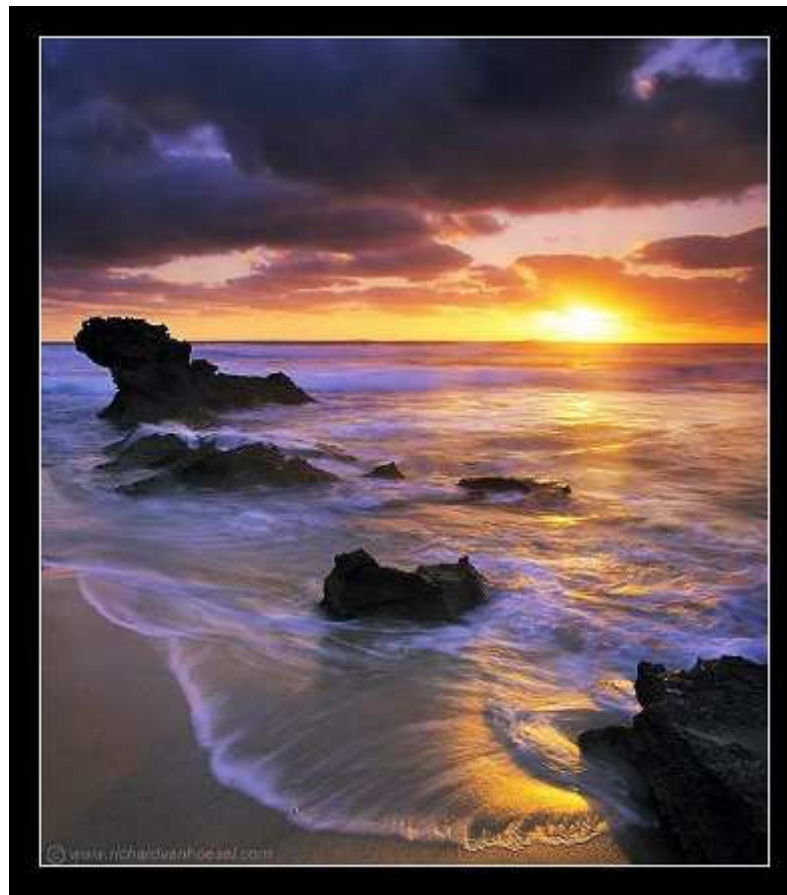


# Capturing Light... in man and machine

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15-463: Computational Photography  
Alexei Efros, CMU, Fall 2011

# Etymology

---

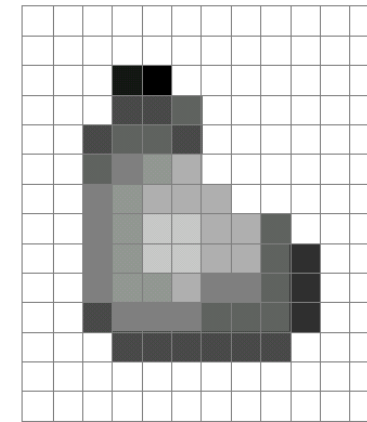
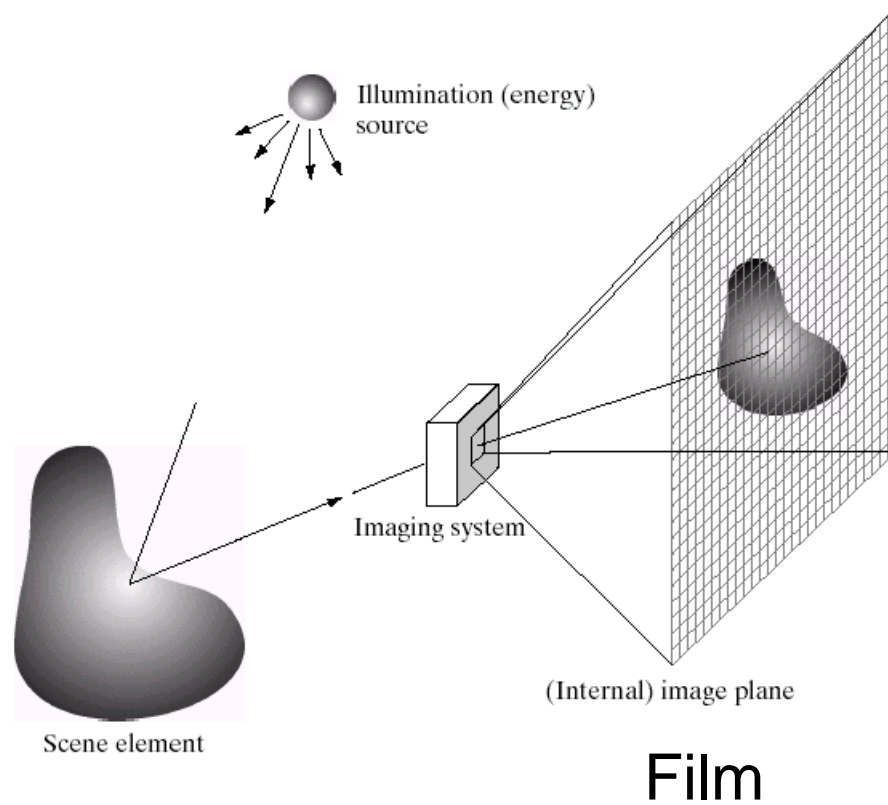
PHOTOGRAPHY

light

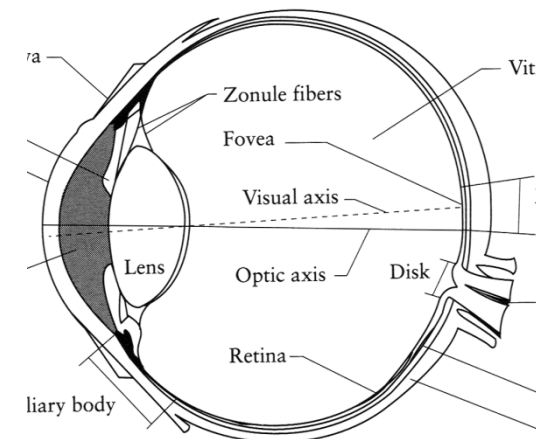
drawing  
/ writing

# Image Formation

---



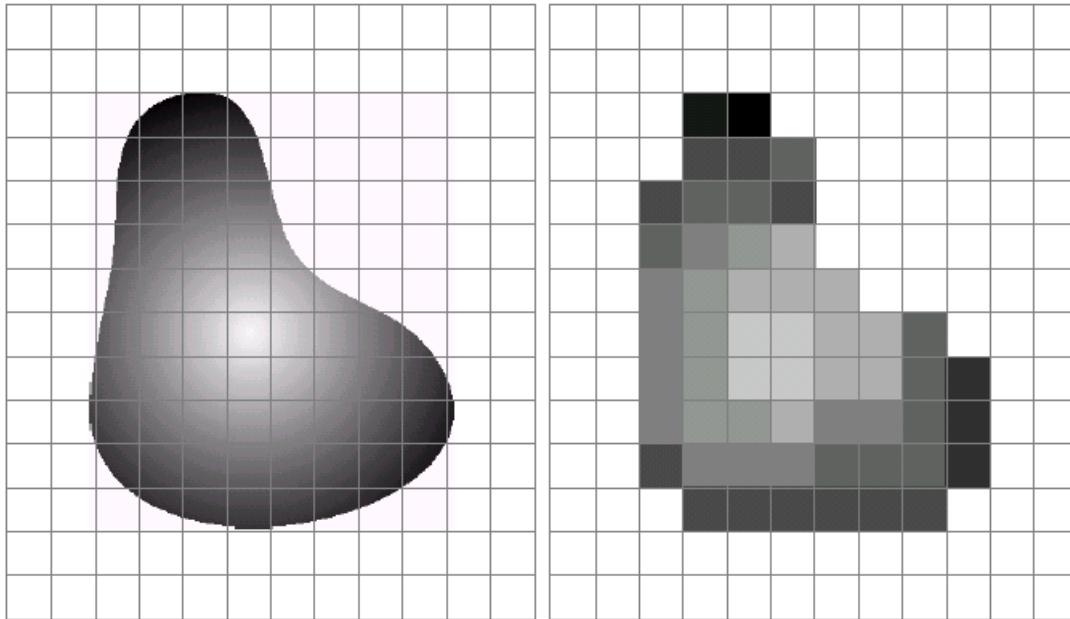
Digital Camera



The Eye

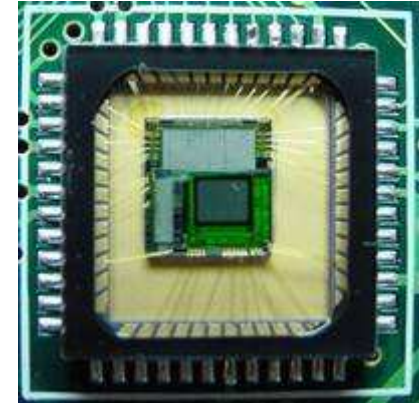
# Sensor Array

---



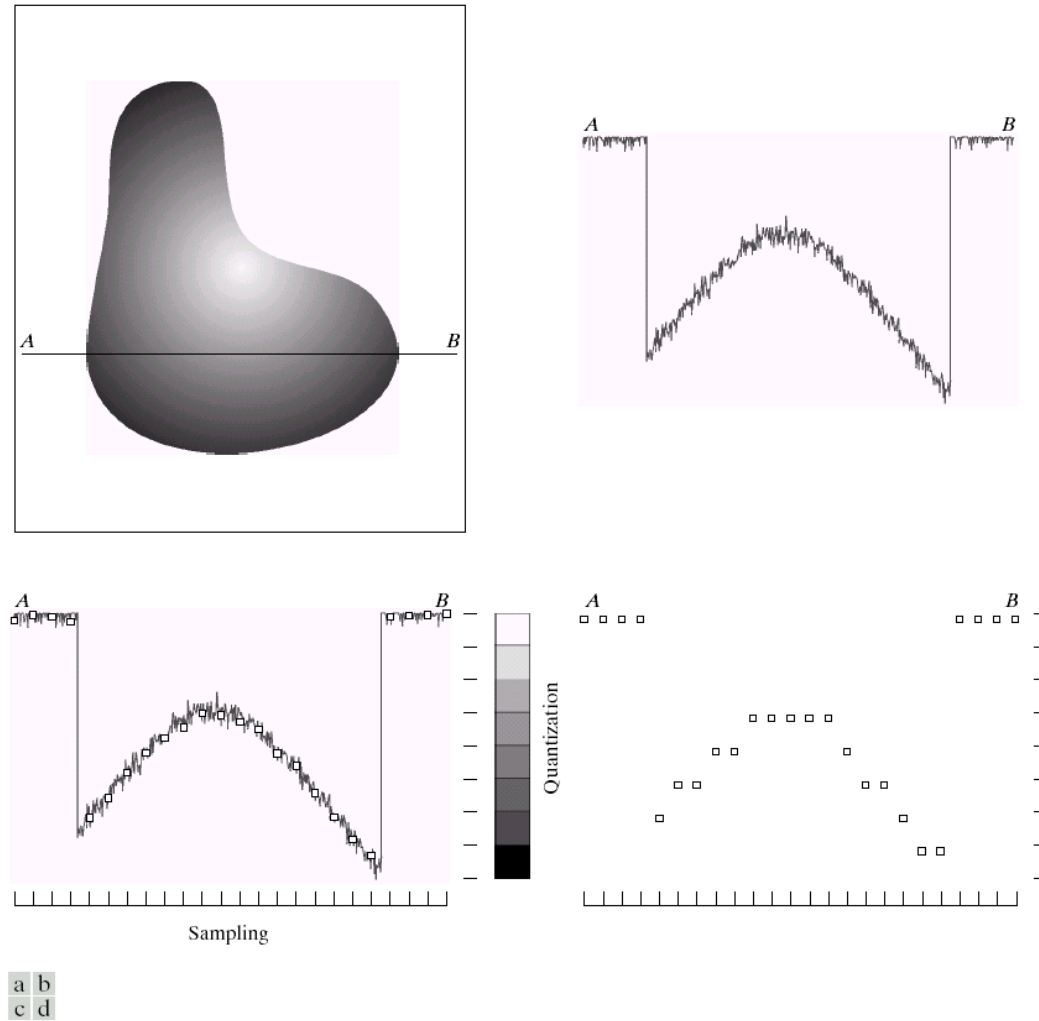
a b

**FIGURE 2.17** (a) Continuous image projected onto a sensor array. (b) Result of image sampling and quantization.



CMOS sensor

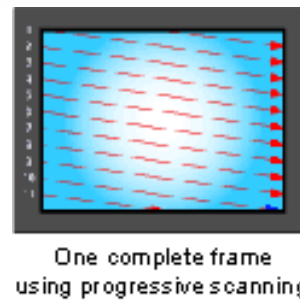
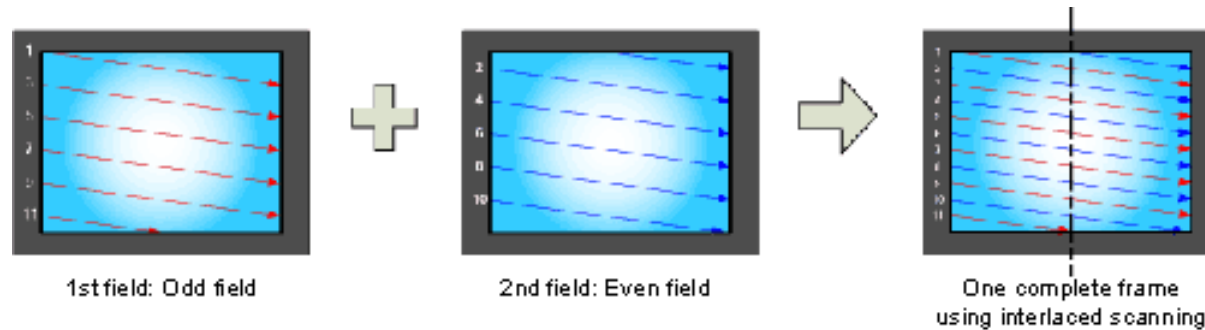
# Sampling and Quantization



**FIGURE 2.16** Generating a digital image. (a) Continuous image. (b) A scan line from *A* to *B* in the continuous image, used to illustrate the concepts of sampling and quantization. (c) Sampling and quantization. (d) Digital scan line.

# Interlace vs. progressive scan

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# Progressive scan

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[http://www.axis.com/products/video/camera/progressive\\_scan.htm](http://www.axis.com/products/video/camera/progressive_scan.htm)

Slide by Steve Seitz



# Interlace

---



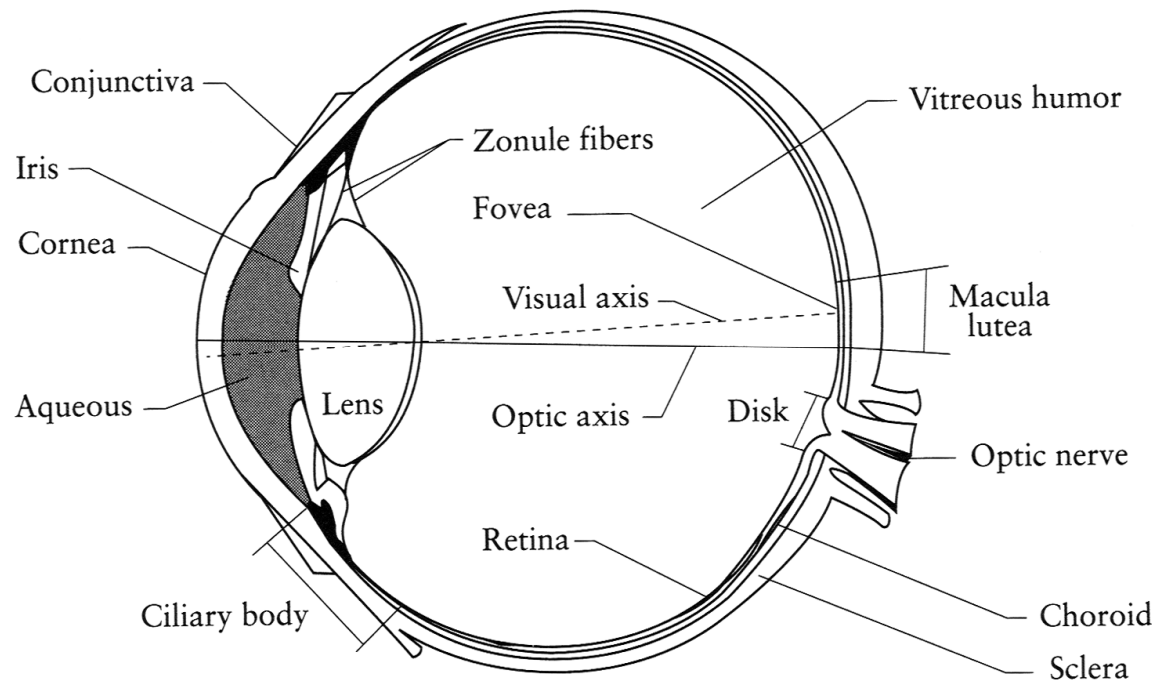
[http://www.axis.com/products/video/camera/progressive\\_scan.htm](http://www.axis.com/products/video/camera/progressive_scan.htm)

Slide by Steve Seitz



# The Eye

---

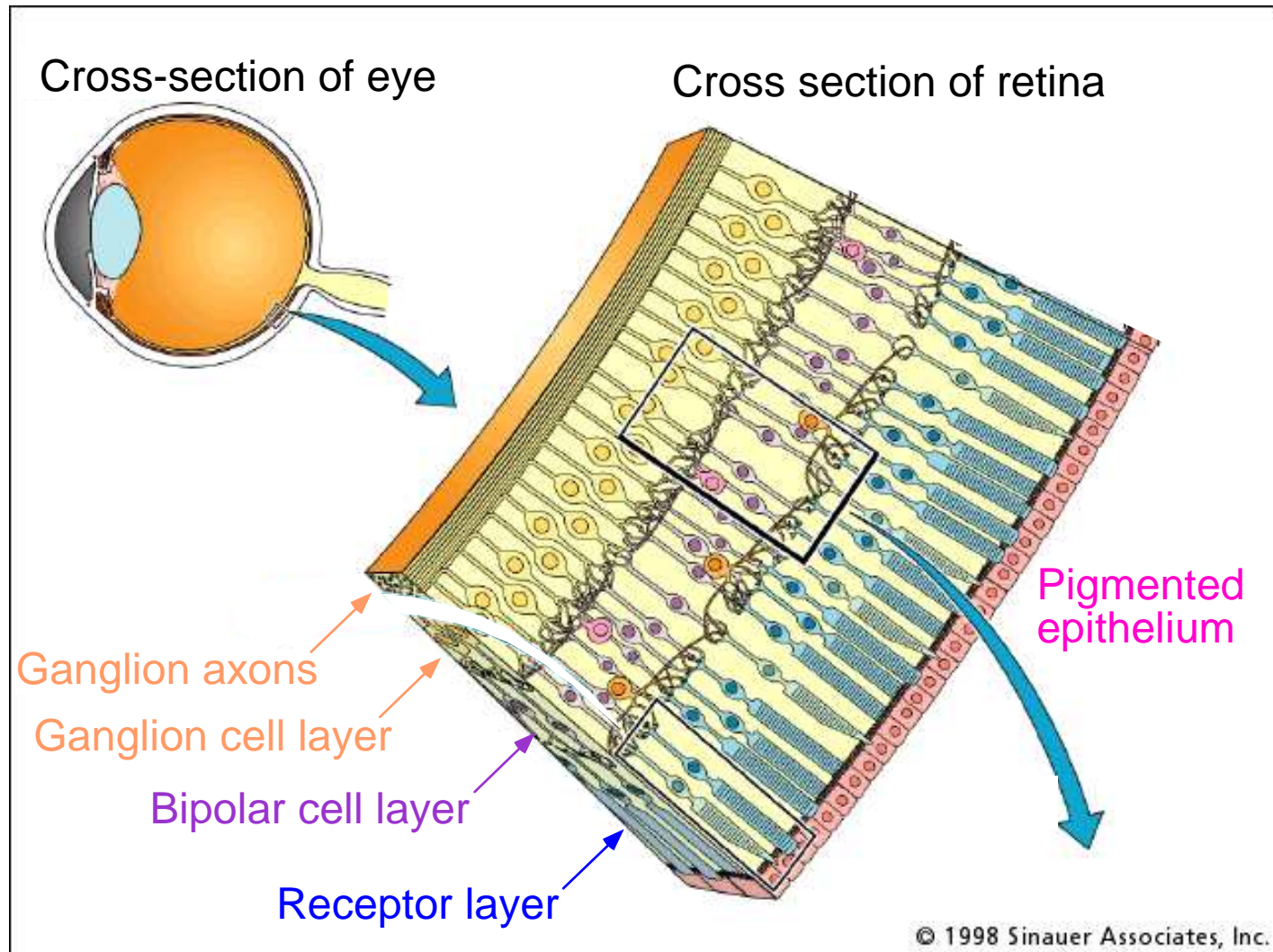


## The human eye is a camera!

- **Iris** - colored annulus with radial muscles
- **Pupil** - the hole (aperture) whose size is controlled by the iris
- What's the "film"?
  - photoreceptor cells (rods and cones) in the **retina**

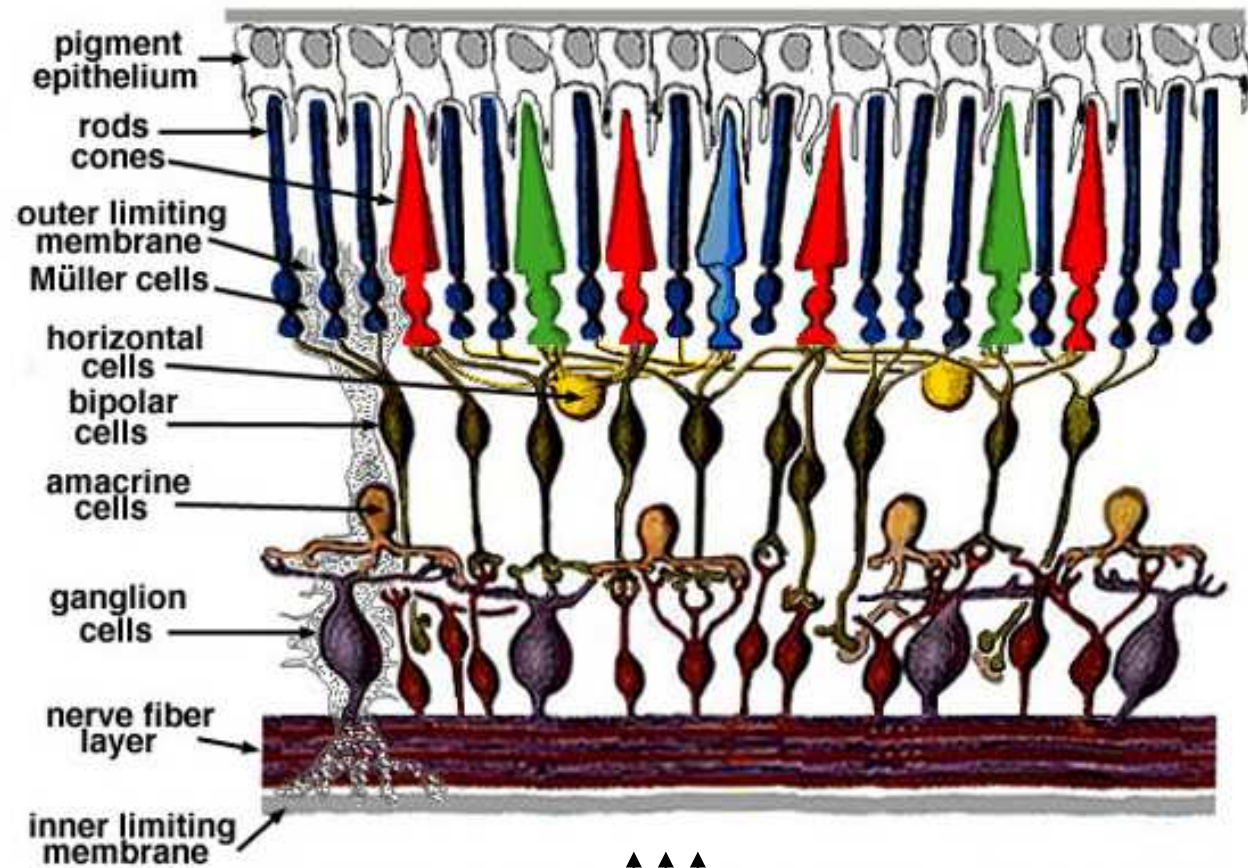
# The Retina

---



# Retina up-close

---



Light

# Two types of light-sensitive receptors

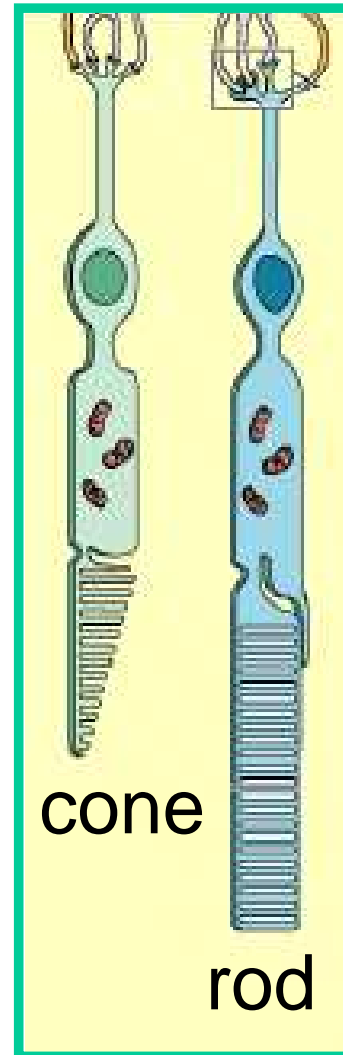
---

## **Cones**

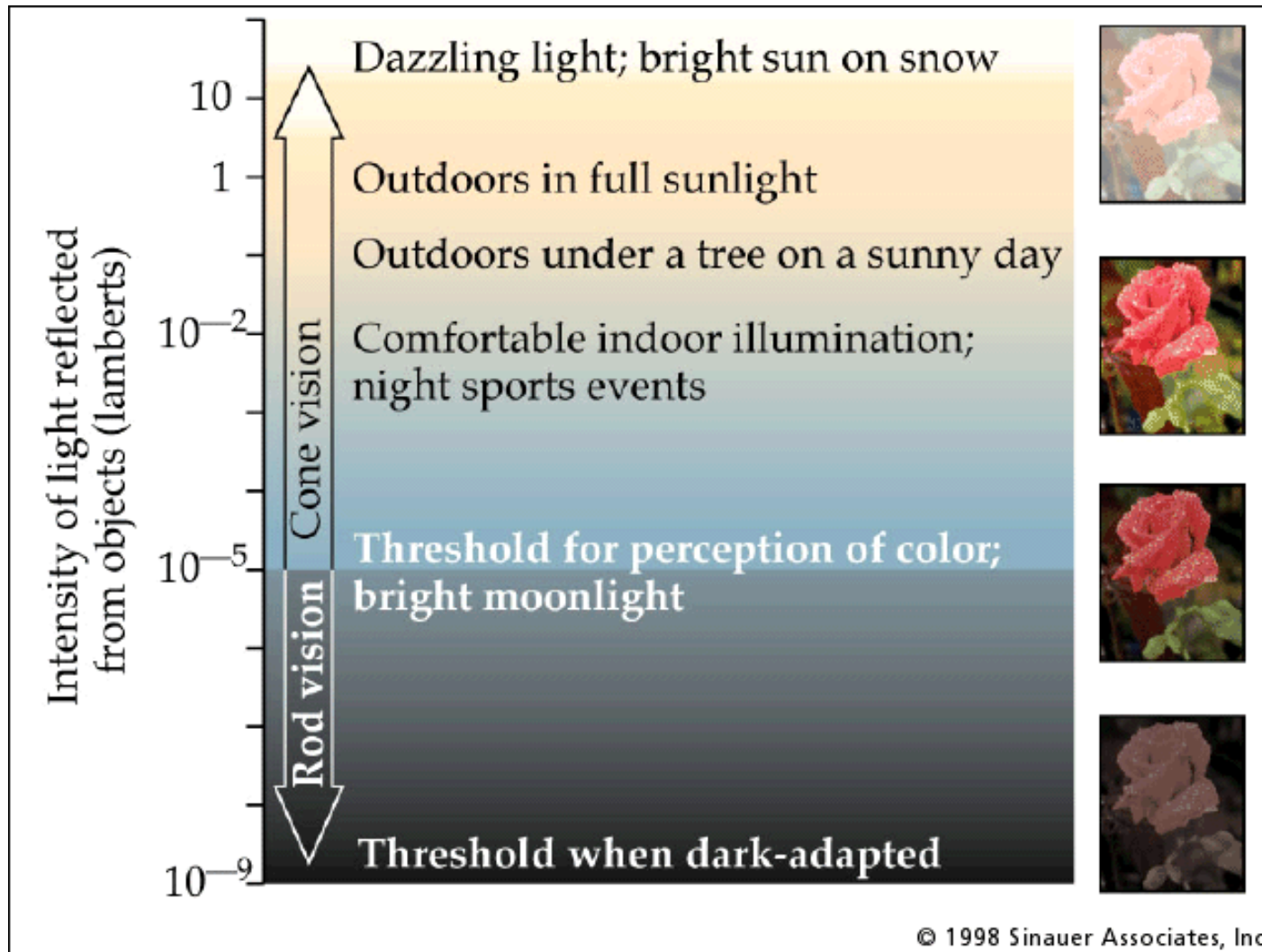
cone-shaped  
less sensitive  
operate in high light  
color vision

## **Rods**

rod-shaped  
highly sensitive  
operate at night  
gray-scale vision



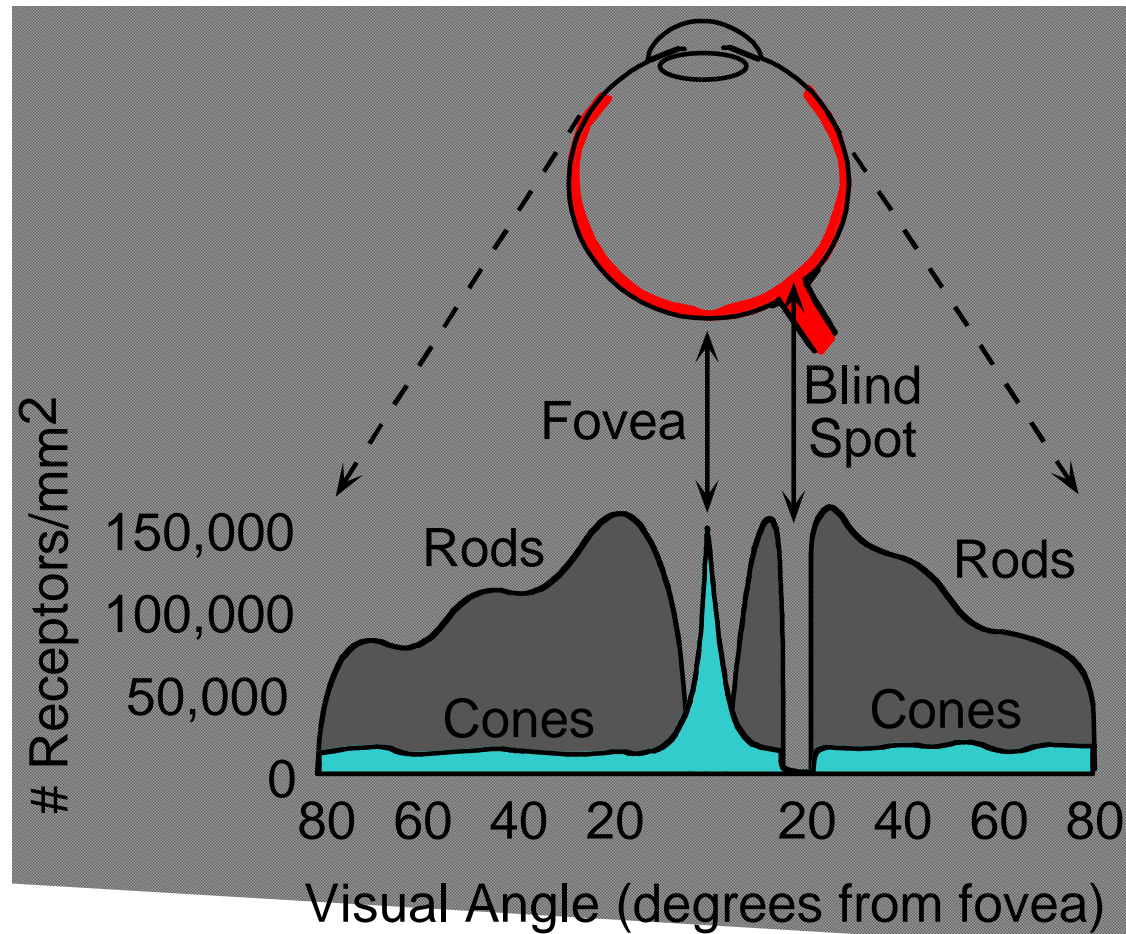
# Rod / Cone sensitivity



The famous sock-matching problem...

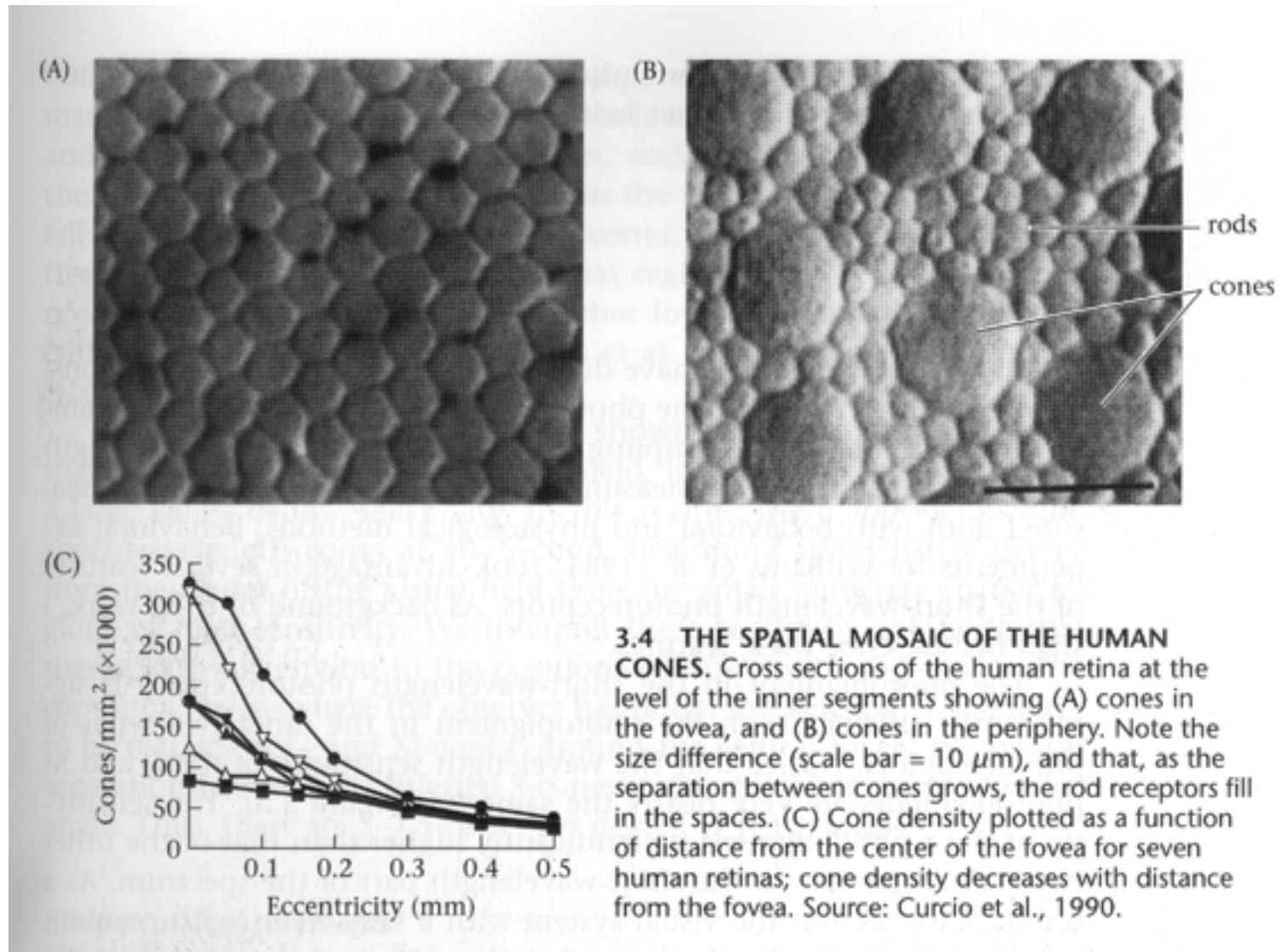
# Distribution of Rods and Cones

---



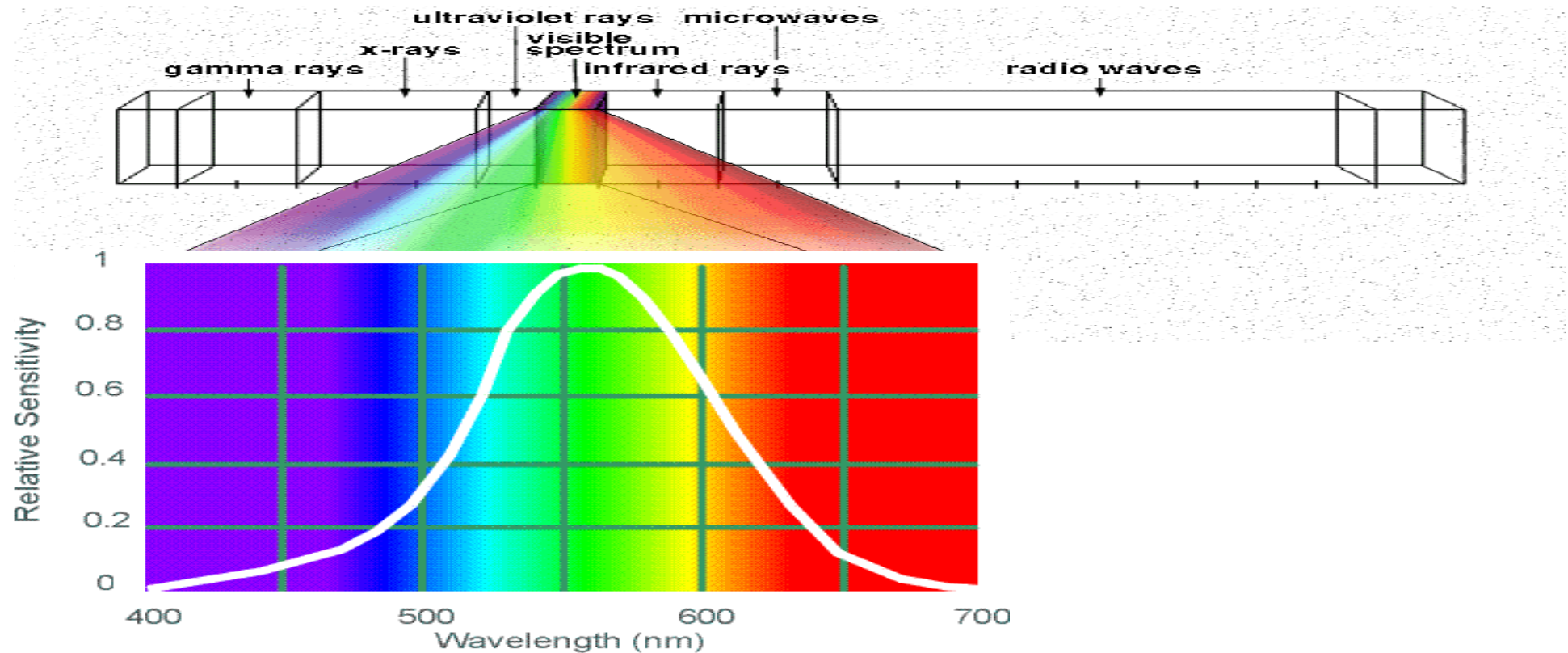
Night Sky: why are there more stars off-center?





# Electromagnetic Spectrum

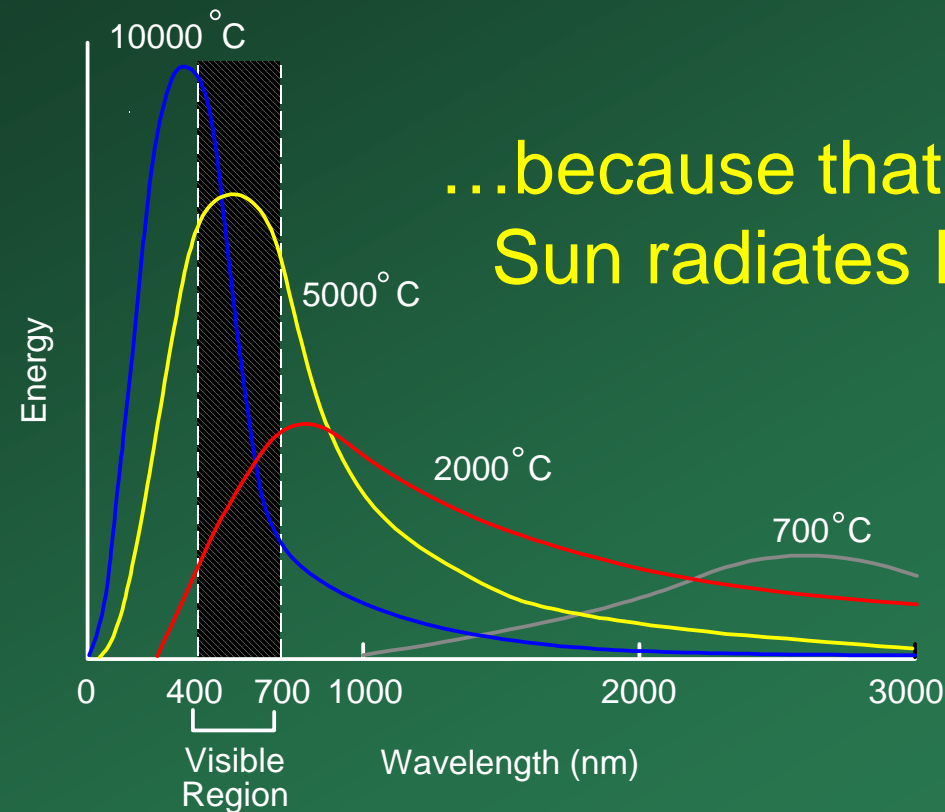
---



Human Luminance Sensitivity Function

# Visible Light

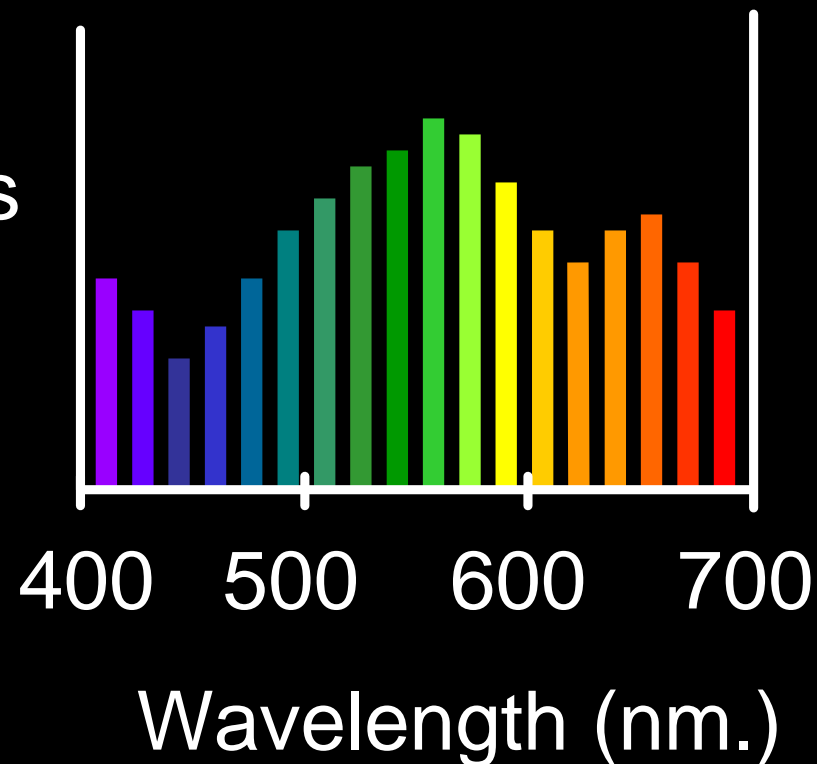
Why do we see light of these wavelengths?



# The Physics of Light

Any patch of light can be completely described physically by its spectrum: the number of photons (per time unit) at each wavelength 400 - 700 nm.

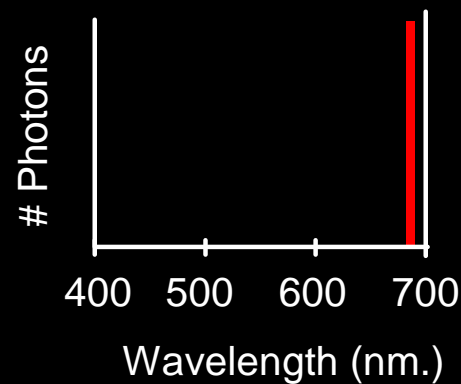
# Photons  
(per ms.)



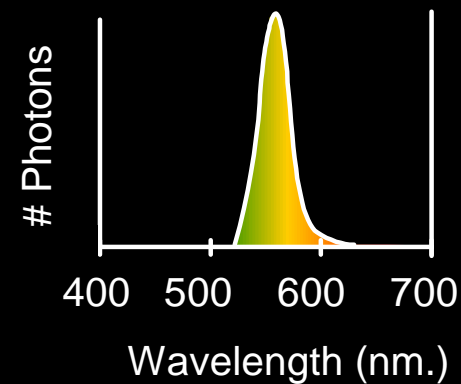
# The Physics of Light

## Some examples of the spectra of light sources

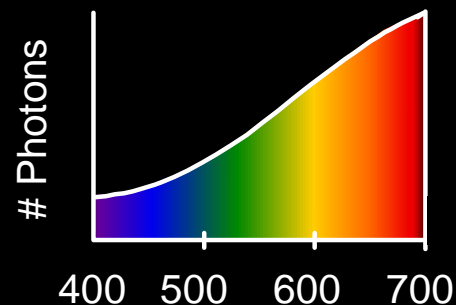
A. Ruby Laser



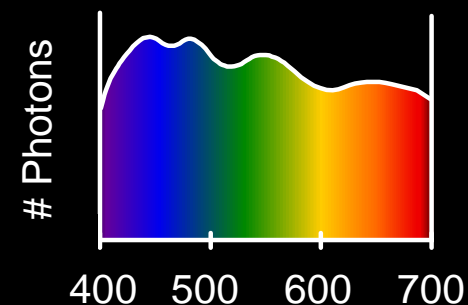
B. Gallium Phosphide Crystal



C. Tungsten Lightbulb



D. Normal Daylight

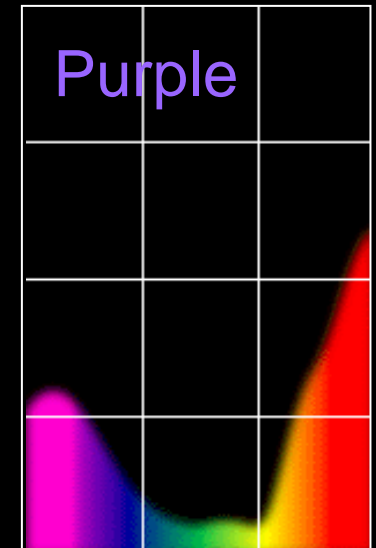
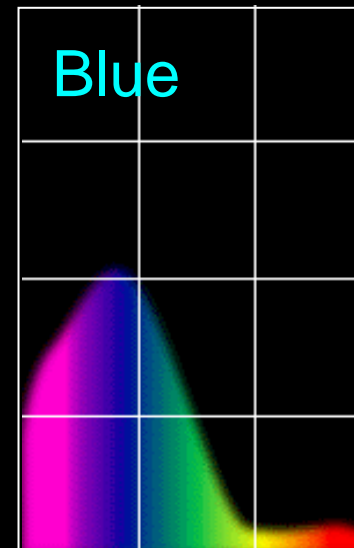
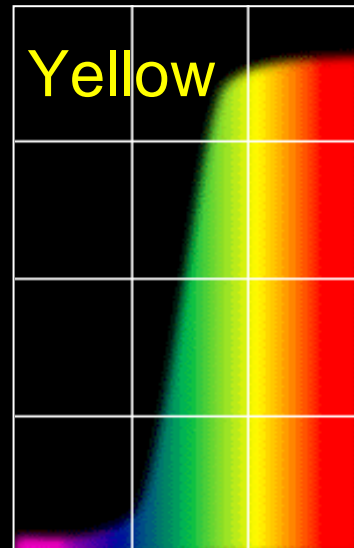
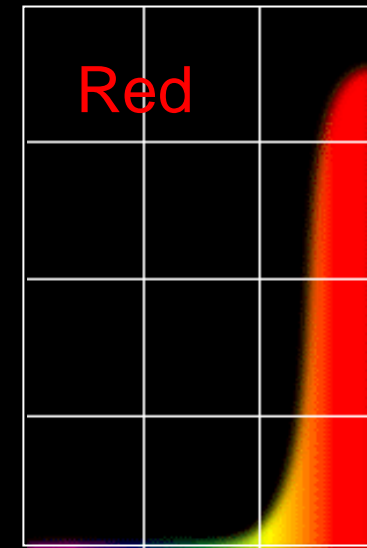


# The Physics of Light

Some examples of the reflectance spectra of surfaces



% Photons Reflected



400

700

400

700

400

700

400

700

Wavelength (nm)

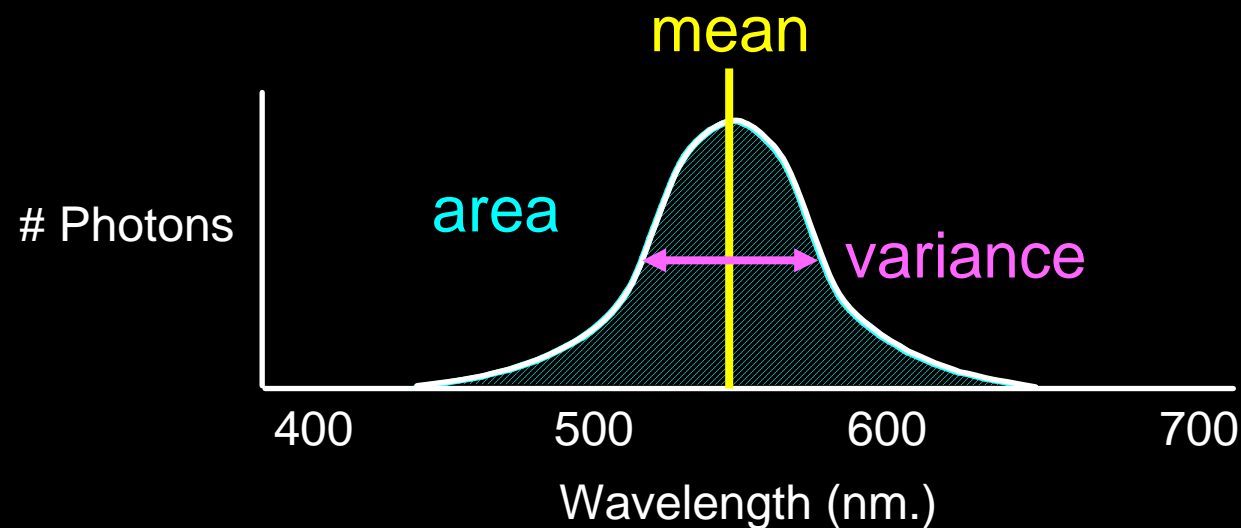


# The Psychophysical Correspondence

There is no simple functional description for the perceived color of all lights under all viewing conditions, but .....

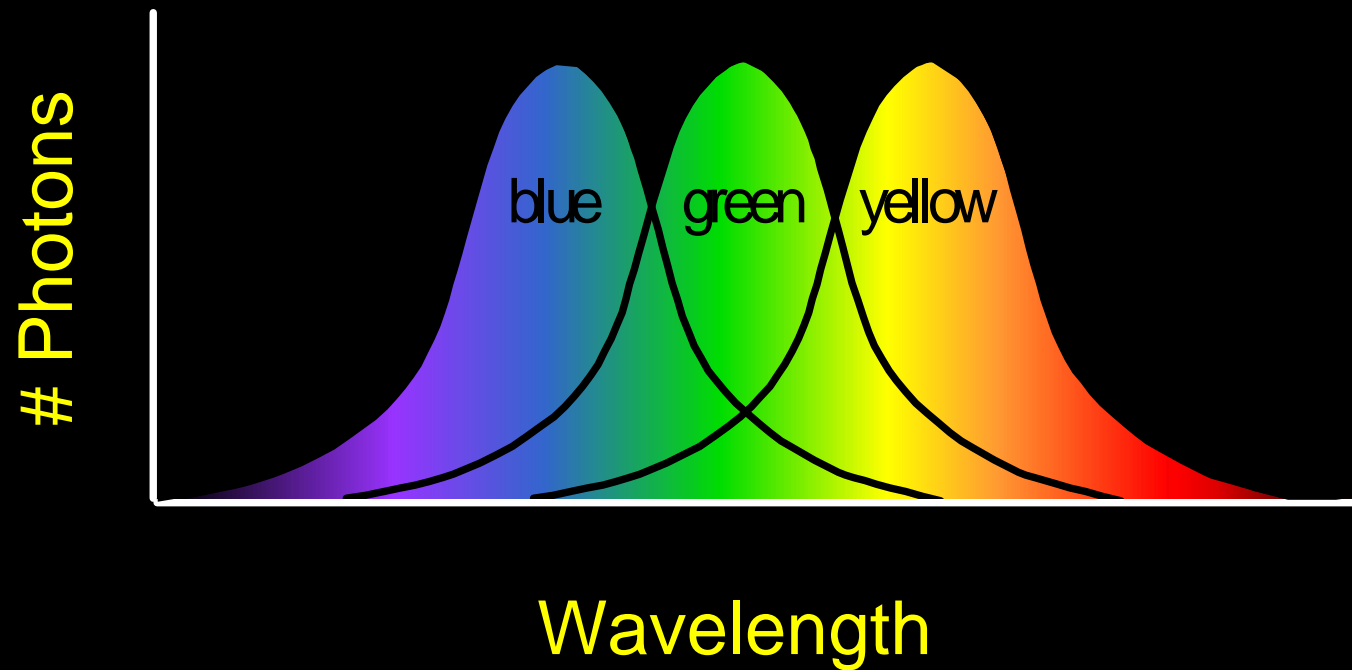
A helpful constraint:

Consider only physical spectra with normal distributions



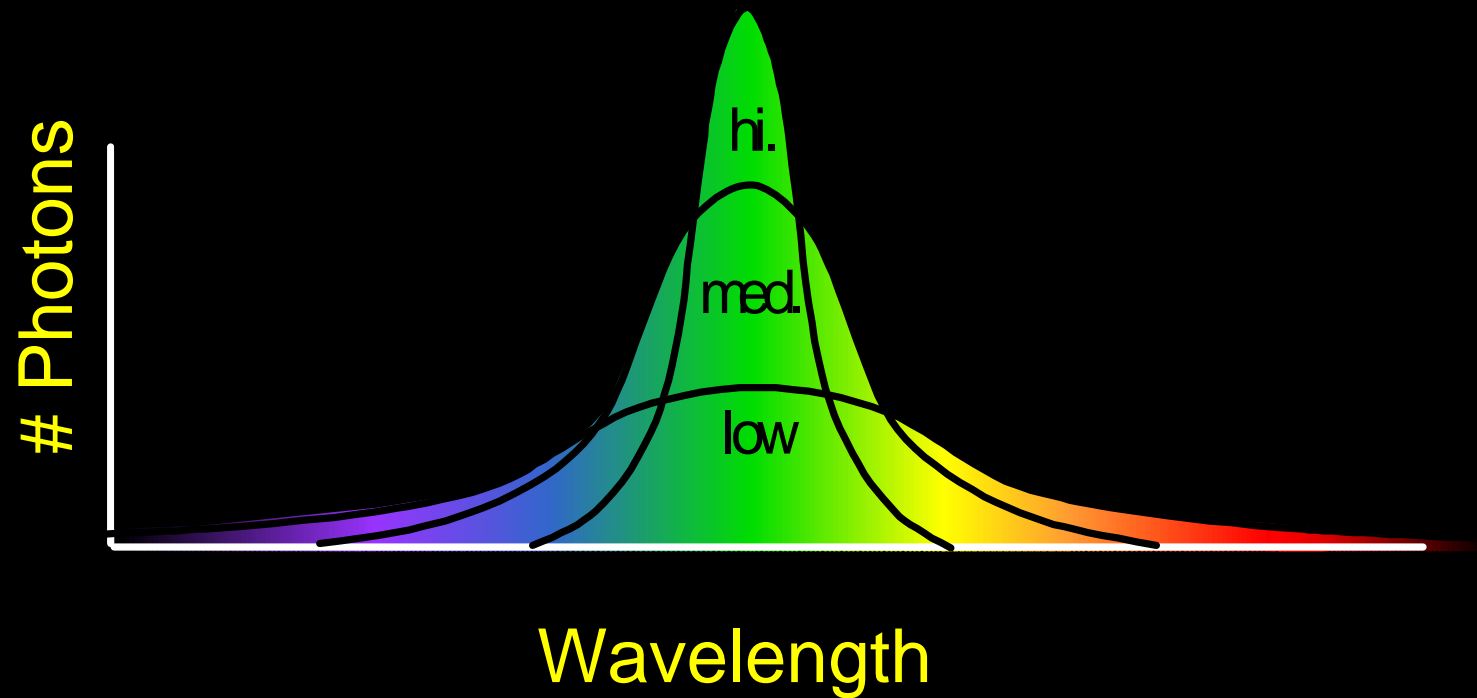
# The Psychophysical Correspondence

Mean  $\longleftrightarrow$  Hue



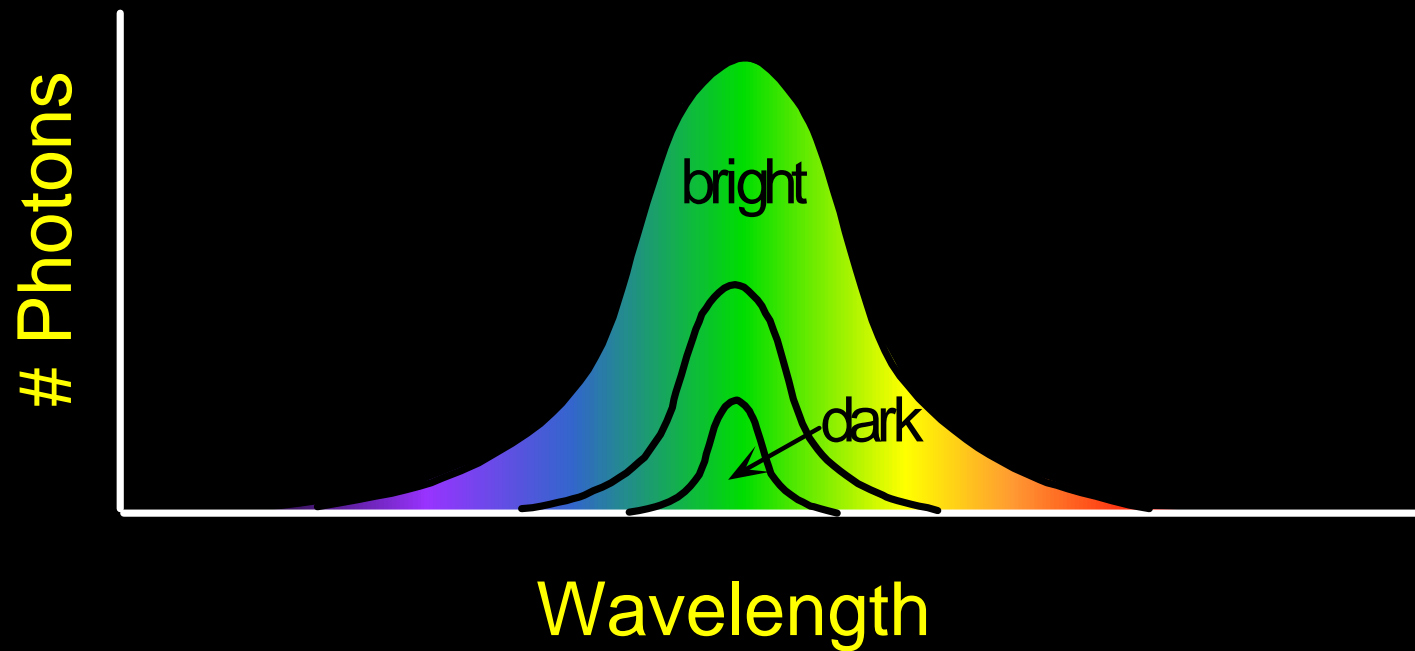
# The Psychophysical Correspondence

Variance  $\longleftrightarrow$  Saturation



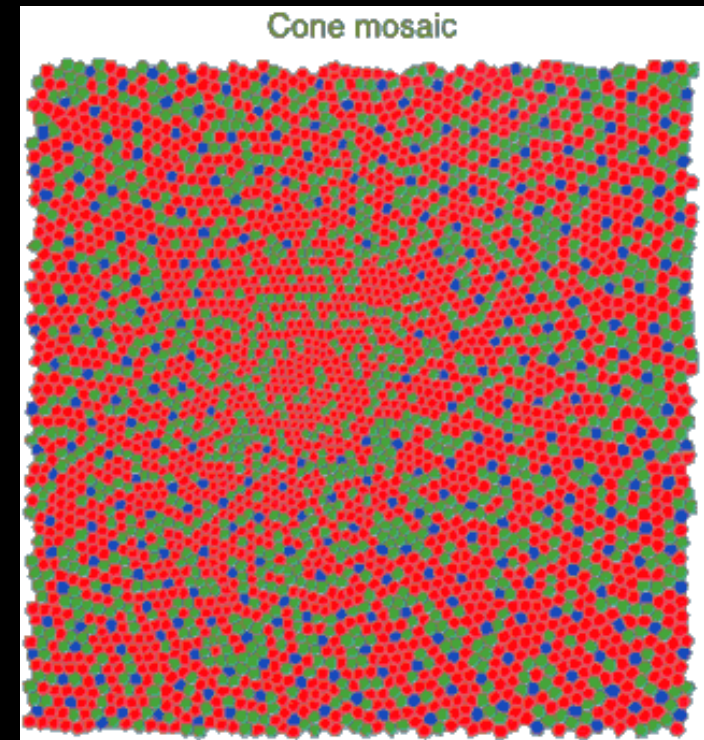
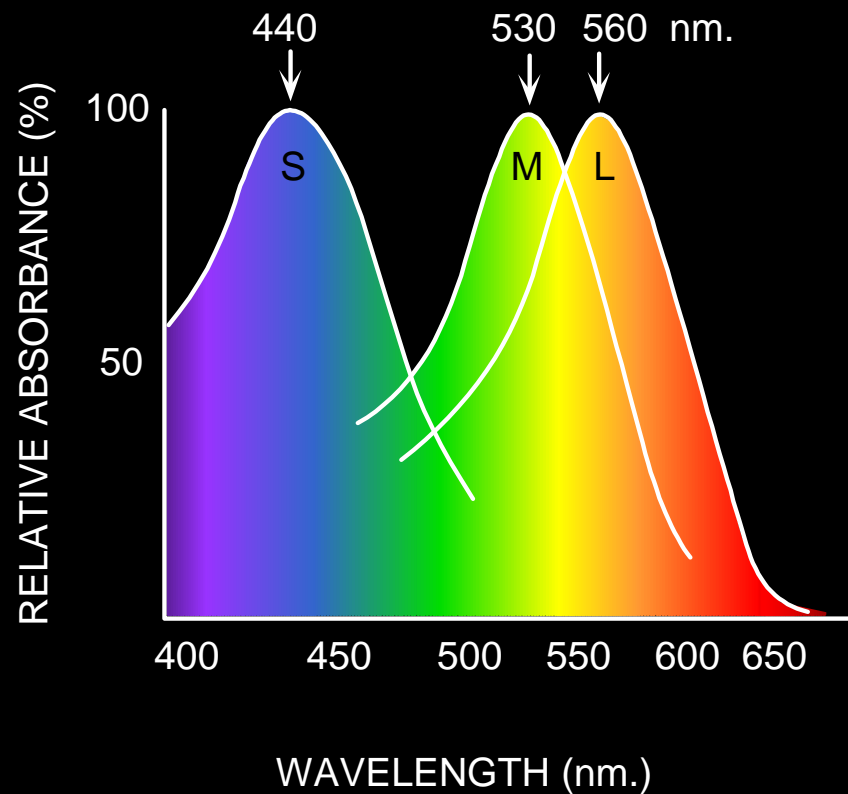
# The Psychophysical Correspondence

Area  $\longleftrightarrow$  Brightness



# Physiology of Color Vision

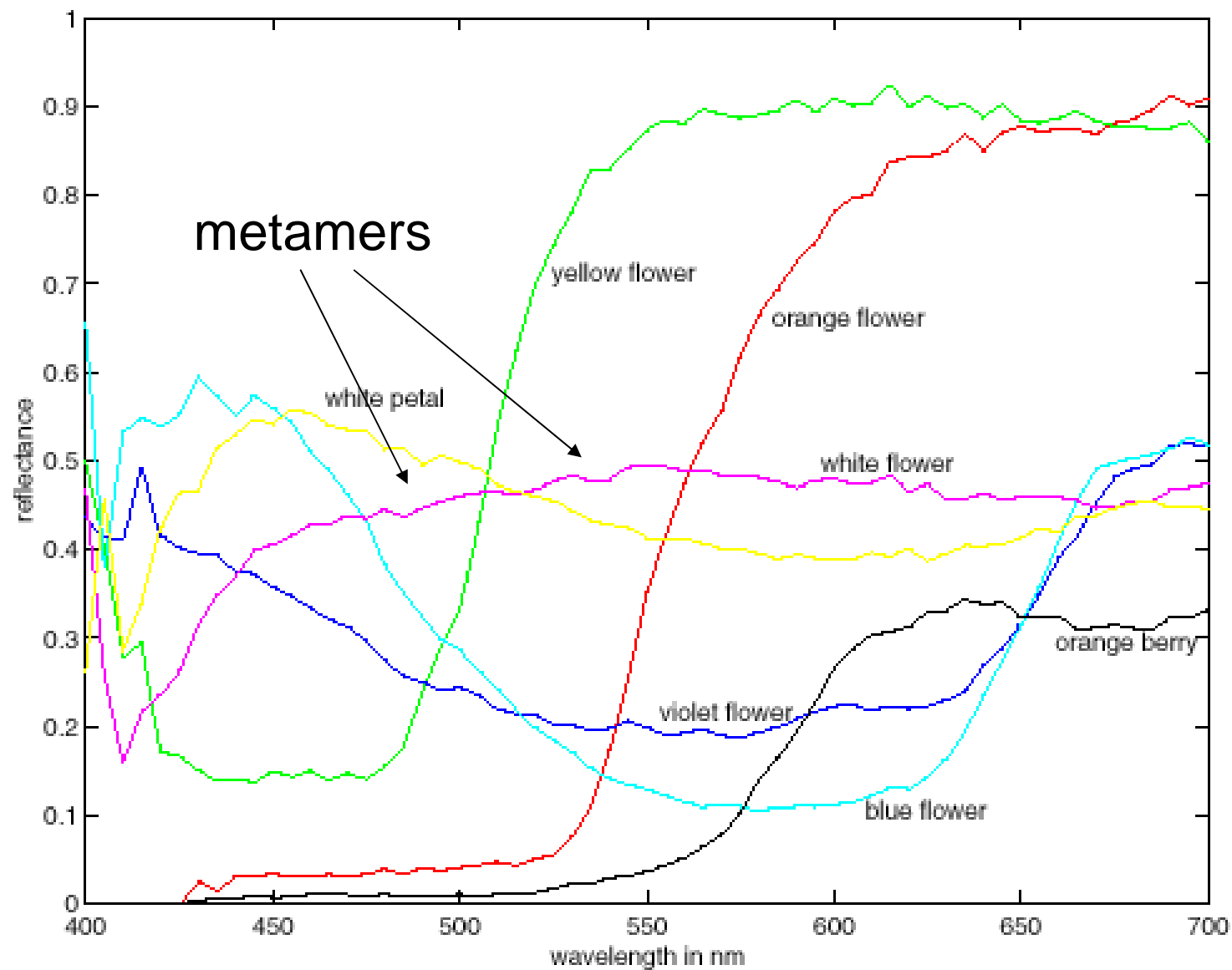
## Three kinds of cones:



- Why are M and L cones so close?
- Why are there 3?

# More Spectra

---





# Color Constancy

The “photometer metaphor” of color perception:  
Color perception is determined by the spectrum of light on each retinal receptor (as measured by a photometer).



# Color Constancy

The “photometer metaphor” of color perception:  
Color perception is determined by the spectrum of light on each retinal receptor (as measured by a photometer).



# Color Constancy

The “photometer metaphor” of color perception:  
Color perception is determined by the spectrum of light on each retinal receptor (as measured by a photometer).



# Color Constancy

~~Do we have constancy over  
all global color transformations?~~



60% blue filter



Complete inversion

# Color Constancy

Color Constancy: the ability to perceive the invariant color of a surface despite ecological Variations in the conditions of observation.

Another of these hard inverse problems:  
Physics of light emission and surface reflection  
underdetermine perception of surface color

# Camera White Balancing

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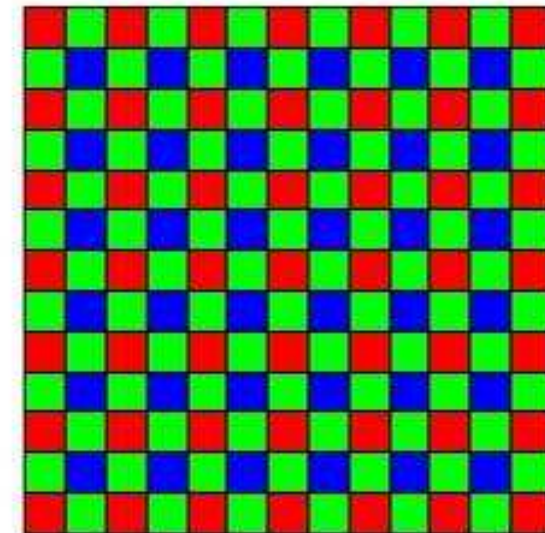
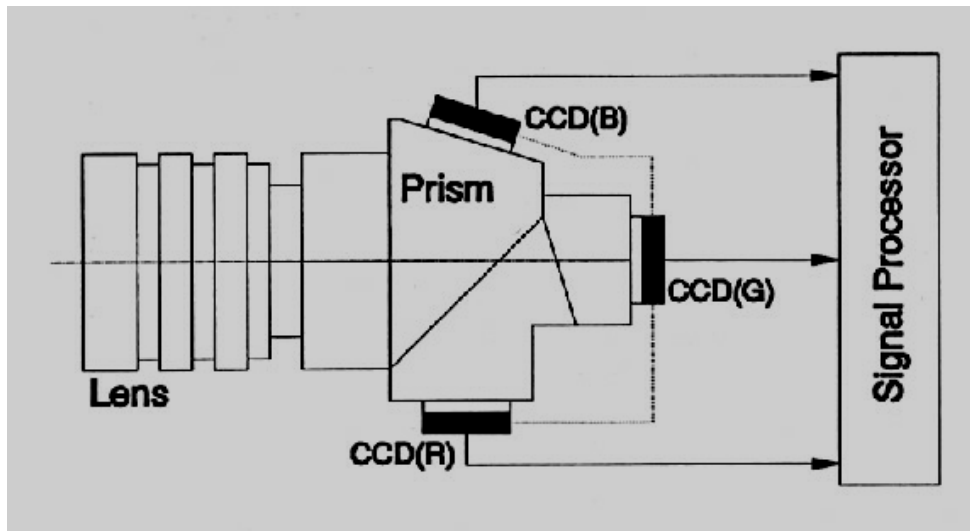
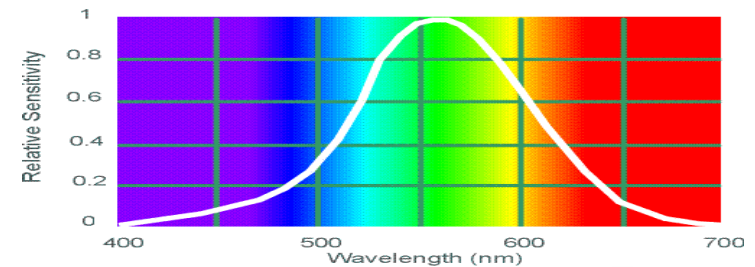
- Manual
  - Choose color-neutral object in the photos and normalize
- Automatic (AWB)
  - Grey World: force average color of scene to grey
  - White World: force brightest object to white



# Color Sensing in Camera (RGB)

3-chip vs. 1-chip: quality vs. cost

Why more green?



**Bayer filter**

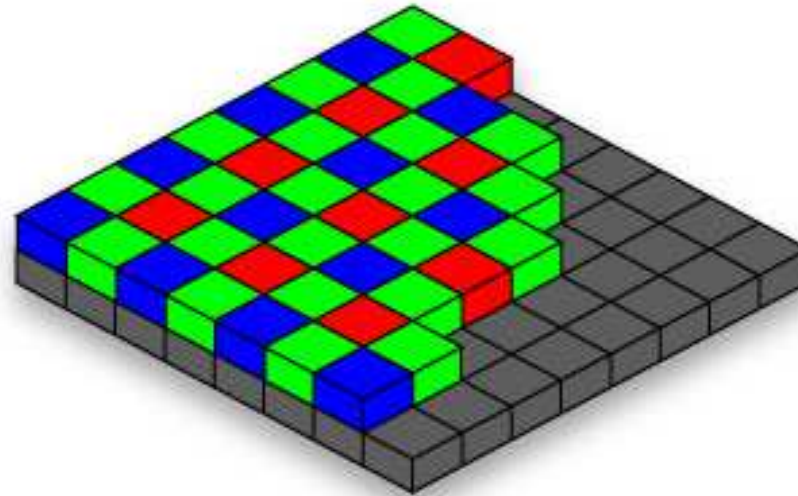
Ituff Works

Why 3 colors?

<http://www.cooldictionary.com/words/Bayer-filter.wikipedia>

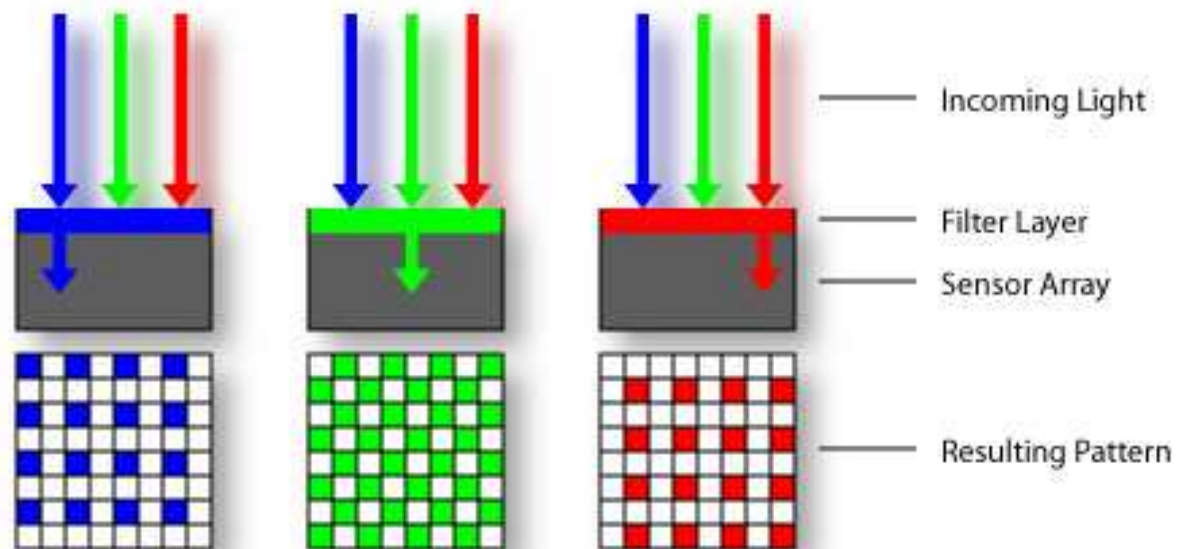
# Practical Color Sensing: Bayer Grid

---



Estimate RGB  
at 'G' cels from  
neighboring  
values

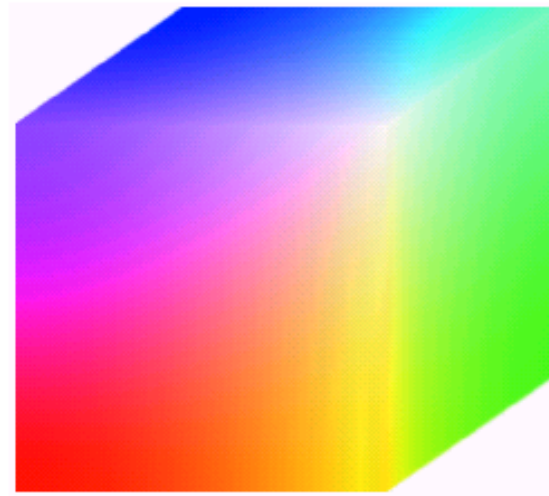
[http://www.cooldictionary.com/  
words/Bayer-filter.wikipedia](http://www.cooldictionary.com/words/Bayer-filter.wikipedia)



Slide by Steve Seitz

# RGB color space

---



**FIGURE 6.8** RGB 24-bit color cube.

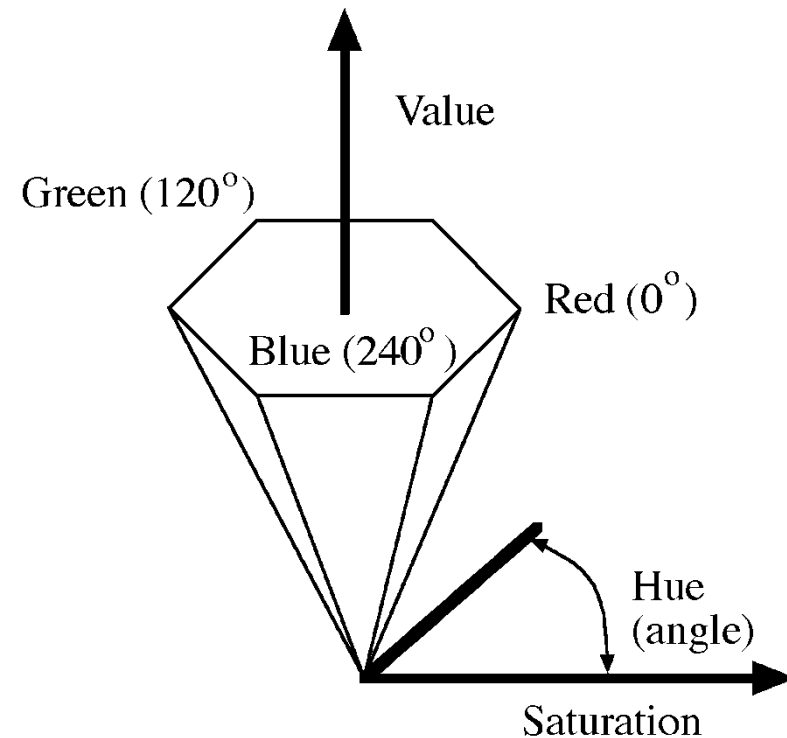
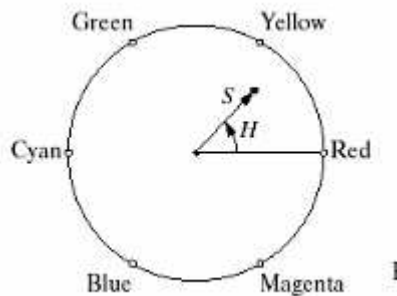
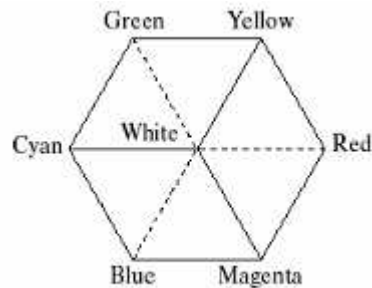
---

## RGB cube

- Easy for devices
- But not perceptual
- Where do the grays live?
- Where is hue and saturation?

# HSV

---



## Hue, Saturation, Value (Intensity)

- RGB cube on its vertex

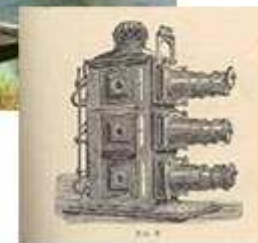
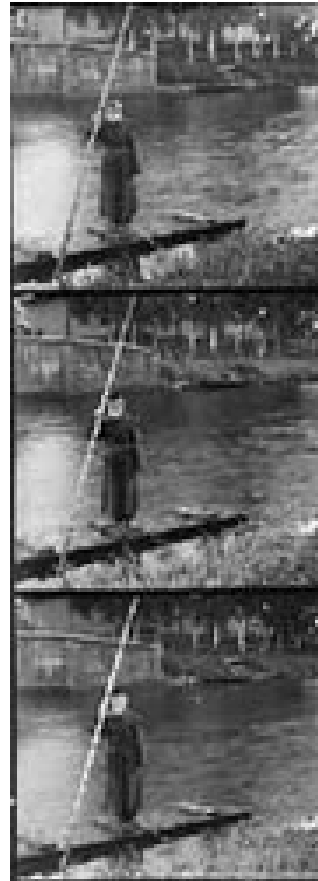
Decouples the three components (a bit)

Use `rgb2hsv()` and `hsv2rgb()` in Matlab

# Programming Project #1

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## Prokudin-Gorskii's Color Photography (1907)



# Programming Project #1

---

- How to compare R,G,B channels?
- No right answer
  - Sum of Squared Differences (SSD):

$$ssd(u, v) = \sum_{(x,y) \in N} [I(u+x, v+y) - P(x, y)]^2$$

- Normalized Correlation (NCC):

$$ncc(u, v) = \frac{\sum_{(x,y) \in N} [I(u+x, v+y) - \bar{I}] [P(x, y) - \bar{P}]}{\sqrt{\sum_{(x,y) \in N} [I(u+x, v+y) - \bar{I}]^2 \sum_{(x,y) \in N} [P(x, y) - \bar{P}]^2}}$$

