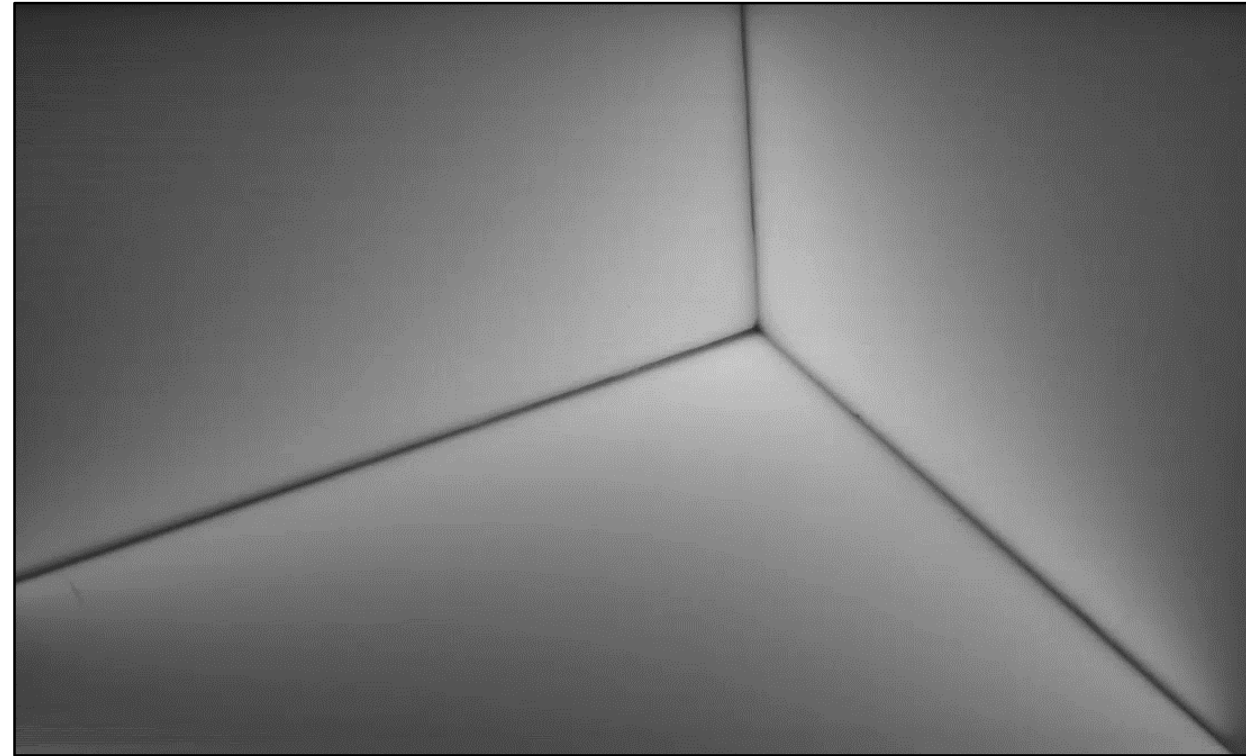
# Measure photons selectively

One of your  
homeworks!

Structured light for epipolar imaging



direct photons

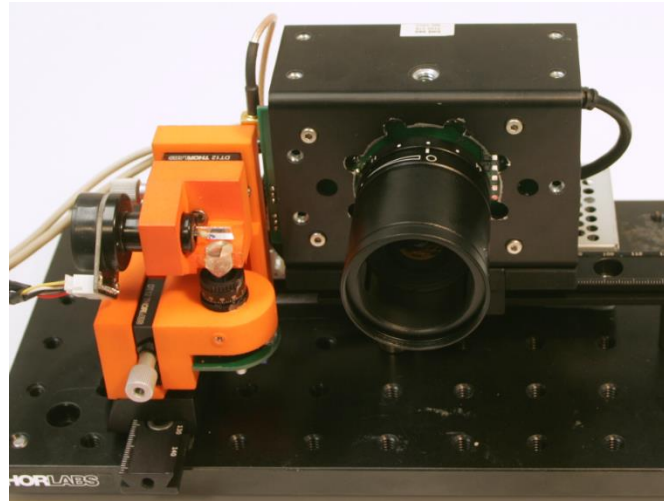


indirect photons

# Computational photography



generalized optics  
between scene and sensor



unconventional sensing  
and illumination



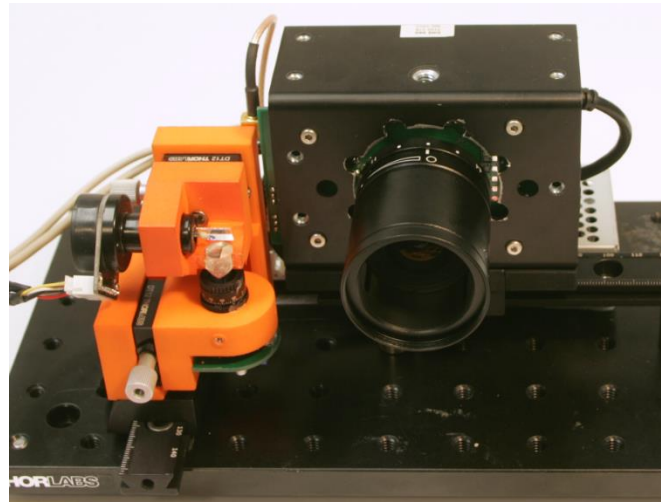
arbitrary computation  
between sensor and image



# Computational photography



generalized optics  
between scene and sensor



unconventional sensing  
and illumination

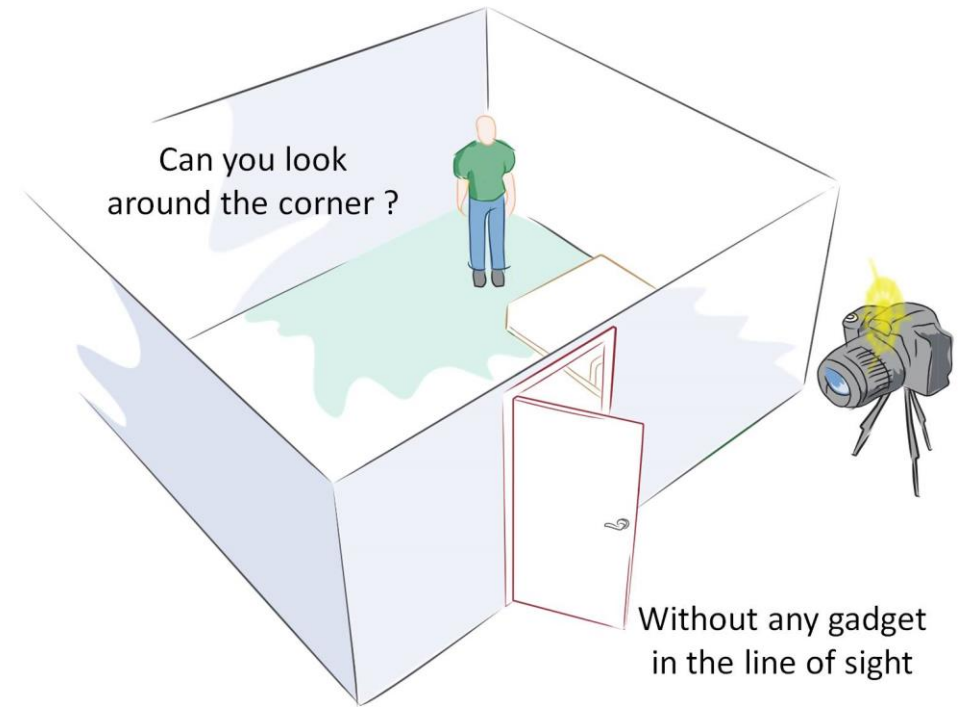


arbitrary computation  
between sensor and image

joint design of optics, illumination, sensors, and computation

# Putting it all together

Looking around corners



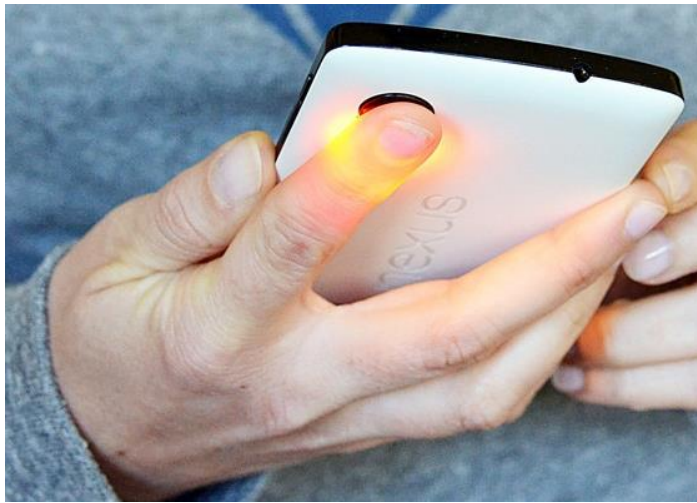
One of your  
homeworks!



# Putting it all together

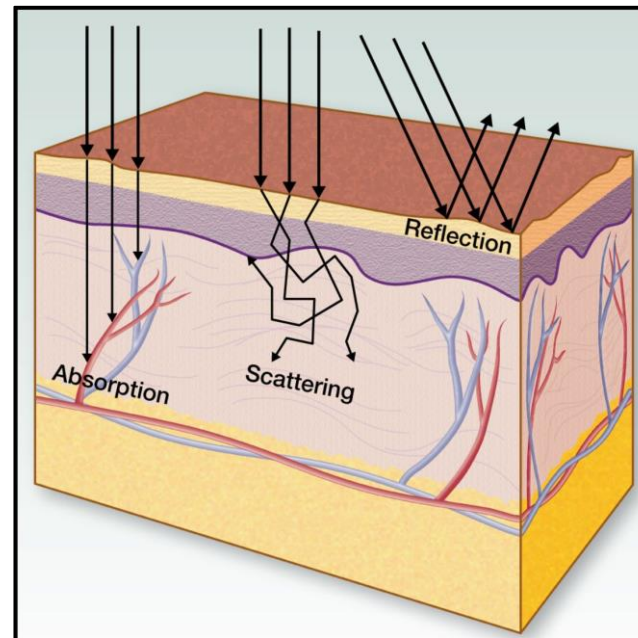
## Looking through tissue

### Opportunity



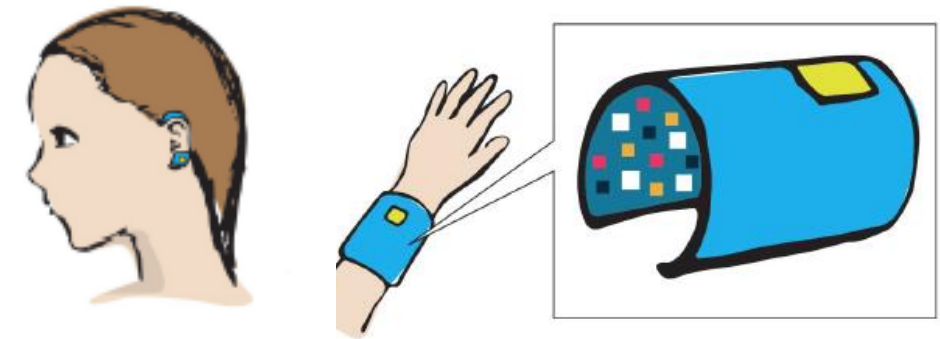
- + Light travels deep inside the body
- + It is non-ionizing (400-1100nm)
- + Cheap to produce and control

### Scattering Barrier

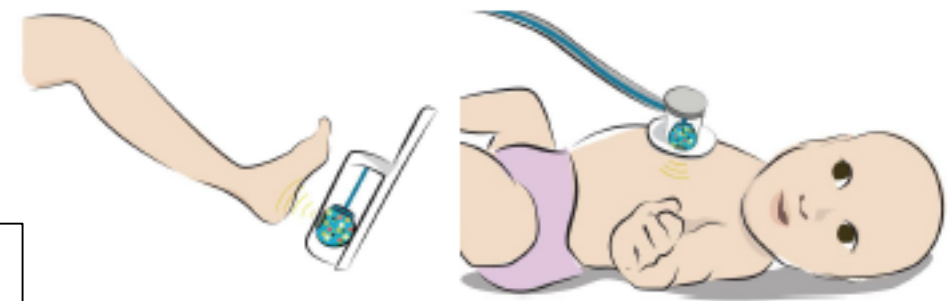


- Most pass-through photons are scattered
- Avg 10 scattering events per mm
- By 50mm, avg 500 scattering events !
- Large-scale inverse problem with low SNR

Practical imaging up to 50mm



Wearables (1-10mm)



Non-invasive point of care devices (10-50mm)

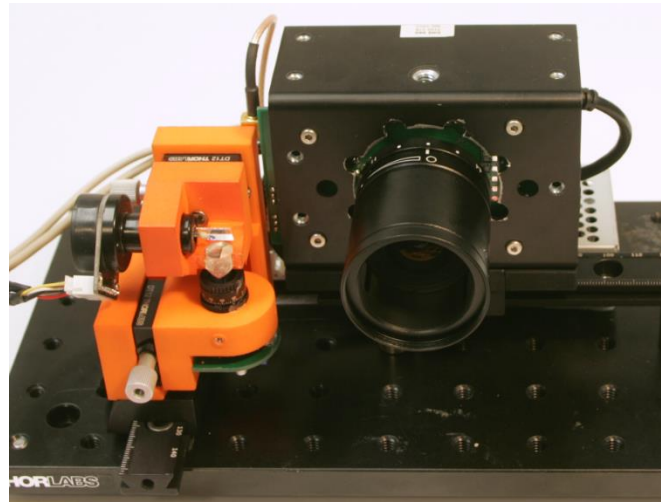
[NSF Expedition]



# Computational photography



generalized optics  
between scene and sensor



unconventional sensing  
and illumination



arbitrary computation  
between sensor and image

joint design of optics, illumination, sensors, and computation

Course fast-forward and logistics

# Course fast-forward

Tentative syllabus at:

<http://graphics.cs.cmu.edu/courses/15-463>

- schedule and exact topics will most likely change during semester
- keep an eye out on the website for updates

# Topics to be covered

## Digital photography:

- optics and lenses
- color
- exposure
- aperture
- focus and depth of field
- image processing pipeline



[Photo from Gordon Wetzstein]



# Topics to be covered

Image manipulation and merging:

- image filtering
- image compositing
- image blending
- image warping
- morphing
- high-performance image processing



# Topics to be covered

## Types of cameras:

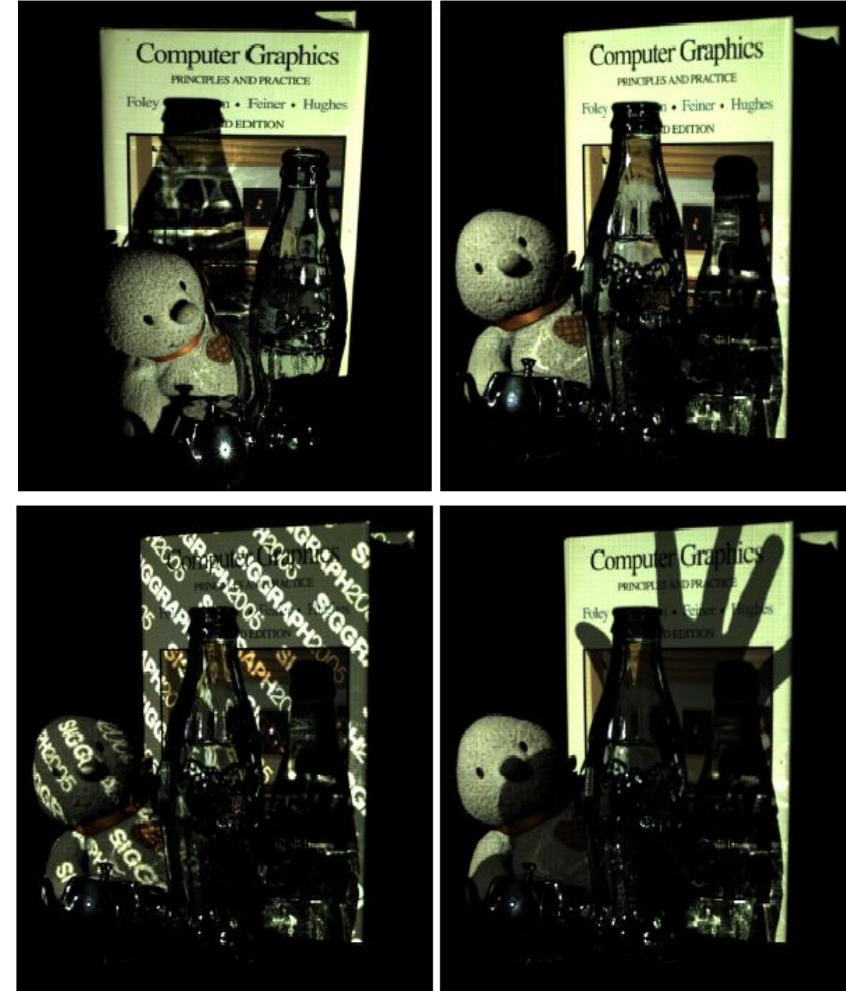
- geometric camera models
- light-field cameras
- coded cameras
- lensless cameras
- compressive cameras
- hyperspectral cameras



# Topics to be covered

## Active illumination and sensing:

- time-of-flight sensors
- structured light
- computational light transport
- transient imaging
- non-line-of-sight imaging
- optical computing



# Course logistics

- Course website:

<http://graphics.cs.cmu.edu/courses/15-463>

- Piazza for discussion and announcements (sign up!):

<https://piazza.com/class/jl5ah6igcgo1ez>

- Canvas for homework submissions:

<https://canvas.cmu.edu/courses/7047>



# Prerequisites

At least one of the following:

- A computer vision course at the level of 16-385 or 16-720.
- A computer graphics course at the level of 15-420.
- An image processing course at the level of 18-793.

# Pop quiz

How many of you know or have heard of the following terms:

- Gaussian and box filtering.
- Convolution and Fourier transform.
- Aliasing and anti-aliasing.
- Laplacian pyramid.
- Poisson blending.
- Homogeneous coordinates.
- Homography.
- RANSAC.
- Epipolar geometry.
- XYZ space.
- Radiance and radiometry.
- Lambertian, diffuse, and specular reflectance.
- $\mathbf{n} \cdot \mathbf{l}$  lighting.
- Monte Carlo rendering.
- Thin lens, prime lens, and zoom lens.
- Demosaicing.
- Refraction and diffraction.

# Evaluation

- Seven homework assignments (70%):
  - programming and capturing your own photographs.
  - all programming will be in Matlab.
  - first assignment will serve as a gentle introduction to Matlab.
  - four late days, you can use them as you want.
- Final project (25%):
  - we will provide more information near the end of September.
  - 15-663, 15-862 require more substantive project.
  - if your ideas require imaging equipment, talk to us in advance.
- Class and Piazza participation (5%):
  - be around for lectures.
  - participate in Piazza discussions.
  - ask questions.

# Do I need a camera?

- You will need to take your own photographs for assignments 1-7 (all of them):
  - Assignment 1: pinhole camera – you need a high-sensitivity camera.
  - Assignment 2: HDR – you need a camera with manual controls.
  - Assignment 3: computational zoom – you need a camera with a manual zoom lens.
  - Assignment 4: lightfields – you can use your phone camera.
  - Assignment 5: deblurring – you can (probably) use your phone camera.
  - Assignment 6: light transport – you need a camera with RAW support.
  - Assignment 7: corner cameras – you need a high-sensitivity camera.
- We have 20 Nikon D3300/3400 kits (camera + lens + tripod) for students.
  - If you have your own camera, please use that!





# Contact information and office hours

- Feel free to email us about administrative questions.
  - please use [15463] in email title!
- Technical questions should be asked on Piazza.
  - we won't answer technical questions through email.
  - you can post anonymously if you prefer.
- Office hours will be determined by poll.
  - feel free to email Yannis about additional office hours.
  - you can also just drop by Yannis' office (Smith Hall (EDSH) Rm 225).

Please take the course survey (posted on Piazza)  
before the next lecture!